

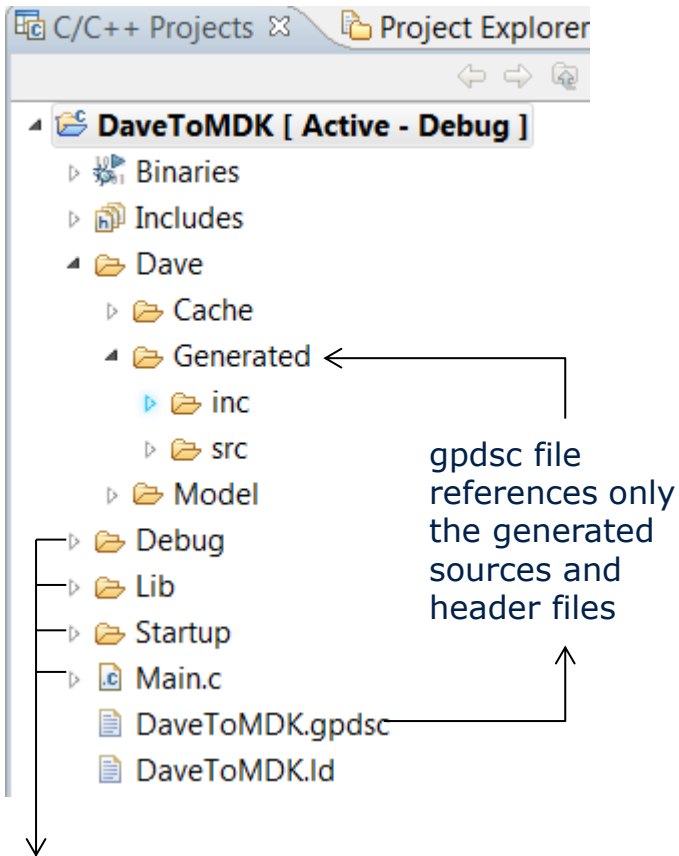
Tutorial to Import DAVE™ version 3 Generated Library Sources to ARM® MDK Using CMSIS® PACK

Version 3, July, 2015



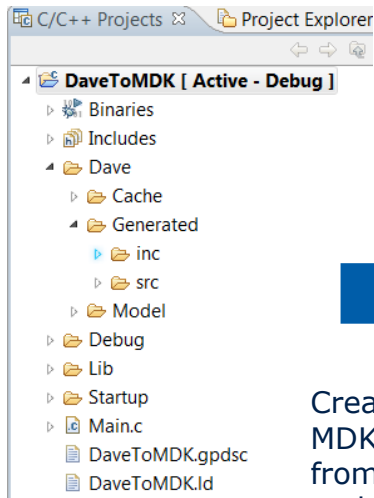
Purpose: Import the DAVE™ v3 generated source files to ARM MDK, no full project migration

DAVE™ project outline

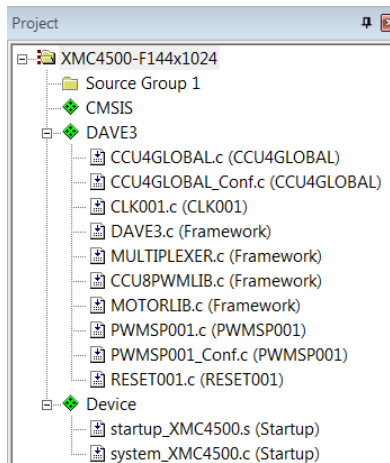


- DAVE™ is a free eclipse based development platform that can generate application libraries from DAVE™ Apps.
- The generated code is included in a DAVE™ project.
- DAVE™ v3.1.10 can optionally generate a CMSIS Pack compliant gpdsc file that references all generated library sources (c sources and header files) to a respective MDK µVision project)
- The gpdsc file references only the generated sources and headers, It is expected that the user develops the user code afterwards in MDK
- Not the full DAVE™ project is ported; to port the full DAVE™ project the existing user code has to be manually referenced

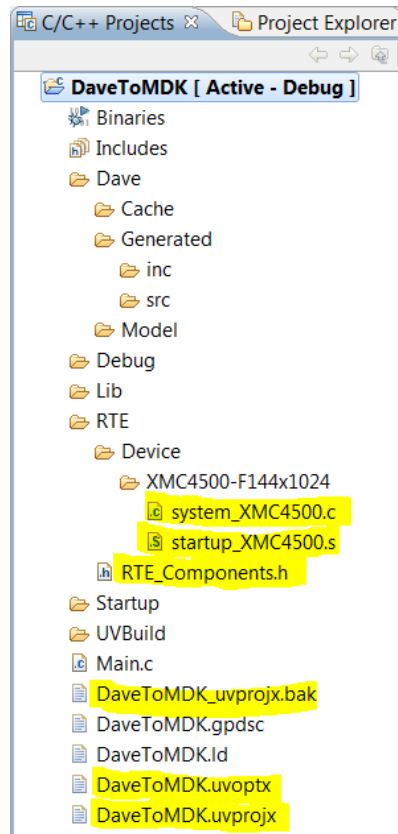
Concept



Creating a
MDK project
from the
gpdsc file



Respective project view in MDK



MDK relevant files
(yellow) added to the
DAVE project.

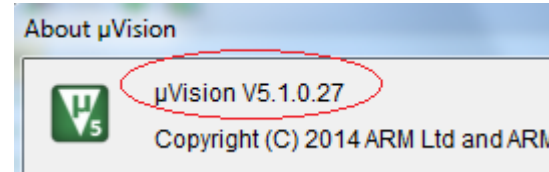
- In addition to the references of generated DAVE™ code the gpdsc file (an xml file) contains conditions for the selected target MCU and preprocessor commands in RTE_Components.h file
- Double click on the gpdsc file will automatically create a ARM MDK project for the target MCU defined in the gpdsc file, and ARM MDK compliant startup files for the target MCU will be added to the project
- These files are added in the project folder of the DAVE™ (eclipse) project; Build in DAVE™ will now create build error, this can be avoided excluding these files from build in the DAVE™ project

Prerequisites to Follow the Tutorial

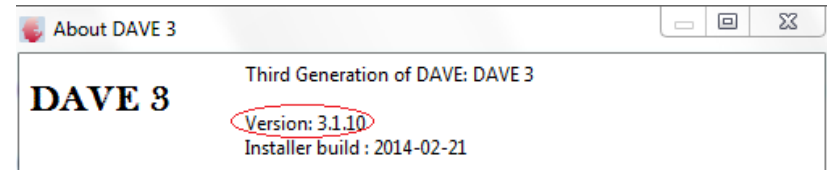
- **µVision v5.10** ARM MDK

Download a free version

Infineon Device PACK v1.5.0



- **DAVE™ v3.1.10**, a PACK file with file extension **gpdsc** is created by code generation, which is dedicated for porting the DAVE™ project to ARM MDK
Download DAVE



- The following pages provide a step wise description how to import the library sources configured and generated in DAVE™ to ARM MDK

Important: just device PACK v1.5.0 or lower supports DAVE™ version 3 generated codes. From v1.5.0 the CMSIS files in MDK PACK are changed and incompatible with previous version.

