# Micrium® uC/Probe™ XMC™ getting started

XMC<sup>™</sup> microcontrollers July 2016





- Objective of this tutorial
- What we need to follow this tutorial?
- Introduction to Micrium® uC/Probe™ XMC™
- 4 Using the dashboard
- 5 Using the oscilloscope
- 6 Other features
- 7 References
- 8 Support material

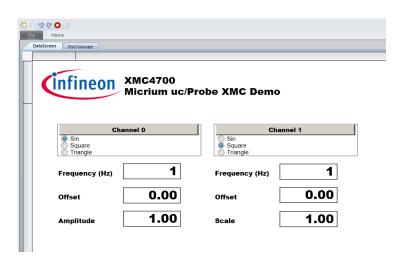


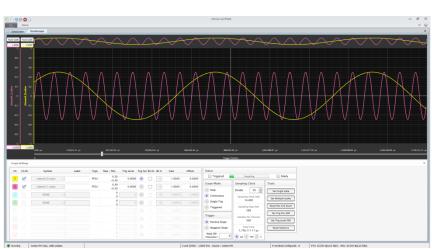
- Objective of this tutorial
- What we need to follow this tutorial?
- 3 Introduction to Micrium® uC/Probe™ XMC™
- 4 Using the dashboard
- 5 Using the oscilloscope
- 6 Other features
- 7 References
- 8 Support material



### Objective of this tutorial

- 1. Download provided example application to your board
- Using DAVE<sup>™</sup> 4 integrated debugger
- → Using XMC<sup>TM</sup> Flasher tool
- 2. Control and monitor your application using the Micrium® uC/Probe™ XMC™ dash board
- 3. Monitor variables using the Micrium® uC/Probe™ XMC™ oscilloscope control







- 1 Objective of this tutorial
- What we need to follow this tutorial?
- 3 Introduction to Micrium® uC/Probe™ XMC™
- 4 Using the dashboard
- 5 Using the oscilloscope
- 6 Other features
- 7 References
- 8 Support material



#### What we need to follow this tutorial?

#### **Software**

- To download to the target the provided example application, use either:
  - DAVE<sup>TM</sup> version 4

Development Platform for XMC<sup>™</sup> microcontrollers

Go to <a href="www.infineon.com/DAVE">www.infineon.com/DAVE</a> and download DAVE<sup>™</sup> version 4

XMC<sup>TM</sup> Flasher

Free of charge programming tool

Go to XMC<sup>™</sup> Software Download and download XMC<sup>™</sup> Flasher

Micrium uC/Probe<sup>™</sup> XMC<sup>™</sup> version 4

Go to  $\underline{www.infineon.com/ucProbeXMC}$  and download the latest version of Micrium® uC/Probe<sup>TM</sup> XMC<sup>TM</sup>

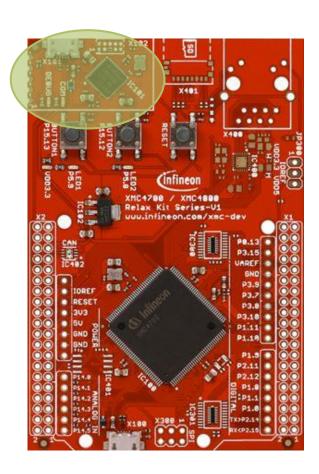
Example application project for DAVE™ version 4 accompanying this document



#### What we need to follow this tutorial?

#### <u>Hardware</u>

- Any Infineon XMC<sup>™</sup> board
- In this document XMC4700 Relax Kit is used featuring:
  - XMC4700-F144 microcontroller based on ARM® Cortex®-M4 at 144 MHz, 2 MB Flash and 352 KB RAM
  - On-board debugger (Segger J-Link)
  - Power over USB
  - ESD and reverse current protection
  - 2 x user button and 2 x user LED
  - Arduino hardware compatible 3.3 V pinout
- On board debugger is used
- Connect the board to your PC using a micro USB cable





- 1 Objective of this tutorial
- What we need to follow this tutorial?
- 3 Introduction to Micrium® uC/Probe™ XMC™
- 4 Using the dashboard
- 5 Using the oscilloscope
- 6 Other features
- 7 References
- 8 Support material



