Please note that Cypress is an Infineon Technologies Company.
The document following this cover page is marked as “Cypress” document as this is the company that originally developed the product. Please note that Infineon will continue to offer the product to new and existing customers as part of the Infineon product portfolio.

Continuity of document content
The fact that Infineon offers the following product as part of the Infineon product portfolio does not lead to any changes to this document. Future revisions will occur when appropriate, and any changes will be set out on the document history page.

Continuity of ordering part numbers
Infineon continues to support existing part numbers. Please continue to use the ordering part numbers listed in the datasheet for ordering.
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Safety Information

Regulatory Compliance

The CY3280-MBR3 Evaluation Kit is intended for use as a development platform for hardware or software in a laboratory environment. The board is an open system design, which does not include a shielded enclosure. This may cause interference to other electrical or electronic devices in close proximity.

In a domestic environment, this product may cause radio interference. The user may then be required to take adequate prevention measures. Also, the board should not be used near any medical equipment or RF devices.

Attaching additional wiring to this product or modifying the product operation from the factory default may affect its performance and cause interference with other apparatus in the immediate vicinity. If such interference is detected, suitable mitigating measures should be taken.

The CY3280-MBR3 Evaluation Kit as shipped from the factory has been verified to meet the requirements of CE as a Class A product.

The CY3280-MBR3 Evaluation Kit contains ESD-sensitive devices. Electrostatic charges readily accumulate on the human body and any equipment, and can discharge without detection. Permanent damage may occur on devices subjected to high-energy discharges. Proper ESD precautions are recommended to avoid performance degradation or loss of functionality. Store unused CY3280-MBR3 boards in the protective shipping package.

End-of-Life/Product Recycling

This kit has an end-of life five years from the date of manufacture mentioned on the back of the box. Contact your nearest recycler for disposing the kit.
General Safety Instructions

ESD Protection

ESD can damage boards and associated components. Cypress recommends that you perform procedures only at an ESD workstation. If an ESD workstation is not available, use appropriate ESD protection by wearing an antistatic wrist strap attached to chassis ground (any unpainted metal surface) on your board when handling parts.

Handling Boards

CY3280-MBR3 boards are sensitive to ESD. Hold the board only by its edges. After removing the board from its box, place it on a grounded, static-free surface. Use a conductive foam pad if available. Do not slide board over any surface.
Thank you for your interest in the CY3280-MBR3 Evaluation Kit (EVK). This kit is designed to showcase the abilities of the CY8CMBR3116 register-configurable CapSense® controller. It is also designed as an Arduino™-compatible shield that supports various Arduino baseboards as well as other stackable shields available in the market. The CY3280-MBR3 EVK features four CapSense buttons, one proximity sensor loop, LEDs, a buzzer, and an onboard USB-I2C bridge to communicate with the EZ-Click™ software tool, which configures the CY8CMBR3xxx controller.

The CY8CMBR3xxx series is the latest addition to the register-configurable CapSense Mechanical Button Replacement (MBR) family of solutions. The CY8CMBR3xxx family of controllers enables you to quickly and easily add capacitive touch sensing to your user interface. See Configuring the CY8CMBR3116 Controller Using EZ-Click on page 18 for information on how to configure a CY8CMBR3116 controller. CY3280-MBR3 offers the best features of Cypress’ CapSense in a small package that is easy to implement and configure. Coupled with the Capacitive Sigma Delta PLUS (CSD PLUS) sensing algorithm and the patented SmartSense™ Auto-Tuning feature, the CY8CMBR3xxx controller provides a robust capacitive sensing solution, with up to 16 CapSense inputs.

SmartSense Auto-Tuning has the following advantages:

- Reduces design effort by eliminating manual tuning
- Adapts to variations in PCB, overlay, paint, and manufacturing that degrade touch-sensing performance
- Eliminates manual tuning in production
- Adapts to changes in the system environment due to noise
- Allows a platform design approach with different overlays, button shapes, and trace lengths

The MBR3 solution delivers a high signal-to-noise ratio (SNR) even in extremely noisy environments and maintains optimal sensor performance at run time. The driven shield capability offers robust proximity sensing and water tolerance, enabling its use in a wide range of applications. The MBR3 solution supports register configurability and SmartSense Auto-Tuning features, which allow customers to gain a faster time-to-market for their end product.

The CY8CMBR3xxx family of controllers is designed with multiple low-power operational states to meet the low-power requirements of battery-powered applications. These controllers have the following operational states: Boot, Active, Look-for-Touch, Look-for-Proximity, Deep Sleep, and Configuration. The CY8CMBR3xxx controllers automatically manage transitions between the four states. The Look-for-Proximity state allows ultra-low power consumption when a human body is not in close proximity. This state is entered only if the wake-on-approach feature is enabled (and toggle is disabled) in the MBR3 register configuration, which can be done using EZ-Click. Refer to the MBR3 device datasheet for more details on the CY8CMBR3xxx family of CapSense controllers.

The kit package includes EZ-Click, which is required to configure the kit. For more information and to download the tool, visit the EZ-Click webpage.
1.1 Kit Contents

The CY3280-MBR3 EVK includes the following components (see Figure 1-1):

- CY3280-MBR3 EVK with a 2-mm overlay
- One additional overlay of 1-mm thickness
- A to Mini-B USB cable
- Water dropper

Figure 1-1. Kit Contents

Inspect the contents of the kit. If you find any part missing, contact your nearest Cypress sales office for help: www.cypress.com/go/support.

1.2 Getting Started

This kit guide helps to familiarize you with the CY3280-MBR3 EVK. The Kit Installation chapter on page 11 describes the installation of the EVK software. The Kit Operation chapter on page 14 explains how to configure the CY8CMBR3116 controller on the kit to test different features using EZ-Click. The hardware details, and configuration files and example projects are explained in their respective chapters. The configuration files and example projects require EZ-Click and PSoC Creator™, respectively. The Advanced Topics chapter on page 70 describes how to use the Bridge Control Panel (BCP) to configure the MBR3 device. The Appendix on page 76 provides the schematics, board layout, pin assignment, and the bill of materials (BOM).
1.3 Factory Default Configuration

The kit installation folder includes three configuration files that demonstrate several features of the CY8CMBR3116 CapSense controller. See Configuration Files on page 46 for more details. The CY3280-MBR3 EVK is configured with the Water Tolerance configuration by default. In this configuration, water tolerance, flanking sensor suppression (FSS), and auto-reset features are enabled for four CapSense buttons. The LEDs are also enabled to provide visual feedback for CapSense button touch. For more details on configuring the MBR3 device, refer to the EZ-Click User Guide, available at <Install_Directory>\EZ-Click\<version>\Documentation.

1.4 Additional Learning Resources

Visit the CY8CMBR3116 CapSense Controller page for additional learning resources.

Visit the CY8CMBR3xxx CapSense Design Guide page for additional Host API-based demo projects.

Visit the CapSense Code Examples page for the list of code examples using CapSense controllers.

1.5 Technical Support

For assistance, go to our support web page, or contact our customer support at +1(800) 541-4736 extension 2 (in the USA), or +1 (408) 943-2600 extension 2 (International).

1.6 Acronyms

Table 1-1. Acronyms Used in the Document

<table>
<thead>
<tr>
<th>Acronyms</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>BCP</td>
<td>Bridge Control Panel</td>
</tr>
<tr>
<td>BOM</td>
<td>bill of materials</td>
</tr>
<tr>
<td>CS</td>
<td>capacitive sensor</td>
</tr>
<tr>
<td>CSD</td>
<td>CapSense sigma delta</td>
</tr>
<tr>
<td>ESD</td>
<td>electrostatic discharge</td>
</tr>
<tr>
<td>EVK</td>
<td>evaluation kit</td>
</tr>
<tr>
<td>FSS</td>
<td>flanking sensor suppression</td>
</tr>
<tr>
<td>GPO</td>
<td>general-purpose output</td>
</tr>
<tr>
<td>GUI</td>
<td>graphical user interface</td>
</tr>
<tr>
<td>I2C/IIC</td>
<td>inter-integrated circuit</td>
</tr>
<tr>
<td>LED</td>
<td>light-emitting diode</td>
</tr>
<tr>
<td>MBR</td>
<td>mechanical button replacement</td>
</tr>
<tr>
<td>NC</td>
<td>not connected</td>
</tr>
<tr>
<td>PC</td>
<td>personal computer</td>
</tr>
<tr>
<td>PCB</td>
<td>printed circuit board</td>
</tr>
<tr>
<td>PSoC®</td>
<td>Programmable System-On-Chip</td>
</tr>
<tr>
<td>SNR</td>
<td>signal-to-noise ratio</td>
</tr>
<tr>
<td>UART</td>
<td>universal asynchronous receiver/transmitter</td>
</tr>
<tr>
<td>USB</td>
<td>universal serial bus</td>
</tr>
</tbody>
</table>
### 1.7 Document Conventions

Table 1-2. Document Conventions for Guides

<table>
<thead>
<tr>
<th>Convention</th>
<th>Usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>Courier New</td>
<td>Displays file locations, user entered text, and source code:</td>
</tr>
<tr>
<td></td>
<td>C:...cd\icc\</td>
</tr>
<tr>
<td><em>Italics</em></td>
<td>Displays file names and reference documentation:</td>
</tr>
<tr>
<td></td>
<td>Read about the <em>sourcefile.hex</em> file in the <em>PSoC Designer User Guide</em>.</td>
</tr>
<tr>
<td><em>[Bracketed, Bold]</em></td>
<td>Displays keyboard commands in procedures:</td>
</tr>
<tr>
<td></td>
<td><em>[Enter]</em> or <em>[Ctrl]</em> <em>[C]</em></td>
</tr>
<tr>
<td>File &gt; Open</td>
<td>Represents menu paths:</td>
</tr>
<tr>
<td></td>
<td>File &gt; Open &gt; New Project</td>
</tr>
<tr>
<td><em>Bold</em></td>
<td>Displays commands, menu paths, and icon names in procedures:</td>
</tr>
<tr>
<td></td>
<td>Click the <em>File</em> icon and then click <em>Open</em>.</td>
</tr>
<tr>
<td>Times New Roman</td>
<td>Displays an equation:</td>
</tr>
<tr>
<td></td>
<td>2 + 2 = 4</td>
</tr>
<tr>
<td>Text in gray boxes</td>
<td>Describes Cautions or unique functionality of the product.</td>
</tr>
</tbody>
</table>
2. Kit Installation

This chapter describes the CY3280-MBR3 EVK software installation and the prerequisites.

2.1 Before You Begin

All Cypress software installations require administrator privileges, but these are not required to run the software after it is installed. Close any other Cypress software that is currently running before installing the kit software.

2.2 CY3280-MBR3 EVK Software

The kit requires Cypress’ proprietary software, such as PSoC Programmer (3.24.2 or later) and EZ-Click (2.0 SP2 or later), and generic software such as .NET Framework, Windows Installer, and Internet Explorer. The CY3280-MBR3 software is available on the kit web page in three formats:

Table 2-1. Kit Software Formats

<table>
<thead>
<tr>
<th>Install Package</th>
<th>File Format</th>
<th>Usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>CY3280-MBR3 Kit ISO</td>
<td>ISO</td>
<td>This package can be used if the PC does not have any Cypress or non-Cypress prerequisite software installed. It first installs the prerequisites and then the kit content (firmware, hardware, and documentation files) in the specified location.</td>
</tr>
<tr>
<td>CY3280-MBR3 Kit Setup</td>
<td>EXE</td>
<td>This package can be used if the PC does not have any Cypress prerequisite software installed. If any non-Cypress prerequisites are found to be missing during installation, the installer provides links to download and install them and then installs the kit content (firmware, hardware, and documentation files) in the specified location.</td>
</tr>
<tr>
<td>CY3280-MBR3 Kit Only</td>
<td>EXE</td>
<td>This package can be used if the PC has all the Cypress and non-Cypress prerequisites installed. It installs only the kit content (firmware, hardware, and documentation files) in the specified location. If any of the prerequisites are found missing during the installation process, the installer prompts you to install all the required software before attempting to install the kit. The installer redirects to the kit web page to download and install any missing Cypress software. Similarly, it provides links to download and install the missing non-Cypress prerequisites.</td>
</tr>
</tbody>
</table>

Notes:

- Adobe Reader is required to view kit documents. If Adobe Reader is not installed on your PC, the installer provides the link to download and install it.
- PSoC Creator is required to execute the PSoC 4 host example projects shipped with the kit. However, it is not a mandatory prerequisite and is not installed along with the kit contents. You can download and install PSoC Creator from www.cypress.com/go/psoccreator.
2.3 **Install the Software**

1. Run `cyautorun.exe` in the kit ISO to start the installation process.
2. Click **Install CY3280-MBR3 EVK** to start the kit installation; see Figure 2-1.

