GTM_TOM_PWM_1 for KIT_AURIX_TC275_LK GTM TOM PWM generation

AURIX[™] TC2xx Microcontroller Training V1.0.2



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GTM TOM is used to generate a PWM signal, which is driving the intensity of an LED.

The LED is driven by pin 5 of the port 00. The state of the pin is controlled by the PWM signal generated by the TOM timer of GTM.



Introduction

- The Generic Timer Module (GTM) is a modular timer unit designed to accommodate many timer applications.
- It has an in-built Timer Output Module (TOM) that can offer up to 16 independent channels to generate output signals.
- The Clock Management Unit (CMU) is responsible for clock generation of the GTM. The Fixed Clock Generation (FXU) is one of its subunits and it provides five predefined non-configurable clocks for GTM modules, including the TOM.



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Hardware setup

This code example has been developed for the board KIT_AURIX_TC275_LITE.

LED1 (1) is used for this example.





Implementation

Configuring the TOM

The configuration of the TOM is done by calling the initialization function *initGtmTomPwm()* containing the following steps:

- > Enable the GTM by calling the function *lfxGtm_enable()*
- > Enable the FXU clocks by calling the function *lfxGtm_Cmu_enableClocks()*

The function *lfxGtm_Tom_Pwm_initConfig()* initializes an instance of the structure *lfxGtm_Tom_Pwm_Config* with its default values.

The *lfxGtm_Tom_Pwm_Config* structure can be modified to set the following parameters to initialize the module:

- *tom* Selection of the TOM which is counting (TOM 1 in this example)
- *tomChannel* Selection of the channel which is driving the LED (Channel 4 in this example)
- > period Setting of the period for the PWM signal to the desired value
- > *pin.outputPin* Selection of the LED as output pin
- > synchronousUpdateEnable Enabling of synchronous update of the timer



Implementation

Configuring the TOM

After configuration, the function *lfxGtm_Tom_Pwm_init()* initializes and activates the TOM with the user configuration.

Start the PWM with the function *lfxGtm_Tom_Pwm_start()*.

Setting the duty cycle

The setting of the duty cycle is done by calling the function **setDutyCycle()**, which contains the following steps:

- Set the *dutyCycle* parameters of the configuration structure to set the duty cycle of the PWM signal to the desired value
- Call the function *lfxGtm_Tom_Pwm_init()* to reconfigure the TOM with the new value of the duty cycle

All the functions used for the configuration of the TOM are provided by the iLLD header *lfxGtm_Tom_Pwm.h*.

Fading the LED

The fading of the LED is done in the function *fadeLED()* by repeatedly adding or removing a step value to the duty cycle of the PWM.



Calculation example

The FXU clock 0 frequency (f_{fxclk0}) is 100 MHz. The period value to have the desired PWM frequency (f_{PWM}) is calculated with the following formula:

$$Period = \frac{f_{fxclk0}}{f_{PWM}}$$

In this example: $Period = \frac{100 MHz}{2 kHz} = 50000 ticks$





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Run and Test

After code compilation and flashing the device, observe the **LED1** (1), which should be fading.



References









- → AURIX[™] Development Studio is available online:
- https://www.infineon.com/aurixdevelopmentstudio
- > Use the *"Import…"* function to get access to more code examples.
- > More code examples can be found on the GIT repository:
- https://github.com/Infineon/AURIX_code_examples
- > For additional trainings, visit our webpage:
- https://www.infineon.com/aurix-expert-training
- → For questions and support, use the AURIX[™] Forum:
- https://www.infineonforums.com/forums/13-Aurix-Forum



Revision history

Revision	Description of change
V1.0.2	Updated board's image
V1.0.1	Update of version to be in line with the code example's version
V1.0.0	Initial version

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Edition 2021-06 Published by Infineon Technologies AG 81726 Munich, Germany

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Document reference GTM_TOM_PWM_1_KIT_TC275_LK

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