

# Quick-start guide for XENSIV™ PAS CO2 Shield2Go

## About this document

### Scope and purpose

This user manual serves as a starting guide and will focus on the setup and communication of the XENSIV™ PAS CO2 Shield2Go. Main focus will be the hardware along with a quick example of how to set up communication and start basic measurement with the provided software library using the XMC 2Go, the Arduino Due and the Arduino Uno in combination with the my IoT adapter.

### Intended audience

Application engineers, system engineers and makers.

### Order information

Sales Name: **SHIELD\_PASCO2\_SENSOR**

SP-No: **SP005569590**

Opn: **SHIELDPASCO2SENSORTOBO1**

## Table of contents

|                                                                |           |
|----------------------------------------------------------------|-----------|
| <b>About this document.....</b>                                | <b>1</b>  |
| <b>Table of contents.....</b>                                  | <b>1</b>  |
| <b>1 Introduction .....</b>                                    | <b>2</b>  |
| 1.1 Shield2Go platform .....                                   | 3         |
| 1.2 XENSIV™ PAS CO2 Shield2Go .....                            | 4         |
| <b>2 Software and library integration.....</b>                 | <b>8</b>  |
| 2.1 Setting up Arduino IDE .....                               | 8         |
| 2.2 Library overview .....                                     | 8         |
| <b>3 Quick start with XMC 2Go .....</b>                        | <b>10</b> |
| 3.1 Step by step CO2 concentration readout example .....       | 11        |
| <b>4 Quick start with Arduino Due .....</b>                    | <b>18</b> |
| <b>5 Quick start with Arduino Uno and My IoT adapter .....</b> | <b>20</b> |
| <b>6 Appendix.....</b>                                         | <b>21</b> |
| <b>Revision history.....</b>                                   | <b>22</b> |

## Introduction

### 1 Introduction

The XENSIV™ PAS CO2 sensor is a real carbon dioxide (CO<sub>2</sub>) sensor in an unprecedentedly small form factor. Designed on the basis of a unique photoacoustic spectroscopy (PAS) concept, the sensor saves more than 75 percent space compared to existing commercial real CO<sub>2</sub> sensors. Its direct ppm readings, SMD capability and simple design allow for quicker and easier integration into customers' systems in low- and high-volume applications alike.

The photoacoustic principle can be traced back to over 100 years ago, first discovered by Alexander Graham Bell in 1880. The photoacoustic effect involves the formation of sound waves (pressure changes) following light absorption in a material sample. The sound signal is quantified by detectors such as microphones. In order to obtain this effect, the light intensity must vary. A PAS gas sensor is based on the principle that gases absorb light in a specific wavelength of the infrared spectrum. CO<sub>2</sub> molecules, for example, have strong absorption in the  $\lambda = 4.2 \mu\text{m}$  wavelength.

The XENSIV™ PAS CO2 sensor module integrates, on the same PCB, the PAS transducer, a microcontroller for signal processing, algorithms and a MOSFET. As depicted in the block diagram, the PAS transducer includes: i) a proprietary infrared emitter with blackbody radiation, which is periodically chopped by the MOSFET; ii) a narrow-band optical filter passing the CO<sub>2</sub> specific wavelength  $\lambda = 4.2 \mu\text{m}$ , significantly improving the sensor selectivity compared to other gases, including humidity; and iii) Infineon's high-SNR (signal-to-noise ratio) MEMS microphone XENSIV™ IM69D130, detecting the pressure changes generated by the CO<sub>2</sub> molecules. All the components are developed and designed in-house in accordance with Infineon's high-quality guidelines. The sensor therefore benefits from Infineon's illustrious record of accomplishments in MEMS design and acoustic capabilities, resulting in it being best-in-class for price/performance.

The XENSIV™ PAS CO2 sensor is ideal for smart-home and building automation as well as various indoor air quality IoT devices such as air purifiers, thermostats, weather stations and personal assistants. The sensor enables end users to track, understand and improve the air quality surrounding them in a timely and highly energy-efficient manner.



**Figure 1** XENSIV™ PAS CO2 sensor

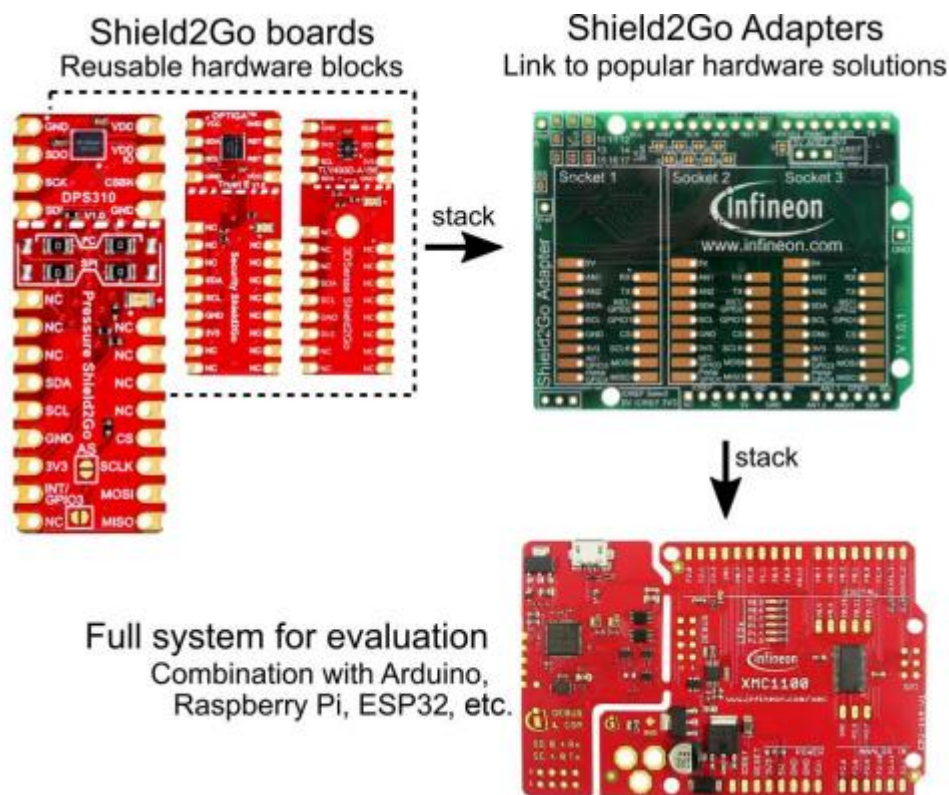
## Introduction

### 1.1 Shield2Go platform

Infineon's Shield2Go boards are equipped with one featured Infineon IC and provide a standardized form factor and pin layout for fast orientation. All boards come with solderless connectors allowing designers to stack the boards instead of soldering them. This makes the Shield2Go boards simple, reusable and flexible. In addition, each Shield2Go comes with a dedicated and free software library for Arduino. The Shield2Go boards are compatible with Arduino Uno with Infineon's My IoT adapter. This combination of flexible hardware components and accompanying software speeds up the prototyping process. Engineers and makers can develop customized system solutions by freely selecting and combining Shield2Go boards in multiple ways based on their needs and use cases. Learn more about the Shield2Go approach and the available portfolio on the dedicated product page.

<https://www.infineon.com/cms/en/tools/landing/infineon-for-makers/shield-2go-my-iot/>

The My IoT adapter board is also part of the evaluation environment that acts as the gateway to external hardware - such as the popular hardware platforms like Arduino, Raspberry Pi or Espressif Wi-Fi Chips -, making it possible to combine the Shield2Go boards into systems easily and flexibly. The adapter offers multiple sockets which allow free and flexible combination of various Shield2Go boards. Thereby, users do not have to care about pin allocation, level shifting or system integration.



**Figure 2 Combining Shield2Go board and My IoT adapter to a system**

More and detailed information can be found on the dedicated My IoT product page.