Figure 2-1. Kit Installer Startup Screen

3. Select the folder to install the CY3280-MBR3 EVK files. Choose the directory and click **Next**, as shown in Figure 2-2. The installation directory is referred to as `<Install_Directory>` in this document.

Figure 2-2. Default Path for EVK Installation
4. When you click **Next**, the CY3280-MBR3 Kit ISO installer automatically installs the required software, if it is not present on your computer.

5. Select the installation type (see Figure 2-3). The drop-down menu contains three options: **Typical** (installs all the required features), **Custom** (lets you choose the features to be installed), and **Complete** (installs all the contents). Click **Next** after you select the installation type. **Note:** It is recommended that you choose the **Complete** installation type.

![Figure 2-3. Installation Type Options](image)

6. Accept the End-User License Agreement and click **Next** to proceed with the installation.

7. When the installation begins, a list of packages appears on the installation page. A green check mark appears adjacent to every package after successful installation.

8. Enter your contact information or select the **Continue Without Contact Information** check box.

9. Click **Finish** to complete the CY3280-MBR3 EVK software installation.

After the installation is complete, the kit contents are available at the following location:

<Install_Directory>\CY3280-MBR3 EVK\<version>

### 2.4 Uninstall the Software

You can uninstall the CY3280-MBR3 EVK software using one of the following methods:

- Go to **Start** > **All Programs** > **Cypress** > **Cypress Update Manager** > **Cypress Update Manager**, select the **Uninstall** button corresponding to the kit software.

- Go to **Start** > **Control Panel** > **Programs and Features**, select the **Uninstall/Change** button corresponding to the kit software.
3. Kit Operation

The CY8CMBR3116 CapSense controller is a register-configurable device that supports multiple features, as listed in Kit Features on page 24. The CY3280-MBR3 EVK hardware includes four CapSense buttons, a proximity sensor loop, a buzzer, and LEDs; it can be used to demonstrate all the features of the MBR3 device.

The CY3280-MBR3 EVK enables you to develop applications using the CY8CMBR3116 controller. Figure 3-1 and Figure 3-2 illustrate the onboard components of the CY3280-MBR3 EVK.

Figure 3-1. CY3280-MBR3 EVK Top View
Figure 3-2. CY3280-MBR3 EVK Bottom View

- Arduino headers
- Buzzer
- Slide switch SW1 (capacitance selector switch for BTN2)
- Slide switch SW3 (trace selection switch for BTN4)
- CY8CMBR3116 CapSense Express controller
- Kit current measurement jumper
- USB connector
- PSoC SLP USB-I2C bridge
- MBR3 current measurement jumper
- I2C selection jumpers
- Buzzer, Shield, and Host Interrupt selection jumpers
- Reset switch
3.1 Powering the Kit

To power the kit, connect the A to Mini-B USB cable, provided with the kit, to your PC or laptop. The kit enumerates as a composite device (see Table 3-1), and three separate devices appear under the Device Manager (Start > Control Panel > Device Manager) option of the Windows operating system, as shown in Figure 3-5.

Table 3-1. CY3280-MBR3 Evaluation Kit in Device Manager after Enumeration

<table>
<thead>
<tr>
<th>Port</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>USB input device</td>
<td>USB-I²C bridge</td>
</tr>
<tr>
<td>KitProg programmer</td>
<td>Programmer and debugger</td>
</tr>
<tr>
<td>KitProg USB-UART</td>
<td>USB-UART bridge appears as COM# port</td>
</tr>
</tbody>
</table>

**Note:** Although the kit supports a programmer and a UART bridge, these functionalities are not used with this kit. Do not use PSoC Programmer to communicate with the PSoC 5LP on the kit, as it may corrupt the kit firmware.

After the driver installation is complete, all the above devices are listed in the Device Manager, as shown in Figure 3-5.
Kit Operation

Figure 3-5. Device Manager View after KitProg is Installed

Note: The Device Manager may have more than one instance of ‘USB Input Device’ and ‘USB Composite Device’, based on the number of USB devices connected to your PC. The USB Input Device and USB Composite Device installed with KitProg can be identified by the hardware IDs (VID and PID); these devices will have hardware IDs 0x4B4 and 0xF139. To find the hardware ID, right-click on the device and select Properties. In the Details tab, select Hardware IDs from the Property field drop-down menu.

Wait until the USB enumeration completes successfully and the board is powered. When the USB enumeration is successful, both the power LED and status LED light up.

The kit is programmed with the Water Tolerance configuration by default. See Water Tolerance on page 53 for more information.
3.2 Communication Between PC Host and Kit

The kit includes PSoC 5LP, an ARM-based PSoC that functions as a USB-I2C bridge between the CY8CMBR3116 controller and the PC host (see Figure 3-6). The CY8CMBR3116 controller communicates with PSoC 5LP using an I2C interface, and the PSoC 5LP transfers the data over USB to the PC and EZ-Click.

Figure 3-6. Block Diagram - Communication Between PC Host and Kit

Cypress provides two USB-I2C software utilities: EZ-Click and Bridge Control Panel (BCP). The CY3280-MBR3 EVK uses EZ-Click for register configuration. BCP is the software provided by Cypress that allows you to communicate over I2C, SPI, or RX8 using your PC and USB. This application currently supports CY3240, MiniProg3, FirstTouch, FirstTouchRF, Touch Tuning Bridge, DVK-Prog1, and KitProg bridges. See Using PSoC 5LP as USB-I2C Bridge on page 70 for more details on using the BCP.

You should install EZ-Click on the PC to evaluate the kit features. This software is part of the kit installer, but it can also be downloaded from www.cypress.com/go/CY3280-MBR3. You can use EZ-Click to configure the CapSense controllers using I2C communication over the USB-I2C bridge. You can also use it to monitor raw count, baseline, SNR, and other CapSense sensor-related information directly.

3.3 Configuring the CY8CMBR3116 Controller Using EZ-Click

Follow these steps to configure the CY8CMBR3116 controller:
1. Connect the CY3280-MBR3 EVK to the PC via the USB port using the USB cable.
2. Open EZ-Click from the default location: Start > All Programs > Cypress > EZ-Click <version> > EZ-Click <version>.
3. Create a new project in EZ-Click by clicking New Project... in the File menu, as shown in Figure 3-7.

Figure 3-7. Creating a New Project in EZ-Click
4. Enter an appropriate name for the project and choose a location to save your project. Select **Target Device** as ‘CY8CMBR3116-LQXI’ from the Product Selector. To launch the Product Selector, click the **Device Selector** button, as shown in the following figure.

![Figure 3-8. New Project Details](image)

5. Ensure that the I²C selection jumpers J13 and J14 are shorted between pins 1 and 2 to allow communication with the onboard PSoc 5LP USB-I²C bridge.

6. Connect the kit to EZ-Click by clicking the **Select Target Device** button ( ) on the EZ-Click tool bar. This opens a **Select I2C Target** window (Figure 3-10); select the following:
   a. KitProg/<kit number> in the **Ports** window.
   b. The I²C slave device in the **Devices** window. **Note:** The CY8CMBR3116 has a slave address of 0x37 by default. If multiple slave devices are connected, you can disconnect from one slave and connect to another by using the **Connect/Disconnect** button in the **Select I2C Target** window. See Figure 3-10.
   c. Select the speed of the I²C communication as **400 kHz**.
   d. Choose the target device voltage by selecting the **3.3 V** radio button.
7. Click **OK**. The **I²C** slave address of the connected device appears on the status bar at the bottom of the EZ-Click window, as shown in Figure 3-11.

8. Enable the button sensors in the **CapSense sensor configuration** tab, as shown in Figure 3-12. See Pin Mapping Between CY8CMBR3116 and CY3280-MBR3 EVK on page 31 to learn about the available button sensors and how they are connected to the CY8CMBR3116 device. In this example, all four available button sensors on the kit are enabled.
Figure 3-12. Enabling Button Sensors Using EZ-Click

<table>
<thead>
<tr>
<th>Buttons</th>
<th>Enable</th>
<th>Pin</th>
<th>Sensor</th>
<th>Sensitivity (PF)</th>
<th>Filter</th>
</tr>
</thead>
<tbody>
<tr>
<td>BTN1</td>
<td></td>
<td>CS3/PS3(1)</td>
<td>Button1</td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>BTN2</td>
<td></td>
<td>CS3/PS2(2)</td>
<td>Button2</td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>BTN3</td>
<td></td>
<td>CS3/GUARD(3)</td>
<td>Button3</td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>BTN4</td>
<td></td>
<td>CS3(4)</td>
<td>Button4</td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>BTN5</td>
<td></td>
<td>CS3(5)</td>
<td>Button5</td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>BTN6</td>
<td></td>
<td>CS3(6)</td>
<td>Button6</td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>BTN7</td>
<td></td>
<td>CS3(7)</td>
<td>Button7</td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>BTN8</td>
<td></td>
<td>CS3/OP0(8)</td>
<td>Button8</td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>BTN9</td>
<td></td>
<td>CS3/OP1(9)</td>
<td>Button9</td>
<td>100</td>
<td></td>
</tr>
</tbody>
</table>

**Note:** The CapSense buttons BTN1/CS3, BTN2/CS4, BTN3/CS5, and BTN4/CS6 on the CY3280-MBR3 EVK correspond to Button4, Button5, Button6, and Button7 in EZ-Click, which map to pins CS3, CS4, CS5, and CS6 respectively on the MBR3 device. Figure 3-14 shows the corresponding four buttons for reference.

9. The sensor names can be modified if desired, as shown in Figure 3-13.

Figure 3-13. Changing Sensor Names
10. Enable the corresponding LEDs in the **Global configuration** tab, as shown in Figure 3-15, to view the LED output for each button touch. Ensure that the GPO logic level is **Active Low** because the LEDs on the CY3280-MBR3 EVK are active low.

**Note:** LED1/GPO3, LED2/GPO4, LED3/GPO5, and LED4/GPO6 on the CY3280-MBR3 EVK correspond to LED4, LED5, LED6, and LED7 in EZ-Click, which map to the general-purpose output (GPO) pins CS11/GPO3, CS12/GPO4, CS13/GPO5, and CS14/GPO6 respectively on the MBR3 device.

If the ‘host control’ feature is disabled in the MBR3 device, the LEDs will be mapped to the corresponding CapSense sensors. This means, CS0 will be mapped to GPO0, CS1 will be mapped to GPO1, and so on. If a sensor is active, the corresponding LED will be turned on even if it is not enabled in EZ-Click. The Enable option in EZ-Click is used only for LED features such as duty cycle, LED duration, and toggle. To disable an LED, you need to enable the ‘host control’ feature and configure the GPO drive mode as **Strong** and GPO logic level as **Active High**.
11. The LEDs can also be renamed, as shown in Figure 3-16.

12. Generate the configuration file by clicking the Generate Configuration File icon on the tool bar or by pressing [Ctrl] + [G]. The status of configuration file generation is shown in the status bar at the bottom of the EZ-Click window (see Figure 3-17).

13. Click the Apply Current Configuration icon on the tool bar in EZ-Click or press [Ctrl] + [L] to download the generated configuration to the MBR3 device.

14. Wait for the message “Device configuration completed successfully” to be displayed on the status bar, as illustrated in Figure 3-18.
15. Touch the buttons on the kit to observe the features as enabled in the configuration.

**Note:** The *Water Tolerance* configuration file is preloaded into the kit. The kit supports the features mentioned in *Water Tolerance on page 53* by default. To learn more about the configurations, see *Configuration Files on page 46.*

### 3.4 Kit Features

The CY3280-MBR3 EVK includes the following features:

- Four CapSense buttons of two different sizes – two buttons of 10-mm diameter (BTN1 and BTN2) and two buttons of 11-mm diameter (BTN3 and BTN4)
- LEDs corresponding to sensors indicating button touch
- A buzzer
- Shield electrode pin for water tolerance
- I²C selection jumpers
- Arduino-compatible headers
- One proximity loop and a corresponding LED to indicate proximity state (on/off)
- A host interrupt pin
- Two slide switches on two CapSense buttons to vary trace capacitance and demonstrate Smart-Sense Auto-Tuning

**Note:** The CS15 pin of the MBR3 device is multiplexed for the CapSense button, host interrupt, and shield electrode. Similarly, GPO7 is multiplexed for general-purpose output, host interrupt, and buzzer output. All three features – host interrupt, buzzer, and shield electrode (water tolerance) cannot be enabled simultaneously. See *Buzzer, Shield, and Host Interrupt Multiplexing Jumper on page 39* for more details on CS15 and GPO7 pin connections.

