

Application Note AN-1058

Programmable High Side Current Switch IR3310/11/12

By David Jacquinod

Table of Contents

	Page
1. Inner Architecture	
Reverse Battery Protection	1
WAIT Function	2
Min. Pulse Function.....	3
Load Dump Protection	3
Current Sensing Accuracy.....	3
Calibration	4
2. Typical Applications	
Programmable Current Shutdown.....	5
Filament Lamp and DC Application.....	5
2 Steps Current Shutdown	6
2 Steps Current Shutdown Controlled by RC.....	7
Current Shutdown Programmed by Analog Value	7
20kHz Current Sense H Bridge Motor Drive	8
Layout Consideration	9
Controlling IR331x by One Wire.....	9

The IR331X devices suit for any application where the load current sensing is required. IR331X is fully protected, programmable current shutdown, over temperature shutdown and reverse battery protection. The current sensing features offer current readout accuracy, high frequency bandwidth, a versatile way to control the current shutdown and replaces the shunt resistor. The IR331X family features a reverse battery protection. In such condition, the current flows in the load and the body diode of the power MOSFET, so the power dissipation is much higher than in normal. In a power MOSFET the current can flow in both direction from drain to source or from source to drain. The system switches on the MOSFET in order to reduce power dissipation.

APPLICATION NOTE

AN-1058

International Rectifier • 233 Kansas Street El Segundo CA 90245 USA

Programmable Current Sensing High-Side Switch IR3310/11/12

By
 David Jacquinod

Topics Covered

Inner Architecture

- Reverse battery protection
- Wait and Min. Pulse functions
- Load dump protection
- Current sensing accuracy

Typical Application

- Programmable current shutdown
- Filament lamp and DC motor application
- Layout consideration
- 20kHz current sense H bridge motor drive

Introduction

The IR331X devices suit for any application where the load current sensing is required. IR331X is fully protected : programmable current shutdown, over temperature shutdown and reverse battery protection.

The current sensing features offer current readout accuracy, high frequency bandwidth, a versatile way to control the current shutdown and replaces the shunt resistor.

1. Inner Architecture

Reverse Battery Protection

The IR331X family features a reverse battery protection. In such condition, the current flows in the load and the body diode of the power MOSFET, so the power dissipation is much higher than in normal condition.

In a power MOSFET the current can flow in both direction from drain to source or from source to drain. The system switches on the MOSFET in order to reduce power dissipation.

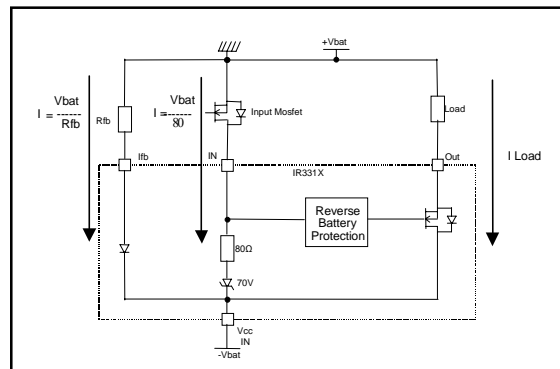


Figure 1 : Reverse battery connection

In reverse battery condition, the current flows through the body diode of the Input MOSFET, so $V_{in} = V_{bat} - 0.6V$. And the load current flows in the body diode of the power MOSFET, $V_{out} = 0.6V$

When $V_{in} - V_{out} (= V_{bat} - 1.2V)$ i.e. $V_{gate} - V_{source}$ reaches the threshold (typ. $2V$), the transistor turns on.

The IR331X reverse battery function works only if a discrete MOSFET is used to drive the input. If a bipolar transistor is used, a diode in parallel is required.

So the power dissipation is :

$$P \text{ dissipated} = P_d (\text{Power MOSFET}) + P_d (R=80\Omega) \\ = R_{dson} \times I_{Load}^2 + V_{bat}^2 / 80\Omega$$

When designing with reverse battery operation, the heat sink calculation must take in account the power dissipation in the 80Ω resistor i.e. $V_{bat}^2 / 80\Omega$.

For example : IR3310

- Iload = 30A
- Tj=125°C
- Tamb=85°C
- Vbat = 14V
- Rds(on) typ.@125°C = 8.8m Ω

$$P \text{ dissipated} = 8.8m \Omega \times 30^2 + 14^2 / 80 \Omega = 10.4 \text{ W}$$

$$R_{th} \text{ junction to amb} = T_j - T_{amb} / P \text{ dissipated} = 3.9 \text{ }^\circ\text{C/W}$$

WAIT Function

To provide a high level of protection, the IC features a WAIT function.