<https://www.infineon.com/cms/en/product/evaluation-boards/my-iot-adapter/>

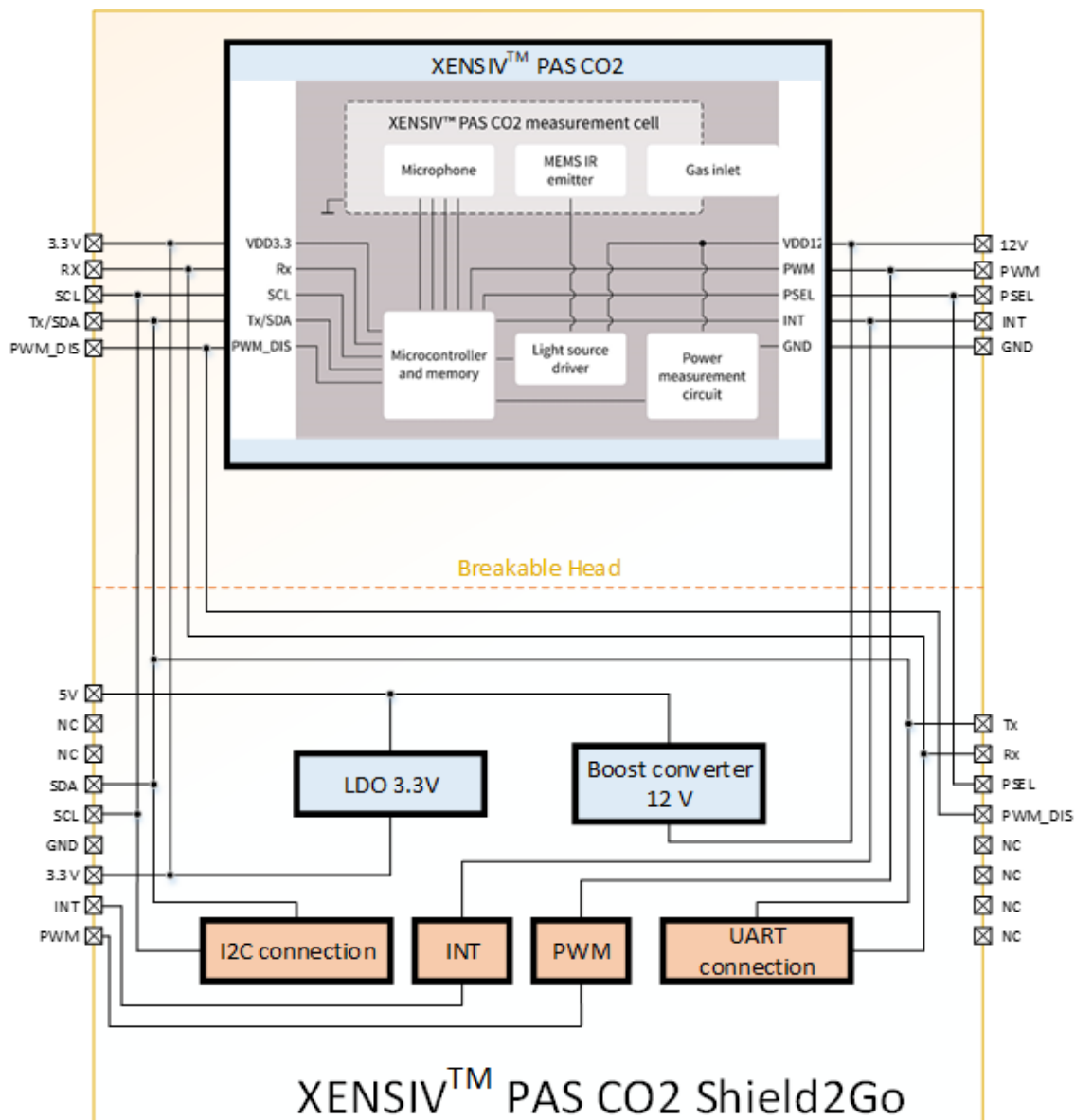
## Introduction

### 1.2 XENSIV™ PAS CO2 Shield2Go

The XENSIV™ PAS CO2 Shield2Go includes every necessary component to fully supply the XENSIV™ PAS CO2 with all the available features enabled and optimized. The necessary stable 12 V supply for the IR emitter is generated on board with a boost converter and also additionally an LDO for the 3.3 V supply is integrated on board which reduces the required supplies to a single 5 V supply. If user wants to use their own design it is possible to break apart the head which only consists of the XENSIV™ PAS CO2 module with all the pins routed out on castellated pads to easily mount the XENSIV™ PAS CO2 to the other PCBs. PWM and INT functionality is also covered in both cases. Please refer to the programming guide and register map for full detailed description and examples.

[https://www.infineon.com/dgdl/Infineon-programming\\_guide\\_PAS\\_CO2\\_evaluationkit-ApplicationNotes-v02\\_00-EN.pdf?filed=5546d4627600a6bc0176041139e77780](https://www.infineon.com/dgdl/Infineon-programming_guide_PAS_CO2_evaluationkit-ApplicationNotes-v02_00-EN.pdf?filed=5546d4627600a6bc0176041139e77780)

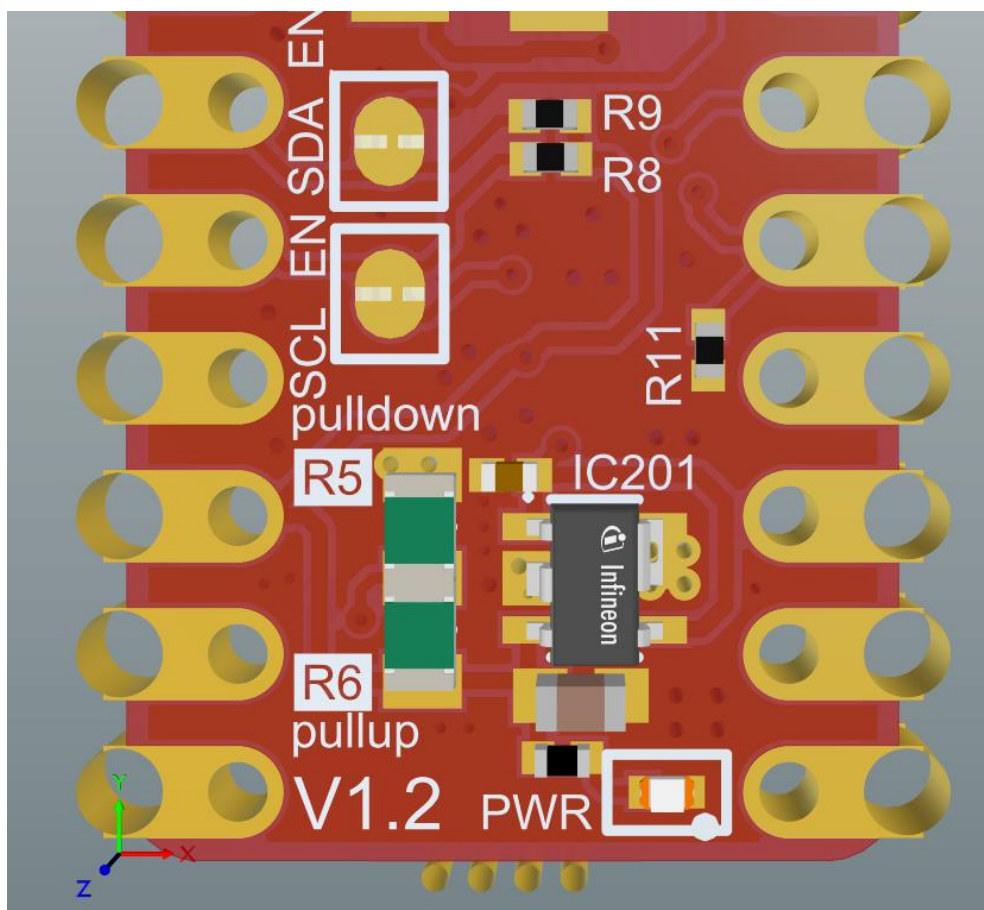
[https://www.infineon.com/dgdl/Infineon-Registermap\\_description\\_PASCO2\\_MA2-ApplicationNotes-v02\\_00-EN.pdf?filed=5546d4627600a6bc017604238d967785](https://www.infineon.com/dgdl/Infineon-Registermap_description_PASCO2_MA2-ApplicationNotes-v02_00-EN.pdf?filed=5546d4627600a6bc017604238d967785)



**Figure 3** Block diagram of XENSIV™ PAS CO2 Shield2Go

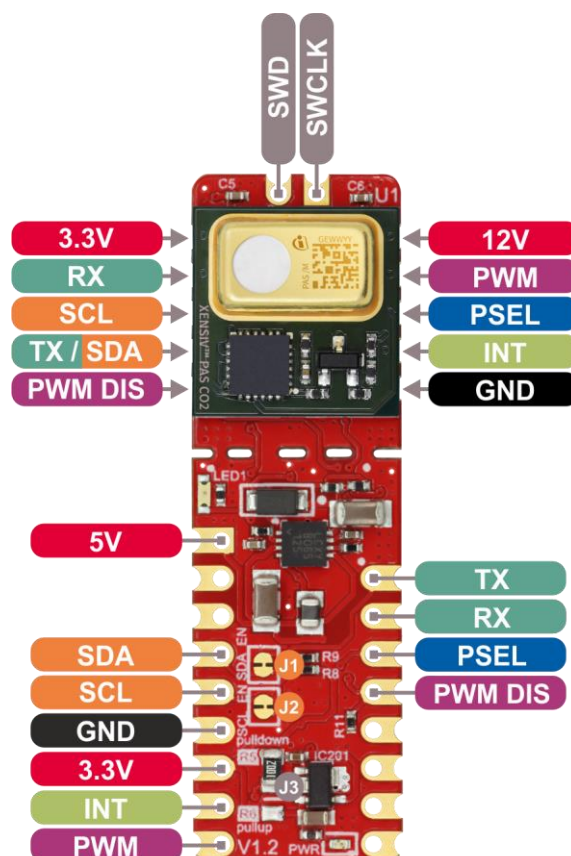
## Introduction

Two communication interfaces are available. By default, the I<sup>2</sup>C interface is configured but with a simple rearrangement from the pull-up resistor R5 to pull-down resistor R6 can the UART interface be selected. To fully disable the I<sup>2</sup>C interface and the connected pull-up resistors on the SDA/Tx and SCL lines solder jumpers can be cut and disconnected. Figure 4 is showing the two positions the resistor can take depending on desired interface and also above the solder jumpers for isolating the pull-up resistors R8 and R9.