#### 3.4.1 SmartSense Auto-Tuning Feature

The CY8CMBR3116 device features SmartSense Auto-Tuning, which is the Cypress proprietary CapSense algorithm that compensates for system, manufacturing, and environmental changes while providing feature-rich CapSense solutions.

- Reduces design effort by eliminating tedious manual tuning
- Adapts to variations in PCB, overlay, paint, and manufacturing that degrade touch-sensing performance
- Eliminates production-related manual tuning
- Adapts to changes in system environment due to noise sources
- Allows a platform design approach with different overlays, button shapes, and trace lengths

The CY8CMBR3116 also supports setting manual thresholds to override the auto-tuning mechanism, if required.

SmartSense Auto-Tuning is demonstrated using three methods on the kit. See *Capacitance Variation Demonstration on page 41* for hardware details:

1. Using the SW1 slide switch to increase capacitance
   a. Power on the kit using USB or an external power supply on pin 4 of the J1 header.
   b. Touch BTN2 on the kit; the corresponding LED will turn on, providing visual feedback on each button touch.
   c. Increase the capacitance of BTN2 by sliding SW1 to add an additional 10-pF or 15-pF external capacitance on the sensor, as shown in *Figure 3-19*; the LED turns on as if a touch.
Kit Operation

2. Using a short/long trace by adjusting the SW3 slide switch on the kit
   a. Power on the kit using USB or an external power supply on pin 4 of the J1 header.
   b. Touch BTN4 on the kit. The LED corresponding to BTN4 will turn on, providing visual feedback on each touch.
   c. Increase the parasitic capacitance of BTN4 by sliding SW3 (see Figure 3-20) to add a longer trace on BTN4.
   d. The LED turns on as if a touch occurred due to the increase in capacitance. Now, press the reset switch, SW2, to reset the board.
   e. Touch BTN4 on the kit; the corresponding LED works normally and provides visual feedback on each touch. This demonstrates the SmartSense Auto-Tuning algorithm, which automatically tunes for the increase in CapSense button capacitance due to the long trace.
3. Using the additional 1-mm overlay provided with the kit, as shown in Figure 3-21:
   a. Power on the kit using USB or an external power supply on pin 4 of the J1 header.
   b. Touch BTN1 on the kit. The LED corresponding to BTN1 will turn on, providing visual feedback on each touch.
   c. Place the additional 1-mm overlay, provided with the kit, on top of the board and press the reset switch, SW2, to reset the board.
   d. Touch BTN1 on the kit; the corresponding LED works normally and provides visual feedback. This demonstrates the SmartSense Auto-Tuning algorithm, which automatically tunes for the increase in CapSense button capacitance due to an increase in overlay thickness.
Figure 3-21. Board with Additional 1-mm Overlay Placed on the 2-mm Overlay
4. Hardware

The CY3280-MBR3 EVK is designed to demonstrate the features of the CY8CMBR3116 register-configurable CapSense controller with four CapSense buttons and a proximity sensor loop. The kit includes five sensor LEDs, which can be used to demonstrate the direct LED control feature of the CY8CMBR3116. It also contains two LEDs to indicate power and kit status. The CY8CMBR3116 controller supports multiple features, which are discussed in Functional Description on page 29.

The CY3280-MBR3 EVK has two communication options:

- A USB interface for the USB-I2C bridge to communicate with EZ-Click.
- The I2C interface on the kit to connect to an external I2C host, for example, the PSoC 4 Pioneer Kit (CY8CKIT-042).

4.1 Board Details

The CY3280-MBR3 EVK consists of the following blocks:

- CY8CMBR3116 silicon
- PSoC 5LP USB-I2C bridge
- Power supply system
- Four button sensors and one proximity loop
- CY3280-MBR3 EVK LEDs: A power, status, and proximity LED and four CapSense LEDs
- Capacitance variation demonstration
  - Two-position slide switch to select long/short trace for BTN4
  - Three-position slide switch to add capacitance on BTN2; the three positions of the slide switch correspond to 10 pF, 15 pF, and no additional capacitance
- Arduino-compatible headers
- Push button to reset the CY8CMBR3116
- Buzzer, shield, and host interrupt pin multiplexing jumper
- I2C selection jumpers to select between onboard PSoC 5LP and external host.

See Figure 3-1 for the CY3280-MBR3 board details.
4.2 Theory of Operation

This section provides a block-level description of the CY3280-MBR3 EVK.

Figure 4-1. Block Diagram

This kit can be powered using the USB Mini-B, the Arduino-compatible header, or an external power supply. You can configure the input voltage (1.8 V, 3.3 V, 5 V, or external supply) while connecting the device to EZ-Click. The voltage is controlled by using a low dropout (LDO) regulator, which can provide regulated power of 1.8 V, 3.3 V, and 4.7 V to the CY8CMBR3116 device. The power to the MBR3 device is controlled by the Power setting in EZ-Click; see Figure 3-10.

The CY3280-MBR3 EVK includes a status LED, a power LED, LEDs corresponding to all CapSense buttons, and a proximity LED corresponding to the proximity loop on the kit. It contains an onboard PSoC 5LP, which acts as a USB-I2C bridge to support I2C communication using a PC host.

This kit also includes a reset button, which connects to the reset pin (XRES) of the CY8CMBR3116 device. All the unused pins of the device are brought out onto the Arduino header J2 on the kit to enable you to test different types of self-designed sensors and observe the output on the oscilloscope.

Note: The kit operation voltage is 4.7 V when the kit is configured for 5 V.

4.3 Functional Description

4.3.1 CY8CMBR3116 CapSense Controller

The CY8CMBR3116 CapSense controller includes the following features:

- SmartSense Auto-Tuning – Cypress’ CapSense algorithm that continuously compensates for system, manufacturing, and environmental changes.
Proximity sensing – Supports configurability of sensors for proximity sensing.

- Button sensor auto-reset – Prevents a stuck sensor when a metal object is placed close to that sensor.
- Flanking sensor suppression (FSS) – Eliminates false touches by distinguishing between signals from closely spaced buttons.
- Toggle (touch on/off) – Mimics the mechanical button functionality by toggling sensor output status on every sensor activation.
- LED-on time – Provides better visual feedback by enabling the general-purpose output (GPO) to be on for a configurable period after the button is released.
- Debounce control – Prevents false trigger by specifying the minimum time for which a sensor must be touched for a valid ON status.
- Buzzer signal output – Enables direct drive of a buzzer with configurable frequency.
- Host-controlled GPO – Enables device GPOs to be controlled by the host (I²C master).
- LED brightness control – Offers duty cycle configurability to control the brightness of the LEDs connected to the GPOs.
- Wake-on approach – Wakes the device from low-power and switches to the active state using proximity sensors.
- Water tolerance – Enables water-tolerant user interface applications. The shield electrode should be enabled through the register map to prevent false touches under wet conditions. To prevent false touches in streaming water conditions, both the shield electrode and guard sensor need to be enabled. However, the MBR3 kit does not have the guard sensor loop. So, water tolerance under streaming water conditions cannot be tested on the board.

- I²C slave – An I²C interface with support for 50/100/400-kHz clock speeds and hardware slave address comparison.
- Host interrupt – Alerts the host processor upon touch detection; for every touch and release event, an active low pulse of typically 250 µs is generated.
- System diagnostics – Supports production testing and debugging.

See the CY8CMBR3116 datasheet for more details on these features.

The CY3280-MBR3 EVK can be configured using EZ-Click. The kit includes three configuration files with specific features described in Configuration Files on page 46. Additional configurations can be generated and applied to the kit using this tool.

See the EZ-Click User Guide for additional details on how to generate more configurations to evaluate the features in this section using EZ-Click. This guide is available at the location <Install Directory>\EZ-Click\<version>\Documentation.
4.3.1.1 Pin Mapping Between CY8CMBR3116 and CY3280-MBR3 EVK

The CY8CMBR3116 device can be configured for 16 button sensors of which two sensors are configurable as proximity sensors. The kit demonstrates four button sensors and one proximity sensor. Table 4-1 maps the device pins to the physical sensors on the kit.

**Table 4-1. Pin Mapping on the Kit**

<table>
<thead>
<tr>
<th>Sensor</th>
<th>Device</th>
<th>Kit</th>
</tr>
</thead>
<tbody>
<tr>
<td>CS0/PS0</td>
<td>CapSense button/proximity sensor, controls GPO0</td>
<td>Connected to proximity loop on kit</td>
</tr>
<tr>
<td>CS1/PS1</td>
<td>CapSense button/proximity sensor, controls GPO1</td>
<td>Routed to Arduino header; can be used for external button/proximity sensor</td>
</tr>
<tr>
<td>CS2/Guard</td>
<td>CapSense button/guard sensor, controls GPO2</td>
<td>Routed to Arduino header; can be used for external button/guard sensor</td>
</tr>
<tr>
<td>CS3</td>
<td>CapSense button, controls GPO3</td>
<td>Used as button BTN1 on the kit</td>
</tr>
<tr>
<td>CS4</td>
<td>CapSense button, controls GPO4</td>
<td>Used as button BTN2 on the kit</td>
</tr>
<tr>
<td>CS5</td>
<td>CapSense button, controls GPO5</td>
<td>Used as button BTN3 on the kit</td>
</tr>
<tr>
<td>CS6</td>
<td>CapSense button, controls GPO6</td>
<td>Used as button BTN4 on the kit</td>
</tr>
<tr>
<td>CS7</td>
<td>CapSense button, controls GPO7</td>
<td>Routed to Arduino header; can be used for external button sensor</td>
</tr>
<tr>
<td>CS8/GPO0</td>
<td>CapSense button/general-purpose output</td>
<td>Connected to proximity LED on the kit; driven by CS0/PS0</td>
</tr>
<tr>
<td>CS9/GPO1</td>
<td>CapSense button/general-purpose output</td>
<td>Routed to Arduino header; can be used for external button sensor/GPO</td>
</tr>
<tr>
<td>CS10/GPO2</td>
<td>CapSense button/general-purpose output</td>
<td>Routed to Arduino header; can be used for external button sensor/GPO</td>
</tr>
<tr>
<td>CS11/GPO3</td>
<td>CapSense button/general-purpose output</td>
<td>Connected to LED1 on the kit; driven by CS3 (BTN1)</td>
</tr>
<tr>
<td>CS12/GPO4</td>
<td>CapSense button/general-purpose output</td>
<td>Connected to LED2 on the kit; driven by CS4 (BTN2)</td>
</tr>
<tr>
<td>CS13/GPO5</td>
<td>CapSense button/general-purpose output</td>
<td>Connected to LED3 on the kit; driven by CS5 (BTN3)</td>
</tr>
<tr>
<td>CS14/GPO6</td>
<td>CapSense button/general-purpose output</td>
<td>Connected to LED4 on the kit; driven by CS6 (BTN4)</td>
</tr>
<tr>
<td>CS15/SH/HI</td>
<td>CapSense button/shield electrode/host interrupt</td>
<td>Connected to header J15 multiplexing buzzer, shield, and host interrupt pin on the kit</td>
</tr>
<tr>
<td>HI/BUZ/GPO7</td>
<td>Host interrupt/buzzer output/general-purpose output</td>
<td>Connected to header J15 multiplexing buzzer, shield, and host interrupt pin on the kit</td>
</tr>
</tbody>
</table>

4.3.2 PSoC 5LP

An onboard PSoC 5LP is used as a USB-i²C bridge for communicating with the PC host. It also sets the operating voltage applied to the target device. The MBR3 device can be operated at either 5.0 V, 3.3 V, and 1.8 V. By default, the onboard PSoC 5LP USB-i²C bridge sets 3.3 V as operating voltage for the MBR3 device. The PSoC 5LP connects to the USB port of the PC through a USB Mini-B connector and to the i²C interface of the CY8CMBR3116 device.

PSoC 5LP is a true system-level solution, providing an MCU, memory, analog, and digital peripheral functions in a single chip. The CY8C58LPxx family offers a modern method of signal acquisition, signal processing, and control with high accuracy, high bandwidth, and high flexibility. Analog capability
spans the range from thermocouples (near DC voltages) to ultrasonic signals. For more information, refer to the PSoC 5LP web page and datasheet.

4.3.3 Power Supply System

The CY8CMBR3116 device supports operation from 1.71 V to 5.5 V. The CY8CMBR3116 device has two modes of operation: internally regulated mode and externally regulated mode. Table 4-2 lists the voltage ranges supported for both the operating modes.

