

# ModusToolbox™ DFU Host tool user guide

ModusToolbox<sup>™</sup> tools package version 3.2.0

DFU Host tool version 2.20.0

A newer revision of this document may be available on the web here.

## About this document

#### Scope and purpose

The Device Firmware Update (DFU) Host tool is a stand-alone program included with the ModusToolbox<sup>™</sup> software. This tool is used to communicate with PSoC<sup>™</sup> 6, PSoC<sup>™</sup> 4, PSoC<sup>™</sup> Edge, and XMC<sup>™</sup>7000 MCUs that have already been programmed with an application that includes the DFU capability.

#### Intended audience

This document helps application developers understand how to use the DFU Host tool as part of creating a ModusToolbox<sup>™</sup> application.

Convention	n Explanation		
Bold	Emphasizes heading levels, column headings, menus and sub-menus		
Italics	Denotes file names and paths.		
Courier New	Denotes APIs, functions, interrupt handlers, events, data types, error handlers, file/folder names, directories, command line inputs, code snippets		
File > New	Indicates that a cascading sub-menu opens when you select a menu item		

#### **Reference documents**

Refer to the following documents for more information as needed:

- <u>ModusToolbox™ tools package user guide</u>
- <u>Eclipse IDE for ModusToolbox<sup>™</sup> user guide</u>
- <u>VS Code for ModusToolbox™ user guide</u>
- <u>KitProg3 user guide</u>



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#### Overview

## 1 Overview

The DFU Host tool is provided as a graphical user interface (GUI) and a command-line interface (CLI).

Eile Actions View Help		
File: er/common/tools/bootloaderhost/cybootloaderhosttest/test_files/ Ports: Filters KitProg3-1718126C03227400 - I2C KitProg3-1718126C03227400 - SPI WICED HCI UART (COM6) - UART WICED Peripheral UART (COM7) - UART KitProg3 USB-UART (COM8) - UART Intel(R) Active Management Technology - SOL (COM3) - UART	cybootloaderhostte Clock speed: Shift direction MSB first LSB first	st/acd.cyacd2 1 MHz ~ Mode (a) Mode 00 (b) Mode 01 (c) Mode 11 (c) Mode 11
Log:		

This tool allows you to:

- Program new application data onto the supported MCU device using supported input files. See <u>Supported</u> <u>devices and file formats</u>.
- Verify the program data that is already contained on the device.
- Erase the application from the device.
- Select the \*.mtbdfu file output from a ModusToolbox<sup>™</sup> application in order to program, write, read, erase and communicate with the device.
- Abort the current operation.

*Note:* This operation leaves the device in whatever state it is in when the abort message is acted upon.

The DFU Host tool supports communicating via I<sup>2</sup>C, SPI, UART, and USB-CDC. They are displayed to configure their settings and view the programming status. For I<sup>2</sup>C and SPI, supported MCU should include the KitProg3 firmware module or other bridge interface, which implements USB-UART, USB-I<sup>2</sup>C, and USB-SPI bridges. For UART, communication can be done directly from the PC simply by connecting an appropriate cable.

Note: The process of initializing the device, two CPUs therein, and executing code in the SROM and supervisory flash, is referred to as "bootloading". The process of installing and updating applications in the field is referred to as "device firmware update". This process uses standard communication channels (UART, I<sup>2</sup>C, USB, etc.) to download new applications from a host.



Supported devices and file formats

## 2 Supported devices and file formats

All MCUs can be used with the all files formats.

Device	File/format			Link	
МСИ	*.mtbdfu	*.hex file	*.cyacd2		
PSoC™ 6	~	~	✓	https://www.infineon.com/cms/en/product/microcontroll er/32-bit-psoc-arm-cortex-microcontroller/psoc-6-32-bit- arm-cortex-m4-mcu/	
PSoC™ 4	~	~	~	https://www.infineon.com/cms/en/product/microcontroll er/32-bit-psoc-arm-cortex-microcontroller/psoc-4-32-bit- arm-cortex-m0-mcu/	
XMC7000	~	~	×	https://www.infineon.com/cms/en/product/microcontroll er/32-bit-industrial-microcontroller-based-on-arm-cortex- m/32-bit-xmc7000-industrial-microcontroller-arm-cortex- m7/	
PSoC™ Edge	~	~	×	https://www.infineon.com/cms/en/product/microcontroll er/32-bit-psoc-arm-cortex-microcontroller/32-bit-psoc- edge-arm/	



