

### Reference design for servo motor and drive integration

UG 2024-16

#### **About this document**

#### Scope and purpose

This user guide provides an overview of REF-DR3KIMBGSIC2MA including its main features, key data, pin assignments, and mechanical dimensions. REF-DR3KIMBGSIC2MA is a reference design that contains two PCBs (driver board and power board), a driver circuit, and a 3-phase inverter for motor-drive applications. The driver circuit is based on the EiceDRIVER™ compact single-channel isolated gate driver 1ED3122MC12H with Miller clamp function. The 2<sup>nd</sup> generation CoolSiC™ MOSFET, IMBG120R040M2H, is the main component in the 3-phase inverter. REF-DR3KIMBGSIC2MA has been developed to provide initial support to customers in designing servo motors with integrated inverters using EiceDRIVER™ IC and CoolSIC™ MOSFET. This reference design is the power component of an integrated servo motor solution, which is an Infineon joint development project with partner JingChuan and Maxsine.



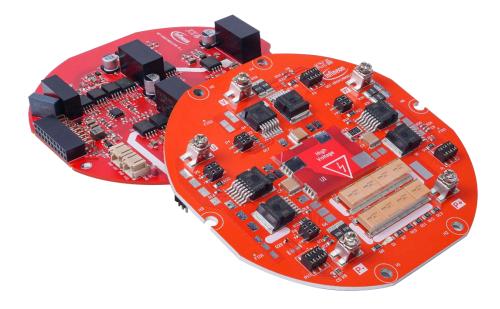




Note: Please note that this product is not qualified according to the AEC Q100 or AEC Q101 documents of the Automotive Electronics Council

#### Intended audience

This user guide is intended for all technical specialists working with REF-DR3KIMBGSIC2MA.



### User guide for REF-DR3KIMBGSIC2MA

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**Important notice** 



#### Reference board/kit

Infineon product(s) embedded on this PCB have functions and form factor close to a commercial design. PCB and auxiliary circuits are optimized for the final design.

Note: Boards do not necessarily meet safety, EMI, and quality standards (for example UL, CE) requirements.

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"Evaluation Boards and Reference Boards" shall mean products embedded on a printed circuit board (PCB) for demonstration and/or evaluation purposes, which include, without limitation, demonstration, reference and evaluation boards, kits and design (collectively referred to as "Reference Board").

Environmental conditions have been considered in the design of the Evaluation Boards and Reference Boards provided by Infineon Technologies. The design of the Evaluation Boards and Reference Boards has been tested by Infineon Technologies only as described in this document. The design is not qualified in terms of safety requirements, manufacturing, and operation over the entire operating temperature range or lifetime.

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### **Safety precautions**

Please note the following warnings regarding the hazards associated with development systems.

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Table 1 **Safety precautions** 



**Warning:** The DC link potential of this board is up to 1000 VDC. When measuring voltage waveforms by oscilloscope, high voltage differential probes must be used. Failure to do so may result in personal injury or death.



**Warning**: The evaluation or reference board contains DC bus capacitors which take time to discharge after removal of the main supply. Before working on the drive system, wait five minutes for capacitors to discharge to safe voltage levels. Failure to do so may result in personal injury or death. Darkened display LEDs are not an indication that capacitors have discharged to safe voltage levels.



**Warning:** The evaluation or reference board is connected to the grid input during testing. Hence, high-voltage differential probes must be used when measuring voltage waveforms by oscilloscope. Failure to do so may result in personal injury or death. Darkened display LEDs are not an indication that capacitors have discharged to safe voltage levels.



Warning: Remove or disconnect power from the drive before you disconnect or reconnect wires, or perform maintenance work. Wait five minutes after removing power to discharge the bus capacitors. Do not attempt to service the drive until the bus capacitors have discharged to zero. Failure to do so may result in personal injury or death.



**Caution:** The heat sink and device surfaces of the evaluation or reference board may become hot during testing. Hence, necessary precautions are required while handling the board. Failure to comply may cause injury.



Caution: Only personnel familiar with the drive, power electronics and associated machinery should plan, install, commission and subsequently service the system. Failure to comply may result in personal injury and/or equipment damage.



Caution: The evaluation or reference board contains parts and assemblies sensitive to electrostatic discharge (ESD). Electrostatic control precautions are required when installing, testing, servicing or repairing the assembly. Component damage may result if ESD control procedures are not followed. If you are not familiar with electrostatic control procedures, refer to the applicable ESD protection handbooks and guidelines.



**Caution:** A drive that is incorrectly applied or installed can lead to component damage or reduction in product lifetime. Wiring or application errors such as undersizing the motor, supplying an incorrect or inadequate AC supply, or excessive ambient temperatures may result in system malfunction.



**Caution:** The evaluation or reference board is shipped with packing materials that need to be removed prior to installation. Failure to remove all packing materials that are unnecessary for system installation may result in overheating or abnormal operating conditions.