To install PACK v1.5.0 please firstly download the PACK here:

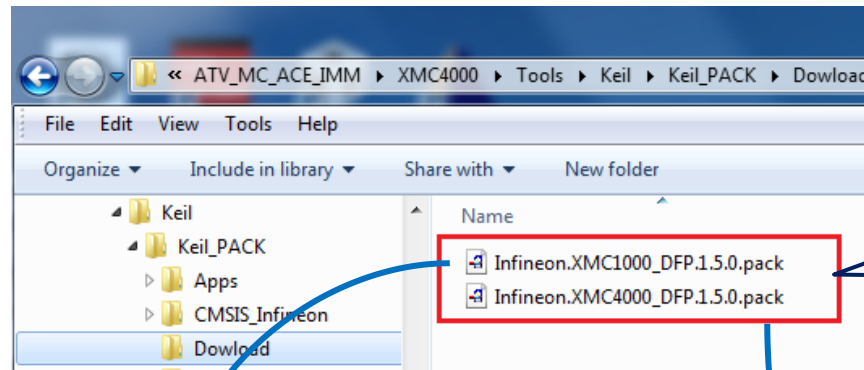
XMC1000:

http://media.infineon.com/mdk/Infineon.XMC1000_DFP.1.5.0.pack

XMC4000:

http://media.infineon.com/mdk/Infineon.XMC4000_DFP.1.5.0.pack

Install Infineon Device PACK v1.5.0 (2/2)



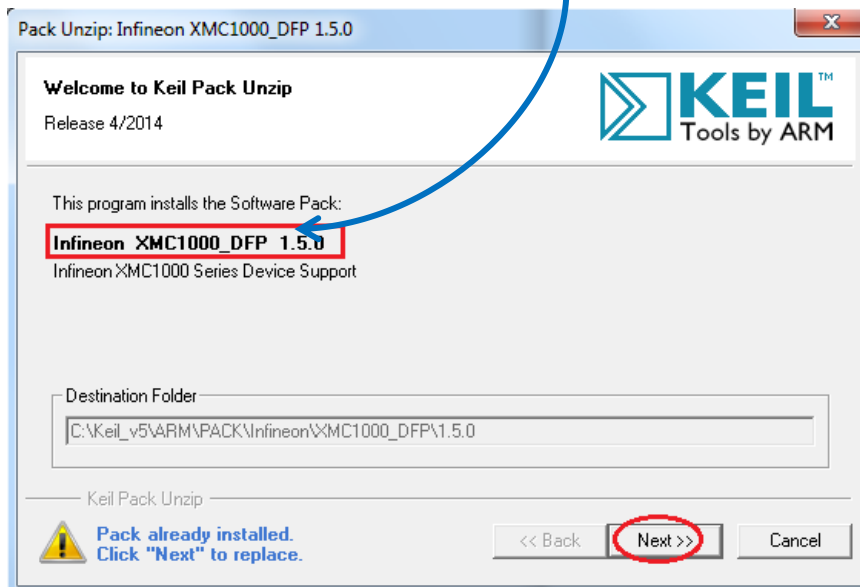
Downloaded
PACK file

Double click

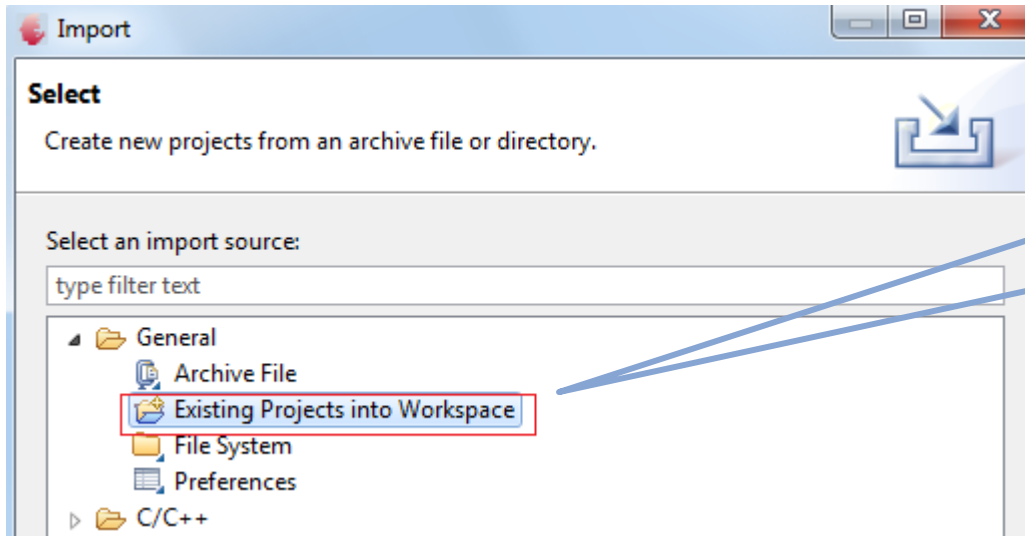
"Infienon_XMC1000_DFP_1.5.0.pack
install XMC1000 PACK"

Double click

"Infienon_XMC4000_DFP_1.5.0.pack
install XMC4000 PACK"



Import an Existing DAVE™ Project or Create a New DAVE™ Project with **DAVE 3.1.10**

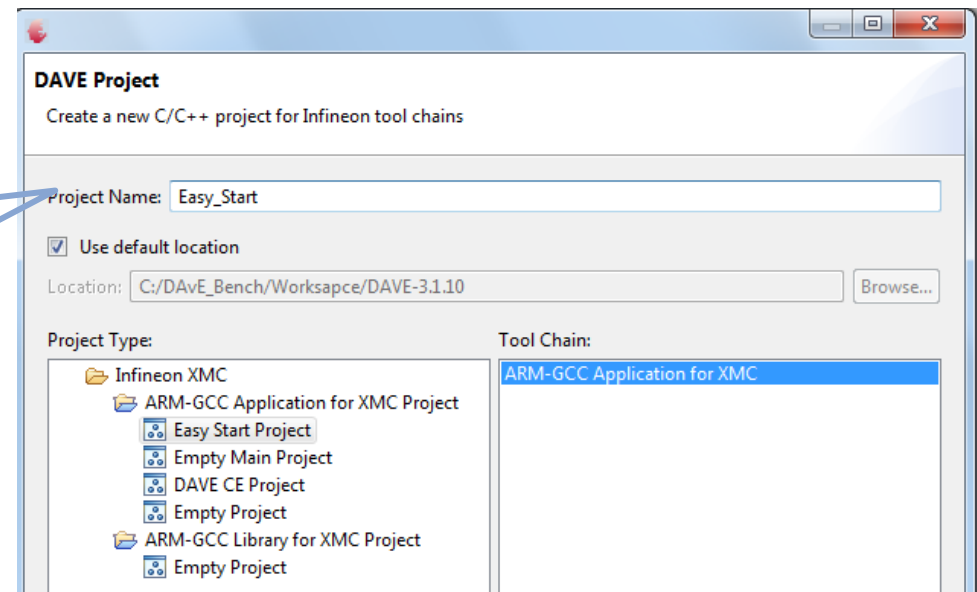


In case of existed project:

Step 1: import the existed project

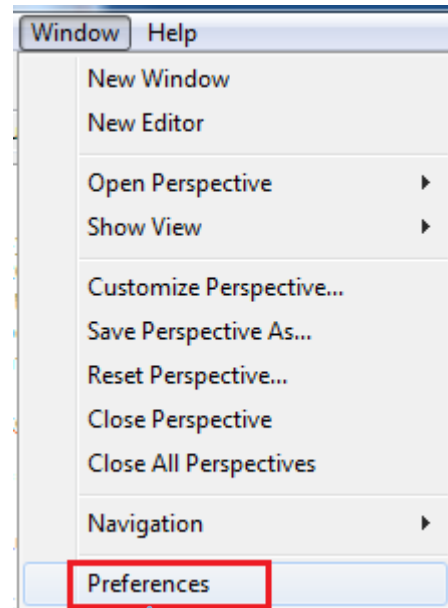
In case of new project:

Step 2: define a new **DAVE CE** project

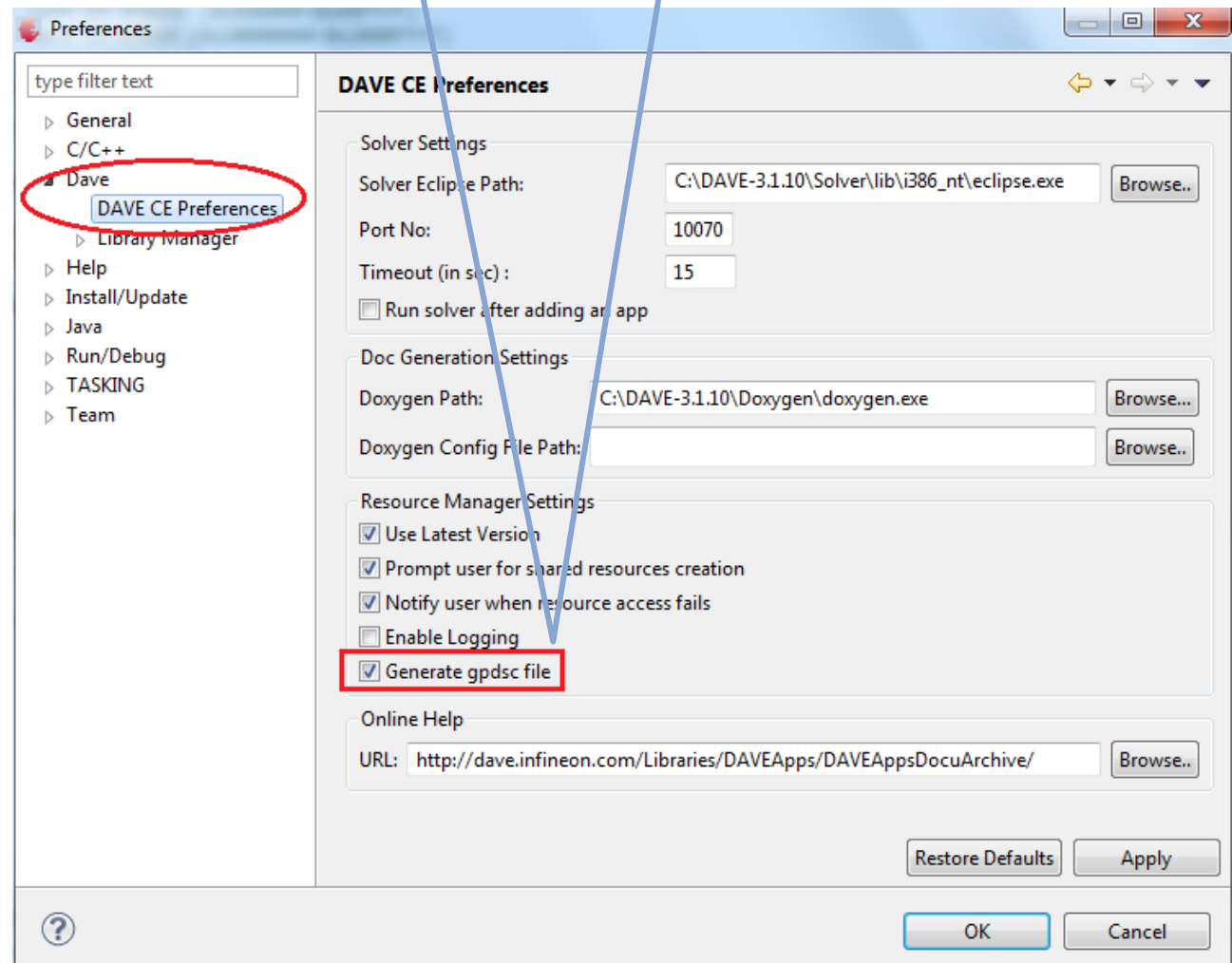


Enable “Generate gpds file” in DAVE™

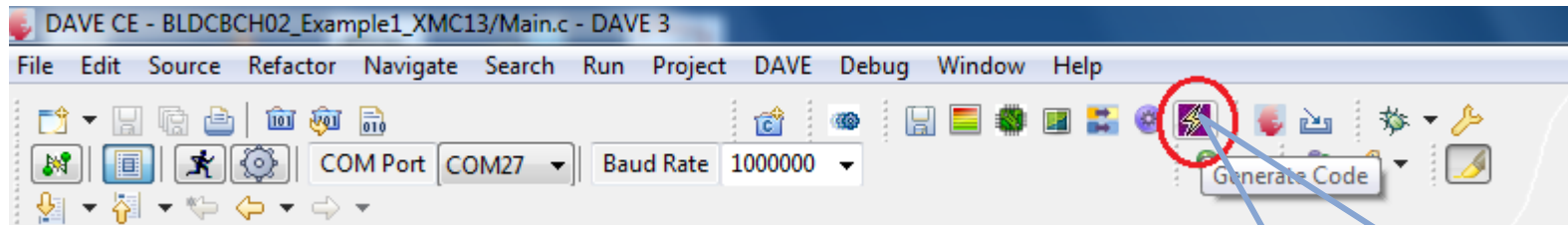
Step 2: select “generate gpds file”