Without the WAIT function, a thermal runaway would occur:

When the IC reaches the over temperature shutdown threshold, the IC switches off. If the user restarts the IC immediately, the IC temperature goes beyond the temperature shutdown threshold because of the over temperature circuitry's delay (due to the turn on delay) . Permanently switching on a short circuit would end up in a destructive thermal run away.

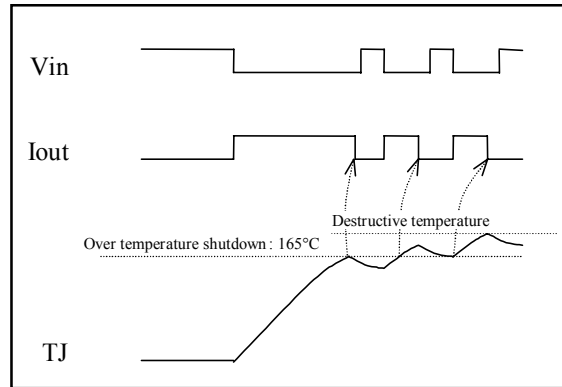


Figure 2 : Waveforms during temperature cycling

Thanks to the WAIT function, the IC turns on after a delay to insure that the IC is cooled enough. So the IC never reaches the destructive temperature. The WAIT delay starts when the system turns off the IR331X by releasing the input pin. The IR331X restarts only if input pin is kept high during a time which is longer than the T reset specified in the datasheet (see figure 7 in the datasheet) .

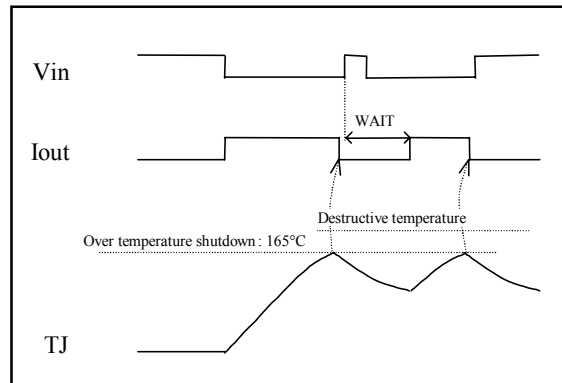


Figure 3 : Waveforms during temperature cycling with WAIT function

Min. Pulse function

When the system switches on IR331X for short times (<Min. Pulse), it doesn't have enough time to measure its temperature. If the system switches on IR331X for short times at high frequency, the temperature increases but the device has not enough time to detect an over-temperature.

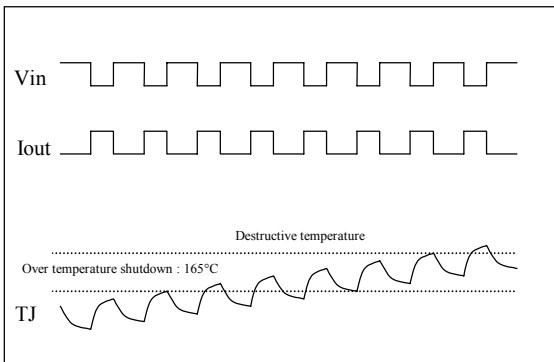


Figure 4 : Waveforms with short pulses

So if a short pulse on the input is detected, the device turns on only after the WAIT time.

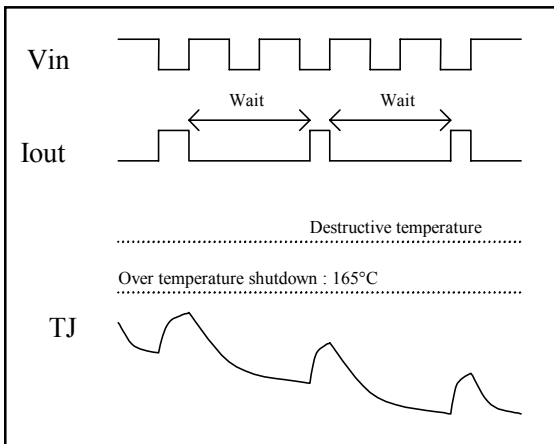


Figure 5 : Waveforms with Min. Pulse Function

Load Dump protection

In the IR331X family, the active clamp voltage occurs when Vcc-Vout reaches 35V. During load dump condition Vcc-Gnd is about 37V. So a dedicated feature disconnects the active clamp circuitry when Vcc-Gnd exceeds 30V. So during load dump, the IR331X is open and the maximum sustainable voltage is the avalanche voltage of the power MOSFET (typ. 43V)