### Example code

## 3 Example code

We provide source code for the DFU Host tool in the installation directory, as follows:

- Windows/Linux: ~/ModusToolbox/tools\_<version>/dfuh-tool/sample\_code/
- **Linux**: ~/ModusToolbox/tools\_<version>/dfuh-tool/share/dfuh-tool/sample\_code/
- **macOS**: /Applications/ModusToolbox/tools\_<version>/dfuh-tool/dfuh-tool.app/Contents/sample\_code/

Use this source code as a reference to build your own tool. Refer to the README.md file for instructions on how to install the required dependencies and build the DFU Host Tool.

Note: This example requires CMake 3.21 or later.



## Quick start

## 4 Quick start

This section contains a simple workflow for how to use the DFU Host tool.

- 1. Ensure that you have a supported MCU that has been programmed with an application that includes the DFU capability.
- 2. Launch the DFU Host tool GUI.
- 3. Click **File > Open** to browse to the location of your application file (\*.cyacd2/\*.mtbdfu/\*.hex).
- 4. Connect a hardware port that supports the communication selected in your bootloader project.
- 5. Wire the hardware port pins to the corresponding pins on the target device.
- 6. Update the <u>port configuration</u>. These values are set from the communication component used by the bootloader component.
- 7. Click **Program/Execute** to load the new application from \*.cyacd2/\*.hex file and to execute and send the commands from the .mtbdfu file.



Launch the DFU Host tool

## 5 Launch the DFU Host tool

There are several ways to launch the DFU Host tool, and those ways depend on how you use the various tools in ModusToolbox<sup>™</sup> software.

## 5.1 make command

As described in the <u>ModusToolbox<sup>™</sup> tools package user guide</u> "Build System" chapter, you can run numerous make commands in the application directory, such as launching the DFU Host tool. After you have created a ModusToolbox<sup>™</sup> application, navigate to the application directory and type the following command in the appropriate bash terminal window:

make dfuh-tool

This command opens the DFU Host tool GUI for the specific application in which you are working.

## 5.2 VS Code and Eclipse

VS Code and Eclipse have tools to launch the DFU Host tool from within an open application. Refer to the applicable user guide for more details:

- <u>VS Code for ModusToolbox<sup>™</sup> user guide</u>
- Eclipse IDE for ModusToolbox<sup>™</sup> user guide

## 5.3 Executable (GUI)

You can launch the DFU Host tool as a stand-alone tool without the Eclipse IDE. By default, it is installed here:

<install\_dir>/ModusToolbox/tools\_3.2/dfuh-tool>

On Windows, you can launch the tool from the **Start** menu. For other operating systems, the installation directory will vary, based on how the software was installed.

## 5.4 Executable (CLI)

Refer to <u>CLI Description</u> to run the *dfuh-cli* tool. You can also run the DFU Host tool GUI executable using the following command line arguments:

-?, -h,help	Displays help on command line options.
help-all	Displays help including Qt specific options.
-v,version	Displays version information.
debug <filename></filename>	Appends logging information to the specified file.



### **GUI description**

## 6 GUI description

### 6.1 Menus

### 6.1.1 File

- **Open...** Opens an existing input file of the supported formats. If a file is already open, it will be closed.
- **Save Log As...** Opens the dialog to save the log file in a specified location.
- **Clear Log** Clears the current log.
- **Exit** Closes the DFU Host tool.

### 6.1.2 Actions

- **Program** Programs the application to the device.
- **Execute** Executes the .mtbdfu file on the host, establishes a DFU session with the target and processes the DFU commands
- **Verify** Verifies the programming of the device.
- Erase All Erases the program from the device.
- **Abort** Aborts the action.

### 6.1.3 View

• Toolbar – Shows/hides the toolbar.