Table 4-2. Operating Voltage Ranges for CY8CMBR3116 Device Modes

<table>
<thead>
<tr>
<th>Operating Voltage Range</th>
<th>Internally Regulated Mode</th>
<th>Externally Regulated Mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.71 V to 1.8 V</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>1.8 V to 1.89 V</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>1.89 V to 5.5 V</td>
<td>Yes</td>
<td>No</td>
</tr>
</tbody>
</table>

Note: See the MBR3 device datasheet for more details.

The power supply system on this board is versatile, allowing the input supply to come from the following sources:
- 5-V power from the onboard USB Mini-B header (J10)
- 5-V power from an Arduino board or an external supply using pin 4 of the J1 header

The power system of this kit is designed to support 1.8-V, 3.3-V, and 4.7-V operation of the CY8CMBR3116 device. At 1.8 V, the kit can be operated in either internally regulated or externally regulated mode. By default, the kit and example projects are designed to operate in internally regulated mode. See Externally Regulated Operation Mode on page 33 to operate the kit in externally regulated mode. The PSoC 5LP firmware configures the required voltage according to the selection made while connecting to the USB-I²C bridge. This configuration is performed by monitoring the Vbus voltage and enabling the LDO regulator (U2–MIC 5219). When the kit is powered externally through the J1 header, the kit operational voltage is regulated to 3.3 V.

When the board is powered using the Arduino header, a PolyZen protection device (U4) is added in series with the 5-V external power line to protect against overvoltage and reverse-voltage scenarios. The device can protect overvoltage and reverse voltage up to 12 V.

Figure 4-2. Power Supply Block Diagram with Protection Circuits
4.3.3.1 **Externally Regulated Operation Mode**

To operate the kit in externally regulated mode at 1.8 V, solder resistors R84 and R85 with 0-Ω resistors. Select the **Supply Voltage (V)** parameter in EZ-Click, as shown in Figure 4-5.
Figure 4-5. Supply Voltage Parameter for Externally Regulated Mode

Populating R84 shorts the VCCD and VDD pin of CY8CMBR3116 for the externally regulated mode. Populating R85 ensures that the board is always powered at 1.8 V. This overrides the power settings done from EZ-Click (see Figure 3-10).

Figure 4-6. R84 and R85 for Externally Regulated Operation at 1.8 V

Note: Do not configure the device with the Supply Voltage (V) parameter set to 1.8±5%, before populating resistors R84 and R85. If you do so, EZ-Click will throw an error, as shown in Figure 4-7. The kit will not be functional until the resistors R84 and R85 are populated.
To switch the kit operation from externally regulated mode to internally regulated mode, follow these steps:

1. Select the **Supply Voltage (V)** parameter in EZ-Click, as shown in Figure 4-8 and apply the configuration. This turns the internal regulator on.
   
   **Caution:** You cannot apply any configuration if you remove resistors R84 and R85 before step 1.

2. Remove the USB cable connected to the kit.
3. Desolder (unpopulate) resistors R84 and R85 (Figure 4-6), which were previously loaded for externally regulated mode operation.
4. Connect the USB cable to the kit and apply the EZ-Click configuration with the Supply Voltage (V) parameter as **1.8-5.5**, as shown in Figure 4-8.

   **Note:** To operate the kit in internally regulated mode, the **Supply Voltage (V)** parameter should be selected as **1.8-5.5**, as shown in Figure 4-8.

### 4.3.3.2 Protection Circuit

The power supply rail has reverse-voltage, overvoltage, and short-circuit protection features.
The PTC resettable fuse is connected to protect the computer's USB ports from overcurrent; see Figure 4-9.

Figure 4-9. USB Power Supply Section Schematic Snippet

- **D2** – A series protection diode to ensure there is no back power to the header; see Figure 4-3.
- **U4** – A PolyZen protection device (ZEN056V075A48LS) that protects the kit against overvoltage and reverse voltage from the headers; see Figure 4-4.

**Caution:** There is no protection on the current measurement jumper, test points, and I/O pins. Do not apply more than 5.5 V on these ports.

### 4.3.3.3 Procedure to Measure the CY8CMBR3116 Current Consumption

This kit provides a way to measure the current consumption of both the whole kit and the CY8CMBR3116 device individually, without soldering. There are two separate jumpers on the board for this purpose.

1. To measure current consumption of only the CY8CMBR3116 device, remove the power supply by either disconnecting the USB cable or removing the power source at pin 4 of the J1 header and connect an ammeter across J12. Now, power the kit again by either connecting the USB cable or supplying power at pin 4 of the J1 header.
2. To measure the current consumption of the whole kit, remove board power and connect an ammeter across J11. Now, power the kit again by connecting the USB cable.

Figure 4-11. Kit Current Consumption Measurement
**Note:** Do not remove the current measurement jumper J12 while the kit is powered. This can damage the MBR3 silicon.

### 4.3.4 Button Sensors and Proximity Loop Sensor

The kit has four CapSense buttons (two circular buttons of 10-mm diameter and two circular buttons of 11-mm diameter) and one proximity loop onboard, as Figure 4-12 shows. These sensors can be driven by the CY8CMBR3116 device to perform touch and proximity detection.

**Figure 4-12. Button Sensor and Proximity Loop Connections on the Kit**

### 4.3.5 CY3280-MBR3 Kit LEDs

The EVK has seven onboard LEDs. A green LED (D15) indicates the status of the USB-I²C bridge. A red LED (D13) indicates the status of the power supplied to the board.

The kit also has an active-low red LED for each CapSense button and proximity loop. The CY8CMBR3116 drives these LEDs by driving the GPO low.

**Figure 4-13 and Figure 4-14** detail the schematic of the LEDs.

**Note:** These LEDs are dim when working at 1.8 V compared to 3.3-V and 4.7-V operation.
4.3.6 **Buzzer, Shield, and Host Interrupt Multiplexing Jumper**

The CS15 pin of the MBR3 device is multiplexed for the CapSense button, host interrupt, and shield electrode. Similarly, GPO7 is multiplexed for general-purpose output, host interrupt, and buzzer output. All three features – host interrupt, buzzer, and shield electrode (water tolerance) cannot be enabled simultaneously. These features can be enabled using the multiplexing jumper J15, which has three combinations.
**Table 4-3. J15 Combinations**

<table>
<thead>
<tr>
<th>Combination</th>
<th>Features</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>Buzzer on GPO7, Host Interrupt on CS15</td>
</tr>
<tr>
<td>B</td>
<td>Host Interrupt on GPO7, Shield on CS15</td>
</tr>
<tr>
<td>C</td>
<td>Buzzer on GPO7, Shield on CS15</td>
</tr>
</tbody>
</table>

**Note:** If water tolerance (shield) is not used and only buzzer or host interrupt features are used, then the shield pin must be connected to ground by shorting pins 5 and 6 of jumper J15.

See the MBR3 device datasheet and the schematic for more details.

**Figure 4-15. Buzzer, Shield, and Host Interrupt Connection**

*AT ANY TIME DON'T LOAD BOTH R66 and R67.*

---

**Setting | J15 Jumper Connection | Enabled Features (2 features at a time)**

<table>
<thead>
<tr>
<th>Setting</th>
<th>J15 Jumper Connection</th>
<th>Enabled Features (2 features at a time)</th>
</tr>
</thead>
<tbody>
<tr>
<td>B</td>
<td>Connect J15-2 and J15-3, J15-4 to J15-5 using 2 shunts</td>
<td>Buzzer Disabled, Host Interrupt Enabled and Water Tolerance is Enabled</td>
</tr>
<tr>
<td>C</td>
<td>By Default connect J15-1 and J15-2, J15-4 to J15-5 using 2 shunts</td>
<td>Buzzer Enabled, Host Interrupt Disabled and Water Tolerance is Enabled</td>
</tr>
</tbody>
</table>
4.3.7 Capacitance Variation Demonstration

The kit provides three methods to demonstrate parasitic capacitance variation on the button sensors available on the kit, as shown in Figure 4-17. These methods are used to showcase the SmartSense auto-tuning capability of the device. See SmartSense Auto-Tuning Feature on page 24 to learn the procedure to test these methods using this kit.

The methods are:

- Using the trace method: Button BTN4 (connected to the CS6 pin of CY8CMBR3116) is connected to the SW3 slide switch, which can be used to provide two different routes between the pin and the sensor pad. One route is longer than the other. Different trace lengths have different parasitic capacitance; therefore, you can change the length of the trace to change the parasitic capacitance on the sensor.

- Using external capacitance: The SW1 switch is provided to add an extra capacitance of 10 pF or 15 pF on BTN2 (connected to the CS4 pin of the CY8CMBR3116).

- Using an additional 1-mm overlay: An additional overlay of 1 mm is provided with this kit. You can place this overlay over the sensors to change the parasitic capacitance.

Note: The kit is shipped with the combination/setting ‘C’ and the third jumper is connected vertically so that it is not shorted to any other pin.
4.3.8 Arduino-Compatible Headers

The I/O headers J1–J4 comply with the Arduino UNO (R3) kit to support Arduino base boards. The Arduino-defined signals include digital/analog signals from the CY8CMBR3116; system power signals are brought to the outer rows of headers J1–J4.

Pin maps of the Arduino-compatible headers J1–J4 are shown in the following tables. The pins connected between the Arduino board and the CY3280-MBR3 EVK appear in red. The pins shown in blue are on the second row of the J2 connector; these are the unused pins of the CY8CMBR3116 device.

This kit also provides additional I²C lines on pins J2.9 (SDA) and J2.11 (SCL). These pins are used by older Arduino boards, such as the Arduino UNO R2 and Arduino Mega boards. These lines are not connected (NC) by default and can be used by loading a 0-Ω resistor on R71 and R72 and removing both jumpers from headers J13 and J14.
### Table 4-4. J1 Arduino Header or Power Connector

<table>
<thead>
<tr>
<th>Pin</th>
<th>Arduino Board Signal</th>
<th>CY3280-MBR3 EVK Signal</th>
</tr>
</thead>
<tbody>
<tr>
<td>J1.1</td>
<td>VIN</td>
<td>NC</td>
</tr>
<tr>
<td>J1.2</td>
<td>GND</td>
<td>GND</td>
</tr>
<tr>
<td>J1.3</td>
<td>GND</td>
<td>GND</td>
</tr>
<tr>
<td>J1.4</td>
<td>V5.0</td>
<td>V5.0</td>
</tr>
<tr>
<td>J1.5</td>
<td>V3.3</td>
<td>NC</td>
</tr>
<tr>
<td>J1.6</td>
<td>RESET</td>
<td>NC</td>
</tr>
<tr>
<td>J1.7</td>
<td>IOREF</td>
<td>NC</td>
</tr>
<tr>
<td>J1.8</td>
<td>NC</td>
<td>NC</td>
</tr>
</tbody>
</table>

### Table 4-5. J2 Arduino Header

<table>
<thead>
<tr>
<th>J2 Connector</th>
<th>Pin</th>
<th>Arduino Board Signal</th>
<th>CY3280-MBR3 EVK Signal</th>
</tr>
</thead>
<tbody>
<tr>
<td>J2[1,3,5,7]</td>
<td>A0 – A3</td>
<td></td>
<td>NC</td>
</tr>
<tr>
<td>J2.9</td>
<td>A4</td>
<td>SDA (Default – NC)</td>
<td></td>
</tr>
<tr>
<td>J2.11</td>
<td>A5</td>
<td>SCL (Default – NC)</td>
<td></td>
</tr>
<tr>
<td>J2.2</td>
<td>NC</td>
<td>CS10</td>
<td></td>
</tr>
<tr>
<td>J2.4</td>
<td>NC</td>
<td>CS9</td>
<td></td>
</tr>
<tr>
<td>J2.6</td>
<td>NC</td>
<td>CS7</td>
<td></td>
</tr>
<tr>
<td>J2.8</td>
<td>NC</td>
<td>PS1</td>
<td></td>
</tr>
<tr>
<td>J2.10</td>
<td>NC</td>
<td>CS2/GAUDR</td>
<td></td>
</tr>
<tr>
<td>J2.12</td>
<td>NC</td>
<td>GND</td>
<td></td>
</tr>
</tbody>
</table>