### Introduction to Micrium® uC/Probe™ XMC™

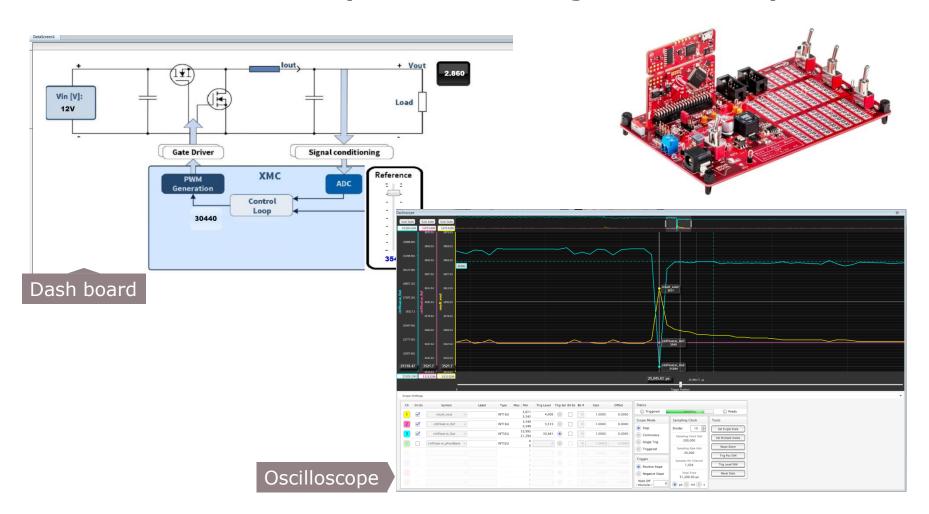
#### What is Micrium® uC/Probe™ XMC™?

- › uC/Probe<sup>™</sup> XMC<sup>™</sup> is a Windows<sup>®</sup> based application that let's you control and monitor a running embedded system
- Allows easy visual access to the internals of your application using the oscilloscope control, gauges, spreadsheets, LEDs and other widgets
- Create rich visually appealing user interfaces for your applications
- Can be used with any toolchain that can generate an ELF fileCan connect to the embedded system using SWD/JTAG, UART, Ethernet or USB
  - SWD communication does not need any target firmware to set or retrieve the values of variables
  - Other communication interfaces need adding a C library to your application to respond to the requests from μC/Probe™ running on the Windows® PC. Library can be obtained at μC/Probe Embedded Target Code



### Introduction to Micrium® uC/Probe™ XMC™

### uC/Probe™ XMC™ example for XMC™ Digital Power Explorer Kit

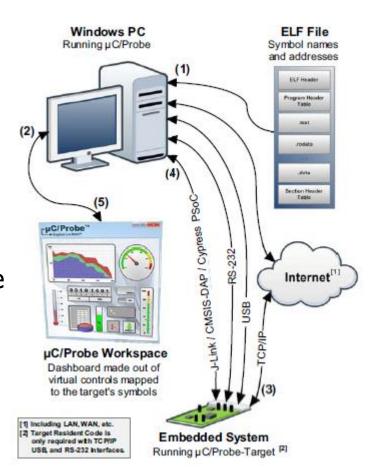




### Introduction to Micrium® uC/Probe™ XMC™

#### **How it works?**

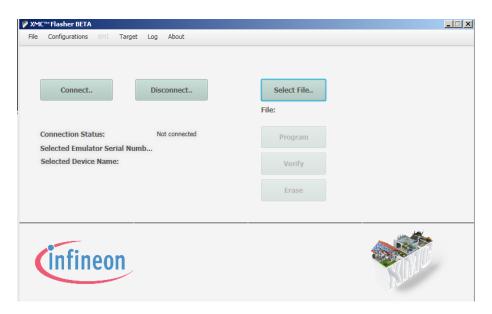
- → uC/Probe<sup>TM</sup> XMC<sup>TM</sup> obtains the address of the variables from the ELF file
- Design your dash board by dragging and dropping widgets
- Associate a variable to each of the widgets
- Configure the communication interface
- Start uC/Probe<sup>™</sup> XMC<sup>™</sup>
- › uC/Probe™ make requests to read the value of all variables used in the dashboard