## 6.1.4 Help

- View Help Opens this document.
- **About** Opens the About box for version information, with links to open <u>https://www.infineon.com</u> and the current session log file.

## 6.2 Main window

File Actions View H	elp
🝺 🔕 🔕 🔊	8
File: Id/APP_CY8CPROTO-	062-4343W/Debug/mtb-example-psoc6-capsense-buttons-slider.hex
File Version:	0x1
Product ID:	01020304
Packet Checksum Type:	0x0
	Generate
Ports: Intel(R) Active Manageme < Log:	Filters     Baud:     115200 ~       ent Technology - SOL (COM3) -     Data bits:     8 ~       Stop bits:     1 ~       Parity:     None ~
2023-05-16 14:49:21.733 P 2023-05-16 14:50:39.842 V 2023-05-16 14:50:39.848 V 2023-05-16 14:50:39.848 V 2023-05-16 14:50:45.075 O	rogramHex.mtbdfu was generated. erify started. erifyHex.mtbdfu was generated. Iperation took 5229 milliseconds.



### **GUI description**

## 6.2.1 File selection

Use this section to select the input file, which contains the DFU commands/firmware image.

## 6.2.2 Ports

This is a list of all the ports attached to the computer that can be used to communicate with the bootloader. Based on which item is selected, different options are available for the Port Configuration.

## 6.2.3 Filters

The Filters button allows for restricting which ports are displayed in the ports list.

Filters - Device Firmware X		
Show I2C ports		
Show SPI ports		
Show UART ports		
OK Cancel		

## 6.3 Port configuration

This section allows for configuring the interface-specific options for communicating with the DFU system. This is necessary to ensure both the DFU and host computer are configured the same.

Refer to the appropriate probe documentation for a list of supported modes.

*Note:* Not all SPI and UART communication properties combinations are supported.

## 6.3.1 l<sup>2</sup>C

For I<sup>2</sup>C communication, there are two required parameters:

I2C address: 12	
I2C speed	
🔘 1 MHz	
400 kHz	
🔘 100 kHz	
🔘 50 kHz	
L	

- The address of the I<sup>2</sup>C-based target DFU system with which the host is communicating. The range for valid addresses is from 8 120.
- The I<sup>2</sup>C SCK signal frequency.

## 6.3.2 SPI

For SPI communication, there are three required parameters:

Clock speed:	2 MHz 🔹
Shift direction	Mode
MSB first	Mode 00
🔘 LSB first	Mode 01
	Mode 10
	Mode 11



### **GUI description**

- The SPI SCLK signal frequency.
- The bit ordering of transferred data.
- The SPI operating mode.

## 6.3.3 UART and USB\_CDC

For UART/USB\_CDC communication, there are four required parameters:

Baud:	115200	•
Data bits:	8	•
Stop bits:	1	•
Parity:	None	•

- The baud (bit) rate at which data is transferred.
- The number of data bits per byte.
- The number of stop bits indicating the termination of a byte.
- The parity bit that is added to a byte.

## 6.4 Log

The log displays the history of what happened while the host was open:

- when operations started/completed
- information about user-initiated operations
- error messages during an operation if any.

## 6.5 Errors

Any errors for various fields display as a red X in the field containing the error, and it contains a tooltip when you hover the mouse cursor on it.



## **CLI description**

## 7 CLI description

In addition to the *dfuh-tool* GUI executable, there is also the *dfuh-cli* executable. The CLI allows programming, verifying, and erasing devices from a command-line prompt or from within batch files or shell scripts. The exit code for the *dfuh-cli* executable is zero if the operation is successful, or non-zero if the operation encounters an error.

To use the *dfuh-cli* executable, provide one of the following flags:

program-device <cyacd2_file></cyacd2_file>	Programs the device with the specified file and exits.
verify-device <cyacd2_file></cyacd2_file>	Verifies the programming of the device with the specified file and exits.
erase-device <cyacd2_file></cyacd2_file>	Erases the specified program from the device and exits.
custom-command <mtbdfu_file></mtbdfu_file>	Sends an .mtbdfu file (JSON format) as the input to the DFU Host tool.
generate-mtbdfu <mtbdfu_file></mtbdfu_file>	Generates an .mtbdfu file from the provided input arguments.