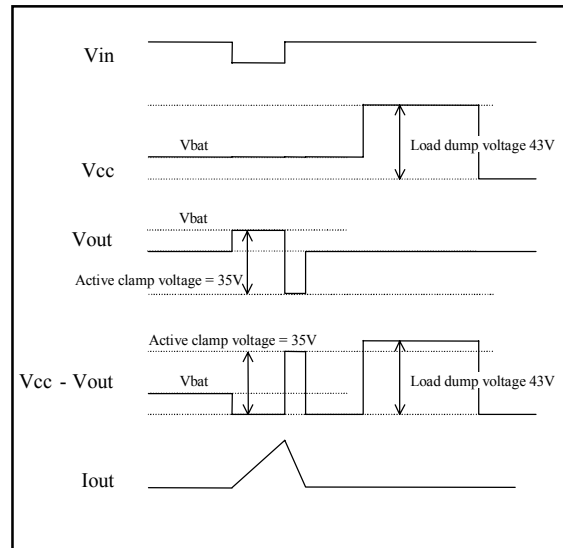


Figure 6 : Load dump protection

Current sensing accuracy

The IR331X family uses current sensing MOSFET to read the current in the load. A small MOSFET connected in parallel to the power MOSFET is flew by the load current divided by a ratio so far the same Vds voltage is applied to both MOSFET. An amplifier maintains the same voltage on the both MOSFET.

Example : IR3310

- Id = 80A
- I offset@25°C = +/- 1.3A
- I offset@-40°C = +/- 1.62A
- I offset@150°C = +/- 0.684A
- Ratio@25°C = 8800
- Rdson@25°C = 5.5mΩ

The worst case is at 150°C

with ratio@150°C = ratio@25°C - 5%

$$\Rightarrow I_{fb}@150^\circ C = \frac{80A - 0.684A}{8800 - 5\%} = 9.49mA$$

$$\Rightarrow I_d \text{ calculated} = 9.49mA \times 8800 + 1.3A = 84.8A$$

$$\Rightarrow \text{Error} = 6\%$$

So the calibration insures that the total error in the temperature range not exceeds 6%.

2. Typical Applications

Programmable current shutdown

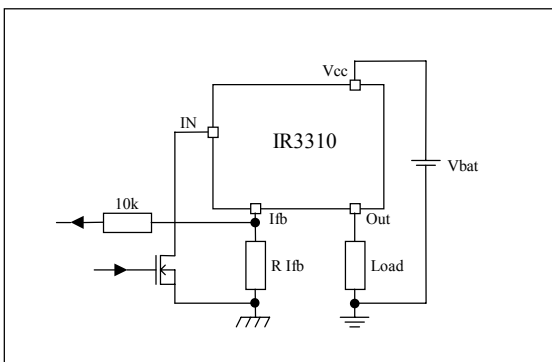


Figure 8 : Typical application

The following oscilloscope waveforms are an example with a pure inductive load.

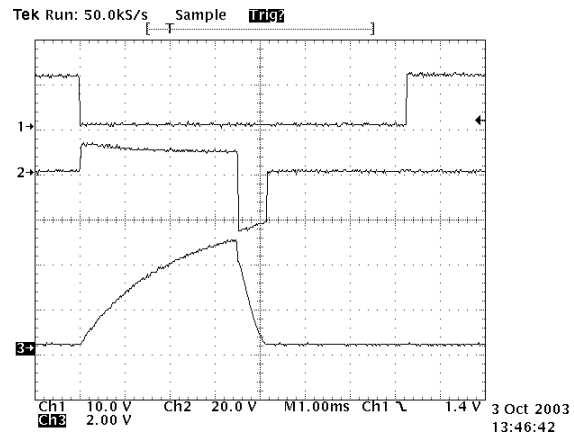


Figure 9 : Waveforms during current shutdown

- Trace 1 : Input voltage
- Trace 2 : Output voltage
- Trace 3 : Ifb pin voltage

When the device turns on, the current increases in the load. The Ifb pin voltage increases until reaching the current shutdown threshold (typically 4.5V) and the device turns off. The voltage across the load is the active clamp voltage.