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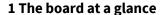
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### 1 The board at a glance

REF-DR3KIMBGSIC2MA is the inverter and gate driver board to demonstrate an integrated servo motor and drive. The driver circuit is based on the EiceDRIVER™ compact single-channel isolated gate driver, 1ED3122MC12H, with Miller clamp function [1]. Second generation CoolSiC™ MOSFET, IMBG120R040M2H, is the main component for the 3-phase inverter [2].

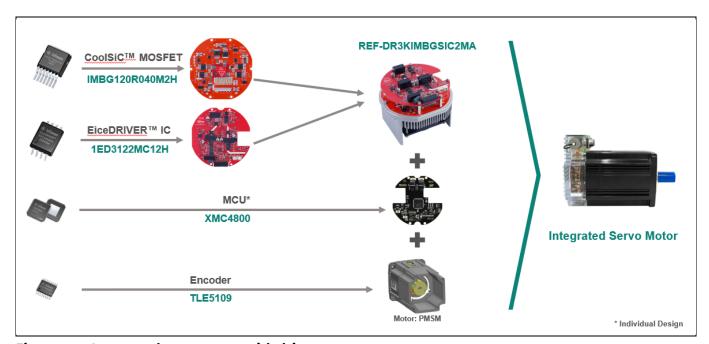


Figure 1 Integrated servo motor with drive

The full set consists of: an inverter board, a gate driver board, a controller board, and a servo motor, as shown in Figure 1. The control board and the motor are not part of the reference design. To evaluate the electrical performance of the system, iMOTION™ MADK EVAL-M1-101TF can be used to provide a simple control. A heatsink and a fan are included for easy evaluation, even though the system can work without a cooling fan. A fan cable is provided for connecting the 24 V supply on REF-DR3KIMBGSIC2MA to the fan.

### 1.1 Delivery contents

The reference design REF-DR3KIMBGSIC2MA is delivered together with complete documentation in an environment-friendly carton box.

As shown in Figure 2, the box contains:

- The reference board of size 12 cm x 12 cm x 10 cm (L x W x H) and weighing 800 grams assembled as a stack; including an inverter board, a gate driver board, a heatsink, and a cooling fan. The PCB diameter (without heatsink) is 11cm.
- A fan cable, for connecting the 24 V supply on REF-DR3KIMBGSIC2MA to the fan
- A user guide
- An introduction sheet

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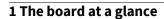






Figure 2 Delivery contents

#### Reference design for motor drive integration





#### 1.3 **Block diagram**

The inverter has a standard 3-phase, 2-level topology, with a DC link capacitor and six CoolSiC™ MOSFETs in D<sup>2</sup>PAK (IMBG120R040M2H) package. The components are soldered on to a single layer Insulated metallic substrate (IMS) board. All the CoolSiC™ MOSFETs are driven by an isolated gate driver EiceDRIVER™ IC -1ED3122MC12H with Miller clamp function.

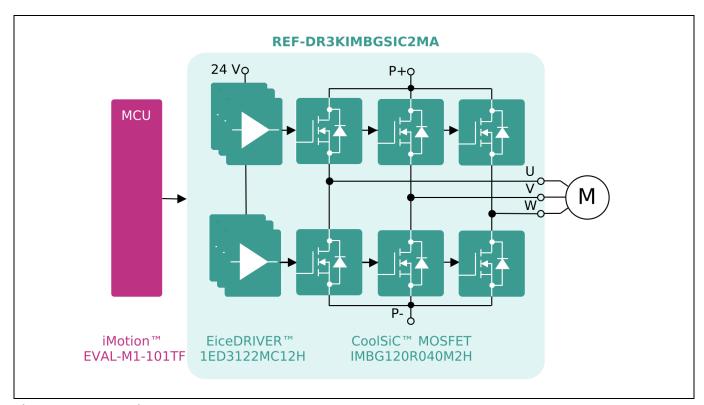


Figure 3 **Block diagram** 

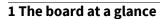
#### **Main features** 1.4

The main features of REF-DR3KIMBGSIC2MA are:

- 3-phase servo motor with integrated drive
- 1200 V/40mΩ CoolSiC™ MOSFET in SMD package (TO263-7), with .XT interconnection technology
- Compact design: PCB diameter 110 mm, 120 mm considering the heatsink
- Insulated metallic substrate (IMS) PCBs with high thermal conductivity
- Overcurrent detection
- Input voltage 350 800 VDC
- Output voltage: 220 V to ~480 V

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## 1.5 Board parameters and technical data

#### **Table 2** Key parameters

| Parameter                        | Value      | Condition                  |
|----------------------------------|------------|----------------------------|
| Input voltage (DC)               | 350 ~800 V |                            |
| Output voltage (AC, 3-phase)     | 220 ~480 V |                            |
| Output current (AC, 3-phase)     | 6.46 A     | Input voltage = 600 V (DC) |
| Output max current (AC, 3-phase) | 14.88 A    | Input voltage = 600 V (DC) |
| Output power                     | 4.2 kW     | Input voltage = 600 V (DC) |
| Ambient temperature              | 0-40°C     |                            |

#### Reference design for motor drive integration

2 System and functional description



### 2 System and functional description

### 2.1 Commissioning

The REF-DR3KIMBGSIC2MA board is intended for evaluating a CoolSiC<sup>™</sup> MOSFET solution in an integrated servo drive application. The control of the servo motor is not the intended focus. This section introduces the minimum connections required to start the evaluation.