# Download the application to your target using XMC<sup>TM</sup> Flasher



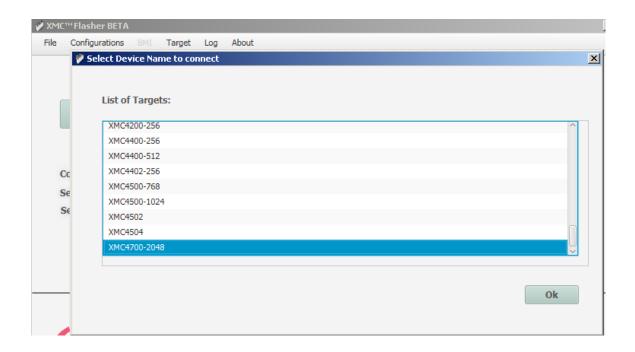
- 1. Connect your board to the PC using a micro USB cable
- Start XMC<sup>™</sup> Flasher
- 3. Select the hex file
  - Click on File in the menu bar
  - Browse to the location of your file



# Download the application to your target using XMC<sup>TM</sup> Flasher



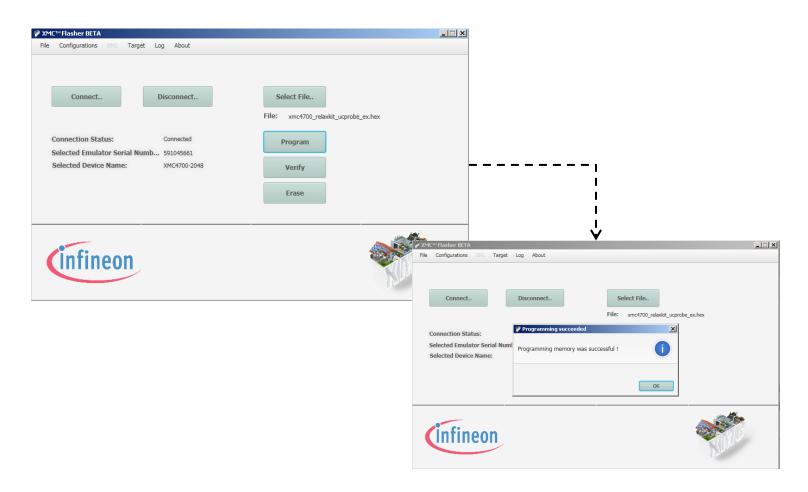
- 4. Connect to your device
  - Click on Connect...
  - Select your device



# Download the application to your target using XMC<sup>TM</sup> Flasher



#### 5. Click on Program...

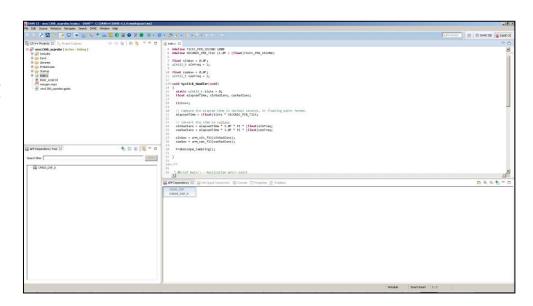


# Download the application to your target using DAVE<sup>TM</sup> version 4



- Start DAVE™ version 4
- 2. Import the example project
- Click on File > Import...
- Select Infineon > DAVE Project
- Click on Next
- Select Archive File
- Click on Browse
- Browse to the location of the example project and select the zip file
- Click on Finish
- 3. Compile the project
- Click on Rebuild Active Project button in the tool bar





# Download the application to your target using DAVE<sup>TM</sup> version 4

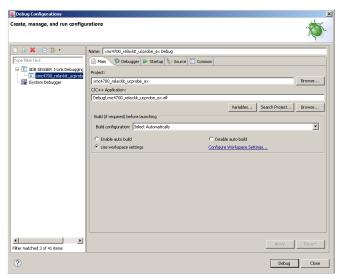


#### 4. Start debugger

Click on Debug button in the toolbar



- Double click on GDB SEGGER J-Link Debugging
- Click on *Debug*



The debugger will program your board. In the debugger view click on Resume button in the toolbar to start your application

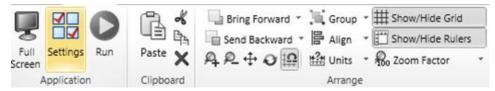




- 1 Objective of this tutorial
- What we need to follow this tutorial?
- 3 Introduction to Micrium® uC/Probe™ XMC™
- 4 Using the dashboard
- 5 Using the oscilloscope
- 6 Other features
- 7 References
- 8 Support material



- This section shows you how to monitor and control your application using the dash board
- By having a dashboard for your C code, you will gain a firm understanding of what the embedded system is doing at any given time
- Use xmc4700\_relaxkit\_ucprobe\_ex1.zip example project
- 1. Start Micrium® uC/Probe™ XMC™
  - Click on in your desktop
- 2. Setup communication to board
  - Click on Settings button in the toolbar