If there is more than one device connected to the host, use the following flag to specify which device to use:

huid (etring)	Specifies the ID of the hardware to program/verify/erase. If this option is skipped, the first
IIWIG (String)	appropriate device found will be used.

### The .mtbdfu generation flags:

product-id <hex></hex>	Sets the product ID as a parameter for the generated .mtbdfu file.
file-version <hex></hex>	Sets the file version as a parameter for the generated .mtbdfu file.
checksum-type <hex></hex>	Sets packet checksum type as a parameter for generated .mtbdfu file.
application-id <hex></hex>	(Optional) Sets the application ID as a parameter for the generated .mtbdfu file. Required only for legacy devices or devices with the DFU-MW-based bootloader.
application-start <hex></hex>	(Optional) Sets the application start address as a parameter for the generated .mtbdfu file. Required only for legacy devices or devices with the DFU-MW-based bootloader.
application-length <hex></hex>	(Optional) Sets the application size as a parameter for the generated .mtbdfu file. Required only for legacy devices or devices with the DFU MW based bootloader.
flash-row-length <hex></hex>	(Optional) Sets the flash row length on the device.
timeout-ms <hex></hex>	(Optional) Alters the timeout for the response packet(milliseconds). Also, applicable to .cyacd2 files usage.

*Note:* The above flags are also used to program the .hex file because it generates an .mtbdfu file and uses the same for programming the .hex file.

Note: The options "--application-start" and "--application-length" can be used to set the address range for filtering the needed part of the .hex file. All extended linear address blocks before the "-application-start" address will be skipped as well as all the data at addresses after "--application-length" address.

In addition, you must provide the appropriate configuration values for one of the following protocols:

#### The **I**<sup>2</sup>**C** flags:

i2c-address <int></int>	Sets the address for the I <sup>2</sup> C protocol. Valid values are between 8 (0x08), and 120 (0x78).
i2c-speed <int></int>	Sets the speed for the I <sup>2</sup> C protocol in kHz. Common values are 50, 100, 400, and 1000.



## **CLI description**

The **SPI** flags:

spi-clockspeed <float></float>	Sets the clock speed for the SPI protocol in MHz.
spi-mode <int></int>	Sets the mode for the SPI protocol in binary. Valid values are 00, 01, 10, and 11.
spi-lsb-first	Specifies that the least-significant bit should be sent first for the SPI protocol. Otherwise, the most-significant bit will be sent first.

#### The **UART** flags:

uart-baudrate <int></int>	Sets the baud rate for the UART protocol.
uart-databits <int></int>	Sets the number of data bits for the UART protocol.
uart-paritytype <string></string>	Sets the parity type for the UART protocol. Valid strings are "None", "Odd", and "Even".
uart-stopbits <float></float>	Sets the stop bits for the UART protocol. Valid values are 1, 1.5, and 2.

*Note:* The DFU Host tool does not require any additional parameters to select the required interface besides the above specified parameters.

## 7.1 Command-line flags

The following flags change the overall functioning of the tool:

-?, -h,help	Displays information about all valid command-line arguments and exits.
-v,version	Displays the version information and exits.
debug	Outputs debugging information to the terminal running the CLI tool during programming, verifying or erasing.
display-hw	Outputs all compatible hardware attached to the computer and exits.

## 7.2 CLI example

The following shows simple examples for using the *dfuh-cli* executable

## 7.2.1 Programming an image via \* .cyacd2 file

1. To program an image using the .cyacd2 file under l<sup>2</sup>C: dfuh-cli.exe --program-device test\_app.cyacd2 --i2c-address 8 --i2c-speed 100