Minimum connections for the gate driver board (see Figure 4):

- An auxiliary power supply connection CN1 (input): 0 ~ 24 V DC from an external power supply
- Gate driver signal connection: J1

Minimum connections for the power board (see Figure 5):

- A DC link connection (input): 350 ~ 800 V DC from an external power supply
- A 3-phase AC (output) connection to 3-phase motor or resistor- inductor (RL) load

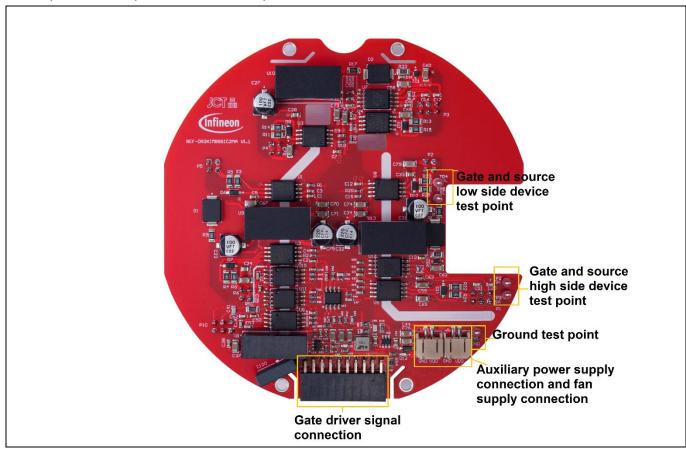


Figure 4 Driver board connections

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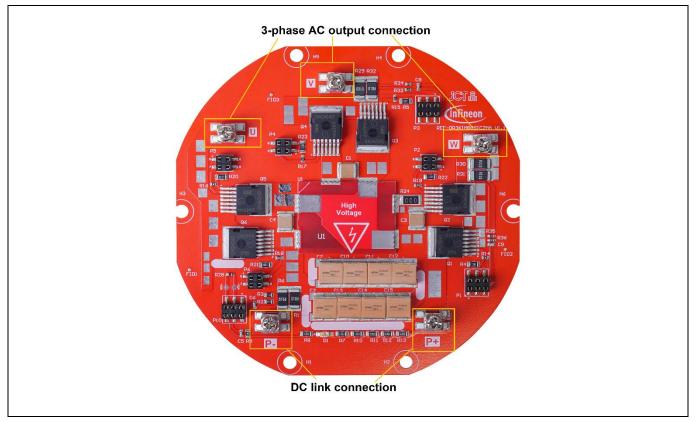


Figure 5 Power board connections

### 2.2 Basic operation using a controller

Table2 indicates electrical key parameters valid for basic operation (including maximum ratings). To evaluate the electrical performance of the system, the iMOTION™ MADK EVAL-M1-101TF control board can be used. Detailed information about the drive card can be found in [3].



Figure 6 iMotion™ MADK EVAL-M1\_101TF

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The connection between REF-DR3KIMBGSIC2MA and EVAL-M1-101TF is pin-to-pin. The details are listed in Table 3 and in Table 8 (gate driver board, connector J1). An adaption cable, jumpers and extra wires are not required for the connection.

Table 3 CoolSiC™ MADK-M1 20-pin interface connector for the control board

| Pin number | Pin      | Details   |
|------------|----------|---|
| 1          | PWMUH    | 3.3 V compatible logic output for high-side gate driver, phase U        |
| 2          | GND      | Ground  |
| 3          | PWMUL    | 3.3 V compatible logic output for low-side gate driver, phase U         |
| 4          | GND      | Ground  |
| 5          | PWMVH    | 3.3 V compatible logic output for high-side gate driver, phase V        |
| 6          | +3.3 V   | On board 3.3 V supply   |
| 7          | PWMVL    | 3.3 V compatible logic output for low-side gate driver, phase V         |
| 8          | +3.3 V   | Onboard 3.3 V supply  |
| 9          | PWMWH    | 3.3 V compatible logic output for high-side gate driver, phase W        |
| 10         | IU+      | Shunt voltage, phase U  |
| 11         | PWMWL    | 3.3 V compatible logic output for low-side gate driver, phase W         |
| 12         | IU-      | Ground  |
| 13         | GK       | Gatekill signal – active low when overcurrent is detected               |
| 14         | DCBSENSE | DC bus positive voltage, scaled in 0 - 3.3 V range by a voltage divider |
| 15         | VTH      | Thermistor input  |
| 16         | IV+      | Shunt voltage, phase V  |
| 17         | IV-      | Ground  |
| 18         | IW+      | Shunt voltage, phase W  |
| 19         | IW-      | Ground  |
| 20         | VCC      | Defined for 15 V power supply (not used on this board)                  |