**Figure 4** Selecting communication interface on the XENSIV™ PAS CO2 Shield2Go

## Introduction



**Figure 5 Pinout XENSIV™ PAS CO2 Shield2Go**

**Table 1 Pin descriptions of body part**

| Pin | Symbol    | Type                 | Function                                                              |
|-----|-----------|----------------------|-----------------------------------------------------------------------|
| 1   | VDD5      | Power supply (5 V)   | 5 V step up to 12 V power supply for the IR emitter                   |
| 2   | NC        | NC                   | Not connected                                                         |
| 3   | NC        | NC                   | Not connected                                                         |
| 4   | P11: SDA  | Input/Output         | I <sup>2</sup> C data pin (3.3 V domain)                              |
| 5   | P10: SCL  | Input/Output         | I <sup>2</sup> C clock pin (3.3 V domain)                             |
| 6   | GND       | Ground               | Ground                                                                |
| 7   | VDD3V3    | Power supply (3.3 V) | 3.3 V digital power supply                                            |
| 8   | P9: INT   | Output               | Interrupt output pin (3.3 V domain)                                   |
| 9   | P8: PWM   | Output               | PWM output pin (3.3 V domain)                                         |
| 10  | P7: TX    | Input/Output         | UART transmitter pin (3.3 V domain)                                   |
| 11  | P6: RX    | Input                | UART receiver pin (3.3 V domain)                                      |
| 12  | P5: RST   | Input                | Communication interface select input pin (3.3 V domain) <sup>1)</sup> |
| 13  | P4: GPIO1 | Input                | PWM disable input pin (3.3 V domain) <sup>2)</sup>                    |
| 14  | NC        | NC                   | Not connected                                                         |
| 15  | NC        | NC                   | Not connected                                                         |
| 16  | NC        | NC                   | Not connected                                                         |
| 17  | NC        | NC                   | Not connected                                                         |

## Introduction

**Table 2** Pin descriptions of head part

| Pin | Symbol  | Type                 | Function                                                              |
|-----|---------|----------------------|-----------------------------------------------------------------------|
| 1   | VDD     | Power supply (3.3 V) | 3.3 V digital power supply                                            |
| 2   | RX      | Input                | UART receiver pin (3.3 V domain)                                      |
| 3   | SCL     | Input/Output         | I <sup>2</sup> C clock pin (3.3 V domain)                             |
| 4   | TX_SDA  | Input/Output         | UART transmitter pin/I <sup>2</sup> C data pin (3.3 V domain)         |
| 5   | PWM_DIS | Input                | PWM disable input pin (3.3 V domain) <sup>2)</sup>                    |
| 6   | GND     | Ground               | Ground                                                                |
| 7   | INT     | Output               | Interrupt output pin (3.3 V domain)                                   |
| 8   | PSEL    | Input                | Communication interface select input pin (3.3 V domain) <sup>1)</sup> |
| 9   | PWM     | Output               | PWM output pin (3.3 V domain)                                         |
| 10  | VDD12   | Power supply (12 V)  | 12 V power supply for the IR emitter                                  |

<sup>1)</sup> High level selects UART and low level selects I<sup>2</sup>C. It is recommended to the user to hard wire the pin to VDD or GND, depending on the wanted interface.

<sup>2)</sup> If a communication interface is used by the application, it is recommended to hard-wire pin PWM\_DIS to GND. Note: In this case the device will start in continuous mode and not idle mode which needs to be considered when changing the measurement period.

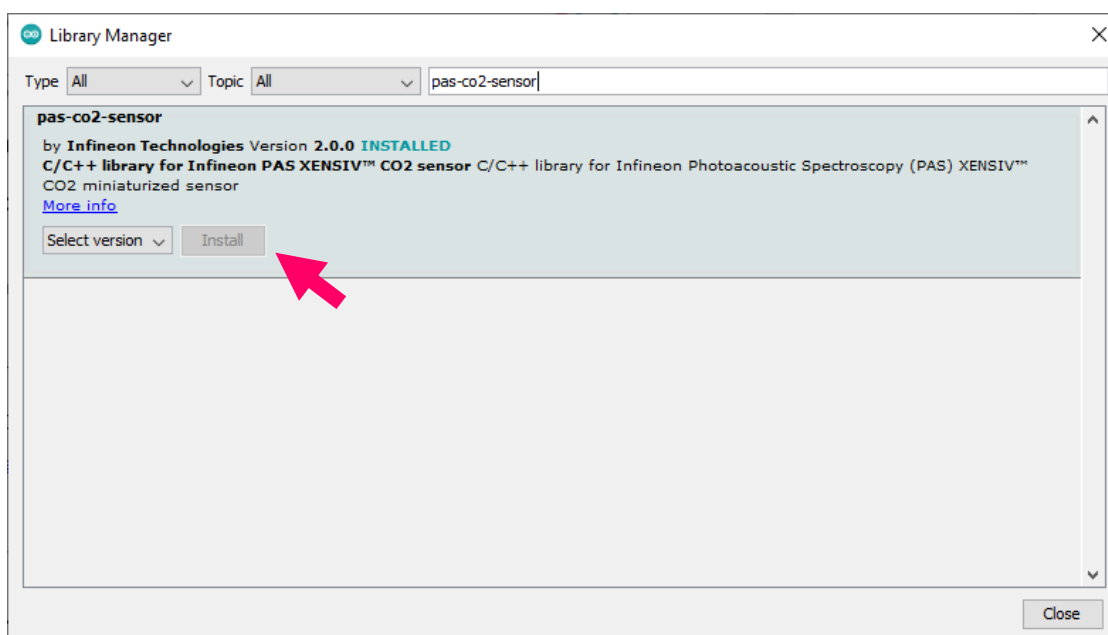
*Note: PSEL and PWM\_DIS are both by default connected to GND on board of XENSIV™ PAS CO2 Shield2Go.*

## Software and library integration

## 2 Software and library integration

### 2.1 Setting up Arduino IDE

1. Install Arduino IDE. If you are new to Arduino, please download the program and install it first. <https://www.arduino.cc/en/software>
2. Install the library. In the Arduino IDE, go to the menu Sketch > Include library > Manage libraries. Type pas-co2-sensor and install the library.



**Figure 6** Installing library in the Arduino library manager

3. In case of using XMC boards as microcontroller, install board package. The official Arduino boards are already available in the Arduino software, but other third-party boards as the Infineon XMC MCU based need to be explicitly included. Follow the instructions in section 3 “Quick start with XMC 2Go” to add the XMC board family to Arduino.

### 2.2 Library overview

The core library is C based and provides a platform-independent driver for the XENSIV™ PAS CO2 sensor. It provides full access to all features of the sensor. The driver consists of 4 files.

**Table 3** Core C driver

| Source code          | Description                                                                       |
|----------------------|-----------------------------------------------------------------------------------|
| xensiv_pasco2_ver.h  | Contains the exact version of the XENSIV™ PAS CO2 sensor                          |
| xensiv_pasco2_regs.h | Contains the register definitions for interacting with the XENSIV™ PAS CO2 sensor |
| xensiv_pasco2.h      | Contains full functions for interacting with the XENSIV™ PAS CO2 sensor           |
| xensiv_pasco2.c      | Contains full functions for interacting with the XENSIV™ PAS CO2 sensor           |

## Software and library integration

Full documentation and overview to the driver can be found on the GitHub.

<https://github.com/Infineon/sensor-xensiv-pasco2>

And the documentation with detail explanation for all macros, enumerations and functions can be found here:

[https://infineon.github.io/sensor-xensiv-pasco2/html/group\\_group\\_board\\_libs.html](https://infineon.github.io/sensor-xensiv-pasco2/html/group_group_board_libs.html)

The Arduino library is using this core C driver with a C++ wrapper to follow the ecosystem design pattern so that Arduino users find in this library what they are used to.

**Table 4**      **Arduino library**

| Source code           | Description                                                                                     |
|-----------------------|-------------------------------------------------------------------------------------------------|
| pas-co2-pal-ino.cpp   | Target platform-specific implementation                                                         |
| pas-co2-platf-ino.hpp | Default board definition and selection by conditional compiling                                 |
| pas-co2-ino.hpp       | Contains functions for interacting with the XENSIV™ PAS CO2 sensor adapted from the core driver |
| pas-co2-ino.cpp       | Contains functions for interacting with the XENSIV™ PAS CO2 sensor adapted from the core driver |

The Arduino library includes 6 examples which the user can modify and use as a reference.

**Table 5**      **Arduino examples**

| Example             | Description                                                                                            |
|---------------------|--------------------------------------------------------------------------------------------------------|
| alarm-notification  | Readout of the sensor CO2 concentration based on threshold crossing and synched via hardware interrupt |
| device-id           | Readout of the sensor devices product and revision identifiers                                         |
| single-shot-mode    | Readout of the sensor CO2 concentration value using single shot measurement mode                       |
| continuous-mode     | Readout of the sensor CO2 concentration value using continuous measurement mode                        |
| forced-compensation | Set CO2 reference offset using forced compensation                                                     |
| early-notification  | Readout of the sensor CO2 concentration based on early notification synched via hardware interrupt     |

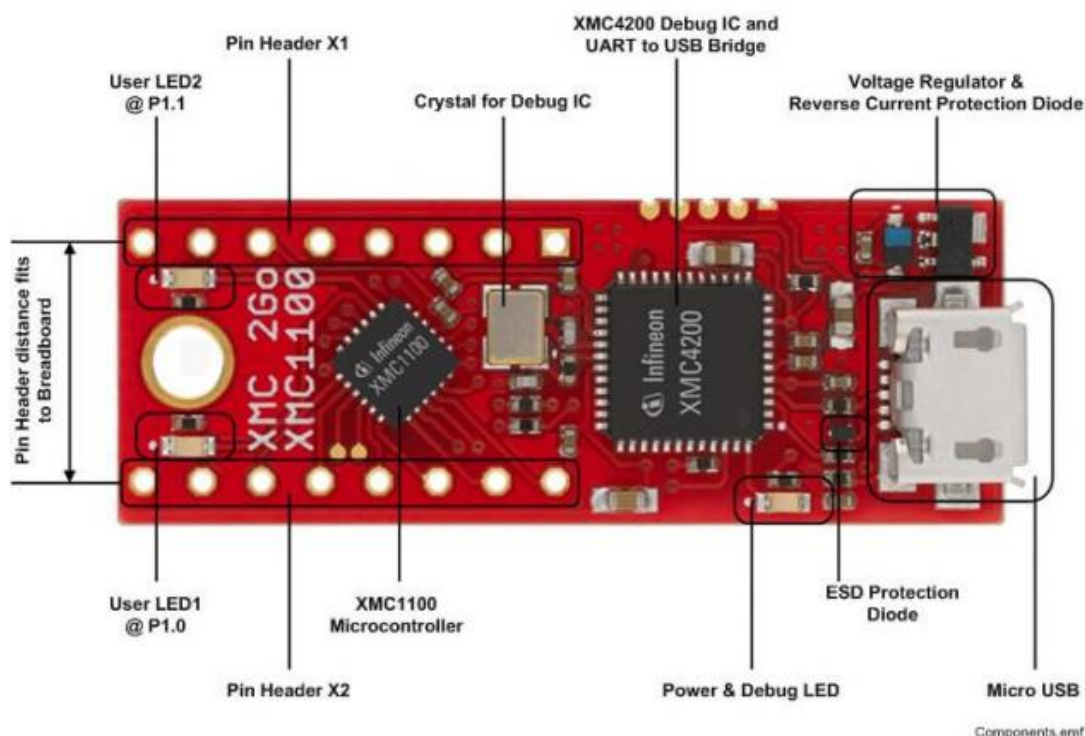
Full documentation of the Arduino library can be found on the GitHub.

