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## Objective

This code example shows how to control an E-INK display using the EmWin Graphics Library in PSoC<sup>®</sup> 6 MCU.

### **Overview**

This code example demonstrates how to display graphics on an E-INK display using the EmWin Graphics Display Library. The EmWin graphics library implements 2D graphics and provides easy-to-use API functions to display text, 2D graphics (lines, rectangles, circles, etc.), and bitmap images. In PSoC Creator™, the EmWin Graphics library is implemented as a PDL middleware library. E-INK displays consume no power for image retention. Together with PSoC 6 MCU and EmWin graphics library, an E-INK display can be used to create user interfaces that have the "always-on" functionality.

This code example assumes that you are familiar with the PSoC 6 MCU and the PSoC Creator Integrated Design Environment (IDE). If you are new to PSoC 6 MCU, see the application note AN210781 – Getting Started with PSoC 6 MCU with Bluetooth Low Energy (BLE) Connectivity.

Details of EmWin Graphics Library API can be found in EmWin documentation *UM03001\_emWin5.pdf* in the *Program Files* (*x86*)\*Cypress\PDL\3.x.x\doc\* folder.

## Requirements

Tool: PSoC Creator 4.2; Peripheral Driver Library (PDL) 3.0.4

Programming Language: C (Arm® GCC 5.4.1)

Associated Parts: All PSoC 6 MCUs

Related Hardware: CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit

### Hardware Setup

1. Plug in the E-INK display shield on to the Pioneer Board as Figure 1 shows.

Figure 1. Hardware Setup





2. Set the switches and jumpers on the Pioneer Board as shown in Table 1.

Switch/Jumper	Position	Location
SW5	3.3 V	Front
SW6	PSoC 6 BLE	Back
SW7	V <sub>DDD</sub> / KitProg2	Back
J8	Installed	Back

Table 1. Switch and Jumper Selection

# Software Setup

Install the CY8CKIT-62-BLE PSoC 6 BLE Pioneer Kit software, which contains all the required software to evaluate this code example. No additional software setup is required.

## Operation

1. Connect the Pioneer Board to your PC using the provided USB cable through the USB connector (J10).



Figure 2. Connecting the USB Cable to the Pioneer Board

2. Program the Pioneer Board with the 'CE23727\_EmWin\_Eink\_Display' project. See the CY8CKIT-062-BLE kit guide for details on how to program firmware into the device.

The E-INK display refreshes and shows the startup screen for three seconds, followed by a screen that displays instructions to press SW2 to scroll through various demo pages. Press SW2 to advance through the following pages that demonstrate various graphics features in EmWin.

- Normal fonts of various sizes
- Bold fonts of various sizes
- Text alignments, modes, and styles
- Text wrap and text rotation
- 2D graphics with vertical lines, horizontal lines, arcs, and rectangle
- 2D graphics with circles and ellipses

Note that it takes about a second to refresh the display with new content.



#### Figure 3. Startup Screen



Figure 4. Pages Shown in Sequence



#### Important Note:

When you build the project, you will see the following notification. Click OK.



Figure 5. Build Messages



After this, the following notification is displayed:

Figure 6. Build Messages Showing Updated Configuration Files

ι	Jpdated Config	uration Files	?	×
-				
	Name LCDConf.h LCDConf.c	Path C:\Perforce\graa_laptop_win10\apps\PSoC1\USER\GRAA\emWin\CE223727_EmWin_Elnk C:\Perforce\graa_laptop_win10\apps\PSoC1\USER\GRAA\emWin\CE223727_EmWin_Elnk	_Display' _Display'	ICE2
	< These configura	tion files are different from files in PDL and might not work with other PDL files. If you click "Repla	ace",	>
	selected files wil	be renamed to mename.old and replaced with PDL tiles. Replace	Cancel	

Deselect both the files (they will be deselected by default) and click **Replace**. If you select these files and click **Replace**, configuration files in the code example project will be replaced by the default configuration files.