The load current decreases following the equation :

$$\frac{dI}{dt} @load = \frac{V_{clamp}}{L}$$

Filament lamp and DC motor application

Both in filament lamp and DC motor application, the main concern is the inrush current. When the filament is cold, its resistance is very low. The inrush current can reach 7 times the nominal current. For DC motor operation, the inrush current is due to the direct start sequence.

The current shutdown strategy must be adapted for such loads, a high current shutdown during start up and a low current shutdown for nominal current.

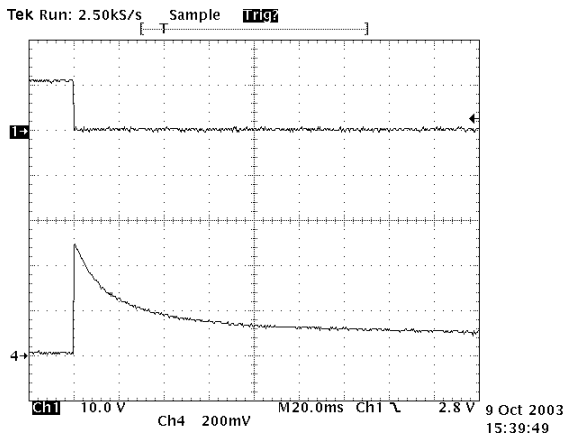


Figure 10 : Typical Inrush current for 2x45W filament lamp.

Trace 1 : input. Trace 2 : load current 20A/div.
I Peak = 50A
I Nom = 7.5A

2 steps current shutdown

The easiest way to implement two programmable current shutdown is to change the resistor I_{fb} value, one for the inrush current and one for the nominal current. A resistor I_{fb} calculated for the inrush current is connected in parallel by a MOSFET :

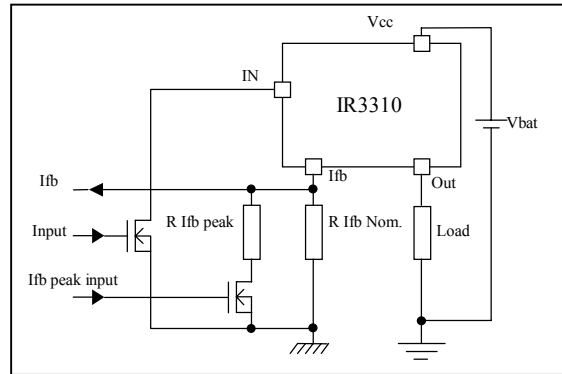


Figure 11 : 2 Steps current shutdown schematic

During inrush current, the system connects the R I_{fb} peak resistor to increase the current shutdown. When the load reaches the nominal current the system disconnects R I_{fb} peak to provide a good over current protection.

R I_{fb} is calculated with :

$$I_{\text{shutdown}} = V_{\text{Ifb}} - V_{\text{in@I}_{\text{sd min}}} \times \text{Ratio min} / R_{\text{fb}}$$

$$\Rightarrow R_{\text{Ifb}} = V_{\text{Ifb}} - V_{\text{in@I}_{\text{sd min}}} \times \text{Ratio min} / I_{\text{shutdown}}$$

Example : 2x45W filament lamp and IR3310

$$I_{\text{Nom}} = 7.5\text{A} \Rightarrow I_{\text{shutdown nom}} = 10\text{A}$$

$$I_{\text{shutdown peak}} = 10 \times I_{\text{nom}} = 75\text{A}$$

$$\Rightarrow R_{\text{Ifb Nom}} = 4\text{V} \times 7500 / 10\text{A} = 3\text{ kW}$$

$$\Rightarrow R_{\text{Ifb peak}} = 4\text{V} \times 7500 / 75\text{A} = 400\text{ W}$$

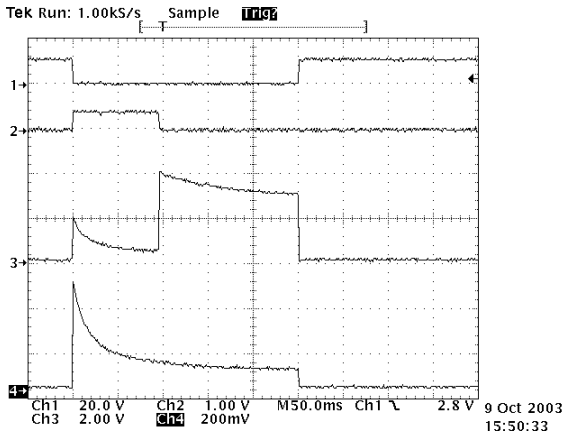


Figure 12 : Waveforms with 2x45W filament lamp.