### Table 4-6. J3 Arduino Header

<table>
<thead>
<tr>
<th>J3 Connector</th>
<th>Pin</th>
<th>Arduino Board Signal</th>
<th>CY3280-MBR3 EVK Signal</th>
</tr>
</thead>
<tbody>
<tr>
<td>J3.1</td>
<td>D8</td>
<td>NC</td>
<td></td>
</tr>
<tr>
<td>J3.2</td>
<td>D9</td>
<td>NC</td>
<td></td>
</tr>
<tr>
<td>J3.3</td>
<td>D10</td>
<td>NC</td>
<td></td>
</tr>
<tr>
<td>J3.4</td>
<td>D11</td>
<td>NC</td>
<td></td>
</tr>
<tr>
<td>J3.5</td>
<td>D12</td>
<td>NC</td>
<td></td>
</tr>
<tr>
<td>J3.6</td>
<td>D13</td>
<td>NC</td>
<td></td>
</tr>
<tr>
<td>J3.7</td>
<td>GND</td>
<td>GND</td>
<td></td>
</tr>
<tr>
<td>J3.8</td>
<td>AREF</td>
<td>NC</td>
<td></td>
</tr>
<tr>
<td>J3.9</td>
<td>SDA</td>
<td>J3_SDA</td>
<td></td>
</tr>
<tr>
<td>J3.10</td>
<td>SCL</td>
<td>J3_SCL</td>
<td></td>
</tr>
</tbody>
</table>
Table 4-7. J4 Arduino Header

<table>
<thead>
<tr>
<th>J4 Connector</th>
<th>Arduino Board Signal</th>
<th>CY3280-MBR3 EVK Signal</th>
</tr>
</thead>
<tbody>
<tr>
<td>J4.1</td>
<td>D0</td>
<td>NC</td>
</tr>
<tr>
<td>J4.2</td>
<td>D1</td>
<td>NC</td>
</tr>
<tr>
<td>J4.3</td>
<td>D2</td>
<td>Host Interrupt</td>
</tr>
<tr>
<td>J4.4</td>
<td>D3</td>
<td>NC</td>
</tr>
<tr>
<td>J4.5</td>
<td>D4</td>
<td>NC</td>
</tr>
<tr>
<td>J4.6</td>
<td>D5</td>
<td>NC</td>
</tr>
<tr>
<td>J4.7</td>
<td>D6</td>
<td>NC</td>
</tr>
<tr>
<td>J4.8</td>
<td>D7</td>
<td>NC</td>
</tr>
</tbody>
</table>

Figure 4-18. Arduino Connectors Schematic Snippet

NOTE: J13 and J14 JUMPER CONFIGURATION

Short J13-1 to J13-2 and J14-1 to J14-2 for using Onboard I2C-USB Bridge

Short J13-2 to J13-3 and J14-2 to J14-3 for connecting the CY8CM3116’s I2C lines to Arduino header J3 pins 9 and 10.

Remove both shunts on J13, J14 and load zero ohm resistor on R71 and R72 for connecting the CY8CM3116 I2C lines to Arduino header J2 pins 9 and 10.

(J1-J4) Arduino Compatible Headers
4.3.9 Push Button to Reset CY8CMBR3116

The kit contains a mechanical reset push button, SW2, to reset the CY8CMBR3116 device, as shown in Figure 4-19.

Figure 4-19. Push Button Reset Switch

4.3.10 I²C Selection Jumpers

The I²C communication lines (SCL and SDA) can be connected to either the onboard USB-I²C bridge (PSoC 5LP) or to the I²C pin location on the Arduino header (J3.9 and J3.10). See Figure 4-18 for the schematic snippet.
5. Configuration Files and Example Projects

This section documents the high-level design process to open, configure, generate, and apply configuration files to the CY3280-MBR3 EVK using EZ-Click. This kit provides three sample configurations. Each sample configuration file has different configuration settings, demonstrating various kit and device features. By default, the kit is configured with the Water Tolerance sample configuration.

Table 5-1. Features in Configuration Files

<table>
<thead>
<tr>
<th>Configuration</th>
<th>Features</th>
</tr>
</thead>
<tbody>
<tr>
<td>LED Toggle</td>
<td>Four CapSense buttons, four LEDs, buzzer, and LED toggle</td>
</tr>
<tr>
<td>Proximity Detection</td>
<td>Four CapSense buttons, four LEDs, proximity loop, proximity LED, buzzer, and LED brightness</td>
</tr>
<tr>
<td>Water Tolerance</td>
<td>Four CapSense buttons, four LEDs, water tolerance, flanking sensor suspension (FSS), auto-reset</td>
</tr>
</tbody>
</table>

To use the sample configuration files, you need EZ-Click, which is installed along with the kit.

5.1 Running Configuration Files and Host Projects

The EZ-Click configuration files and PSoC 4 host projects require administrator privileges if they are run directly from the default install location (C:\Program Files\Cypress). If you do not have administrator privileges, copy the Firmware folder from the default install location to any other location on your PC and use the files.

5.2 Configuration Files

Follow these steps to run the configuration files and verify the features. Before running any of the configuration files, short pins 1 and 2 on J13 and J14. This is required to short the I2C communication lines (SCL and SDA) of the MBR3 device to the PSoC 5LP I2C lines.

The jumper J15 should be in setting C, as shown in Figure 5-1.
5.2.1 LED Toggle

This configuration file configures the CY8CMBR3116 for demonstrating the LED toggle (touch on/off) and buzzer drive features for all four available button sensors.

5.2.1.1 Loading LED Toggle Configuration

1. Connect the CY3280-MBR3 EVK to the PC via the USB port using the USB cable. Ensure that the status and power LEDs glow.
2. Open EZ-Click from the default location: `Start > All Programs > Cypress > EZ-Click <version> > EZ-Click <version>`.
3. Click `Open Project` in the `File` menu. Figure 5-2 shows the default location of the `Load Project` action.

4. Navigate to the project directory in the `Open Project` window.
5. Double-click the `LED Toggle.cprj` file to open it.
6. Ensure that the I²C selection jumpers J13 and J14 are shorted between pins 1 and 2 to allow communication with the PSoC 5LP onboard USB-I²C bridge.

7. Connect the kit to EZ-Click using the following steps.
   a. Click the **Select Target Device** button ( ) on the tool bar of EZ-Click.
   b. Select **3.3 V** as target power and **400 kHz** as I²C speed; click **OK** to connect to the CY3280-MBR3 EVK, which has the slave address of 0x37.

Figure 5-3. Connecting the Kit with the Customizer

8. Select **Apply Current Config** in the **Configuration** menu to apply the configuration to the kit, as illustrated in **Figure 5-4**.

Figure 5-4. Apply Current Configuration

9. Wait until the message “Device configuration completed successfully” appears on the status bar at the bottom of the EZ-Click window, as displayed in **Figure 5-5**.
10. Verify the following features:
   a. Toggle (touch on/off) feature: Touch any CapSense button; the respective LED toggles its status.
   b. Buzzer feature (frequency of 4 kHz and duration of 100 msecs): Touch any CapSense button; the respective LED toggles along with an audio feedback for 100 msecs at a 4-kHz frequency.
5.2.2 Proximity Detection

This configuration file configures the CY8CMBR3116 to demonstrate proximity detection, CapSense buttons, LED brightness, and buzzer drive features.

5.2.2.1 Loading Proximity Detection Configuration

1. Follow steps 1 to 4 as described in section 5.2.1.1 Loading LED Toggle Configuration.
2. Double-click the Proximity Detection.cprj file to open it.
3. Follow steps 6 to 9 as described in section 5.2.1.1 Loading LED Toggle Configuration to continue.
4. Verify the following features:
   a. CapSense buttons: Touch any CapSense button; the corresponding LED turns on, detecting your touch.
   b. LED brightness feature (93 percent Active duty cycle and 7 percent Inactive duty cycle): The LEDs are driven by a pulse width modulator (PWM); the percentage of active and inactive duty cycles represent the PWM duty cycle for which the LEDs will be on. According to the configuration settings, when none of the CapSense buttons are touched, the LEDs glow with a faint brightness with a PWM duty cycle of 7 percent. When a CapSense button is touched, the LED glows with higher brightness, with a PWM duty cycle of 93 percent.
   c. Buzzer feature (1-kHz frequency and 1-second duration): Touch a CapSense button or proximity loop; the respective LED turns on along with an audio feedback for 1 second at a 1-kHz frequency.

Figure 5-7. LEDs with 7 Percent Inactive Duty Cycle
d. Proximity: Hover your hand/finger (3-cm distance) over the kit; the proximity LED lights up, showcasing proximity detection.

The proximity sensor has three states: OFF, Proximity, and ON (or Touch). The buzzer is enabled when the Proximity state becomes ON – when the proximity loop is touched. The change in Proximity state can be seen in the System Diagnostics tab in EZ-Click. In the **System Diagnostics** tab, select **Sensor1** from the drop-down list and click **Start** to monitor the sensor status and SNR for the selected CapSense sensor.

**Figure 5-9. Selecting Proximity Sensor in System Diagnostics**

**Figure 5-10. Proximity Sensor in Off State**
Figure 5-11. Proximity Sensor in Proximity State

In the Proximity state, the LED brightness increases.

Figure 5-12. Proximity Sensor in ON State

In this state, the buzzer is also enabled.

**Note:** The EZ-Click customiser tool computes the SNR. To establish a reliable noise range, the tool should be allowed to collect data samples for at least 30 seconds before a button press or proximity sensor state change. If sufficient noise samples are not collected, the EZ-Click tool reports an error and extremely high values for SNR.

Figure 5-13. Verify Proximity Sensor
5.2.3 Water Tolerance

This configuration file configures the CY8CMBR3116 to demonstrate water tolerance, FSS, and the button auto-reset feature. The Water Tolerance configuration is the factory default configuration for the CY3280-MBR3 EVK.

5.2.3.1 Loading Water Tolerance Configuration

1. Follow steps 1 to 4 as described in section 5.2.1.1 Loading LED Toggle Configuration.
2. Double-click the Water Tolerance.cprj file to open it.
3. Follow steps 6 to 9 as described in section 5.2.1.1 Loading LED Toggle Configuration to continue.
4. Verify the following features:
   a. FSS feature: Touch any CapSense button; the corresponding LED turns on. Keep your finger on the same button and touch any of the other buttons; the LED corresponding to the second button does not turn on. Remove your finger from the first button and then touch the second button again; the corresponding LED turns on.

Figure 5-14. Verify FSS Feature

b. Button auto-reset feature (5 seconds): Touch any CapSense button; the corresponding LED turns on. Do not release your finger; the LED turns off automatically after 5 seconds.
Figure 5-15. Auto-Reset Feature - LED Output on Button Touch

Figure 5-16. Auto-Reset Feature - LED Output Five Seconds After Button Touch

Note: For the buzzer and LED effect features, use a voltage setting of 5 V or 3.3 V for optimal performance.
c. Water tolerance feature: Place the additional 1-mm overlay on top of the 2-mm overlay. Place water droplets on top of the CapSense buttons using the water dropper provided with the kit. Observe that the LEDs do not turn on indicating that none of the CapSense buttons were triggered due to water.

Figure 5-17. Verify Water Tolerance - Without Finger

Touch a CapSense button and observe that it is triggered even in the presence of water droplets.
Figure 5-18. Verify Water Tolerance - With Finger

Note: The board does not have a guard sensor loop and cannot detect false touches in streaming water conditions. Therefore, while testing the board for water tolerance failure, ensure that the water droplets placed on one CapSense button do not come in contact with water droplets placed on another CapSense button.

Note: If the liquid in the dropper has significant conductivity, false touch may occur when the dropper touches the overlay on the board. This is not observed with clean water.

Water Tolerance Failure Demonstration: In the existing Water Tolerance configuration, uncheck the Enable Shield check box in the Global Configuration tab.

Figure 5-19. Water Tolerance Failure Demonstration

Now, click the 'Generate Config File' icon to generate the configuration; apply it to the board by clicking the 'Apply Current Config File' icon.

Press the reset switch, SW2, on the board and place water droplets on the CapSense button using the water dropper; observe that the LED turns on as if the button has been touched.

Note: The MBR3 SmartSense algorithm constantly updates baseline measurements, which may compensate for small droplets of water such that water tolerance failure is not observed. Therefore, a sufficient volume of water (one full dropper) is required to demonstrate water tolerance failure without the shield enabled.
5.3  PSoC 4 Host Example Projects

In this section, you learn how to use the CY3280-MBR3 EVK as an Arduino shield with boards compatible with the Arduino UNO form factor. The example projects in this section use the CY8CKIT-042 PSoC 4 Pioneer Kit as the baseboard. You can mount the CY3280-MBR3 EVK directly on top of the PSoC 4 Pioneer Kit, as displayed in Figure 5-20.

The kit can be used with other Arduino boards in a similar fashion. To begin, configure your kit for communication with the embedded host. On the CY3280-MBR3 EVK:

- Change the jumper position on header J13 to connect pins J13-2 and J13-3.
- Change the jumper position on header J14 to connect pins J14-2 and J14-3.
- Change the jumper position of J15 to position A; see Figure 5-21.