## **Design and Implementation**

This project uses a CY8CKIT-028-EPD E-INK Display Shield together with CY8CKIT-062-BLE Pioneer Board. The E-INK Shield has a 2.7-inch E-INK display with a resolution of 264×176 pixels.

For details on the Pioneer Board and E-INK Display Shield, see the Pioneer Kit Guide.

There are three important parts in this code example:

- 1. **EmWin Graphics Library:** The EmWin Graphics Library is implemented as a middleware in PDL and implements all graphics functions. The library manages a display buffer and updates this display buffer with pixel data according to graphics operations performed.
- 2. E-INK Driver: The E-INK driver takes care of transferring the pixel data from the display buffer to the E-INK driver IC through a SPI Master interface and several GPIOs.
- 3. **Application Code:** The application code calls EmWin graphics APIs to perform graphic functions, manages an application display buffer with cache (needed by the E-INK library), and calls the E-INK display library to update the display.

#### Include and Configure EmWin Graphics Library

1. In PSoC Creator, go to **Project** > **Build Settings** and select **Peripheral Driver Library**. Under the **Graphics** > **emWin** section, select the **Core** and **LCD Driver** options.

Build Settings	9 9 9 4	1 2 1				8 X
Configuration:	Debug (Active)	•				
Toolchain:	ARM GCC 5.4-2016-q2-updat	e 🔻				
E223726_EmV	Vin_TFT_Display_ST77895 ation	Default (Tools > Options):     Outom	:\Program File	es (x	:86)\Cypre	ss\PDL\3.1.0\
⊕ Customizer Peripheral D Target IDEs	river Library	Software package imports: 장고 Expand 같고 Collapse IV Check	All 🗖 Uncl	hecl	k All	
E CM0 + ARM	GCC 5.4-2016-q2-update	Package	Variant		Version	Description
	cc 3.4-2010-q2-update	PDL				
		crypto	Full library		2.10.0	CRC, DES, SHA, PRNG, TRNG, CMAC, HM
		. ⊟- Graphics				
		🖻 emWin			5.46	emWin graphical user interface library
		Core	nOSnTS	•	5.46	No RTOS and no Touch support
		LCD Driver	FlexColor	•	5.46	FlexColor driver
		🖶 bootloader				
•	III •	I I I I I I I I I I I I I I I I I I I				•
					ОК	Apply Cancel

Figure 7. Set Core and LCD Driver Options for the Project

2. Select the **nOSnTS** option for **Core** because this project does not use RTOS or Touch support.

#### Figure 8. Core Option

<b>Ģ</b> . • Graphics			
⊟…emWin		5.46.0	Graphical user interface library from the
Core	nOSnTS 👻	5.46.0	No RTOS and no Touch support
	nOSnTS	)	FlexColor driver
🖻 bootloader	OSnTS	Γ	
⊡ bootloader_sdk	OSTS		

3. Select the **BitPlains** option for the **LCD Driver** parameter. With the BitPlains driver, EmWin library manages only the graphics display buffer in memory. This driver can support color profiles from 1 bit per pixel (1bpp) to 8 bits per pixel (8bpp). As the E-INK supports Black/White, this project uses the 1bpp color profile.



#### Figure 9. Select Color Profile

🛱 Graphics				
⊟∼emWin			5.46.0	Graphical user interface library from the S
Core	nOSnTS	•	5.46.0	No RTOS and no Touch support
LCD Driver	BitPlains	•	5.46.0	FlexColor driver
⊟ bootloader	FlexColor	FlexColor CompactColor_16 BitPlains		
⊡ · bootloader_sdk	BitPlains			

#### 4. Click Generate Application.





PSoC Creator generates the configuration files for EmWin under the Shared Files folder.

Figure 11. Configuration Files Generated



 Open the LCDConf.c file and configure the X and Y size of the display and color conversion. The E-INK display used in the E-INK shield has a resolution of 264x176 pixels. GUICC\_1 sets the color profile to 1bpp. See the EmWin user guide for details of the color profiles.