## 7.2.2 Generating and programming an image via \* .mtbdfu file and \*.hex file

- 1. To generate an .mtbdfu file (without metadata): dfuh-cli.exe --generate-mtbdfu test\_gen.mtbdfu --mtbdfu-data-file blinky\_cm4\_crc.hex --file-version 0x1 --product-id 01020304 --checksum-type 0x0
- 2. To generate an .mtbdfu file for legacy devices (with metadata): dfuh-cli.exe --generate-mtbdfu test\_gen.mtbdfu --mtbdfu-data-file blinky\_cm4\_crc.hex --file-version 0x1 --product-id 01020304 --checksum-type 0x0 --application-id 0x1 --application-start 1005 --application-length fffc
- 3. To program the .hex file through the .mtbdfu file under UART (without metadata): dfuh-cli --program-device test\_app.hex --hwid COM5 --uart-baudrate 115200 -uart-databits 8 --uart-paritytype None --uart-stopbits 1 --file-version 0x1 --product-id 01020304 --checksum-type 0x0
- 4. To execute or send commands through the .mtbdfu file under SPI:



## **CLI description**

```
dfuh-cli --custom-command test.mtbdfu --hwid MiniProg4-0C0806F801071400 --
spi-clockspeed 1.0 --spi-mode 0
```



## 8 Input files

The DFU Host tool requires the .mtbdfu file (JSON format) as an input to retain the backward compatibility for PSoC<sup>™</sup> 4 and PSoC<sup>™</sup> 6 legacy devices. It also supports the .cyacd2 file format as an input for the basic program, verify, and erase operations.

The details for the supported input file:

- 1. \*.mtbdfu file: The JSON input file for the DFU Host tool. It can be used for communication with the device using different commands available in the file. It should include a set of commands with respective data to be sent to the device through the DFU Host tool, using the DFU Command-Response protocol.
- 2. \*.cyacd2 file: This can only be used for the firmware update use case. The file will consist of the required header information for the firmware image along with the firmware binary and address where data will be loaded. This format is only supported for PSoC<sup>™</sup> 6 and PSoC<sup>™</sup> 4 devices.

However, for the basic program, verify, and erase operations, the DFU Host tool can generate an .mtbdfu file using the .hex file provided as an input with the necessary header parameters required for the .mtbdfu file. The below figure shows the dynamic window of the DFU Host tool, which displays when the .hex file is selected as the input.

File Actions View Help			
File: Id/APP_CY8CPROTO-062-434	3W/Debug/mtb-example-psoc6-capsense-buttons-slider.hex		
File Version: 0x1			
Product ID: 01020	304		
Packet Checksum Type: 0x0			
	Generate		
Ports:     Filters     Baud:     115200 ~       Intel(R) Active Management Technology - SOL (COM3) -     Data bits:     8 ~       Stop bits:     1 ~       Parity:     None ~			
2023-05-16 14:49:21.733 Program 2023-05-16 14:50:39.842 Verify sta 2023-05-16 14:50:39.848 VerifyHex 2023-05-16 14:50:45.075 Operation	Hex.mtbdfu was generated. rted. :.mtbdfu was generated. n took 5229 milliseconds.		
Ready			

- 1. The green box on the toolbar indicates the actions available for using the .hex file as an input: program, verify, and erase the device. Modify the required parameter shown in the image and select the required option.
- 2. The blue box displays the .hex file path selected as an input to the host tool. Only limited operations/actions are possible with selecting the .hex file as the input. For complex operation, use the .mtbdfu file with the required set of commands.
- 3. The orange box indicates the "APPinfo" section of the .mtbdfu file to be generated. The window displays the default value for the same, the values must be modified per device and use case. For more details refer <u>.mtbdfu</u> section above. The **Generate** button generates the reference .mtbdfu file for the program use case, the file will be saved at the installation directory of the DFU Host Tool.



Sample JSON generated for the basic program use case

```
"APPInfo": {
  "File Version": "0x1",
  "Product Id": "01020304",
  "Packet Checksum Type": "0x0"
"commands": [
 {
  "dataFile":"blinky_cm4_crc.hex",
  "commandSet":[
    "cmdId":"0x37",
    "dataLength":"0x10",
    "repeat":"0x20"
  },
  {
   "cmdId": "0x49",
   "dataLength": "0x08"
  1.
  "repeat":"EoF",
  "flashrowlength":"0x200"
1
```

The above JSON sample displays the template .mtbdfu file generated from the given .hex file as the input. The DFU Host Tool will use \* .mtbdfu file for programming the firmware .hex file to the device.