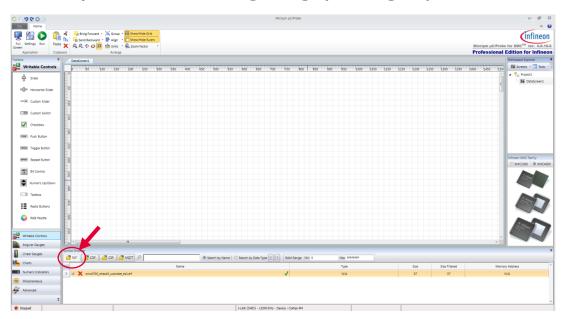


- Select Debug Interfaces > J-Link
- Click Ok



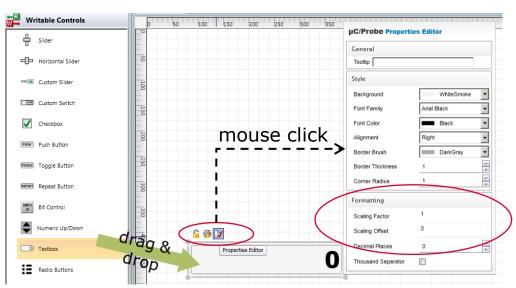
#### 3. Load an ELF file

- Click on ELF button in Symbol Browser window
- Browse to the location of the ELF file in the Debug folder of the example project
- Select the file. Click Open
- Now you are ready to start designing your graphical UI



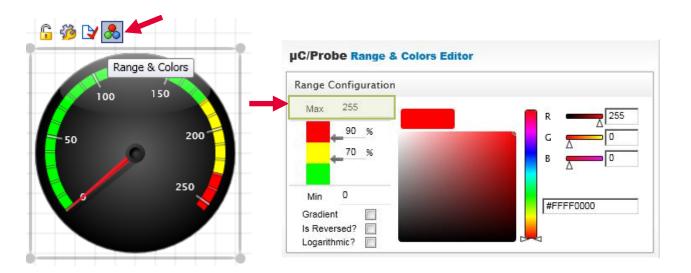


- 4. Drag and drop controls to build your user interface
- In this example we will monitor and control a global variable of our application
- Add a **Textbox** from the Writable Controls. We will use this control to change the value of the variable
- In the Properties Editor you could apply scaling to the read value of the form y = scale\*x + offset. You can also adjust the Decimal Places. These settings are available for almost all controls





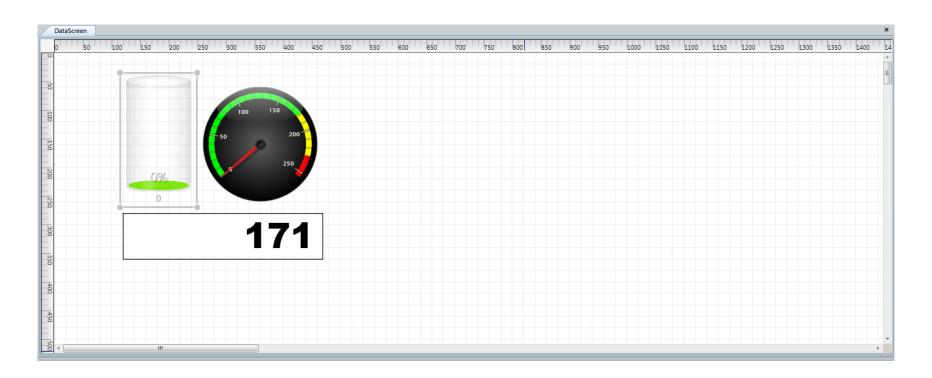
- Add a Radial 1 from the Angular Gauges. We will use this control to monitor the value of the variable.
  - In the Range and Colors of the control select maximum value 255



- Add a Cylinder 1 from the Linear Gauges. We will use this control to monitor the value of the variable.
  - In the Range and Colors of the control select maximum value 255



