GTM_TOM_PWM_1
for KIT_AURIX_TC375_LK
GTM TOM PWM generation

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Scope of work

GTOM TOM is used to generate a PWM signal, which is driving the intensity of an LED.

The LED is driven by pin 5 of the port 00. The state of the pin is controlled by the PWM signal generated by the TOM timer of GTM.
Introduction

› The Generic Timer Module (GTM) is a modular timer unit designed to accommodate many timer applications.

› It has an in-built Timer Output Module (TOM) that can offer up to 16 independent channels to generate output signals.

› The Clock Management Unit (CMU) is responsible for clock generation of the GTM. The Fixed Clock Generation (FXU) is one of its subunits and it provides five predefined non-configurable clocks for GTM modules, including the TOM.
Hardware setup

This code example has been developed for the board KIT_A2G_TC375_LITE.

LED1 (1) is used for this example.
Implementation

Configuring the TOM

The configuration of the TOM is done by calling the initialization function `initGtmTomPwm()` containing the following steps:

- Enable the GTM by calling the function `IfxGtm_enable()`
- Enable the FXU clocks by calling the function `IfxGtm_Cmu_enableClocks()`

The function `IfxGtm_Tom_Pwm_initConfig()` initializes an instance of the structure `IfxGtm_Tom_Pwm_Config` with its default values.

The `IfxGtm_Tom_Pwm_Config` structure can be modified to set the following parameters to initialize the module:

- `tom` – Selection of the TOM which is counting (TOM 1 in this example)
- `tomChannel` – Selection of the channel which is driving the LED (Channel 4 in this example)
- `period` – Setting of the period for the PWM signal to the desired value
- `pin.outputPin` – Selection of the LED as output pin
- `synchronousUpdateEnable` – Enabling of synchronous update of the timer
Implementation

Configuring the TOM

After configuration, the function `IfxGtm_Tom_Pwm_init()` initializes and activates the TOM with the user configuration. Start the PWM with the function `IfxGtm_Tom_Pwm_start()`.

Setting the duty cycle

The setting of the duty cycle is done by calling the function `setDutyCycle()`, which contains the following steps:

› Set the `dutyCycle` parameters of the configuration structure to set the duty cycle of the PWM signal to the desired value
› Call the function `IfxGtm_Tom_Pwm_init()` to reconfigure the TOM with the new value of the duty cycle

All the functions used for the configuration of the TOM are provided by the iLLD header `IfxGtm_Tom_Pwm.h`.

Fading the LED

The fading of the LED is done in the function `fadeLED()` by repeatedly adding or removing a step value to the duty cycle of the PWM.
**Implementation**

**Calculation example**

The FXU clock 0 frequency ($f_{fxclk0}$) is 100 MHz. The period value to have the desired PWM frequency ($f_{PWM}$) is calculated with the following formula:

$$Period = \frac{f_{fxclk0}}{f_{PWM}}$$

In this example: $Period = \frac{100 \text{ MHz}}{2 \text{ kHz}} = 50000 \text{ ticks}$
Run and Test

After code compilation and flashing the device, observe the **LED1 (1)**, which should be fading.
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https://www.infineon.com/aurixdevelopmentstudio
Use the „Import...“ function to get access to more code examples.

More code examples can be found on the GIT repository:
https://github.com/Infineon/AURIX_code_examples

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## Revision history

<table>
<thead>
<tr>
<th>Revision</th>
<th>Description of change</th>
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</thead>
<tbody>
<tr>
<td>V1.0.1</td>
<td>Updated board's images</td>
</tr>
<tr>
<td>V1.0.0</td>
<td>Initial version</td>
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