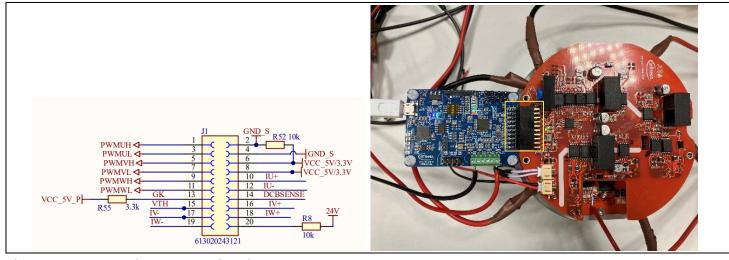


Figure 7 Connection between iMotion™ MADK EVAL-M1-101TF and REF-DR3KIMBGSIC2MA

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# 3 System design

### 3.1 Schematics

The schematics of the power board is shown in Figure 8.

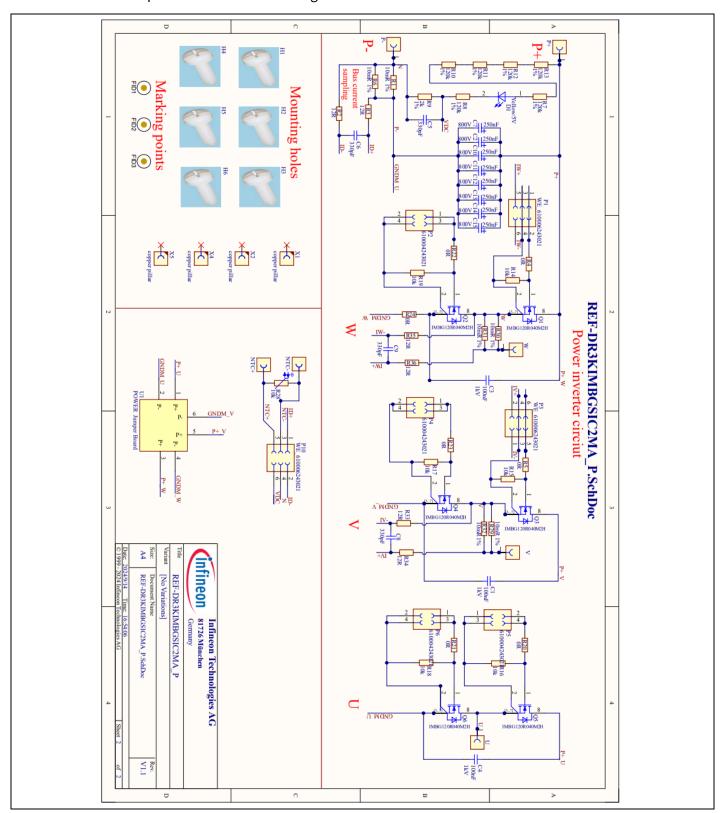
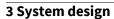


Figure 8 The schematics of the power board (REF-DR3KIMBGSIC2MA)

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The schematics of the gate driver board is shown in Figure 9 and Figure 10.

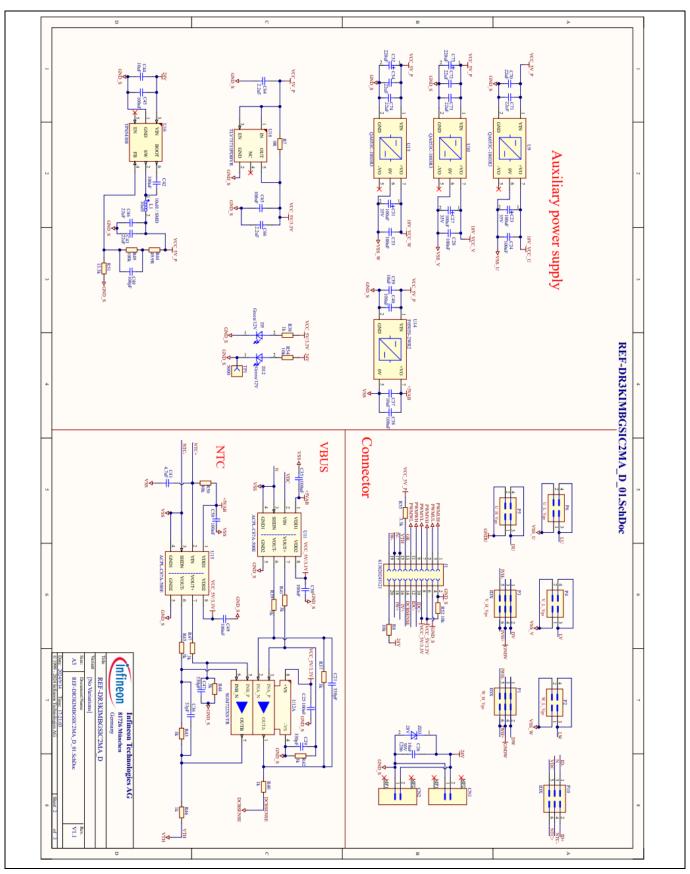
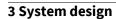