	Figure 12.	Setting the X	and Y Values	s and Color	Conversion
--	------------	---------------	--------------	-------------	------------

55	_ /************************************
56	*
57	<ul> <li>* Layer configuration</li> </ul>
58	*
59	***********
60	L*/
61	11
62	// Physical display size
63	11
64	<pre>#define XSIZE_PHYS 264</pre>
65	<pre>#define YSIZE_PHYS 176</pre>
66	
67	11
68	<pre>// Initial color conversion API</pre>
69	11
70	<pre>#define COLOR_CONVERSION GUICC_1</pre>
71	

EmWin allocates the display buffer based on the defined X and Y sizes.

6. Open the *GUIConf.c* file. This file manages the RAM allocation for EmWin. The value of the GUI\_NUMBYTES macro must be set according to the approximate memory requirement based on EmWin features used by the application. See Section 37.2, "Memory Requirements", in the EmWin user guide for details on the memory usage for various features. For this code example, the memory size has been set to an arbitrary value of 0x1000 bytes.

The *GUI\_X.c* file has timing functions used by EmWin. The content of this file varies based on the OS support selected. No modifications are required in this file for this code example.

#### **CY E-INK Driver**

This code example contains the required library functions for driving the E-INK display. However, the actual hardware driver functions are not covered in this document. See the E-INK display driver document for more details.

Figure 13 shows the PSoC Creator schematic that implements the hardware required for the E-INK display library.

Figure 13. TopDesign Schematic: E-INK Library

CY	E-INK Library
SPI Master that communicates with E-INK driver	Additional GPIOs for controlling the E-INK display
CY EINK SPIM SPI Master Motorola	Display busy (input) CY_EINK_DispBusy ₪
	Display reset (output)
	떽 CY_EINK_DispRst
Firmware controlled Slave Select line	
G CY_EINK_Ssel	Display enable (output)
	Interpretation in the second seco
Timer that synchronizes E-INK display updates	Display discharge (output)
CY EINK Timer	CY_EINK_Discharge
contribute undrifitute compare	Display border (output)
EINK_Clock	Display I/O enable (output)
	™ CY_EINK_DispicEn



PSoC 6 MCU controls the E-INK display's reset, enable, discharge, and border pins. PSoC 6 MCU also reads the status of the display to determine whether the display is busy with a previous operation. A load switch on CY8CKIT-028-EPD, which is controlled by the PSoC 6 MCU device, can be used to turn the display ON/OFF. A voltage level translator is connected between the E-INK display and PSoC 6 MCU GPIOs so that PSoC 6 MCU can operate with variable V<sub>DD</sub>. The enable input of the voltage level translator is also connected to a PSoC 6 MCU GPIO so that PSoC 6 MCU can disable the level translator to reduce power consumption when the E-INK display is not used.

CY\_EINK\_SPIM implements a SPI Master interface using which the PSoC 6 communicates with the E-INK controller. CY\_EINK\_Ssel is the GPIO that implements the Slave Select signal for the E-INK controller.

CY\_EINK\_Timer implements a 1-ms timer that is used for timing functions for the E-INK display function.

E-INK Library and Driver Files:

The following files implement the E-INK driver:

- *cy\_eink\_library.c/.h* files contain the E-INK library functions and macros.
- pervasive\_eink\_configuration.h file contains definitions of register indexes and hardware parameters of the E-INK display provided by the display vendor.
- pervasive\_eink\_hardware\_driver.c/.h files contain low-level display hardware driver functions provided by the display vendor.
- cy\_eink\_psoc\_interface.c/.h files contain the PSoC 6 MCU Component-level interface to the display hardware.

Note: Do not edit these files because it may cause an undesirable operation of the E-INK display.

See CE218133 – PSoC 6 MCU E-INK Display with CapSense® for details of the APIs in the E-INK display library.