<https://github.com/Infineon/arduino-pas-co2-sensor>

## Quick start with XMC 2Go

### 3 Quick start with XMC 2Go

The XMC 2Go is designed to evaluate the capabilities of the XMC1100 Microcontroller and the powerful, free of charge tool chain DAVE™. Thanks to the standardized form factor of the XENSIV™ PAS CO2 Shield2Go it is directly compatible with the XMC 2Go and can be used easily used in combination by plugging the XENSIV™ PAS CO2 Shield2Go on top of the XMC 2Go. But one important thing to consider is that the 5 V supply for the XENSIV™ PAS CO2 Shield2Go is not provided by the XMC 2Go and therefore needs to be supplied externally.



**Figure 7 XMC 2Go Kit board overview**

**Table 6 Features of the XMC 2Go Kit with XMC1100**

| Topic            | Features                                                                                                                                                                                            |
|------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Processor        | XMC1100 microcontroller (ARM® Cortex™-M0 based) in a 4 x 4 mm VQFN-24 package                                                                                                                       |
| Flash            | 64 kB                                                                                                                                                                                               |
| RAM              | 16 kB                                                                                                                                                                                               |
| Clock Generation | Internal Oscillator                                                                                                                                                                                 |
| Frequencies      | 32 MHz CPU clock, 64 MHz Timer clock                                                                                                                                                                |
| Dimensions       | 14.0 x 38.5 mm                                                                                                                                                                                      |
| Power Supply     | from USB via Debug probe (J-Link) or 3.3V external power                                                                                                                                            |
| Connectors       | Two 8-pin header (pin pitch: 2.54 mm $\pm$ 0.1" / between rows: 10.16 mm $\pm$ 0.4")<br>Pin header fits to breadboard                                                                               |
| Debugger         | On-Board J-Link Debugger supports <ul style="list-style-type: none"> <li>Serial Wire Debug (SWD, ARM Standard)</li> <li>Single Pin Debug (SPD)</li> <li>UART-to-USB bridge (virtual COM)</li> </ul> |

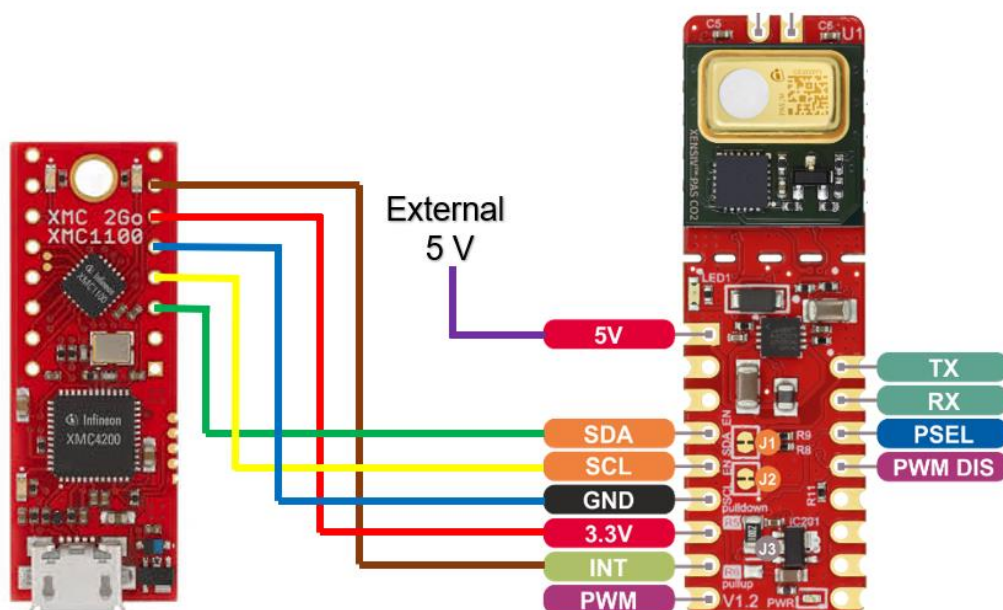
## Quick start with XMC 2Go

|             |                                                                                                                                                                                                                                                                                                                                                                                    |
|-------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Peripherals | Mapped to pin header X1/X2: <ul style="list-style-type: none"> <li>• 2 Channel USIC (UART, SPI, I2C, I2S, LIN)</li> <li>• 6 Channel Analog to Digital Converter (12-Bit resolution)</li> <li>• External Interrupts (via ERU)</li> <li>• 4 x 16-Bit Timer</li> </ul> Others: <ul style="list-style-type: none"> <li>• Real Time Clock</li> <li>• Random Number Generator</li> </ul> |
| Others      | 2 User LEDs @ P1.0 and P1.1                                                                                                                                                                                                                                                                                                                                                        |

More and detailed information can be found on the dedicated XMC 2Go product page.

[https://www.infineon.com/cms/de/product/evaluation-boards/kit\\_xmc\\_2go\\_xmc1100\\_v1/](https://www.infineon.com/cms/de/product/evaluation-boards/kit_xmc_2go_xmc1100_v1/)

### 3.1 Step by step CO2 concentration readout example



**Figure 8** XENSIV™ PAS CO2 Shield2Go I<sup>2</sup>C interface connection to XMC 2Go

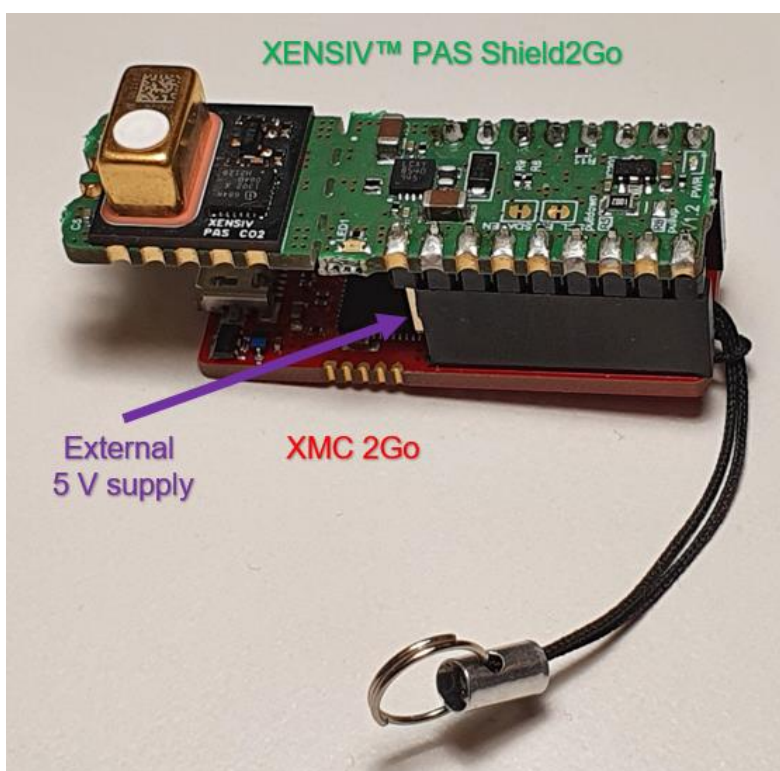
**Table 7** Pin connections

| Position | Symbol   | Connection to the XMC 2Go                                                  |
|----------|----------|----------------------------------------------------------------------------|
| 1        | VDD5     | Not available on XMC 2Go, 5 V power supply needs to be supplied externally |
| 2        | NC       | Not connected                                                              |
| 3        | NC       | Not connected                                                              |
| 4        | P11: SDA | I <sup>2</sup> C data pin (3.3 V domain)                                   |
| 5        | P10: SCL | I <sup>2</sup> C clock pin (3.3 V domain)                                  |

## Quick start with XMC 2Go

|    |                     |                              |
|----|---------------------|------------------------------|
| 6  | GND                 | Ground                       |
| 7  | VDD3V3              | 3.3 V power supply           |
| 8  | P9: INT             | Digital pin D9               |
| 9  | P8: PWM             | Not connected (in this case) |
| 10 | P7: TX              | Not connected (in this case) |
| 11 | P6: RX              | Not connected (in this case) |
| 12 | P5: RST (PSEL)      | Not connected (in this case) |
| 13 | P4: GPIO1 (PWM_DIS) | Not connected (in this case) |
| 14 | NC                  | Not connected                |
| 15 | NC                  | Not connected                |
| 16 | NC                  | Not connected                |
| 17 | NC                  | Not connected                |

Figure 8 is just to visualize the connection because the XENSIV™ PAS CO2 Shield2Go can be simply stacked on top of the XMC 2Go via pin headers as seen in figure 9.