Figure 9 Auxiliary power supply of the driver board (REF-DR3KIMBGSIC2MA)

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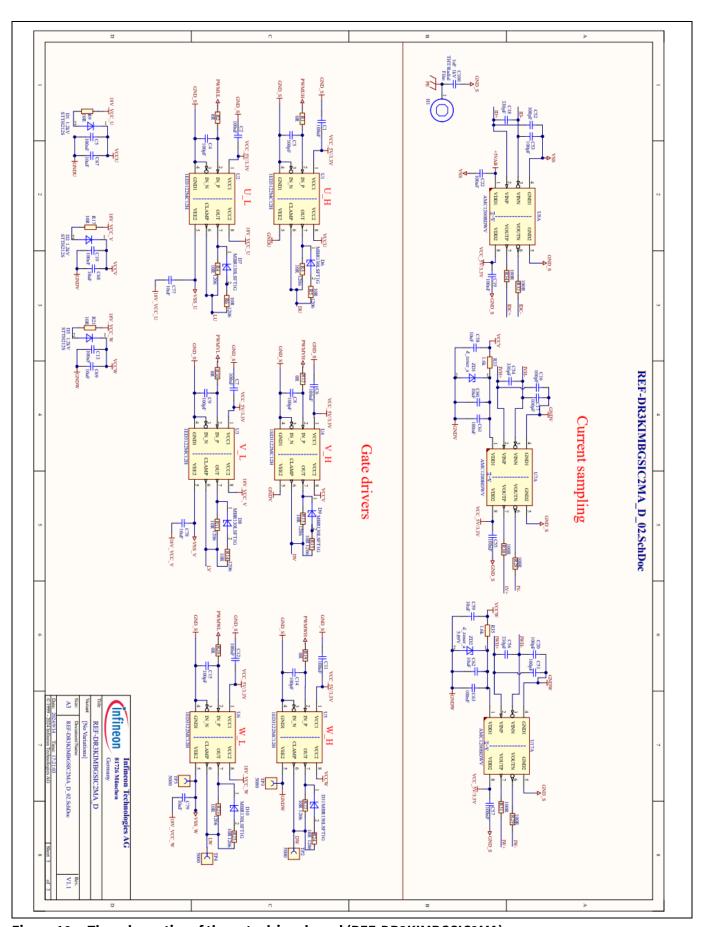


Figure 10 The schematics of the gate driver board (REF-DR3KIMBGSIC2MA)

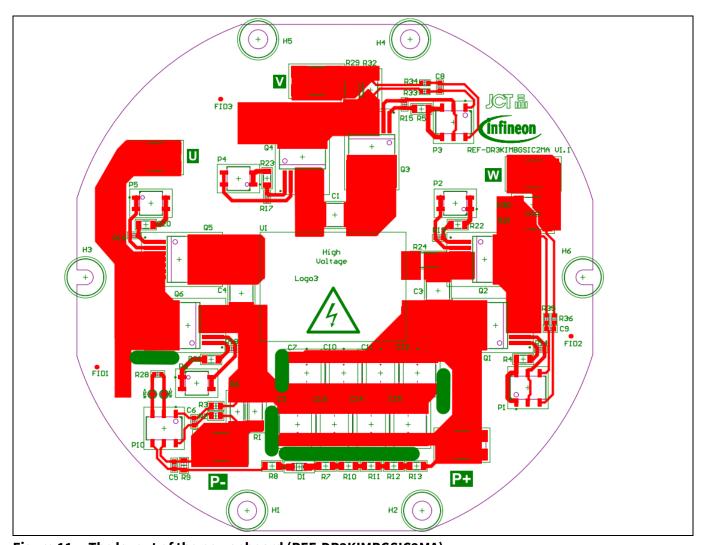






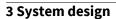
#### Layout 3.2

The power board is a single-layer IMS board. The gate driver board is a 4-layer PCB board. The layouts of the boards are shown in Figure 11 and Figure 12 respectively.