R lfb nom=3.3kW, R ifb peak=390W
Trace 1 : Input
Trace 2 : Ifb peak input
Trace 3 : Ifb pin voltage
Trace 4 : Current load

2 steps current shutdown controlled by RC

If an logical output is not available to drive 2 scales current shutdown, a simple circuit can increase the current shutdown.

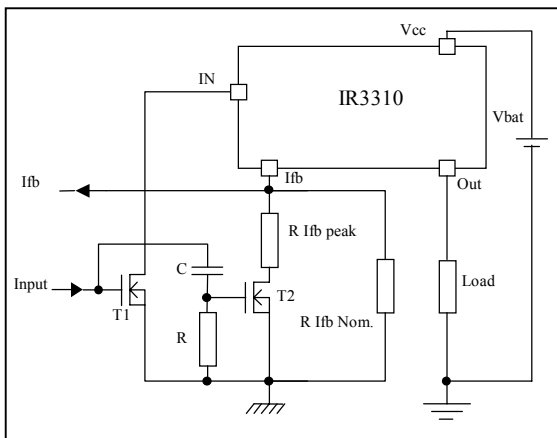


Figure 13 : 2 steps current shutdown schematic

R lfb Nom. and R lfb peak is calculated as above. RC networks provides the time during R lfb peak is connected to lfb pin.

$$RC = \frac{t_{\text{peak step}}}{\ln \frac{V_{\text{in}}}{V_{\text{gsth}}}}$$

t peak step : time during R lfb peak is connected

Vin : input voltage

Vgsth : threshold of T2

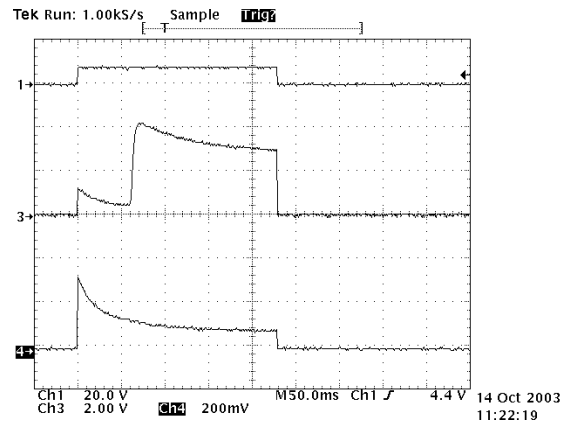


Figure 14 : Waveforms with 2 x 45W filament lamp

R lfb nom=3.3kW, R ifb peak=390W, R=470k, C=100nF
Trace 1 : Input
Trace 3 : Ifb pin voltage
Trace 4 : Current load

Current shutdown programmed by analog voltage

A versatile solution is to connect a controlled current source to lfb pin in order to control dynamically the current shutdown threshold.

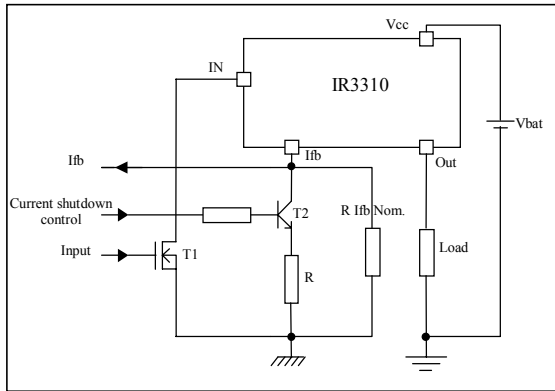


Figure 15 : Dynamically current shutdown threshold

For a filament lamp application the best profile for current shutdown threshold is the current profile plus a little margin :

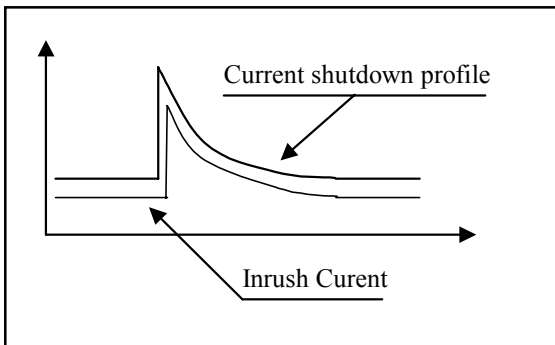


Figure 16 : Current shutdown profile

The current shutdown control voltage waveform applied to T2 is calculate with :