**Figure 9** XENSIV™ PAS CO2 Shield2Go I²C interface connection to XMC 2Go

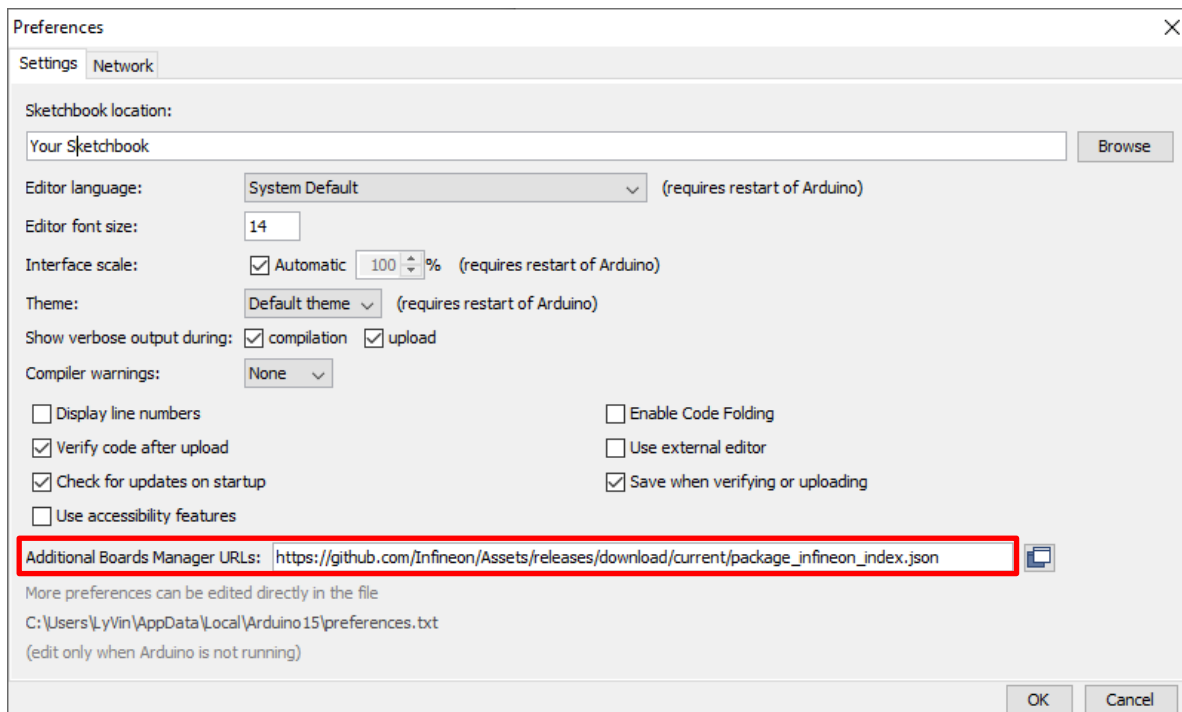
In order to use and program the Infineon XMC microcontrollers in the Arduino IDE, SEGGER J-Link must be installed first. Please follow the link to SEGGER J-Link and install the J-Link Software and Documentation Pack for your operating system. If you have already installed 'DAVE™ - Development Platform for XMC™ Microcontrollers', you can skip this step as the respective drivers/programs are already installed on your system.

<https://www.segger.com/downloads/jlink>

## Quick start with XMC 2Go

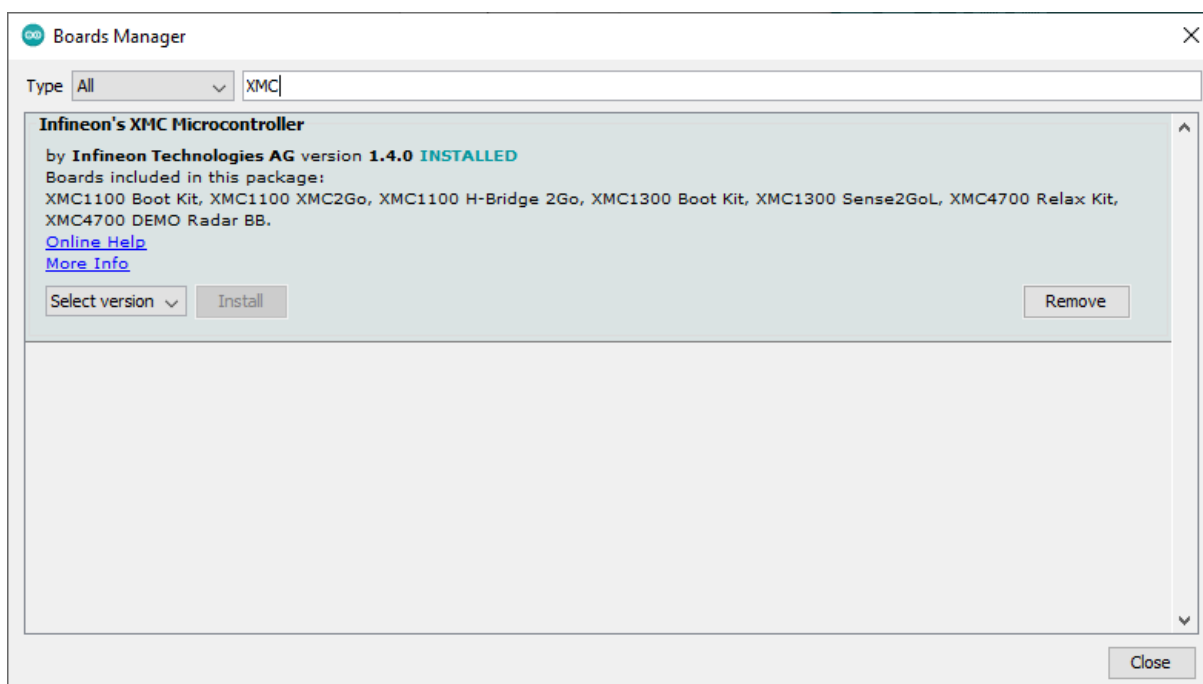
Afterwards Infineon's microcontroller boards can be added to the Arduino IDE by pasting the following URL into the 'Additional Boards Manager URLs' input field under **File > Preferences**.

[https://github.com/Infineon/Assets/releases/download/current/package\\_infineon\\_index.json](https://github.com/Infineon/Assets/releases/download/current/package_infineon_index.json)



**Figure 10** Adding XMC boards to the Arduino IDE in the 'Preference' section

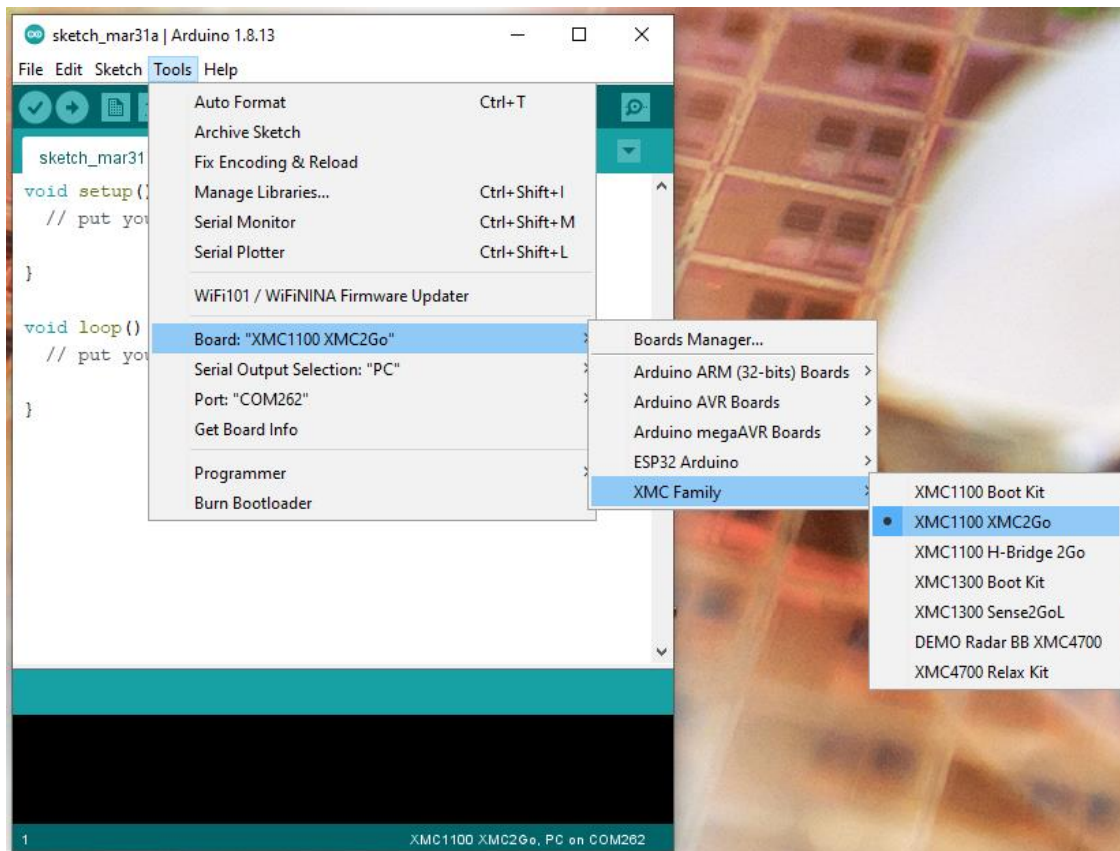
To install the boards, please navigate to **Tools > Board > Boards Manager...** and search for XMC. You will find options to install the board files for the microcontrollers. Click "Install" to add the boards to your Arduino IDE.