The default flow of the DFU-MW-based firmware download follows the set of repetitive send data command(0x37) with 32Bytes of data and a program row command(0x49) with the leftover row data, row checksum, and the row address to write.

The JSON file uses the **APPInfo** object required for the DFU communication setup. It contains potential information, the image version, product ID of the device the same as loaded with the loader application along with the checksum type for DFU command packet.

The sample contains the command object, which contains the list of command sent to the device. This object can be used to send a single as well as multiple DFU commands in the sequence required. The object contains another sub-object **commandSet**, which can group multiple commands to provide shared data across the group and repeat the set of commands.

This set is repeated till the end of the image file, the command requires the flash row length to divide the packets into multiple sets. For more details, refer to <u>AN 213924</u>.

## 8.1 .mtbdfu file

The file contains the following sections:

AppInfo - Provides information about the device and the application

- File version Indicates the application version, can be used to track updates.
- Product ID Unique ID of the device communicating with the host.
- Checksum type Used for the .hex file, for DFU packet checksum.

**Command** – Consists of the details of the command to be sent to the device along with the data.



#### JSON fields available in the Command section:

Field	Description
cmdId	Command field. Specifies the DFU command number; the valid range is 0x00 - 0xFF. [0x00 - 0x49]: A standard DFU command range [0x50-0xFF]: Reserved for Future Use
commandSet	Used to denote a set of commands, required for repeating a set of commands.
dataBytes	(Optional) The actual payload to be used in a command.
dataFile	(Optional) Specifies the name of the input file from where the payload data will be read.
dataLength	(Optional) The length of the payload data in bytes.
flashRowLeng	th Specifies the flash row length on the device. Valid only if dataFile is defined.
repeat	Repeats the command for a specified number of times. Valid only when dataFile is defined. For example: repeat: "10" means that the command will be repeated 10 times. Repeat: "EoF" means that the command will be repeated until the end of the data file.
startOffset	Specifies the file offset from where data bytes will be read. Valid only if dataFile is defined.
sessions	(Optional) Used to define multiple DFU sessions in the .mtbdfu file.
outFile	(Optional) Specifies the filename to store intermediate packets generated by the tool.
outCli	(Optional) Output response data from the device to the command line.
msg	(Optional) Used to add comments to the .mtbdfu file. These will not be sent to the device, they will be available in the output message from the DFU Host Tool.
rsp	(Optional) A response is expected for the defined command. If no response is defined, the default expected response is 0x00(DFU_SUCCESS).
retriesCount	Restart the connection lost for a specified number of times or until the channel gets active again. The DFU Host tool will reconnect to the device with all previous selected configuration of the channel, speed, address mode, etc
	Reconnection means establishing the channel communication again and sending the DFU start command. After successful reconnection, JSON will define the next set of tasks/commands. Equals 0 by default.
timeoutS	Alters the timeout for the response packet(seconds). It will apply for all retries of the operation if the "retriesCount" is non-zero.
timeoutMS	Alters the timeout for the response packet(milliseconds). It will apply for all retries of the operation if the "retriesCount" is non-zero.
timeoutUS	Alters the timeout for the response packet(microseconds). It will apply for all retries of the operation if the "retriesCount" is non-zero.
delayS	Sets the amount of time to wait between two commands in seconds. It is defined in a separate JSON object in the "commands" array without any additional fields in it.
delayMS	Sets the amount of time to wait between two commands in milliseconds. It is defined in a separate JSON object in the "commands" array without any additional fields in it.
delayUS	Sets the amount of time to wait between two commands in microseconds. It is defined in a separate JSON object in the "commands" array without any additional fields in it.
Note:	The APPInfo section is mandatory for the JSON file; it is required to start the DFU communication.
Note:	Optional commands must be defined per use case.
Note:	All number values must be in the hexadecimal format.



Sample to use JSON fields in .mtbdfu file



Note: The above sample JSON is used only to demonstrate how to use the various arbitrary fields in the .mtbdfu file. This .mtbdfu file is only a reference template and does not correspond to any specific use case.