**Step 1: open
Preferences window**

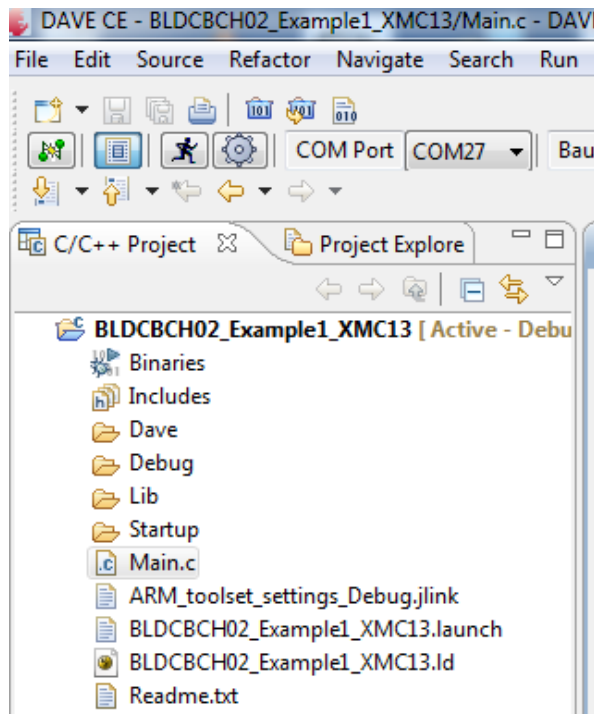


In Cases an Existing DAVE™ Example Project is Used

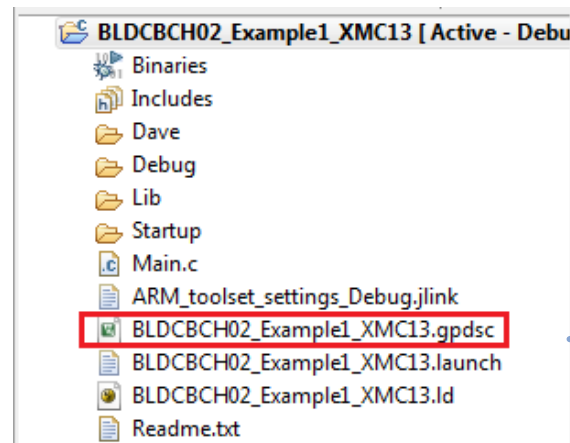


Step 1:

- **Re-generate** Code



Before code regeneration



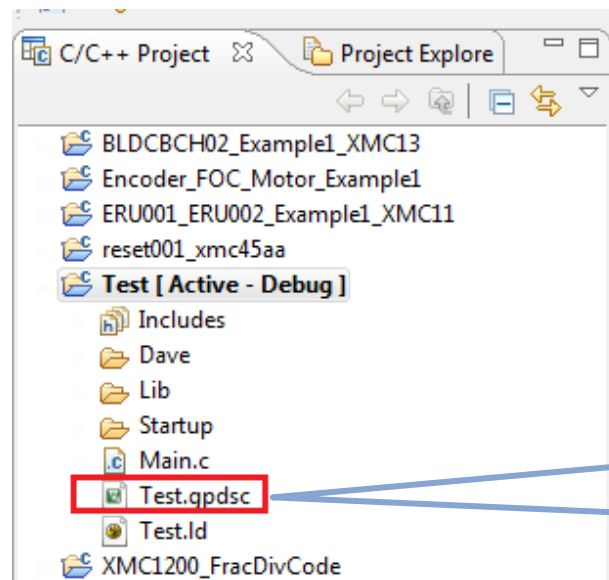
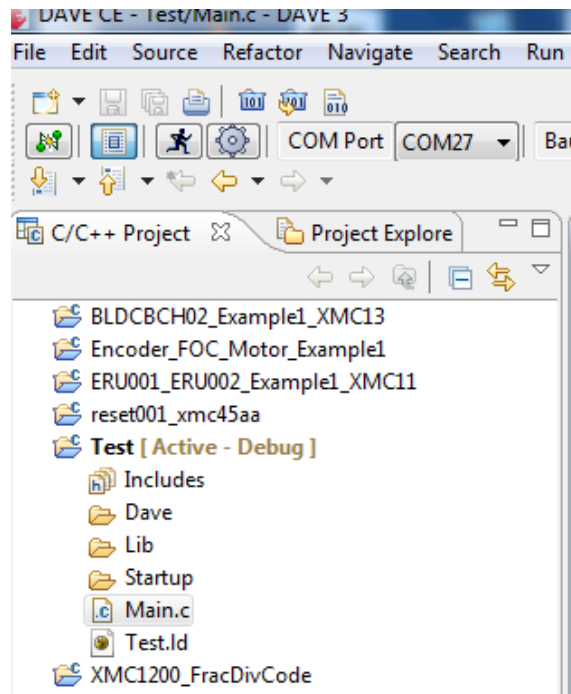
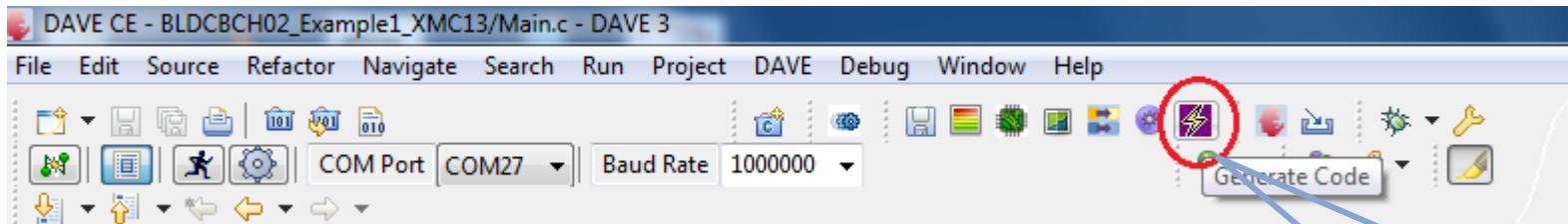
After code regeneration

BLDCBCH02_Example1_XMC13.gpdsc
is generated.

If required, existing user code (main.c) has to be manually added to the MDK project

In Case of New DAVE™ Project

Note: Before continue with step 4.1 select and configure the required DAVE Apps



Step 1:
• **Generate Code**

Test.gpdsc is generated.