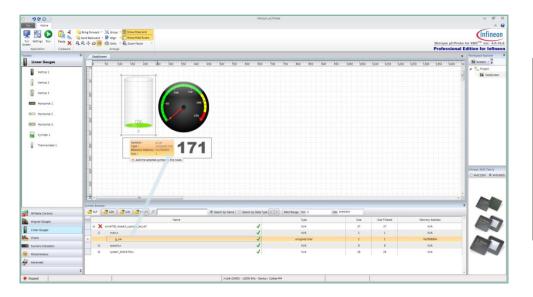
- Your dash board should look like as shown below
- You can always save your workspace by Ctrl-S or File > Save for later use or for sharing





#### 5. Associate variables to controls

- Search for the g\_var symbol in the Symbol Browser:
  - Either use the search function if you know the name of the variable
  - Or unfold the ELF file and navigate through the modules
- Drag the g\_var variable and drop it over the Textbox control
  - Do the same for all the other controls



Alternatively you can associate a variable to a control by double clicking on the variable if previously the control was selected by clicking on it.



5. Since we are connecting to a XMC4700 board, select XMC4000 in the Infineon  $XMC^{TM}$  Family window

7. Before the next step ensure your board is running, i.e. not halted by debugger



- 6. Click on Run button in toolbar
- The controls visualization will get updated periodically according to the value of the variable g\_var
- In this case the application increments the variable g\_var in a loop
- You can also modify the value of the variable in run time

#### No programming is required!

No need to instrument your embedded code nor need to write any single line of code in the PC to get insight of your application.

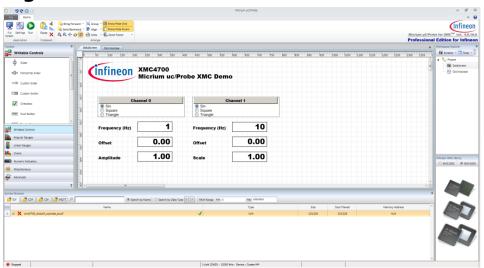


- 1 Objective of this tutorial
- What we need to follow this tutorial?
- 3 Introduction to Micrium uC/Probe™ XMC™
- 4 Using the dashboard
- 5 Using the oscilloscope
- 6 Other features
- 7 References
- 8 Support material



In this section will explore the capabilities of the oscilloscope control of Micrium® uC/Probe<sup>TM</sup> XMC<sup>TM</sup>

- Use xmc4700\_relaxkit\_ucprobe\_ex2.zip example project
- 1. In this section you will open an existing Workspace (.wspx)
- Simply double click on the provided .wspx file in the example project.
- Micrium® uC/Probe™ XMC™ will start, showing the panel control for a software "signal generator"





#### 2. Add uC/Probe™ Embedded Target code

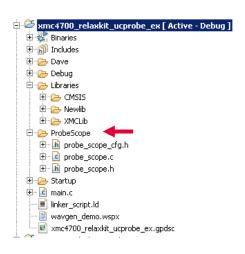
- To use the oscilloscope control, it requires adding to your application the Scope library which is part of the Target Code included in the μC/Probe<sup>TM</sup> XMC<sup>TM</sup> download package or can be downloaded from μC/Probe Embedded Target Code
  - Add folder and adjust the compiler settings, i.e. Include Paths
  - Include probe\_scope.h into your application code
- The library provide two functions:
  - ProbeScope\_Init()

Initializes the internals of the Oscilloscope module. It sets the time base indicated as a parameter to the function, i.e. the frequency of calling the sampling function



Take a sample of each active oscilloscope channel. This function should be called in periodic function, i.e. control loop or timer ISR like in the example

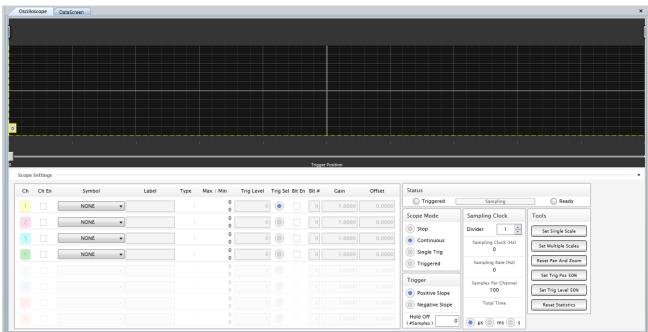
- > The library can be configured adapting the defines in probe\_scope\_cfg.h
  - Number of channels
  - Number of sample per channel
    - It determines the length of the waveform, i.e. T = sampling period X number of samples per channel