The layout of the power board (REF-DR3KIMBGSIC2MA) Figure 11

### Reference design for motor drive integration





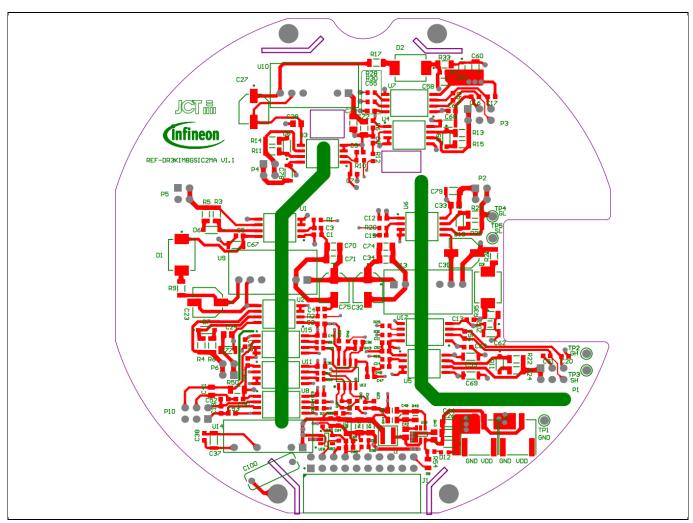


Figure 12 The layout of the driver board (REF-DR3KIMBGSIC2MA)

### 3.3 Bill of material

The complete bill of material is available in the Download section of Infineon's website.

Table 4 BOM of the power board

| No. | Designator                | Value   | Description   | Manufacturer             | Manufacturer P/N |
|-----|---------------------------|---|---|--------------------------|------------------|
| 10  | Q1, Q2, Q3, Q4, Q5,<br>Q6 | IMBG120R040<br>M2H  | CoolSiC 1200V SiC Trench MOSFET Silicon Carbide MOSFET, Sense pin for optimized switching performance, Reduction of system complexity and cost, Qualified for industrial applications | Infineon<br>Technologies | IMBG120R040M2H   |
| 21  | X1, X2, X4, X5            | copper pillar,<br>connect Power<br>Board to Driver<br>Board | copper pillar from WURTH,<br>manufacture order number<br>971190324  | Wurth                    | 971190324        |

### **User guide for REF-DR3KIMBGSIC2MA**

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#### Table 5 **BOM** of the gate driver board

| No. | Designator                  | Value        | Description   | Manufacturer             | Manufacturer P/N |
|-----|-----------------------------|--------------|---|--------------------------|------------------|
|     |                             |              |   |                          |                  |
| 2   | C3, C4, C8, C9, C14,<br>C15 | 100pF        | CAP / CERA / 100pF / 25V / 10% /<br>X7R (EIA) / -55°C to 125°C /<br>0603(1608) / SMD / -  | Wurth Elektronik         | 885012206053     |
| 12  | C48                         | 100pF        | CAP / CERA / 100pF / 50V / 5% /<br>COG (EIA) / NPO / -55°C to 125°C /<br>0805(2012) / SMD / -   | Wurth Elektronik         | 885012007057     |
| 19  | J1                          | 613020243121 | WR-PHD 2.54 mm Angled Dual<br>Socket Header   | Wurth Elektronik         | 613020243121     |
| 20  | L1                          | 10uH         | IND / STD / 10uH / 3.05A / 20% / - 40°C to 125°C / 100.8Ω / SMD / Inductor, SMD, 2.37 mm pitch, 2 Pin, 4.10 mm L X 4.10 mm W X 3.10 mm H body / SMD / - | Wurth Elektronik         | 74438357100      |
| 21  | P1, P3, P10                 | 61300621121  | WR-PHD Dual Pin Header,<br>2.54mm Pitch, Double row, 6 Pins   | Wurth Elektronik         | 61300621121      |
| 22  | P2, P4, P5, P6              | 61300421121  | Header, 4pins, 2.54mm pitch,<br>Board to Board  | Wurth Elektronik         | 61300421121      |
| 37  | U1, U2, U3, U4, U5,<br>U6   | 1ED3122MC12H | Single channel isolated IGBT gate driver IC   | Infineon<br>Technologies | 1ED3122MC12H     |

#### **Connector details** 3.4

General information about the connectors of the REF-DR3KIMBGSIC2MA evaluation board is provided in the following tables.

**Power board connectors** Table 6

| PIN   | Label | Function                       |
|-------|-------|--------------------------------|
| P+,P- | P+,P- | Power supply input for DC link |
| U,V,W | U,V,W | AC power output for motor      |
| VDD   | P24V  | Auxiliary power supply input   |
| R24   | R24   | Source current test point      |

**Gate driver board test points** Table 7

| PIN | Label | Function                    |
|-----|-------|-----------------------------|
| TP2 | GH    | High-side gate test point   |
| TP4 | GL    | Low-side gate test point    |
| TP3 | SH    | High-side source test point |
| TP5 | SL    | Low-side source test point  |
| TP1 | GND   | Ground test point           |