**Figure 11** Installing XMC microcontroller board files

## Quick start with XMC 2Go

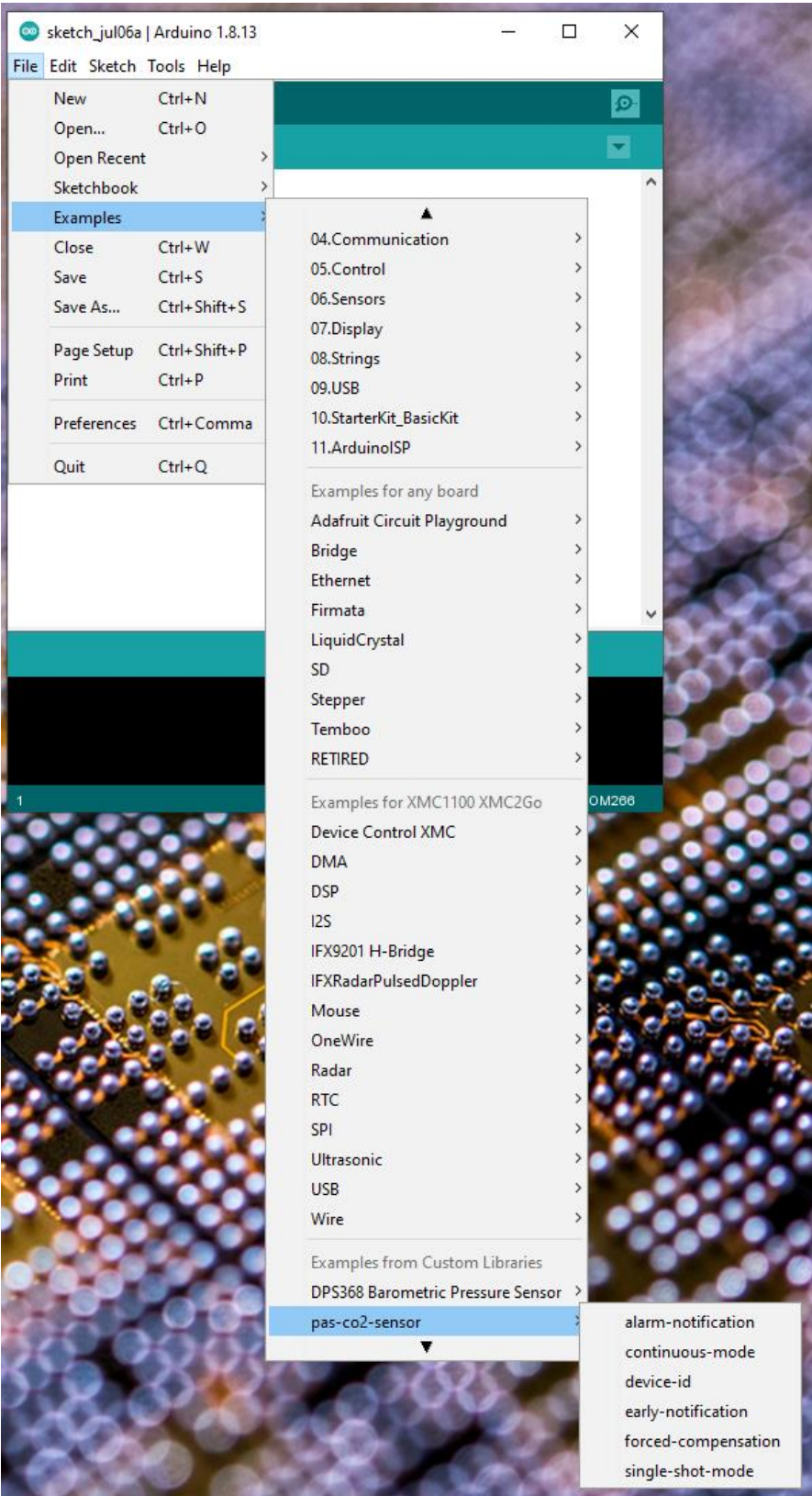
In the boards list **Tools > Board**, the XMC microcontroller boards are added and can be used from now on. After that make sure to select the respective board (**XMC1100 XMC2Go**) and COM port in the Tools dropdown menu.



**Figure 12**      **Selecting XMC 2Go board**

## Quick start with XMC 2Go

With everything ready, one of the library examples can now be opened, uploaded and run. The library examples provided can be opened in **File > Examples > pas-co2-sensor**.

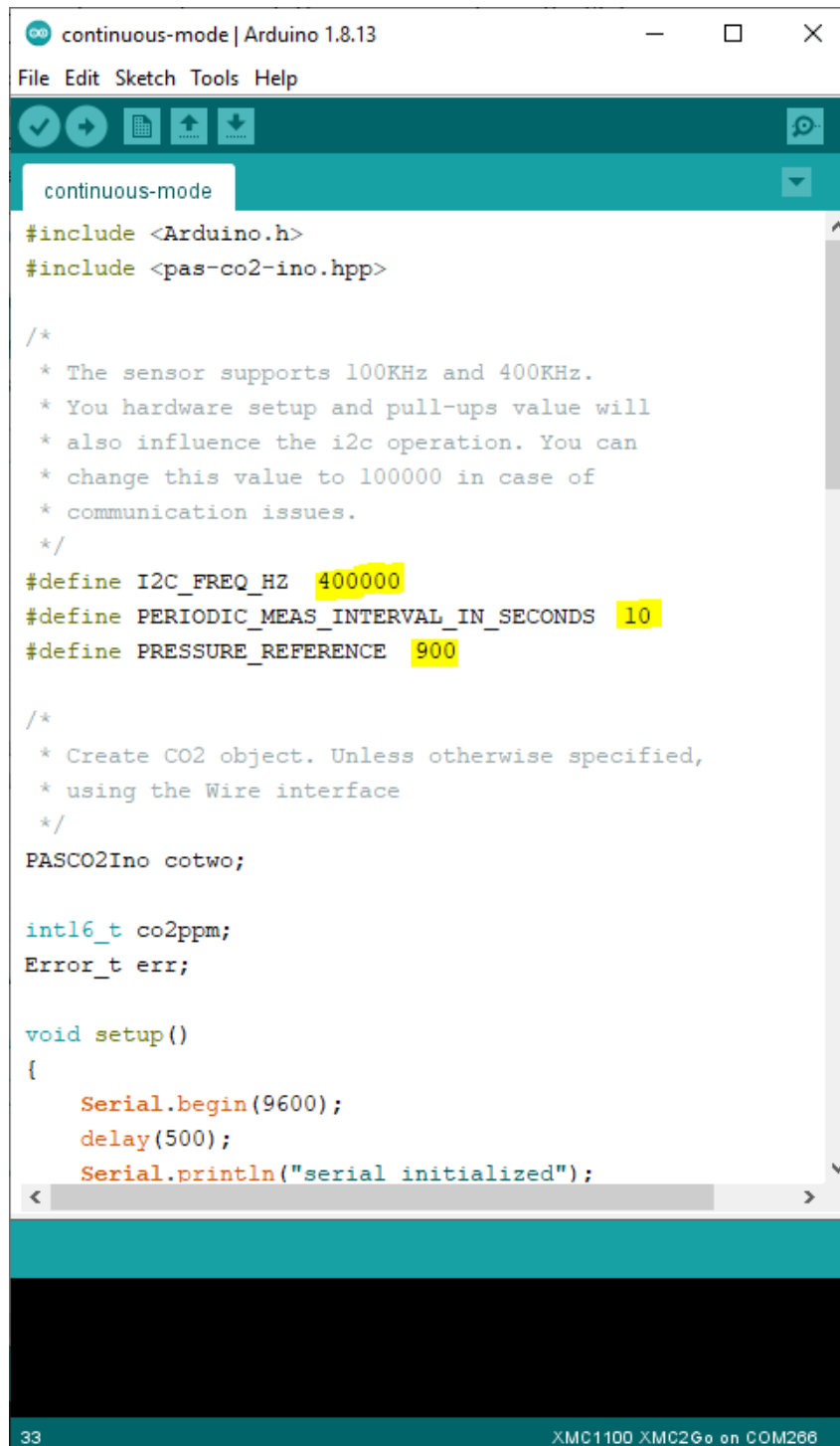


**Figure 13**      **Arduino library examples**

## Quick start with XMC 2Go

In this case the serial-periodic example is used. The user can configure the I<sup>2</sup>C frequency, measurement period and reference pressure. The sensor supports both standard-mode (100 kHz) and fast-mode (400 kHz). In case of communication issues, it is recommended to lower the frequency to the standard-mode. For the measurement period the default value is 10 s and it is recommended to not go lower than that. In this example the pressure is set to 900 hPa. For correct operation, the user shall ensure that the pressure value programmed is within the specified pressure operating range of the device. This valid range of operation is 750 hPa to 1150 hPa.