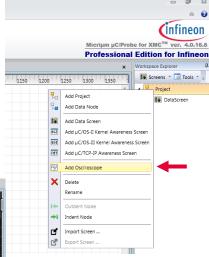


# Using Micrium® uC/Probe™ XMC™ Oscilloscope control



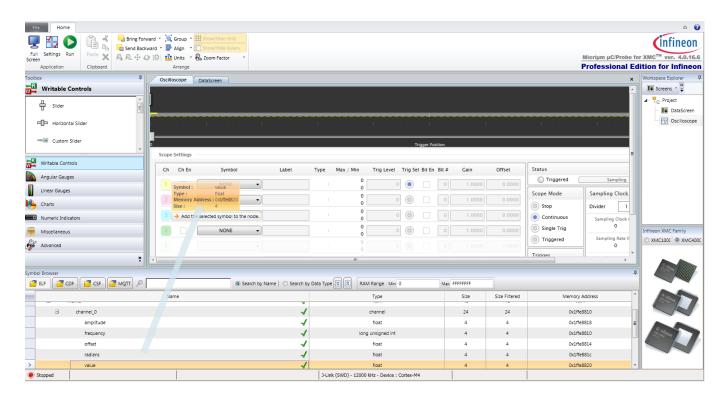
- 3. Create an oscilloscope
- Click on Project > Add Oscilloscope
- A new tab is created in the workspace containing the oscilloscope control





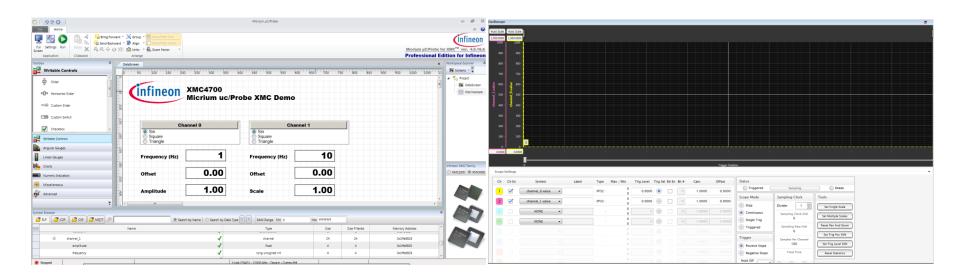


- 4. Associate variables to the oscilloscope channels
- Using the symbol browser drag and drop the variables channel\_0.value and channel\_1.value to the oscilloscope channels





- 5. Change the layout of the workspace
- To easily access the controls of the dashboard and simultaneously observe the oscilloscope, right click on the tab **Oscilloscope** and select *Floating*. The oscilloscope window will be detached from the main window of Micrium® uC/Probe<sup>TM</sup> XMC<sup>TM</sup>





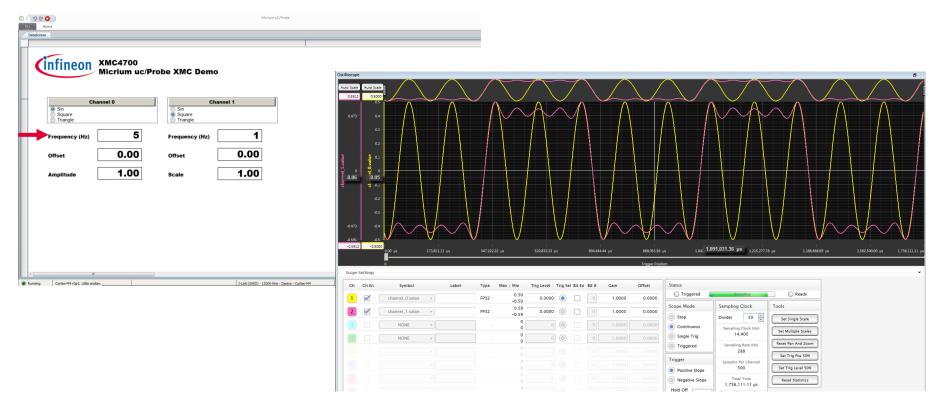
- Ensure target is running.
- Click on Run button in toolbar.
- 8. Adjust the oscilloscope channel scale.
- Click on Set Multiple Scales (1) in Tools to adjust the vertical scale.
- Set the Sampling Clock Divider (2) to adjust the time base scale.