After code regeneration

Before code regeneration

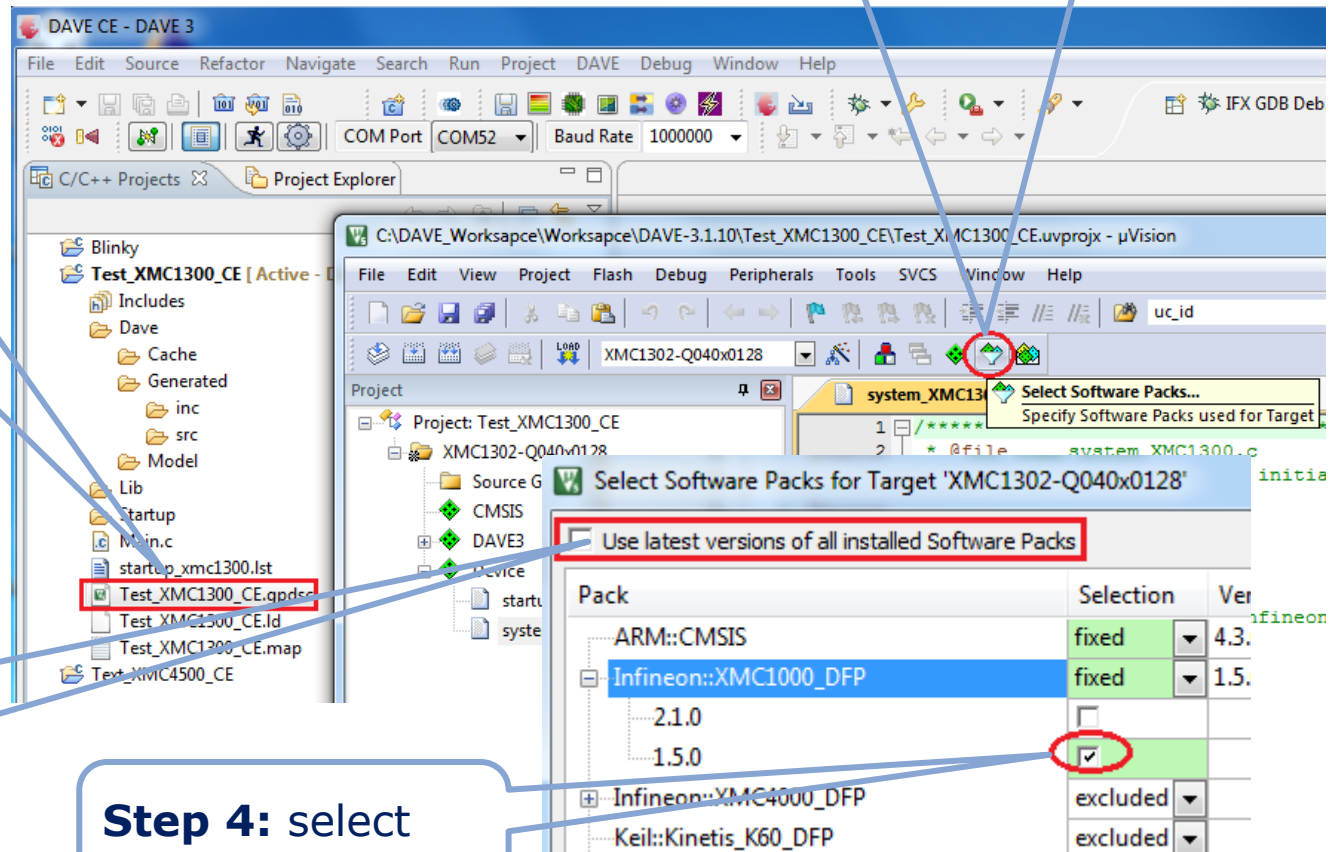
Open MDK Project and Select PACK v1.5.0 (1/3)

Step 1: double click **.gpdsc** file to open the Keil μ Vision

Step 2: click "Select Software Packs"

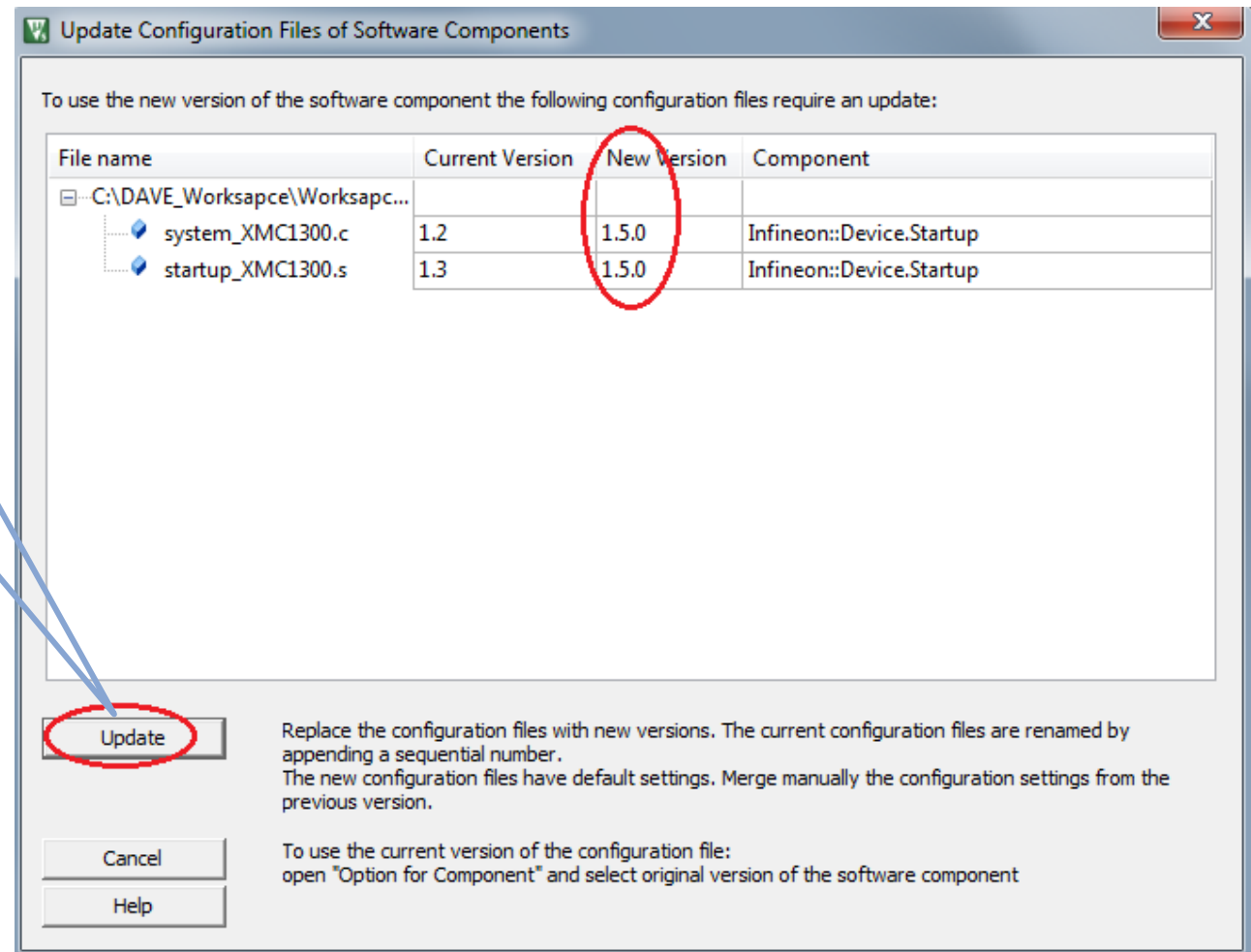
Step 3: deselect "use latest versions"

Step 4: select PACK v1.5.0



Open MDK Project and Select PACK v1.5.0 (2/3)