Pressure must be set between 750 hPa and 1150 hPa



```

continuous-mode | Arduino 1.8.13
File Edit Sketch Tools Help

continuous-mode

#include <Arduino.h>
#include <pas-co2-ino.hpp>

/*
 * The sensor supports 100KHz and 400KHz.
 * You hardware setup and pull-ups value will
 * also influence the i2c operation. You can
 * change this value to 100000 in case of
 * communication issues.
 */
#define I2C_FREQ_HZ 400000
#define PERIODIC_MEAS_INTERVAL_IN_SECONDS 10
#define PRESSURE_REFERENCE 900

/*
 * Create CO2 object. Unless otherwise specified,
 * using the Wire interface
 */
PASCO2Ino cotwo;

int16_t co2ppm;
Error_t err;

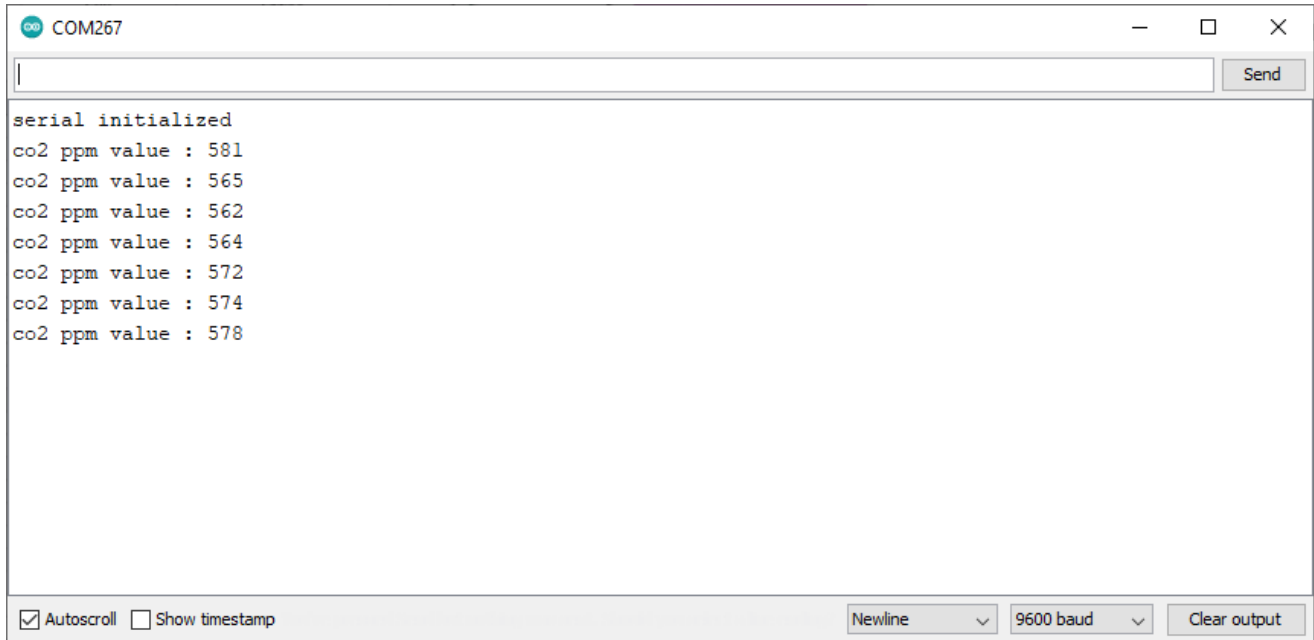
void setup()
{
    Serial.begin(9600);
    delay(500);
    Serial.println("serial initialized");
}
    
```

**Figure 14** Arduino library example continuous-mode

## Quick start with XMC 2Go

Remember to connect the 5 V pin prior to starting sensor

Ensure J-Link is installed before compiling



The screenshot shows a serial terminal window with the title 'COM267'. The output text is as follows:

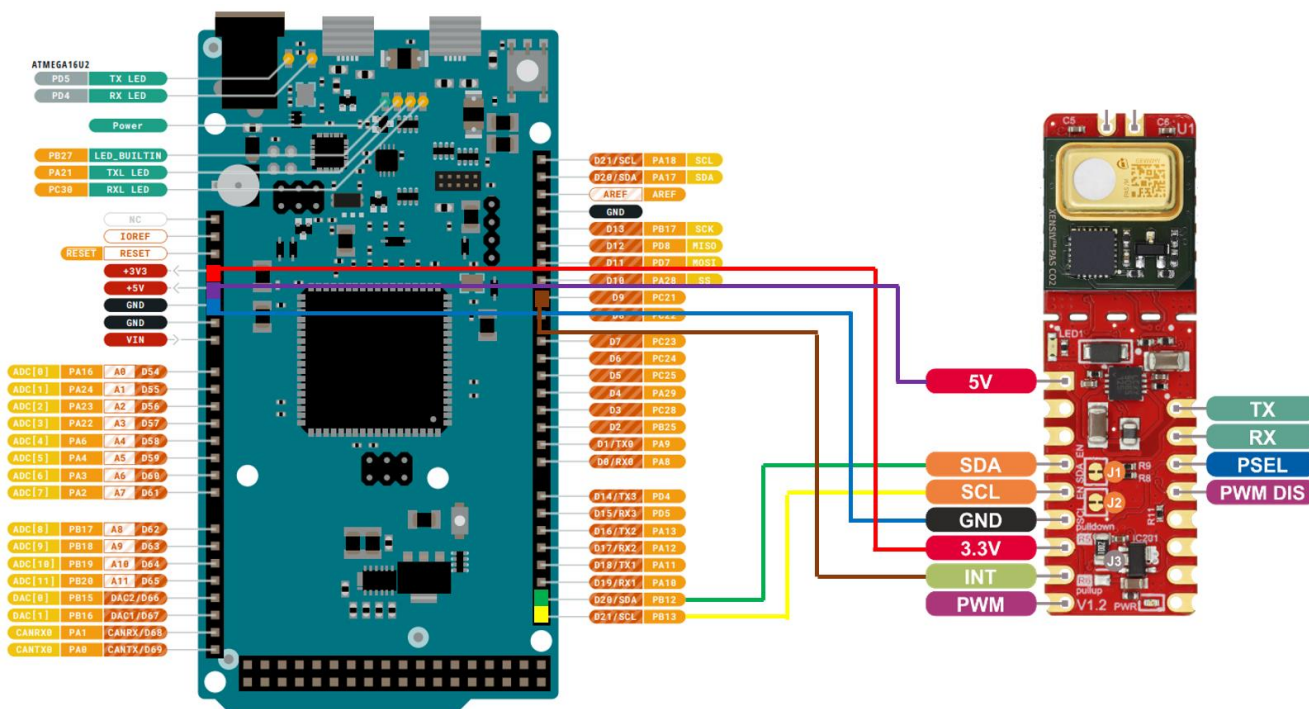
```
serial initialized
co2 ppm value : 581
co2 ppm value : 565
co2 ppm value : 562
co2 ppm value : 564
co2 ppm value : 572
co2 ppm value : 574
co2 ppm value : 578
```

At the bottom of the window, there are controls: a checked 'Autoscroll' checkbox, an unchecked 'Show timestamp' checkbox, a 'Newline' dropdown menu, a '9600 baud' dropdown menu, and a 'Clear output' button.

**Figure 15** Serial-periodic CO2 results output

## Quick start with Arduino Due

## 4 Quick start with Arduino Due

Figure 16 XENSIV™ PAS CO2 Shield2Go I²C interface connection to Arduino Due<sup>3)</sup>

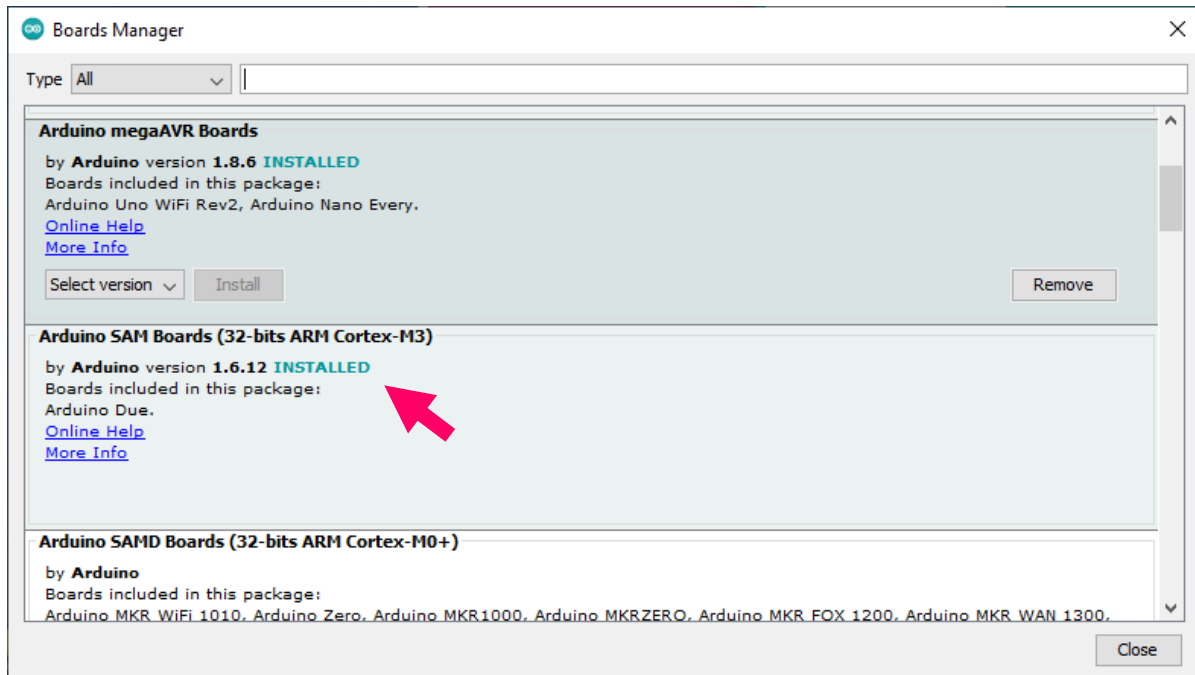
<sup>3)</sup> Pinout of Arduino Due from [https://content.arduino.cc/assets/Pinout-Due\\_latest.pdf](https://content.arduino.cc/assets/Pinout-Due_latest.pdf)

Table 8 Pin connections

| Position | Symbol              | Connection to the Arduino Due |
|----------|---------------------|-------------------------------|
| 1        | VDD5                | 5 V power supply              |
| 2        | NC                  | Not connected                 |
| 3        | NC                  | Not connected                 |
| 4        | P11: SDA            | I²C data pin (3.3 V domain)   |
| 5        | P10: SCL            | I²C clock pin (3.3 V domain)  |
| 6        | GND                 | Ground                        |
| 7        | VDD3V3              | 3.3 V power supply            |
| 8        | P9: INT             | Digital pin D9                |
| 9        | P8: PWM             | Not connected (in this case)  |
| 10       | P7: TX              | Not connected (in this case)  |
| 11       | P6: RX              | Not connected (in this case)  |
| 12       | P5: RST (PSEL)      | Not connected (in this case)  |
| 13       | P4: GPIO1 (PWM_DIS) | Not connected (in this case)  |
| 14       | NC                  | Not connected                 |
| 15       | NC                  | Not connected                 |
| 16       | NC                  | Not connected                 |
| 17       | NC                  | Not connected                 |

## Quick start with Arduino Due

Similar as with the XMC 2Go the Arduino Due board package needs to be installed first. As it is not a third-party board like the XMC 2Go, the right package “Arduino SAM Boards” (32-bit ARM® Cortex-M3) which is including the Arduino Due can be directly added with the board manager.