Connect the two kits such that the USB ports of both kits align with each other. When the USB ports are aligned, the J1, J2, J3, and J4 headers on the PSoC 4 Pioneer Kit connect to J1, J2, J3, and J4 headers on the CY3280-MBR3 EVK.

Note: The J2 header on the PSoC 4 Pioneer Kit is a dual-row header and has three extra pins for which there are no corresponding pins on the CY3280-MBR3 EVK.

Figure 5-20. Final Mounted Kit
Two example projects showcase how to configure the MBR3 device and how to communicate with the device. To open these projects, you need PSoC Creator 3.3 CP3 or later. Download and install the software from www.cypress.com/PSoCCreator, if required.

To verify these projects, you need a PSoC 4 Pioneer Kit.

See Running Configuration Files and Host Projects on page 46 for information on how to access the example projects.

5.3.1 Host_LED_Toggle_Buzzer_PSoC4_Pioneer_Kit

5.3.1.1 Project Description

This example project uses PSoC 4 as the \text{i}^2\text{C} master (host) to configure the CY8CMBR3116 device. This project shows how to write data to the CY8CMBR3116 device using \text{i}^2\text{C} communication lines.

In this project, PSoC 4 loads the 128-byte configuration data to the MBR3 device using \text{i}^2\text{C} communication. The 128-byte configuration data of the LED Toggle configuration is sent to the MBR3 device.

This project can be used to learn the process of configuring the device using an external host. See Configuring the MBR3 Device From the PSoC 4 Pioneer Kit on page 68 for details.
5.3.1.2 Hardware Connections

Connect the CY3280-MBR3 EVK to the PSoC 4 Pioneer Kit, as discussed in PSoC 4 Host Example Projects on page 57.

Ensure that the jumper J15 is connected in position A (see Figure 5-21). Table 5-2 shows the pin connections used for I²C communication; the corresponding pins of the EVK are connected to the CY8CMBR3116 device I²C pins.

Table 5-2. Pin Connections

<table>
<thead>
<tr>
<th>Component Pin Name</th>
<th>Port Pin Used</th>
</tr>
</thead>
<tbody>
<tr>
<td>SCB:scl\</td>
<td>P4[0]</td>
</tr>
<tr>
<td>SCB:sda\</td>
<td>P4[1]</td>
</tr>
<tr>
<td>FAIL_LED</td>
<td>P0[3]</td>
</tr>
</tbody>
</table>

Ensure that I²C selection jumpers J13 and J14 are shorted on pins 2 and 3, as shown in Figure 5-21.
5.3.1.3 Flow Chart

Figure 5-23 shows the flow chart of the code implemented in `main.c`.

Figure 5-23. Project Flow Chart

```
Start

Initialize I2C Master component

Configure and load toggle and buzzer feature to MBR3

Configuration was loaded to MBR3 successfully?

Yes

MBR3 drives the LEDs and buzzer on touch

No

The RGB LED on CY8CKIT-042 blinks continuously indicating I2C write error
```

5.3.1.4 Build and Program the PSoC 4 Project

Follow these steps to open and program code examples:

1. Launch PSoC Creator from the Start menu.
2. On the Start Page, expand CY3280-MBR3 under Examples and Kits > Kits and select `Host_LED_Toggle_Buzzer_PSoC4_Pioneer_Kit.cywrk` from the list of example projects, as shown in Figure 5-24.
3. Select a location to save the project and click OK.
4. Build the code example by choosing Build > Build <Project name> or by selecting Build <project name> in the menu options obtained by right-clicking on the project name in the Workspace Explorer to generate the hex file (see Figure 5-25).

Figure 5-25. Building the Project from PSoC Creator

5. To program, connect the PSoC 4 Pioneer Kit to a computer using the USB cable connected to the USB port/J10 of the PSoC 4 Pioneer Kit.

6. Choose Debug > Program in PSoC Creator (see Figure 5-26).
7. The CY8CKIT-042 is detected as “KitProg/<serial number>” and is seen in the Select Debug Target window. If the PSoC 4 device is not yet acquired, PSoC Creator opens the Programming window. Select the KitProg and click the **Port Acquire** button (see Figure 5-27).

Figure 5-27. Acquiring the Device from PSoC Creator

8. After the device is acquired, it is shown in a tree structure below the KitProg. Click the **Connect** button (see Figure 5-28).
9. Click **OK** to exit the window and start programming.

### 5.3.1.5 Verify Output

Ensure that the EVK is connected to the PSoC 4 Pioneer Kit. Touch any CapSense button on the kit; the corresponding LED toggles, with audio feedback through the buzzer (see Figure 5-29). If an I²C write error occurs while loading the configuration to the MBR3 device, the RGB LED on the PSoC 4 Pioneer Kit blinks in blue continuously indicating an I²C write error.
5.3.2 Host Interrupt LED ON Time PSoC4 Pioneer Kit

5.3.2.1 Project Description

This example project uses PSoC 4 as the I²C master (host) to implement the LED-on time feature on the CY3280-MBR3 EVK using the host interrupt and host-controlled GPOs feature. This project also shows how to read the status register of the device with an I²C master upon an interrupt from the device.

In this project, PSoC 4 loads the following configuration:

- Four button sensors enabled
- Host interrupt enabled
- Host-controlled GPOs

On every touch and release, the device issues a host interrupt (active-low pulse of 250-µs duration) to the PSoC 4 Pioneer Kit. Upon receipt of the interrupt, PSoC 4 sends an I²C read command to read the button status register (0xAA-0xAB). Depending upon the content of the register, PSoC 4 controls the onboard RGB LED. See Table 5-4 for the expected RGB output. Also, it detects if the host interrupt was generated because of a touch or a release. If a button is released, the corresponding RGB LED keeps glowing for one second before going off. This is implemented using the counter (TCPWM component) available in PSoC 4.
5.3.2.2 Hardware Connections

Connect the CY3280-MBR3 EVK to the PSoC 4 Pioneer Kit, as shown in Figure 5-20. Ensure that the jumper J15 is connected in position A (see Figure 5-21). No specific hardware connection is required for this project because all connections are hard wired.

Table 5-3 lists the pin connections used for I2C communication; the corresponding pins of the EVK are connected to the CY8CMR3116 device I2C pins.

Table 5-3. Pin Connections

<table>
<thead>
<tr>
<th>Component Pin Name</th>
<th>Port Pin Used</th>
</tr>
</thead>
<tbody>
<tr>
<td>\texttt{SCB:scl}\</td>
<td>P4[0]</td>
</tr>
<tr>
<td>\texttt{SCB:sda}\</td>
<td>P4[1]</td>
</tr>
<tr>
<td>Blue</td>
<td>P0[3]</td>
</tr>
<tr>
<td>Green</td>
<td>P0[2]</td>
</tr>
<tr>
<td>HostInt_Pin</td>
<td>P0[7]</td>
</tr>
<tr>
<td>Red</td>
<td>P1[6]</td>
</tr>
</tbody>
</table>
5.3.2.3 Flow Chart

Figure 5-31 shows the flow chart of the code implemented in main.c.

Figure 5-31. Project Flow Chart

Start

- Initialize I2C, Counter and Interrupt components

- Turn off all LEDs on Host

- Wait for 1 sec for MBR3 to bootup

- Configure MBR3

  - Is MBR3 configured successfully?
    - Yes: Blink blue LED continuously
    - No: Turn off all LEDs on MBR3

  - Is host interrupt flag set?
    - Yes: Read sensor status
    - No: Update host RGB LEDs

- Is any LED active?
  - Yes: Blink Red LED continuously
  - No: Turn on/off MBR3 LEDs

- Is any button active?
  - Yes: Update host RGB LEDs
  - No: Reset host interrupt flag

- Is counter expired?
  - Yes: Reset LED status flag
  - No: Start Counter

- Reset LED status flag

- Stop counter

- Initialize counter interrupt flag

- Turn off all LEDs
5.3.2.4 *Build and Program the PSoC 4 Project*

Follow these steps to open and program code examples:

1. Launch PSoC Creator from the Start menu.
2. On the Start Page, expand CY3280-MBR3 under Examples and Kits > Kits and select Host_In-terrupt_LED_ON_Time_PSoC4_Pioneer_Kit.cywrk from the list of example projects.
3. Follow steps 3 to 9 as described in Build and Program the PSoC 4 Project on page 60 to con-tinue.

5.3.2.5 *Verify Output*

Ensure that the EVK is connected to the PSoC 4 Pioneer Kit. Touch a CapSense button. Observe that the corresponding LED on the CY3280-MBR3 EVK turns on; the RGB LED also turns on based on the button touched according to Table 5-4. Remove the finger from the CapSense button. Observe that the corresponding LED on the CY3280-MBR3 EVK turns off immediately but the RGB LED turns off one second after removing the finger (see Figure 5-32).

Table 5-4. RGB LED Mapping on PSoC 4 Pioneer Kit with Button Sensors on CY3280-MBR3 EVK

<table>
<thead>
<tr>
<th>Button Sensor Touched</th>
<th>LED Connection on PSoC 4 Pioneer Kit</th>
</tr>
</thead>
<tbody>
<tr>
<td>BTN1</td>
<td>Green LED</td>
</tr>
<tr>
<td>BTN2</td>
<td>Red LED</td>
</tr>
<tr>
<td>BTN3</td>
<td>Blue LED</td>
</tr>
<tr>
<td>BTN4</td>
<td>All three LEDs</td>
</tr>
</tbody>
</table>

*Note:* When the LED is on and a touch is detected before the one-second elapse time, the touch is not processed.
5.3.3 Configuring the MBR3 Device From the PSoC 4 Pioneer Kit

The MBR3 device can be configured as required from an external host such as the CY8CKIT-042 PSoC 4 Pioneer Kit. This can be done using the configuration files generated by EZ-Click. Follow these steps to configure the MBR3 device from an external host:

1. Open EZ-Click.
2. Create a new project and select the CY8CMBR3116 device in the Product Selector Guide.
3. Configure the features as needed, considering the kit pin mapping (see Pin Mapping Between CY8CMBR3116 and CY3280-MBR3 EVK on page 31).
4. Generate the configuration file.
5. Navigate to the EZ-Click project directory and look for `<file name>.h` file inside the directory.
6. Open `<file name>.h` either from within PSoC Creator or using any text editor such as WordPad.
7. Copy and paste the 128-byte array CY8CMBR3116_configuration[128] in `<filename>.h` to the LED_Toggle.h file located in the MBR3_Configuration folder.

**Note:** When configuring the MBR3 device from an external host such as the PSoC 4 Pioneer Kit, ensure that a blank configuration or a slave address of 0x00 is not sent to the device. If this happens, see Restoring to Factory Default Slave Address from 0x00 on page 74 to revert the kit back to factory default. The valid slave address for the MBR3 device is from 0x08–0x77.
8. Build the project (see steps 3 to 8 in Build and Program the PSoC 4 Project on page 60) and program it on to the PSoC 4 Pioneer Kit; verify the functionality on the CY3280-MBR3 EVK.
6. Advanced Topics

6.1 Using PSoC 5LP as USB-I\(^2\)C Bridge

The PSoC 5LP on the CY3280-MBR3 EVK serves as a USB-I\(^2\)C bridge, which can be used to communicate with USB-I\(^2\)C software such as Bridge Control Panel. Bridge Control Panel (BCP) is installed along with PSoC Programmer during kit installation. BCP works with I\(^2\)C, SPI, and RX8 bridges, which communicate with slave devices. This application currently supports CY3240, MiniProg3, FirstTouch, FirstTouchRF, Touch Tuning Bridge, DVKProg1, and KitProg bridges.

The following steps describe how to use the USB-I\(^2\)C bridge, which can communicate between BCP and CY8CMBR3116 device.

1. Open BCP from **Start > All Programs > Cypress > Bridge Control Panel <version number>**.
2. Connect the CY3280-MBR3 EVK to your PC via a USB port using the USB cable.
3. Ensure that the I\(^2\)C selection jumpers J13 and J14 are shorted between pins 1 and 2 to enable I\(^2\)C communication between PSoC 5LP and the MBR3 device. Connect jumper J15 in setting C, as shown in Figure 5-1.
4. Select the KitProg in the BCP to use the USB-I\(^2\)C functionality. On successful connection, the 'Connected' and 'Powered' tabs turn green, as shown in Figure 6-1.

Figure 6-1. KitProg USB-I\(^2\)C Connected in Bridge Control Panel
5. EZ-Click generates an IIC file, which can be used in the BCP software. Click File > Open File and navigate to the EZ-Click project directory in `<Install_Directory>\CY3280-MBR3 EVK\<version>\Firmware\Config Files\` and open the required project and select the IIC file.