Step 1: update
the CMSIS files
to PACK v1.5.0

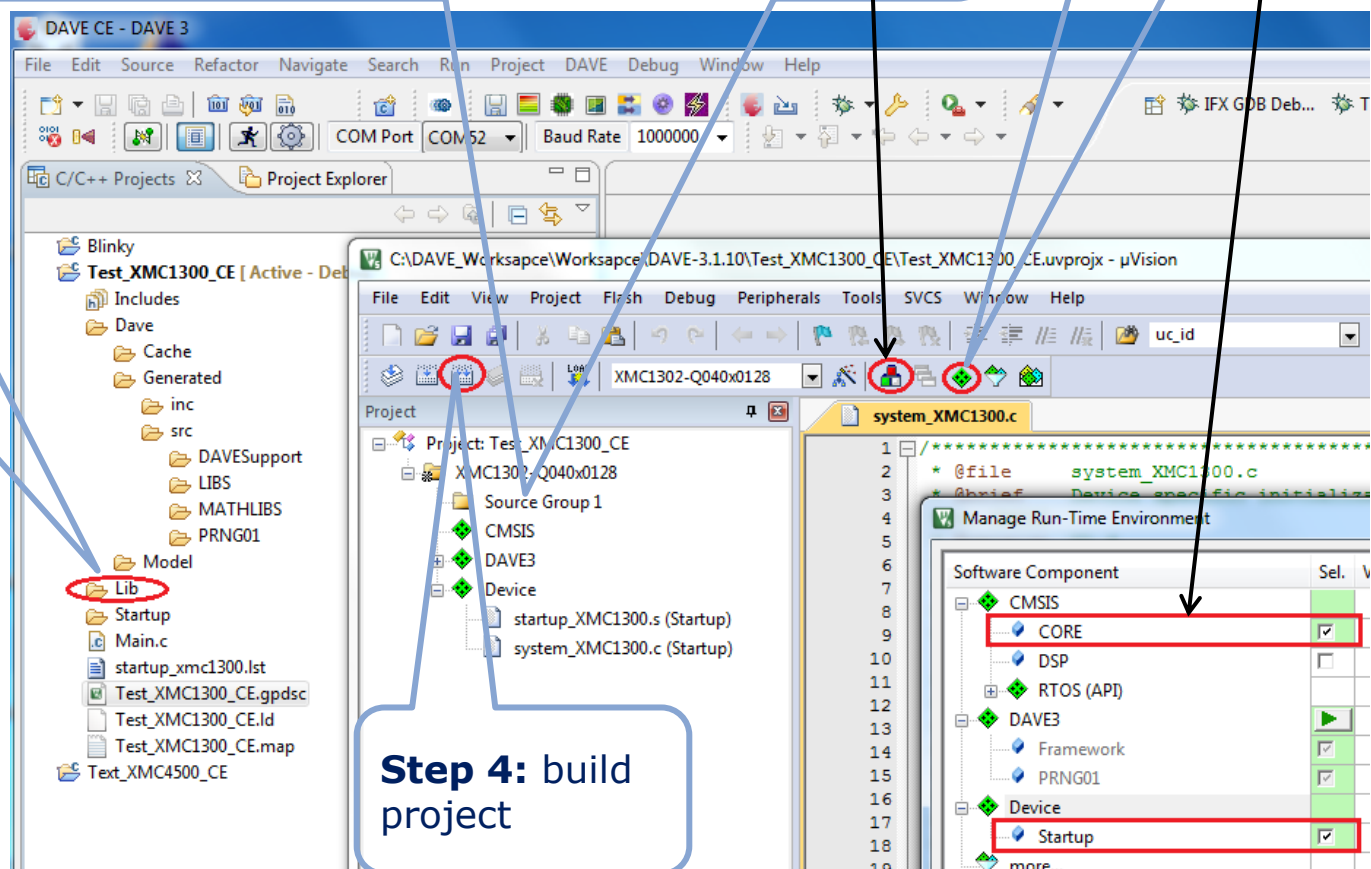


Open MDK Project and Select PACK v1.5.0 (3/3)

Step 2: add the application codes in "Source Group" of project
Important: *gpdsc* file just imports the DAVE generated codes into Keil MDK Project. The application codes must be manually added.

Step 1: check if CMSIS and Startup files are included

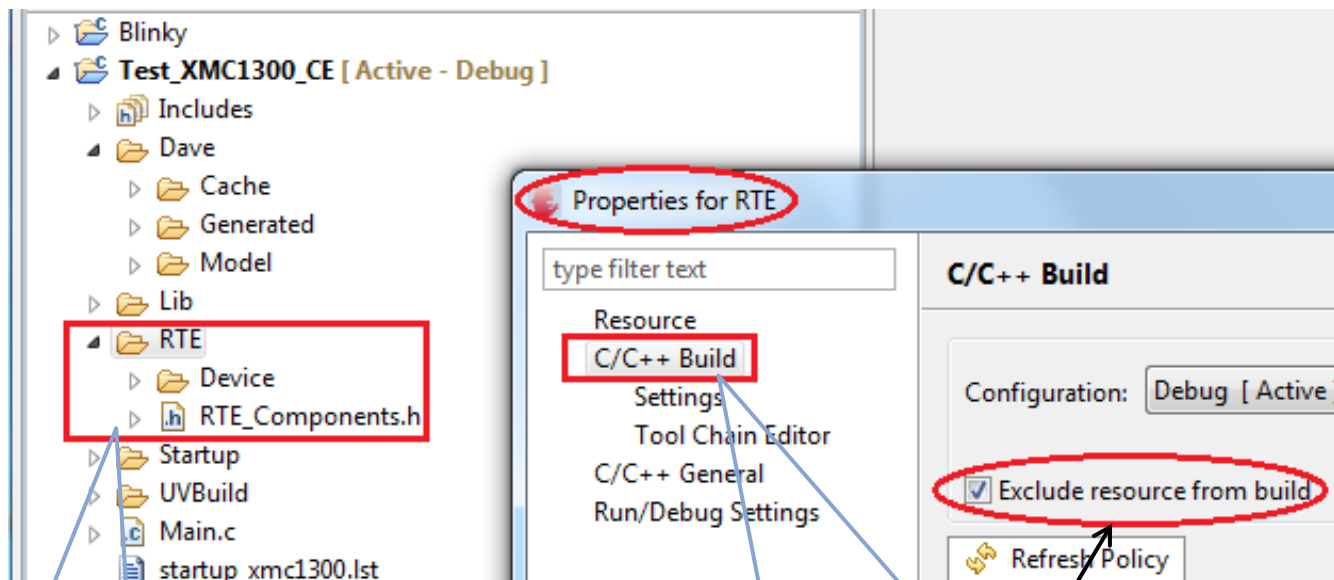
Step 3: Add the library contained in DAVE project into MDK project, if it is necessary.