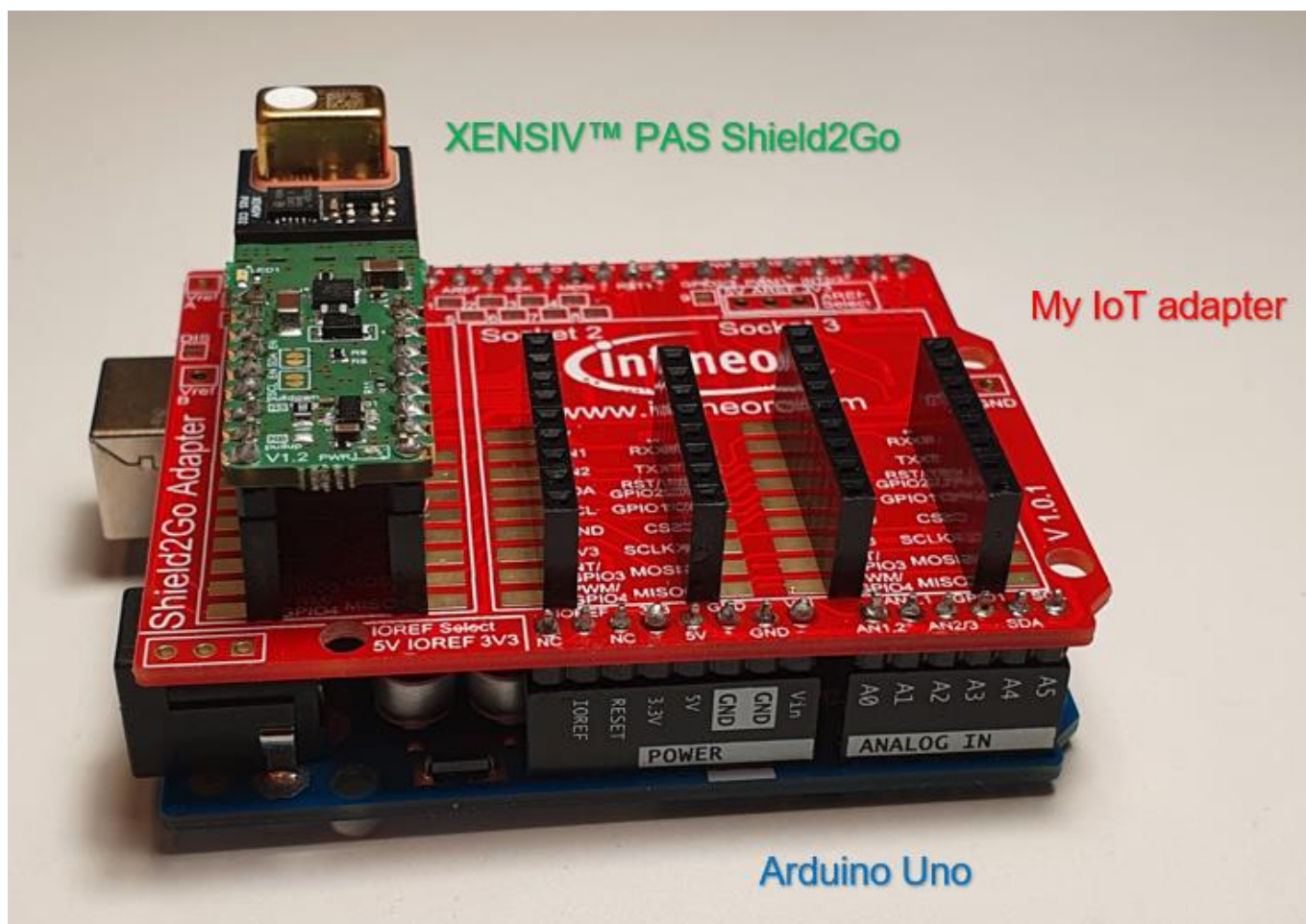
**Figure 17**      **Arduino IDE settings: adding Arduino Due with the board manager**

Afterwards the exact same steps with selecting the right board/COM port and opening, uploading and running a library example can be done as instructed previously with the XMC 2Go.

## Quick start with Arduino Uno and My IoT adapter

### 5 Quick start with Arduino Uno and My IoT adapter

As introduced in section 1.2 the XENSIV™ PAS CO2 Shield2Go in combination with the My IoT adapter can be simply stacked on top of the Arduino Uno via pin headers. Pin allocation, level shifting and system integration is already covered.



**Figure 18** XENSIV™ PAS CO2 Shield2Go with My IoT adapter stacked to Arduino Uno<sup>4)</sup>

<sup>4)</sup> Pinout of Arduino Due from <https://docs.arduino.cc/hardware/uno-rev3>

Afterwards the exact same steps with selecting the right board/COM port and opening, uploading and running a library example can be done as instructed previously with the XMC 2Go.

In case of any technical questions please visit our community forum and have a look if similar questions are already posted or create a new one.

<https://community.infineon.com/t5/CO-sensor/bd-p/CO2Sensors>

Appendix

6 Appendix

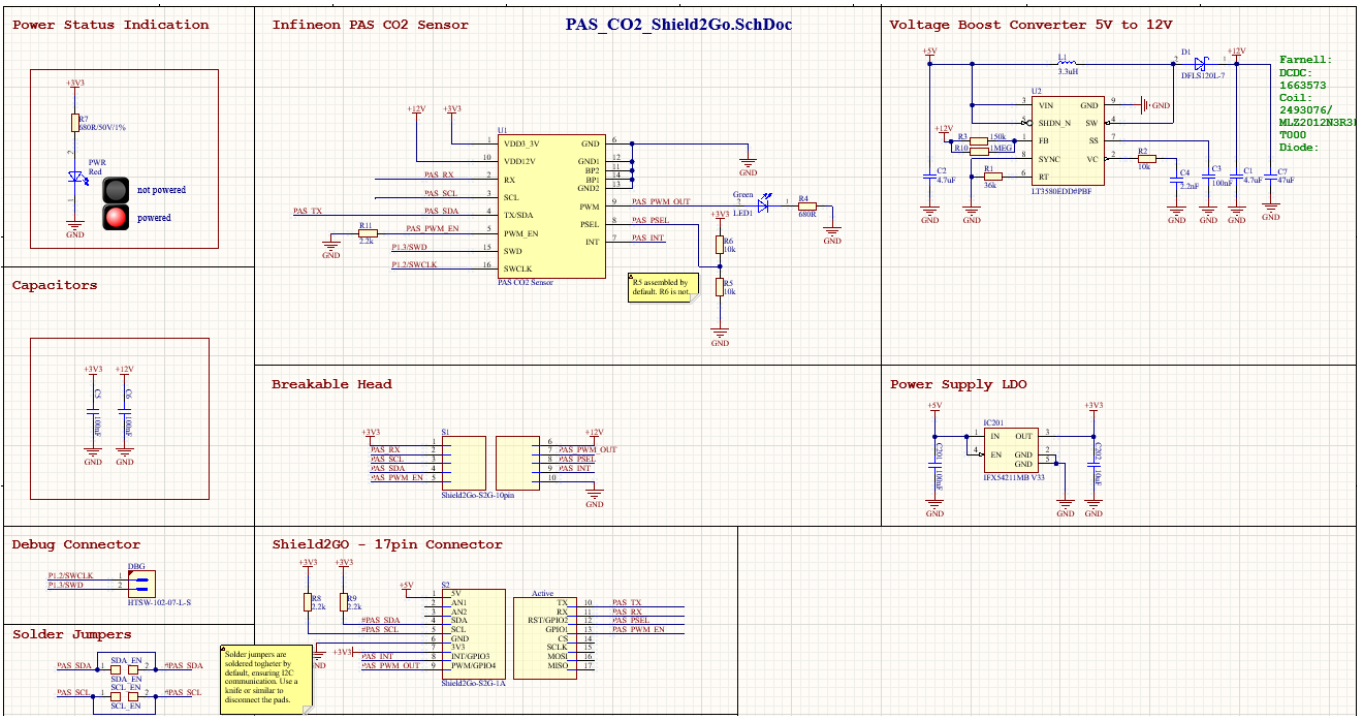


Figure 19 XENSIV™ PAS CO2 Shield2Go schematic

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## Revision history

### Revision history

| Document version | Date of release | Description of changes                                                  |
|------------------|-----------------|-------------------------------------------------------------------------|
| V 1.0            | 01.04.2022      | Creation                                                                |
| V 1.1            | 01.07.2022      | Update library overview and figures, added example using My IoT adapter |
| V1.2             | 15.08.2022      | Highlighting important notes                                            |
|                  |                 |                                                                         |

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