**Figure 6-2. Opening IIC File**

![Image of Bridge Control Panel](image)

**Figure 6-3. LED Toggle.iic File**

![Image of File Explorer](image)

**Note:** The location of the *LED Toggle.iic* file is shown as reference. Any IIC file can be used.
6. The MBR3 device is in a deep-sleep state until a CapSense or \( \text{I}^2\text{C}\) activity occurs. When receiving an \( \text{I}^2\text{C}\) command while in deep sleep, MBR3 will NACK the request and begin to wake from sleep. This \( \text{I}^2\text{C}\) approach is in lieu of \( \text{I}^2\text{C}\) clock stretching, which may corrupt non-stretching compliant devices on the bus. An \( \text{I}^2\text{C}\) command sent from BCP may not be acknowledged. Therefore, resend the \( \text{I}^2\text{C}\) command until the MBR3 device wakes and acknowledges. Two dummy write operations to the MBR3 device are sufficient before sending the 128-byte configuration. To send a dummy write, edit each write command in the IIC file with the prefix "w 37 0 p w 37 0 p".

7. From the BCP, transfer the 128-byte configuration data to the MBR3 device; to do this, place the cursor on the command to be sent to the MBR3 device and click the **Send** button on the GUI or press the **Enter** key on your keyboard. The log shows if the transaction is a success or failure. A "+" after each byte indicates that the transaction is a success and a "–" indicates that it is a failure (see Figure 6-4).

8. Send both \( \text{I}^2\text{C}\) commands in the IIC file to see the configuration in effect on the CY3280-MBR3 kit.

9. Press the reset switch, SW2, on the kit. The configuration specified by 128 bytes in the first command will take effect.

   **Note:** See LED Toggle on page 47 for more details and expected output of the LED Toggle configuration.

Figure 6-4. Writing to \( \text{I}^2\text{C}\) Slave in BCP

10. Read five bytes of data from the register offset address 0x00 of the MBR3 device. The log shows if the transaction is a success or a failure.
The command format to communicate with this kit using the BCP is as follows:

- **Write data command format**: To write 'N' bytes of data after the register offset address, use this format to send data.

<table>
<thead>
<tr>
<th>w</th>
<th>Slave address</th>
<th>Register offset</th>
<th>Data to write (N bytes)</th>
<th>p</th>
</tr>
</thead>
</table>

- **Read data command format**: To read 'N' bytes of data beginning with the register offset address, use this format to receive data.

<table>
<thead>
<tr>
<th>w</th>
<th>Slave address</th>
<th>Register offset</th>
<th>r</th>
<th>Slave address</th>
<th>write 'N' number of x's with spaces</th>
<th>p</th>
</tr>
</thead>
</table>

**Notes:**

- The Write/Read transaction with an MBR3 device requires specifying an offset address to the MBR3 device from which the data reading/writing should start. The MBR3 device automatically increments the register address for every byte after the offset address. Therefore, a Read/Write transaction with an MBR3 device starts with an I²C write operation to specify the register offset to the MBR3 device.
- All bytes in the IIC file are in hex format.

The status box below the editor window shows the offset register content, where:

- **w** – Write command.
- **Address** – Slave device address (in hex). Default address for the device on this kit is 0x37.
- **Register offset** – Offset address of the configuration register you want to write. See the datasheet for the list of registers and their offset addresses.
- **Data** – Write 'N' byte data here to write sequentially beginning with the offset address.
- **r** – Read command.
6.2 Restoring to Factory Default Slave Address from 0x00

When configuring the MBR3 device from an external host such as the CY8CKIT-042 PSoC 4 Pioneer Kit, ensure that either a blank configuration (128 bytes of 0x00) or a slave address of 0x00 is not programmed into the MBR3 silicon. The valid slave address for MBR3 is 0x08–0x77 (8–119).

If a slave address is configured to the MBR3 device, the kit becomes unusable because it cannot be reconfigured from EZ-Click. In such a situation, follow these steps to restore the slave address to the default slave address 0x37.

1. Disconnect the CY3280-MBR3 kit from the external host or CY8CKIT-042.
2. Change the I²C selection jumpers J13 and J14 in positions 1 and 2.
3. Change the J15 setting to setting C.
4. Launch BCP, as explained in steps 1 to 4 in 6.1 Using PSoC 5LP as USB-I²C Bridge.
5. Click File > Open and navigate to the Water Tolerance configuration project directory and open Water Tolerance.iic in BCP.
6. Change "37" next to w to "00" in both the IIC commands. Also, edit the IIC commands with dummy write operations and send the configuration to the MBR3 device, as explained in step 6 of Using PSoC 5LP as USB-I²C Bridge on page 70.

7. Both the I²C commands are sent one after another. Ensure that all bytes of the I²C command are ACK'ed (acknowledged). If any I²C command is NACK'ed (not acknowledged), send the I²C commands again. See Figure 6-4 for ACK and NACK indications.
8. After both the commands are successfully sent to the MBR3 device, that is, all bytes are ACK'ed, press the reset switch (SW2) on the CY3280-MBR3 EVK.
9. The kit will become operational again and exhibit the "Water Tolerance" output. Refer to Water Tolerance on page 53. The kit will also be recognized with the slave ID of 0x37 in EZ-Click.
## 6.3 Connecting External CapSense Sensors to the CY3280-MBR3 EVK

In some situations, it is required to connect external sensors to the CY3280-MBR3 EVK to evaluate the sensor performance. The CY3280-MBR3 EVK provides an option to connect up to five external sensors to header J2, as shown in Figure 6-7. In Figure 6-7, four CapSense button sensors and one proximity sensor is connected to the kit. The driven shield signal from the CY8CMBR3116 controller can also be connected to the external shield electrode by connecting a wire from pin 4 (HI/SHIELD) in header J15 to the external shield electrode. This will allow users to test proximity and liquid tolerance performance of external sensors with the driven shield signal.

![Figure 6-7. External CapSense Sensors Connected to Header J2](image)
A. Appendix

A.1 Schematic

NOTE: DONT LOAD R54

NOTE: By default O/P VADJ is 3.3V.

NOTE: Load R84 and R85 only during 1.8V externally regulated mode of operation only. WARNING: When R84 is loaded DO NOT operate the kit at any voltage more than 1.8V i.e. 3.3V or 5V. Otherwise the CY83336KLV silicon will get damaged.
USB MiniB

NOTE: DO NOT POWER FROM J11 JUMPER

For Kit Current Consumption: Connect an Ammeter between J11-1 and J11-2 pins
BY Default Connect J11-1 to J11-2

External Power Supply Protection

The PolyZen Protection Device will Protect the kit from Voltages upto 12V.

NOTE: DONT LOAD R55 and R63.
NOTE: Keep VCCD and CMOD cap near U2. And keep the CMOD Cap Trace thick like power Trace.

NOTE: Load R84 and R85 only during 1.8V externally regulated mode of operation.
WARNING: When R84 is loaded DO NOT operate the kit at any voltage more than 1.8V i.e. 3.3V or 5V. Otherwise the CY8CMBR3116 silicon will get damaged.

NOTE: DO NOT POWER FROM J12 JUMPER
J12 for Current Measurement
J12 is shorted By Default
External Pull Up for XRES and HOST Interrupt pin of CY8CMBR3116

TP7 BLACK
and Test Point

CY8CMBR3116 Reset Switch
AT ANY TIME DONT LOAD BOTH R66 and R67.

J15 Jumper is used to select between buzzer, Water Tolerance and Host Interrupt Feature.

NOTE: At any time a maximum 2 features can be enabled out of 3 features.

<table>
<thead>
<tr>
<th>Setting</th>
<th>J15 Jumper Connection</th>
<th>Enabled Features (2 features at a time)</th>
</tr>
</thead>
<tbody>
<tr>
<td>B</td>
<td>Connect J15-2 and J15-3, J15-4 to J15-5 using 2 shunts</td>
<td>Buzzer Disabled, Host Interrupt Enabled and Water Tolerance is Enabled</td>
</tr>
<tr>
<td>C</td>
<td>By Default connect J15-1 and J15-2, J15-4 to J15-5 using 2 shunts</td>
<td>Buzzer Enabled, Host Interrupt Disabled and Water Tolerance is Enabled</td>
</tr>
</tbody>
</table>
Long Trace/Short Trace selection for CapSense Button4 (BTN4)

<table>
<thead>
<tr>
<th>SW3 Selection</th>
<th>Additional Parasitic Capacitance on BTN4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pos/Pin 1</td>
<td>Long Trace</td>
</tr>
<tr>
<td>Pos/Pin 2</td>
<td>Short Trace</td>
</tr>
</tbody>
</table>

Parasitic Capacitance on Button2 (BTN2)

<table>
<thead>
<tr>
<th>SW1 Selection</th>
<th>Additional Parasitic Capacitance on BTN2</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pos/Pin 1</td>
<td>15pF</td>
</tr>
<tr>
<td>Pos/Pin 2</td>
<td>10pF</td>
</tr>
<tr>
<td>Pos/Pin 3</td>
<td>0pF</td>
</tr>
</tbody>
</table>

LED1
- D9
- R30 330 ohm
- LED Red

LED2
- D10
- R29 330 ohm
- LED Red

LED3
- D11
- R31 330 ohm
- LED Red

LED4
- D12
- R32 330 ohm
- LED Red

PROX_LED
- D14
- R59 330 ohm
- LED Red

VADJ
NOTE: J13 and J14 JUMPER CONFIGURATION

Short J13-1 to J13-2 and J14-1 to J14-2 for using Onboard I2C-USB Bridge

Short J13-2 to J13-3 and J14-2 to J14-3 for connecting the CY8CMR3116’s I2C lines to Arduino header J3 pins 9 and 10.

Remove both shunts on J13, J14 and load zero ohm resistor on R71 and R72 for connecting the CY8CMR3116 I2C lines to Arduino header J2 pins 9 and 10.