# Using Micrium® uC/Probe™ XMC™ Oscilloscope control



- Use the dash board to control your application and observe the effect on the oscilloscope
- For example, change frequency of the waveform generator channel 0
   Hz to 5 Hz. You should observe something similar to the picture below





#### 10. Oscilloscope trigger options

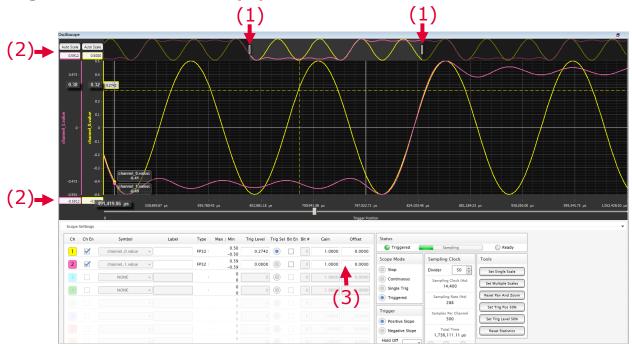
- One of the main features of the Oscilloscope control is the capability of triggering with the following options:
  - Trigger channel selection (1)
  - Trigger level (2)
  - Rising or falling edge (3)
  - Pre trigger (4)
  - Single trigger or continuous trigger (5)





#### 11. Oscilloscope other features

- Time axis zoom
  - Use the scroll bars in the top area of the Oscilloscope window (1)
- Individual Y vertical channel scale (2)
- Offset and gain of channels (3)





- 1 Objective of this tutorial
- What we need to follow this tutorial?
- 3 Introduction to Micrium® uC/Probe™ XMC™
- 4 Using the dashboard
- 5 Using the oscilloscope
- 6 Other features
- 7 References
- 8 Support material

### Micrium® uC/Probe<sup>TM</sup> XMC<sup>TM</sup> Other features



#### Data logging control

Log the values of any variable(s) in your symbols browser to a CSV file

### Microsoft<sup>®</sup> Excel<sup>®</sup> Bridge

Map an embedded target's symbol to a cell in Microsoft® Excel®

#### uC/OS Kernel Awareness

The  $\mu$ C/OS Kernel Awareness in  $\mu$ C/Probe<sup>TM</sup> is a series of prebuilt screens that allows you to see the run time behavior of all the  $\mu$ C/OS-II kernel objects used in your embedded application

#### Terminal Window

Interact with your embedded target in a shell-like fashion

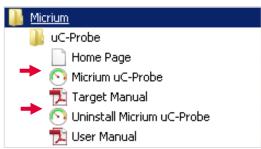


- 1 Objective of this tutorial
- What we need to follow this tutorial?
- 3 Introduction to Micrium uC/Probe™ XMC™
- 4 Using the dashboard
- 5 Using the oscilloscope
- 6 Other features
- 7 References
- 8 Support material



#### References

- Micrium® uC/Probe™ XMC™ documentation
  - Accessible in the Start menu of Windows®
  - Or in the File tab



Micrium® uC/Probe™ XMC™ features

https://www.micrium.com/tools/ucprobe/features/

→ uC/Probe<sup>TM</sup> Oscilloscope Feature: BLDC Design Case Study

https://www.micrium.com/new-%C2%B5cprobe-featuressimplify-bldc-design/



- 1 Objective of this tutorial
- What we need to follow this tutorial?
- 3 Introduction to Micrium uC/Probe™ XMC™
- 4 Using the dashboard
- 5 Using the oscilloscope
- 6 Other features
- 7 References
- 8 Support material



### Support material

### Collaterals and Brochures





- > Product Briefs
- Selection Guides
- Application Brochures
- Presentations
- > Press Releases, Ads

www.infineon.com/XMC

#### **Technical Material**





- Application Notes
- Technical Articles
- Simulation Models
- Datasheets, MCDS Files
- PCB Design Data

- www.infineon.com/XMC
- > Kits and Boards
- DAVETM
- Software and Tool Ecosystem

#### **Videos**



- Technical Videos
- Product Information Videos

- > Infineon Media Center
- → XMC<sup>TM</sup> Mediathek

#### Contact



- Forums
- Product Support

- Infineon Forums
- Technical Assistance Center (TAC)



#### Disclaimer

The information given in this training materials is given as a hint for the implementation of the Infineon Technologies component only and shall not be regarded as any description or warranty of a certain functionality, condition or quality of the Infineon Technologies component.

Infineon Technologies hereby disclaims any and all warranties and liabilities of any kind (including without limitation warranties of non-infringement of intellectual property rights of any third party) with respect to any and all information given in this training material.



Part of your life. Part of tomorrow.