### User guide for REF-DR3KIMBGSIC2MA

### Reference design for motor drive integration



3 System design

Table 8 Gate driver connector J1

| Pin number | Pin      | Details   |
|------------|----------|---|
| 1          | PWMUH    | Gating signal, high side, phase U                                       |
| 2          | GND      | Ground  |
| 3          | PWMUL    | Gating signal, low side, phase U  |
| 4          | GND      | Ground  |
| 5          | PWMVH    | Gating signal, high side, phase V                                       |
| 6          | +3.3V    | On board 3.3 V supply   |
| 7          | PWMVL    | Gating signal, low side, phase V  |
| 8          | +3.3V    | On board 3.3 V supply   |
| 9          | PWMWH    | Gating signal, high side, phase W                                       |
| 10         | IU+      | Shunt voltage phase U   |
| 11         | PWMWL    | Gating signal, low side, phase W  |
| 12         | IU-      | Ground  |
| 13         | GK       | Gatekill signal – active low when overcurrent is detected               |
| 14         | DCBSENSE | DC bus positive voltage, scaled in 0 - 3.3 V range by a voltage divider |
| 15         | VTH      | Thermistor input  |
| 16         | IV+      | Shunt voltage phase V   |
| 17         | IV-      | Ground  |
| 18         | IW+      | Shunt voltage phase W   |
| 19         | IW-      | Ground  |
| 20         | VCC      | Defined for 15 V power supply (not used in this board)                  |

### Reference design for motor drive integration





## 4 System performance

Efficiency of the 2<sup>nd</sup> generation CoolSIC<sup>™</sup> MOSFET was proven through a system performance test.

The test platform comprised:

- A DC power supply
- A DC high-voltage power supply
- A precision power analyzer
- A thermal camera
- An RL load
- An oscilloscope
- MADK EVAL-M1\_101TF
- REF-DR3KIMBGSIC2MA

The setup and block diagram of the experiment are shown in Figure 13 and Figure 14, respectively.

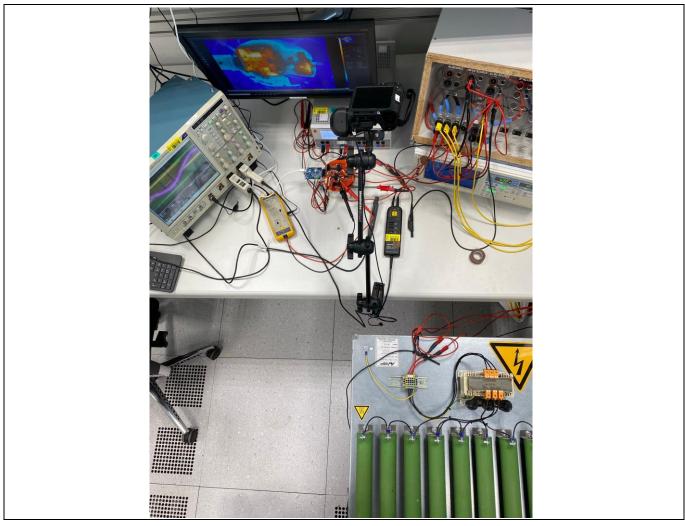


Figure 13 Image of the test setup

### Reference design for motor drive integration



### 4 System performance

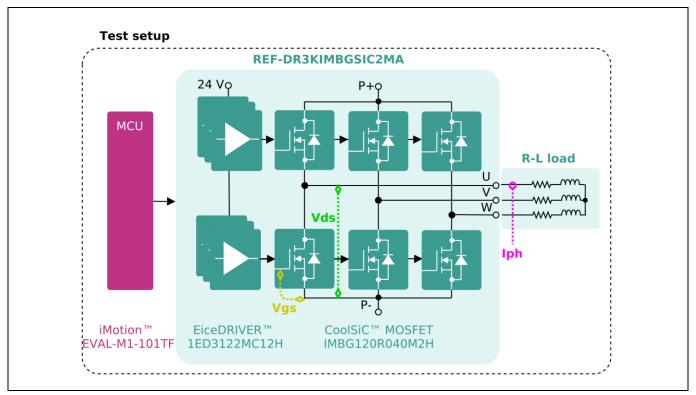


Figure 14 Block diagram of the test setup

The test was performed under the following conditions:

- 600 V DC bus voltage
- 24 V supplied for auxiliary power supply
- Board fan in operation versus board fan not in operation
- 8 kHz switching frequency
- 3 x 33 Ω load resistance

Figure 15 shows the  $V_{gs}$  (channel 1) and  $V_{ds}$  (channel 4) measured on the low side of the device, and the phase current  $I_{ph}$  (channel 3) measured on the U inverter leg.

### Reference design for motor drive integration



#### 4 System performance

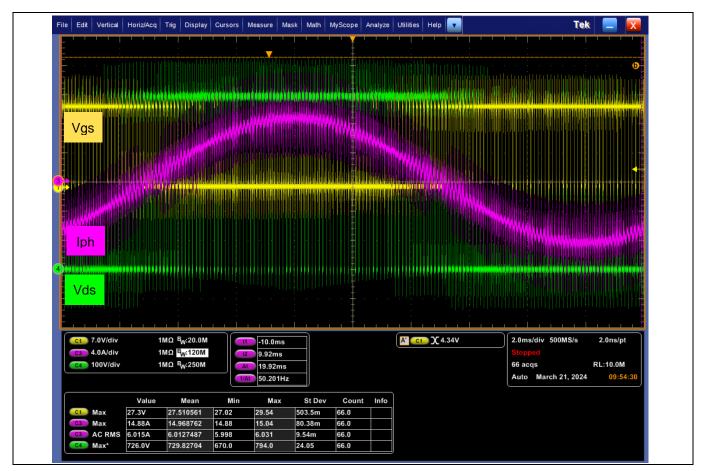


Figure 15 50 Hz phase current

More information was obtained using a precision power analyzer. The results are listed in Table 9.