Customizing the DFU Host Tool

## 9 Customizing the DFU Host Tool

The DFU Host tool uses a set of timeouts for read operation before disconnecting and sending the timeout error. These internal configurations are suited for the development and field upgrade operations for programming the firmware or communicating with the device.

However, these configurations might require modification while debugging the DFU applications with transports using the multiple breakpoint in the target side. Due to the breakpoint, the device will pause execution and might not be able to send a response desired by the DFU Host Tool. Recommended – modify the timeout configuration and rebuild the DFU Host Tool while debugging the application using the DFU transport.

Modify the source code available at Windows:

~/ModusToolbox/tools\_3.2/dfuh-tool/sample\_code/

Go to ~/sample\_code/include/backend/cychannel.h and alter variable DEFAULT\_TIMEOUT\_MS. By default, it is equal to 300 milliseconds.

After making the above modification in the source code of the DFU Host tool, build the DFU Host tool again. For details of building the DFU Host tool, refer to section <u>Example code</u>.



## Troubleshooting

## **10** Troubleshooting

Problem	Workaround
On common Linux distributions, the serial UART ports (usually /dev/ttySx or /dev/ttyUSBx devices) belong to the root user and to the dialout group. Standard users are not allowed to access these devices.	An easy way to allow the current user access to the Linux machine's serial ports is by adding the user to the dialout group. This can be done using the following command:
On Linux, attempts to set up or start DFU Host tool communication causes the tool to close without any messages.	To enable DFU Host tool communication under Linux, install the udev rules for KitProg3: Disconnect the KitProg device. Execute in the terminal (root access required): sh \$CYSDK/tools/fw-loader/udev_rules/install_rules.sh Reconnect the KitProg device.
On common Linux distributions, the DFU Host tool forbids communication protocol selection after re-plugging KitProg during communication.	Refer to the "Installation Procedure on Ubuntu Linux (x64)" section in the CYPRESS™ Programmer 2.1 CLI User Guide.
KitProg3 UART is accessible but not able to read data on Linux kernel 4.15 and above or Mac OS X 10.13 and above.	Use a third-party UART to USB bridge. Update the KitProg3 firmware to version 1.11.243 or above.
After updating firmware and middleware for your application, SPI transfer speed is not as fast as expected.	You may be able to improve performance by modifying the <i>src/backend/cychannelspi.cpp</i> file. Remove the calls to QThread::msleep(1) when building your bootloader host tool.
Sending command 0x47 to a PSoC™ 6 device via SPI is not supported.	Command 0x37 can be used for transferring a large amount of data to a PSoC <sup>™</sup> 6 device.



## Version changes

## **11** Version changes

Version	Change Descriptions
1.0	New tool.
	Added Notice List.
1.1	Added command-line interface (CLI) and handling of invalid command line arguments.
	Added logging for firmware update process.
1.2	Removed Notice List.
1.30	Updated versioning to support patches.
1.40	Fixed minor defects.
1.50	Added PSoC <sup>™</sup> 4 device support.
1.00	Updated versioning to support internal libraries update.
1.60	Changed the device library file from xml to <i>props.json</i> .
	Added the .mtbdfu file format support.
2.0	Added the .hex file format support.
	Added the XMC7000 device support.
2.10	Added the PSoC <sup>™</sup> Edge device support.
	Added new features for the .mtbdfu file support.
	Added new CLI parameters.
2.20	Fixed minor bugs.
2.20	Added Qt 6 support.

This section lists and describes the changes for each version of this tool.





## **Revision history**

Revision	Date	Description
**	2018-11-09	New document.
*A	2019-10-16	Updated to version 1.1.
*В	2020-03-27	Updated to version 1.2.
*C	2020-09-01	Updated to version 1.30.
*D	2020-10-16	Added information about code example.
*E	2021-03-11	Updated to version 1.40.
*F	2022-05-10	Updated to version 1.50.
*G	2022-09-30	Updated to version 1.60.
*H	2023-05-19	Updated to version 2.0.
*I	2023-05-24	Added information to Troubleshooting section: "Sending command 0x47 to a PSoC <sup>™</sup> 6 device via SPI is not supported".
*J	2023-11-29	Updated to version 2.10.
*K	2024-01-24	Updated to version 2.20.

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