The screenshot displays the Keil MDK IDE interface with several windows open. The 'Project Explorer' on the left shows the project structure for 'Test_XMC1300_CE'. The 'Project' window in the center shows the project settings, including the 'Source Group 1' containing 'CMSIS', 'DAVE3', and 'Device'. The 'system_XMC1300.c' file is open in the editor, showing the 'Manage Run-Time Environment' dialog. This dialog lists software components with checkboxes for selection. Arrows from the text boxes point to specific elements: Step 1 points to the 'CMSIS' and 'Startup' components in the 'Manage Run-Time Environment' dialog; Step 2 points to the 'Source Group 1' in the 'Project' window; Step 3 points to the 'Lib' folder in the 'Project Explorer'; and Step 4 points to the 'Project' window.

Step 4: build project

If it is required to keep the project buildable in DAVE™: Exclude RTE folder from DAVE™ build



The folder "RTE" is created by Keil project, and **must be** excluded from DAVE3 project.

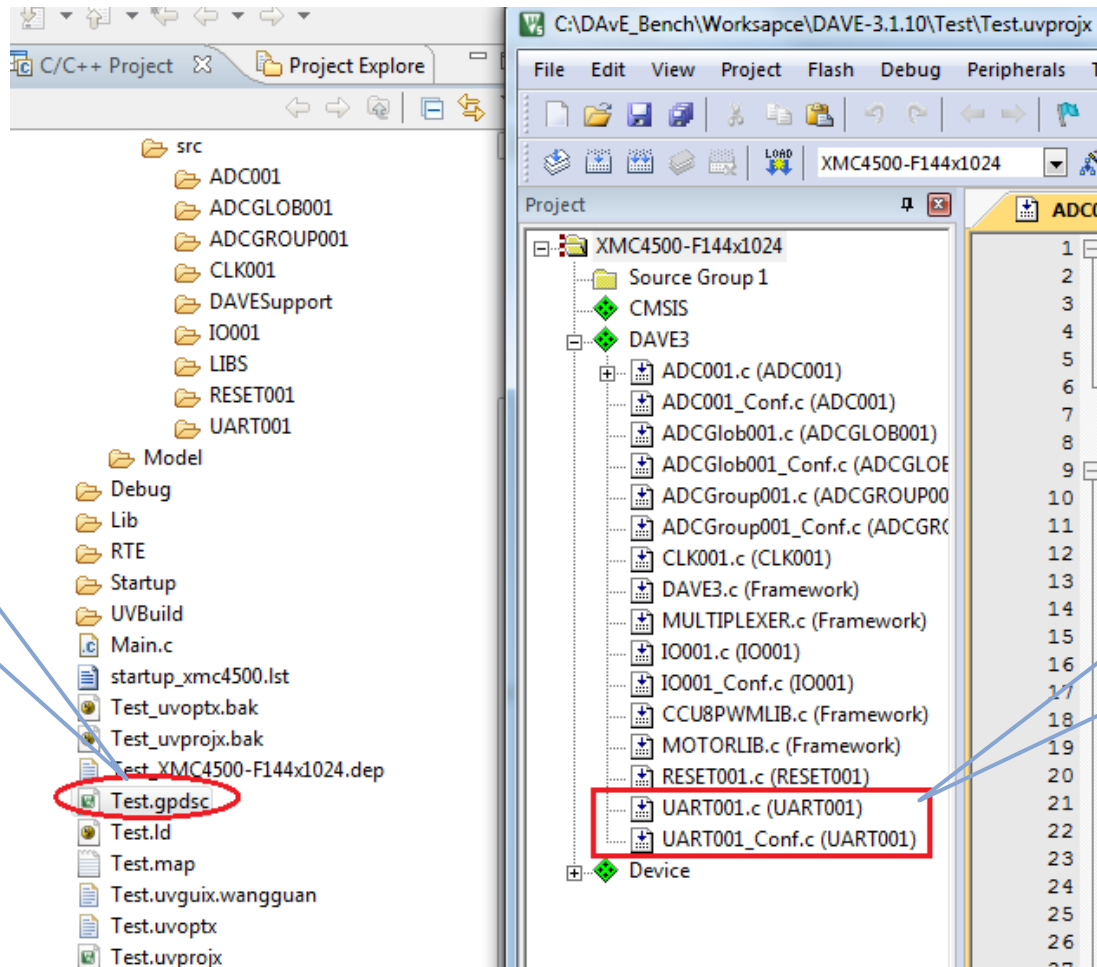
Step 1:

- open "Properties for RTE"
- go to "C/C++ Build"
- select "Exclude resource from build"

IF additional new DAVE™ Apps will be added to the DAVE™ project

This step is just needed, if the **new DAVE™ Apps** are added and the sources are **regenerated** in the DAVE™ project. In this case the new sources must be updated in the MDK project.

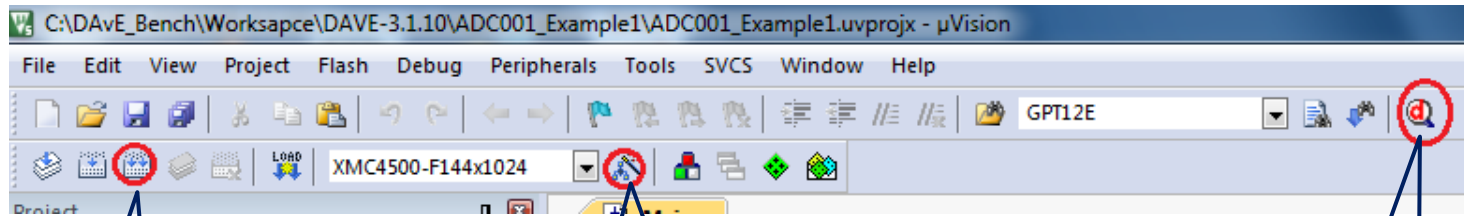
Step 1:
double click the
.gpdsc file



The new
source files
are added
in Keil MDK
project.

Build and download MDK project to a XMC4000/1000 Evaluation Board (1/2)

To make the MDK project work Segger JLINK v4.80f or higher should be installed. Furthermore, some steps need to be done manually as follows.