$$I_{T2} = (\text{Current shutdown control voltage} - 0.6V) / R$$

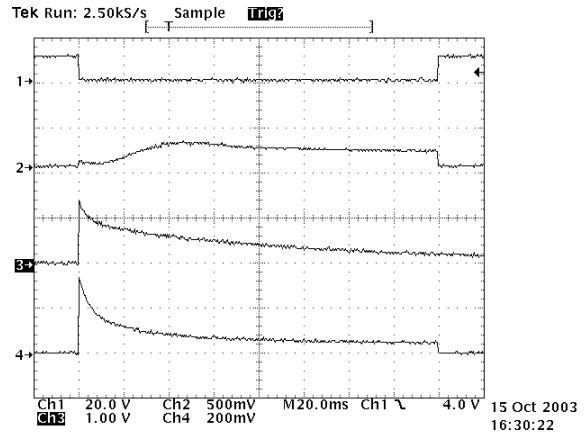


Figure 17 : Waveforms with 2 x 45W filament lamp

R lfb nom=3.3kW, R =120W

Trace 1 : Input

Trace 2 : Ifb pin voltage

Trace 3 : Current shutdown control voltage

Trace 4 : Current load

20kHz current sense H bridge motor drive

With two IR331Xs and two MOSFETs, a fully protected H bridge can be designed. The IR331Xs feature the current sensing and the protections. The low side MOSFETs provide the 20kHz switching capability. In order to protect the low sides with the IR331X over temperature shutdown, the power dissipation must be lower in the low side. The designer may choose a Rds(on) half lower for the low sides.

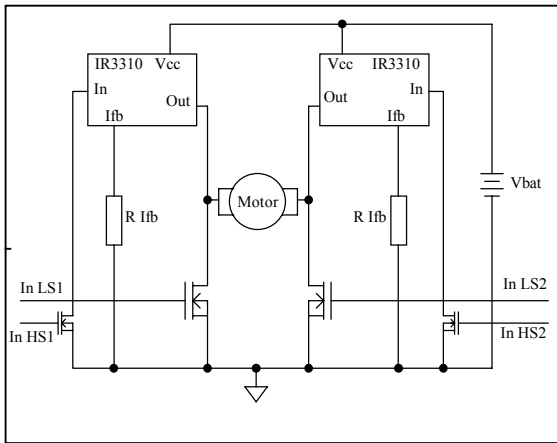


Figure 18 : H_Bridge schematic

Layout consideration

The designer must pay attention to the layout. If logic ground is connected to power ground, the load current can return into the logic ground. This current introduces an error voltage between I_{fb} and IN pin which can shutdown the device. Moreover the current sensing reading is disturbed.

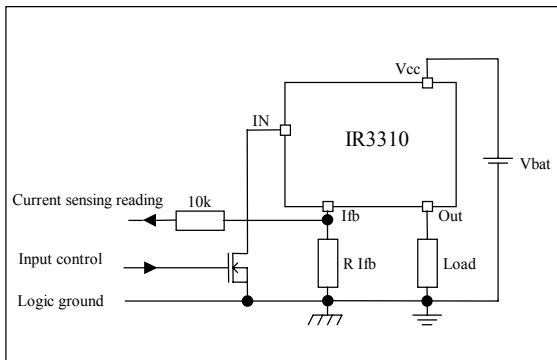
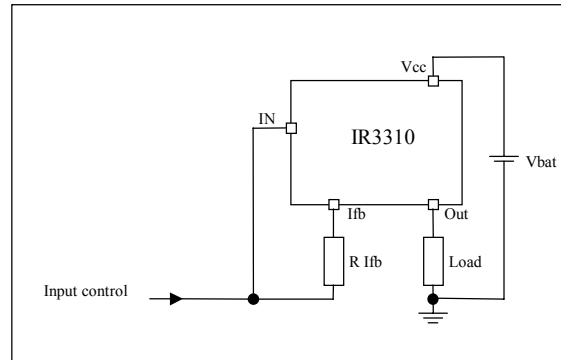


Figure 19 : Logic ground connected to power ground

To insure the integrity of current sensing reading and the current shutdown, the logic ground must be connected to body of the car near to the controller.

Controlling IR331X by one wire

If the system requires only the programmable current shutdown and not the current readout, the IR331X can be controlled by only one wire.



As the input threshold is referenced to V_{cc}, the device switches on when V_{cc}-V_{in} reaches V_{IH}. The current shutdown is defined by the difference voltage between V_{ifb} and V_{in}, so the input system does not need a ground reference.