 Table 9
 Power analyzer results

|              | One phase (RMS) | DC link  |
|--------------|-----------------|----------|
| Voltage      | 218.12 V        | 601.6 V  |
| Current      | 6.46 A          | 7.12 A   |
| Active power | 1.408 kW        | 4.283 kW |

The total output power with the given conditions is 4.2 kW.

Figures 16 and 17 show the images from a thermal camera when the board fan is operational and when it is disconnected, respectively. The spots Sp1 and Sp2 denote the high side and low side MOSFETs in the W inverter leg.

### Reference design for motor drive integration





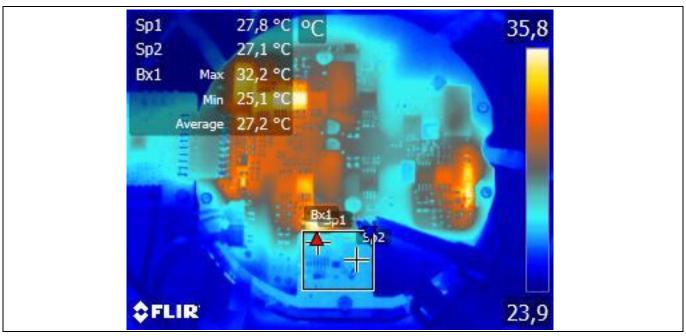


Figure 16 Thermal camera image - 600 VDC, 8 kHz switching frequency, with active fan

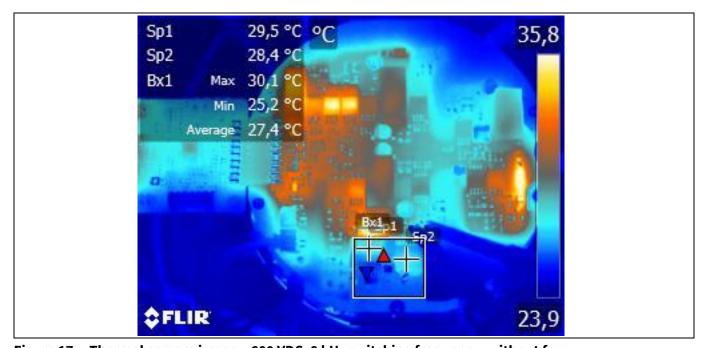


Figure 17 Thermal camera image - 600 VDC, 8 kHz switching frequency, without fan

With active fan high side and low side devices temperatures are respectively 27.8°C and 27.1°C. Without the fan the high side and low side devices temperatures are respectively 29.5°C and 28.4°C. In both cases the temperature does not differ more than 6°C than the ambient temperature.

# User guide for REF-DR3KIMBGSIC2MA

### Reference design for motor drive integration





#### References

- [1] <a href="https://www.infineon.com/dgdl/Infineon-IMBG120R040M2H-DataSheet-v01\_00-EN.pdf?fileld=8ac78c8c8d1b852e018d2200102020d0">https://www.infineon.com/dgdl/Infineon-IMBG120R040M2H-DataSheet-v01\_00-EN.pdf?fileld=8ac78c8c8d1b852e018d2200102020d0</a>
- [2] <a href="https://www.infineon.com/dgdl/Infineon-1ED31xxMC12H-1ED-X3">https://www.infineon.com/dgdl/Infineon-1ED31xxMC12H-1ED-X3</a> Compact-DataSheet-v01 10-EN.pdf?fileId=5546d46277fc7439017802de09e5671d
- [3] [iMOTION™ MADK EVAL-M1-101TF user manual]; https://www.infineon.com/dgdl/Infineon-UG-2020-15\_EVAL-M1-101TF-UserManual-v01\_00-EN.pdf?fileId=5546d46277921c320177d97457631fd2

# **User guide for REF-DR3KIMBGSIC2MA**Reference design for motor drive integration



Glossary

### **Glossary**

PCB

Printed circuit board

**SMD** 

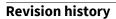
Surface mounted device

IMS

Insulated metallic substrate

### User guide for REF-DR3KIMBGSIC2MA

### Reference design for motor drive integration





# **Revision history**

| Document revision | Date       | Description of changes                               |  |
|-------------------|------------|--|--|
| 1.00              | 2024-04-17 | Initial version                                      |  |
| 1.1               | 2024-10-04 | Board pictures, BOM, schematics, and layout updated. |  |
|                   |            |  |  |

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