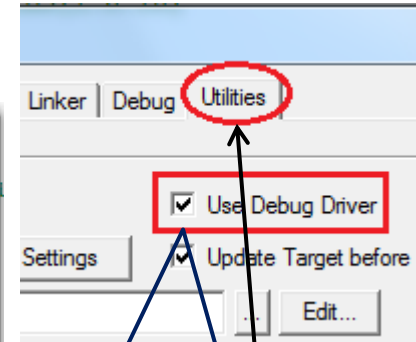
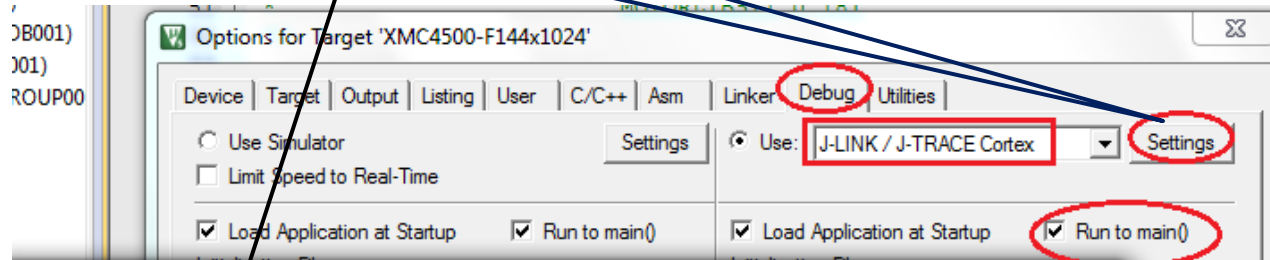
Step 1:
Build
project

Step 2: select JLINK debugger

Step 3:
Start
debugger

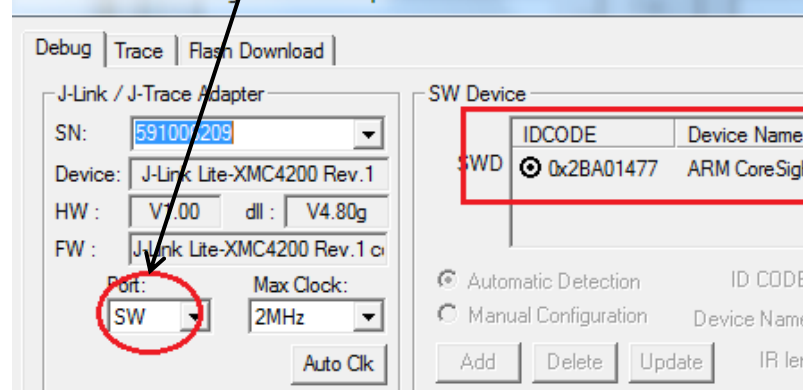
Build and download MDK project to a XMC4000/1000 Evaluation Board (2/2)

Step 1: JLINK settings: SW

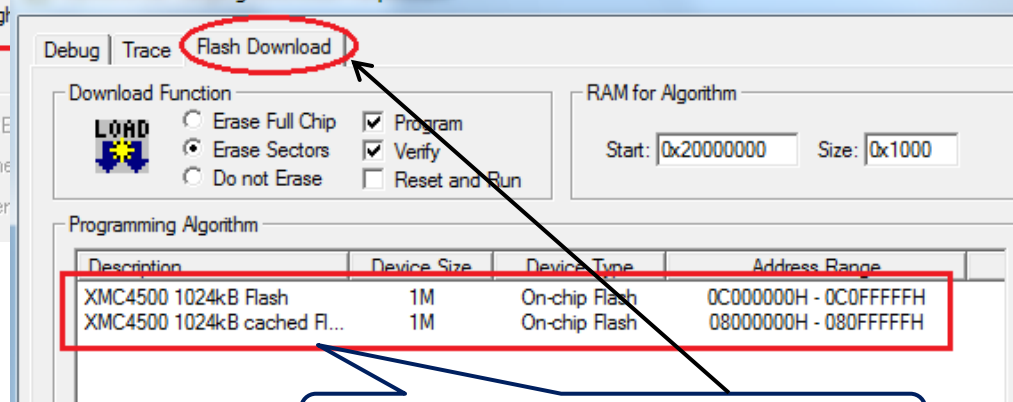


Step 2: select use Debug Driver

Cortex JLink/JTrace Target Driver Setup

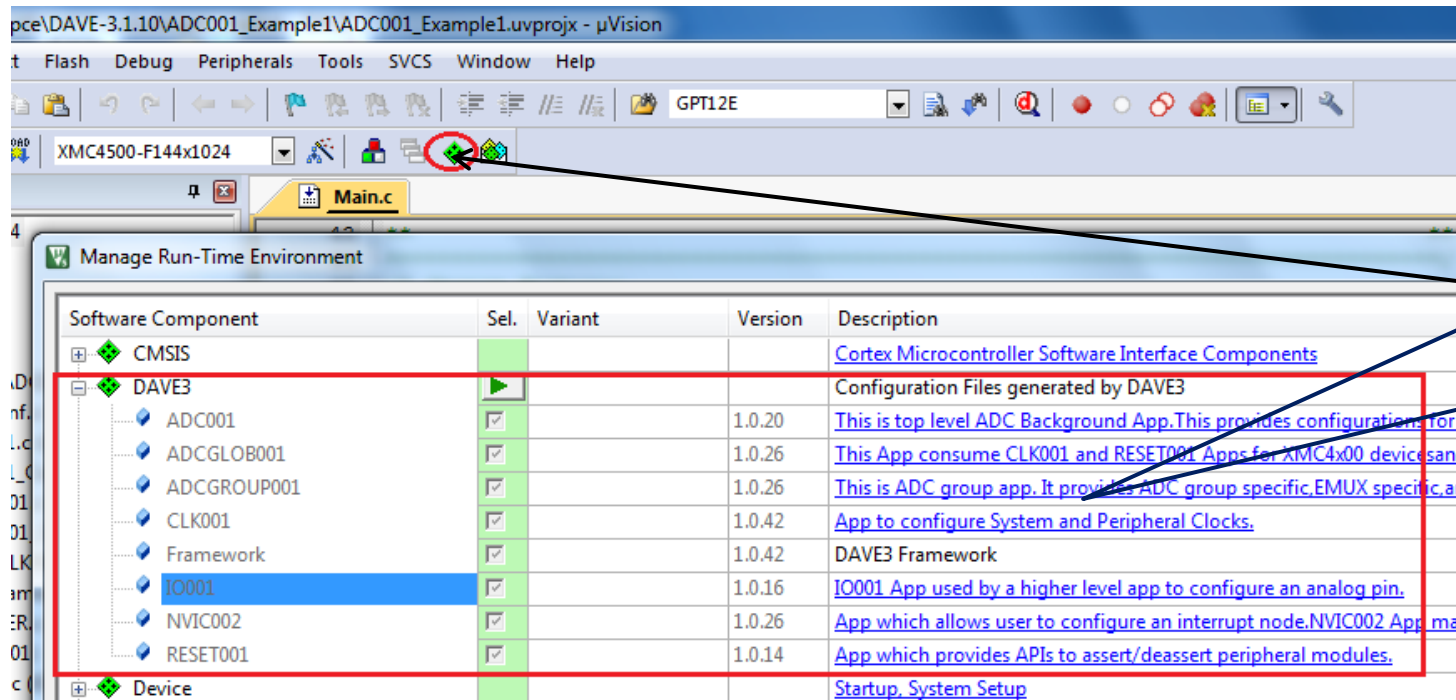


Cortex JLink/JTrace Target Driver Setup



Step 3: JLINK settings: add Flash programming

Further Information



Here you can find the documents about DAVE3 Apps

- There is also an App-Note from Keil that describes the importing of the DAVE generated source files into MDK v5.10:
http://www.keil.com/appnotes/docs/apnt_258.asp



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