(J1-J4) Arduino Compatible Headers
A.2 Pin Assignment Table

<table>
<thead>
<tr>
<th>Pin No.</th>
<th>Pin Name</th>
<th>Type</th>
<th>Description</th>
<th>Usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>CS0/PS0</td>
<td>I/O</td>
<td>CapSense button/proximity sensor, controls GPO0</td>
<td>Proximity loop.</td>
</tr>
<tr>
<td>2</td>
<td>CS1/PS1</td>
<td>I/O</td>
<td>CapSense button/proximity sensor, controls GPO1</td>
<td>Brought out to dual header through a 560-Ω resistor.</td>
</tr>
<tr>
<td>3</td>
<td>CS2/GUARD</td>
<td>I/O</td>
<td>CapSense button/guard sensor, controls GPO2</td>
<td>Brought out to dual header through a 560-Ω resistor.</td>
</tr>
<tr>
<td>4</td>
<td>CS3</td>
<td>I/O</td>
<td>CapSense button/guard sensor, controls GPO2</td>
<td>BTN1 (10-mm diameter)</td>
</tr>
<tr>
<td>5</td>
<td>CMOD</td>
<td>I/O</td>
<td>External modulator capacitor.</td>
<td>Connect 2.2-nF capacitor.</td>
</tr>
<tr>
<td>6</td>
<td>VCCD</td>
<td>Power</td>
<td>CapSense button/guard sensor, controls GPO2</td>
<td>2.2 nF Cmod capacitor (COG type).</td>
</tr>
<tr>
<td>7</td>
<td>VDD</td>
<td>Power</td>
<td>CapSense button/guard sensor, controls GPO2</td>
<td>Bypass capacitor of 0.1 uF.</td>
</tr>
<tr>
<td>8</td>
<td>VSS</td>
<td>Power</td>
<td>CapSense button/guard sensor, controls GPO2</td>
<td>VADJ= 5 V, 3.3 V, or 1.8 V.</td>
</tr>
<tr>
<td>9</td>
<td>CS15/SH/HI</td>
<td>I/O</td>
<td>CapSense button/shield electrode/host interrupt/buzzer output</td>
<td>This pin will be connected to a 6-pin jumper to select between Hash GND for water proofing or host interrupt.</td>
</tr>
<tr>
<td>10</td>
<td>CS14/GPO6</td>
<td>I/O</td>
<td>CapSense button/general-purpose output</td>
<td>LED 4 for button 4 (BTN4).</td>
</tr>
<tr>
<td>11</td>
<td>CS13/GPO5</td>
<td>I/O</td>
<td>CapSense button/general-purpose output</td>
<td>LED 3 for button 3 (BTN3).</td>
</tr>
<tr>
<td>12</td>
<td>CS12/GPO4</td>
<td>I/O</td>
<td>CapSense button/general-purpose output</td>
<td>LED 2 for button 2 (BTN2).</td>
</tr>
<tr>
<td>13</td>
<td>CS11/GPO3</td>
<td>I/O</td>
<td>CapSense button/general-purpose output</td>
<td>LED 1 for button 1 (BTN1).</td>
</tr>
<tr>
<td>14</td>
<td>CS10/GPO2</td>
<td>I/O</td>
<td>CapSense button/general-purpose output</td>
<td>Brought out to dual header through a 560-Ω resistor.</td>
</tr>
<tr>
<td>15</td>
<td>CS9/GPO1</td>
<td>I/O</td>
<td>CapSense button/general-purpose output</td>
<td>Brought out to dual header through a 560-Ω resistor.</td>
</tr>
<tr>
<td>16</td>
<td>CS8/GPO0</td>
<td>I/O</td>
<td>CapSense button/general-purpose output</td>
<td>Proximity LED.</td>
</tr>
<tr>
<td>17</td>
<td>CS7</td>
<td>I/O</td>
<td>CapSense button, controls GPO7</td>
<td>Cannot be used because GPO7 is multiplexed with the host interrupt so brought out to a header.</td>
</tr>
<tr>
<td>18</td>
<td>CS6</td>
<td>I/O</td>
<td>CapSense button, controls GPO6</td>
<td>BTN4 (11-mm diameter): A long trace option will be provided on this pin.</td>
</tr>
<tr>
<td>19</td>
<td>CS5</td>
<td>I/O</td>
<td>CapSense button, controls GPO5</td>
<td>BTN3 (11-mm diameter).</td>
</tr>
<tr>
<td>20</td>
<td>CS4</td>
<td>I/O</td>
<td>CapSense button, controls GPO4</td>
<td>BTN2 (10-mm diameter): Button 2 will have a slide switch, which varies the Cp to 10 pF or 15 pF, depending on the position of the switch.</td>
</tr>
<tr>
<td>21</td>
<td>I2C</td>
<td>SDA</td>
<td>I2C data</td>
<td>This pin will be connected to a 3-pin jumper, to choose between the onboard I2C-USB bridge or external host.</td>
</tr>
<tr>
<td>22</td>
<td>I2C</td>
<td>SCL</td>
<td>I2C clock</td>
<td>This pin will be connected to a 3-pin jumper, to choose between the onboard I2C-USB bridge or external host.</td>
</tr>
<tr>
<td>23</td>
<td>HI/BUZ/GPO7</td>
<td>O</td>
<td>Host interrupt/buzzer output/general-purpose output</td>
<td>This pin will be connected to a 6-pin jumper to select the host interrupt or buzzer.</td>
</tr>
<tr>
<td>24</td>
<td>XRES</td>
<td>XRES</td>
<td>External reset</td>
<td>Reset switch and an SIO pin on PSoC 5LP I2C-USB bridge.</td>
</tr>
</tbody>
</table>

**Note:** Pins shaded blue are left open; the other pins have been used for some function.
## A.3 Bill of Materials

<table>
<thead>
<tr>
<th>Item</th>
<th>Qty</th>
<th>Reference</th>
<th>Description</th>
<th>Manufacturer</th>
<th>Manufacturer Part No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>6</td>
<td>C11,C13,C18,C19,C23,C33</td>
<td>CAP CER 1UF 10V 10% X5R 0603</td>
<td>TDK Corporation</td>
<td>C1608X5R1A105K080AC</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>C4</td>
<td>CAP TANT 10UF 16V 10% 1206</td>
<td>AVX</td>
<td>TAJA106K016R</td>
</tr>
<tr>
<td>3</td>
<td>1</td>
<td>C5</td>
<td>CAP CER 22UF 10V 20% JB 0805</td>
<td>TDK Corporation</td>
<td>C2012JB1A226M125AB</td>
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<tr>
<td>4</td>
<td>9</td>
<td>C7,C12,C14,C15,C17,C20,C21,C24,C30</td>
<td>CAP CER 0.1UF 10V 10% X5R 0402</td>
<td>Taiyo Yuden</td>
<td>LMK105BJ104KV-F</td>
</tr>
<tr>
<td>5</td>
<td>1</td>
<td>C16</td>
<td>CAP 10000PF 16V CERAMIC 0402 SMD</td>
<td>TDK Corporation</td>
<td>C1005X7R1C103K050BA</td>
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<tr>
<td>6</td>
<td>1</td>
<td>C26</td>
<td>CAP, CER, 2200pF, 50V, 5%, COG, 0805</td>
<td>Murata</td>
<td>GRM2165C1H22JJA01D</td>
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<tr>
<td>7</td>
<td>1</td>
<td>C31</td>
<td>CAP CER 15PF 50V 5% NP0 0603</td>
<td>TDK Corporation</td>
<td>C1608C0G1H150J080AA</td>
</tr>
<tr>
<td>8</td>
<td>1</td>
<td>C32</td>
<td>CAP CER 10PF 50V 5% NP0 0603</td>
<td>Samsung Electro-Mechanics America, Inc</td>
<td>CL10C100JB8NNNC</td>
</tr>
<tr>
<td>9</td>
<td>1</td>
<td>C34</td>
<td>CAP CER 100PF 50V 5% NP0 0402</td>
<td>TDK Corporation</td>
<td>C1005C0G1H101J050BA</td>
</tr>
<tr>
<td>10</td>
<td>1</td>
<td>D2</td>
<td>DIO, SCHOTTKY, 20V, 0.5A, SOD-123</td>
<td>Fairchild Semiconductor</td>
<td>MBR0520L</td>
</tr>
<tr>
<td>11</td>
<td>3</td>
<td>D6,D7,D8</td>
<td>DIO, SUPPRESSOR ESD 5VDC 0603 SMD</td>
<td>Bourns Inc.</td>
<td>CG0603MLC-05LE</td>
</tr>
<tr>
<td>12</td>
<td>6</td>
<td>D9,D10,D11,D12,D13,D14</td>
<td>LED Red Clear 1206 Rear MNT SMD</td>
<td>Stanley Electric Co</td>
<td>BR1111R-TR</td>
</tr>
<tr>
<td>13</td>
<td>1</td>
<td>D15</td>
<td>LED Green Clear 1206 Rear MNT SMD</td>
<td>Lite-On Inc</td>
<td>LTST-C230GKT</td>
</tr>
<tr>
<td>14</td>
<td>7</td>
<td>R29,R30,R31,R32,R58,R59,R62</td>
<td>RES 330 OHM 1/8W 5% 0805 SMD</td>
<td>Panasonic</td>
<td>ERJ-6GEYJ331V</td>
</tr>
<tr>
<td>15</td>
<td>2</td>
<td>R80,R81</td>
<td>RES 330 OHM 1/10W 5% 0402 SMD</td>
<td>Panasonic Electronic Components</td>
<td>ERJ-2GEJ331X</td>
</tr>
<tr>
<td>16</td>
<td>10</td>
<td>R49,R50,R51,R52,R74,R75,R76,R77,R78,R79</td>
<td>RES 560 OHM 1/16W 5% 0402 SMD</td>
<td>Yageo Corporation</td>
<td>RC0402JR-07560RL</td>
</tr>
<tr>
<td>17</td>
<td>4</td>
<td>R5,R45,R67,R56</td>
<td>RES 0.0 OHM 1/8W 0805 SMD</td>
<td>Panasonic-ECG</td>
<td>ERJ-6GEY0R00V</td>
</tr>
<tr>
<td>18</td>
<td>1</td>
<td>R82</td>
<td>RES 0.0 OHM .125W JUMP 0402 SMD</td>
<td>Vishay Dale</td>
<td>CRCW04020000Z0EDHP</td>
</tr>
<tr>
<td>19</td>
<td>1</td>
<td>R60</td>
<td>RES 0.0 OHM 1/10JUMP 0603 SMD</td>
<td>Panasonic Electronic Components</td>
<td>ERJ-3GEY0R00V</td>
</tr>
<tr>
<td>20</td>
<td>2</td>
<td>R8,R9</td>
<td>RES 2.2K OHM 1/10W 5% 0603 SMD</td>
<td>Panasonic Electronic Components</td>
<td>ERJ-3GEYJ222V</td>
</tr>
<tr>
<td>21</td>
<td>1</td>
<td>R13</td>
<td>RES 100K OHM 1/10W 5% 0402 SMD</td>
<td>Panasonic Electronic Components</td>
<td>ERJ-2GEJ104X</td>
</tr>
<tr>
<td>22</td>
<td>2</td>
<td>R26,R27</td>
<td>RES 22 OHM 1/10W 1% 0603 SMD</td>
<td>Panasonic Electronic Components</td>
<td>ERJ-3KEF22R0V</td>
</tr>
<tr>
<td>23</td>
<td>3</td>
<td>R37,R39,R70</td>
<td>RES 15K OHM 1/10W 5% 0603 SMD</td>
<td>Panasonic Electronic Components</td>
<td>ERJ-3GEYJ153V</td>
</tr>
<tr>
<td>24</td>
<td>2</td>
<td>R73,R83</td>
<td>RES 4.7K OHM 1/10W 5% 0603 SMD</td>
<td>Panasonic Electronic Components</td>
<td>ERJ-3GEYJ472V</td>
</tr>
<tr>
<td>25</td>
<td>2</td>
<td>R43,R68</td>
<td>RES, 10K OHM, 1/16W, 1%, 0603, SMD</td>
<td>Yageo</td>
<td>RC0603FR-0710KL</td>
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<tr>
<td>26</td>
<td>4</td>
<td>R38,R40,R46,R69</td>
<td>RES 30K OHM 1/10W 1% 0603 SMD</td>
<td>Panasonic Electronic Components</td>
<td>ERJ-3KEF3002V</td>
</tr>
<tr>
<td>27</td>
<td>1</td>
<td>R44</td>
<td>RES 37.4K OHM 1/10W .5% 0603 SMD</td>
<td>Yageo</td>
<td>RT0603DR0737K4L</td>
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<tr>
<td>28</td>
<td>1</td>
<td>R47</td>
<td>RES 5.49K OHM 1/10W 1% 0603 SMD</td>
<td>Panasonic Electronic Components</td>
<td>ERJ-3KEF5491V</td>
</tr>
<tr>
<td>29</td>
<td>1</td>
<td>LS1</td>
<td>BUZZER PIEZO 4KHZ 12.2MM PC MNT</td>
<td>TDK CORPORATION (VA)</td>
<td>PS1240P02BT</td>
</tr>
</tbody>
</table>
### A.4 Regulatory Compliance Information

The CY3280-MBR3 EVK has been tested and verified to comply with the following electromagnetic compatibility (EMC) regulations.

- EN 55022:2010 Class A – Emissions
- EN 55024:2010 - Immunity

#### Parts List

<table>
<thead>
<tr>
<th>Item</th>
<th>Qty</th>
<th>Reference</th>
<th>Description</th>
<th>Manufacturer</th>
<th>Manufacturer Part No.</th>
</tr>
</thead>
<tbody>
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#### No Load Components

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**Revision History**

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<td>02/18/2014</td>
<td>SASH</td>
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<td>*A</td>
<td>02/21/2014</td>
<td>SASH</td>
<td>Updated EZ-Click images</td>
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<td>*B</td>
<td>03/10/2014</td>
<td>PAVA</td>
<td>Updates to include support for externally regulated operating mode at 1.8 V</td>
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<td>*C</td>
<td>04/16/2014</td>
<td>DIMA</td>
<td>Updated board images and Figure 5-22, Figure 5-31, and Figure 5-33. Added section 6.3 Connecting External CapSense Sensors to the CY3280-MBR3 EVK. Added links to Host API projects and CapSense code examples web page in section 1.4 Additional Learning Resources.</td>
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<td>SRDS</td>
<td>Updated PSoC Creator version to 3.3 CP3. Updated Figure 5-31. Updated to new template.</td>
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<td>SRDS / MBNM</td>
<td>Updated EZ-Click version to 2.0 SP2 and modified the corresponding images.</td>
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<td>SRDS / MBNM</td>
<td>Updated Configuration Files and Example Projects chapter on page 46: Updated “PSoC 4 Host Example Projects” on page 57: Updated “Host_LED_Toggle_Buzzer_PSoC4_Pioneer_Kit” on page 58: Updated “Hardware Connections” on page 59: Updated Table 5-2: Removed “Red LED” and corresponding details. Updated details in “Component Pin Name” column. Updated “Host_INTERRUPT_LED_ON_Time_PSoC4_Pioneer_Kit” on page 64: Updated “Hardware Connections” on page 65: Updated Table 5-3: Updated details in “Component Pin Name” column.</td>
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