#### Main Application:

The main application is implemented in the *main\_cm4.c* file. The following functions are performed in main.

- 1. Initializing the EmWin graphics engine
- 2. Initializing the E-INK driver
- 3. Displaying the startup screen
- 4. Displaying the instructions screen that prompts the user to press SW2 to scroll through various display pages.
- 5. In an infinite loop, displaying the following pages; after displaying each page, waiting for a press and release event of SW2.
  - a. Displaying normal fonts
  - b. Displaying bold fonts
  - c. Displaying various text modes and alignment
  - d. Displaying word wrap and rotation
  - e. Displaying 2D graphics screen #1 that shows vertical lines, horizontal lines, arcs and filled rectangle
  - f. Displaying 2D graphics screen #2 that shows concentric circles and concentric ellipses.

Figure 14 shows the hardware to read SW2. SW2 is connected to a Status Register Component which is clocked at 100 Hz. The Status Register provides the debounced state of the switch.

#### Figure 14. Switch Debounce and Status





# Components

|--|

Component	Instance Name	Function
SPI (SCB)	CY_EINK_SPIM	The SPI Component is configured as a SPI master that communicates with the E-INK display driver.
Timer Counter (TCPWM)	CY_EINK_Timer	The Timer Counter is configured to have 1LSB = 1 ms. The count value is used for E-INK display timing.
Digital Output Pin	CY_EINK_Ssel CY_EINK_DispRst CY_EINK_DispEn CY_EINK_Discharge CY_EINK_Border CY_EINK_DisploEn	These GPIOs are configured as firmware-controlled output pins that are used to provide control signals to the E-INK display.
Digital Input Pin	CY_EINK _DispBusy	This GPIO is a digital input without any hardware connection. It is used to read the status of the E-INK display.
	SW2	This Digital Input Pin is connected to the input of the flip-flop to read the SW2 status.
Status Register	Status_SW2	This status register is used to read the status of the switch. A clock of 100 Hz is used for the Status Register, which also acts as a debounce to the switch.

See the PSoC Creator project for more details on PSoC Component configurations and design-wide resource settings.

# **Related Documents**

Application Notes				
AN210781 – Getting Started with PSoC 6 MCU with Bluetooth Low Energy (BLE) Connectivity	Describes PSoC 6 MCU with BLE Connectivity devices and how to build your first PSoC Creator project			
AN215656 – PSoC 6 MCU: Dual-CPU System Design	Describes the dual-CPU architecture in PSoC 6 MCU, and shows how to build a simple dual-CPU design			
AN219434 – Importing PSoC Creator Code into an IDE for a PSoC 6 MCU Project	Describes how to import the code generated by PSoC Creator into your preferred IDE			
CE218133 – MCU E-INK Display with CapSense	Describes how to implement a E-INK display solution with CapSense®			
PSoC Creator Component Datasheets				
Pins	Supports connection of hardware resources to physical pins			
Timer Counter (TCPWM)	Supports fixed-function Timer/Counter implementation			
Clock	Supports local clock generation			
Interrupt	Supports generating interrupts from hardware signals			
CapSense	Supports touch sensing			
Device Documentation				
PSoC 6 MCU: PSoC 63 with BLE Datasheet	PSoC 6 MCU: PSoC 63 with BLE Architecture Technical Reference Manual			
Development Kit Documentation				
CY8CKIT-062-BLE PSoC 6 BLE Pioneer Kit				
Training Videos				
PSoC 6 101: Lesson 1-4 FreeRTOS				





# **Document History**

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Revision	ECN	Submission Date	Description of Change
**	6299270	09/18/2018	New code example
*A	6634885	08/05/2019	<ol> <li>Updated the CE project</li> <li>Increased the SPI data rate from 8.33Mbps to 20Mbps</li> <li>Instead of application code maintaining two buffers (current and cache), changed application code to use only one buffer for cache. emWin's display buffer is directly used as current buffer in Elnk page update function calls</li> <li>Minor code cleanup</li> </ol>



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