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Objective

This example demonstrates the custom methods to detect stuck conditions, like those resulting from temperature, humidity, or other environment changes, and to recover from them by resetting the CapSense® baseline.

Requirements

Tool: PSoC Creator™ 4.2

Programming Language: C (Arm® GCC 5.4.1 and Arm MDK 5.22)

Associated Parts: All PSoC® 4 MCU parts

Related Hardware: CY8CKIT-149 PSoC 4100S Plus Prototyping Kit, CY8CKIT-145-40XX PSoC 4000S CapSense Prototyping Kit

Overview

The example demonstrates detection of two conditions at which baseline or sensor is stuck. For instance, baseline stuck to a constant value or sensor status stuck at ON. Both these conditions are demonstrated using either time-based detection or sample-based detection.

This project features the CapSense Component configured with three mutual capacitance buttons. However, the detection technique is equally applicable to any sensor type (such as self-capacitance sensing) and widget type (sliders, touchpads, and so on).

Hardware Setup

This example uses the kit's default configuration. See the [kit guide](#) to ensure the kit is configured correctly.

Software Setup

The example uses terminal software, such as CapSense Tuner (which is included with PSoC Creator).

Background

Baseline is a low-pass filtered value of raw count¹ and acts as a reference for calculating the signal. Ideally baseline should always be at 'no touch' raw count value. An abnormal condition such as temperature, humidity, or other environment changes can cause the baseline to be stuck at certain levels.

A change in temperature or humidity can cause variation in actual capacitance value as well as the operation of internal components (IDAC, clock, and so on) and can lead to variation in measured raw count. In normal situations, the baseline should follow the raw count for any environment changes. Sometimes if there are sudden changes to temperature or humidity, and raw count increases suddenly, baseline may not follow immediately and can get stuck at lower values. In some cases, the sudden change may be as big or higher than the touch response, in which case, the sensor will be stuck at ON indefinitely.

You may want to detect the abnormal conditions and reset the baseline to bring the system back to a normal state.

Design and Implementation

This code example demonstrates two approaches to reset the baseline.

¹ Sensor capacitance is converted into a count value by the CapSense algorithm. The unprocessed count value is referred to as raw count. (For more details, see the Definitions section of [AN64846 - Getting Started with CapSense](#)).

1. Time-based Baseline Reset

In this approach, raw count values are monitored to check if the sensor is stuck. A baseline reset is executed if the sensor is stuck for a user defined period. For time-based approach, a software counter array is used to track the duration each sensor is stuck.

System timer (SysTick) is used to create a callback every 100 milliseconds and increment the software counter of each sensor. When the counter reaches the user defined time-out period, a 'baseline reset' function is called to reset the baseline for that sensor. The counter is reset when the raw count is out of stuck condition or after the baseline reset. In this example SysTick is used as a timer. You can use any method to create a periodic interrupt and increment the software counter.

The sensor baseline reset time can be calculated as the product of the callback interval (default 100 ms) and user-defined time-out period.

2. Sample-based Baseline Reset

In this approach, raw count values are monitored to check if the sensor is stuck. A baseline reset is executed if the sensor is stuck for a user defined number of samples (i.e., number of CapSense scans). For sample-based approach, a software counter array is used to track the number of samples for which each sensor is stuck.

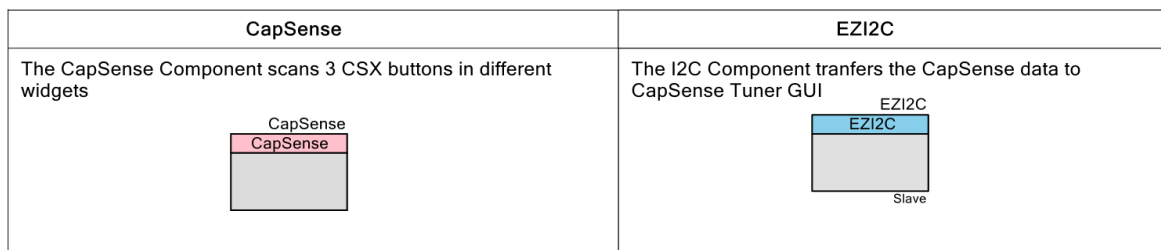
In this approach, the software counter is incremented when the raw count reaches the user-defined stuck condition. When a counter reaches the user-defined sample limit, a 'baseline reset' function is called to reset the baseline for that sensor. The counter is reset when the raw count is out of stuck condition or after the baseline reset.

This code example defines two conditions at which the sensors can be stuck. You can enable or disable these conditions:

1. Sensor raw count stuck between noise threshold and finger threshold.
2. Sensor is stuck at 'ON' state.

Figure 1 shows the PSoC Creator schematic for this code example.

Figure 1. TopDesign Schematic of CE229140_CapSense_CustomBaselineReset



Operation

1. Open the 'custom_baseline_reset.h.' file to configure this project. Define 'RESET_CONFIGURATION' to time-based reset or sample-based reset.

```
/* Configure to TIME_BASED or SAMPLE_BASED */
#define RESET_CONFIGURATION    TIME_BASED
```

2. Enable or disable the baseline reset for the two stuck conditions.

```
/* Raw count stuck between Noise Threshold and Finger Threshold */
#define SENSOR_STUCK_BETWEEN_NT_FT    ENABLE
```

```
/* Sensor status continuously stuck at '1' (ON) */
#define SENSOR_STUCK_AT_ONE    ENABLE
```

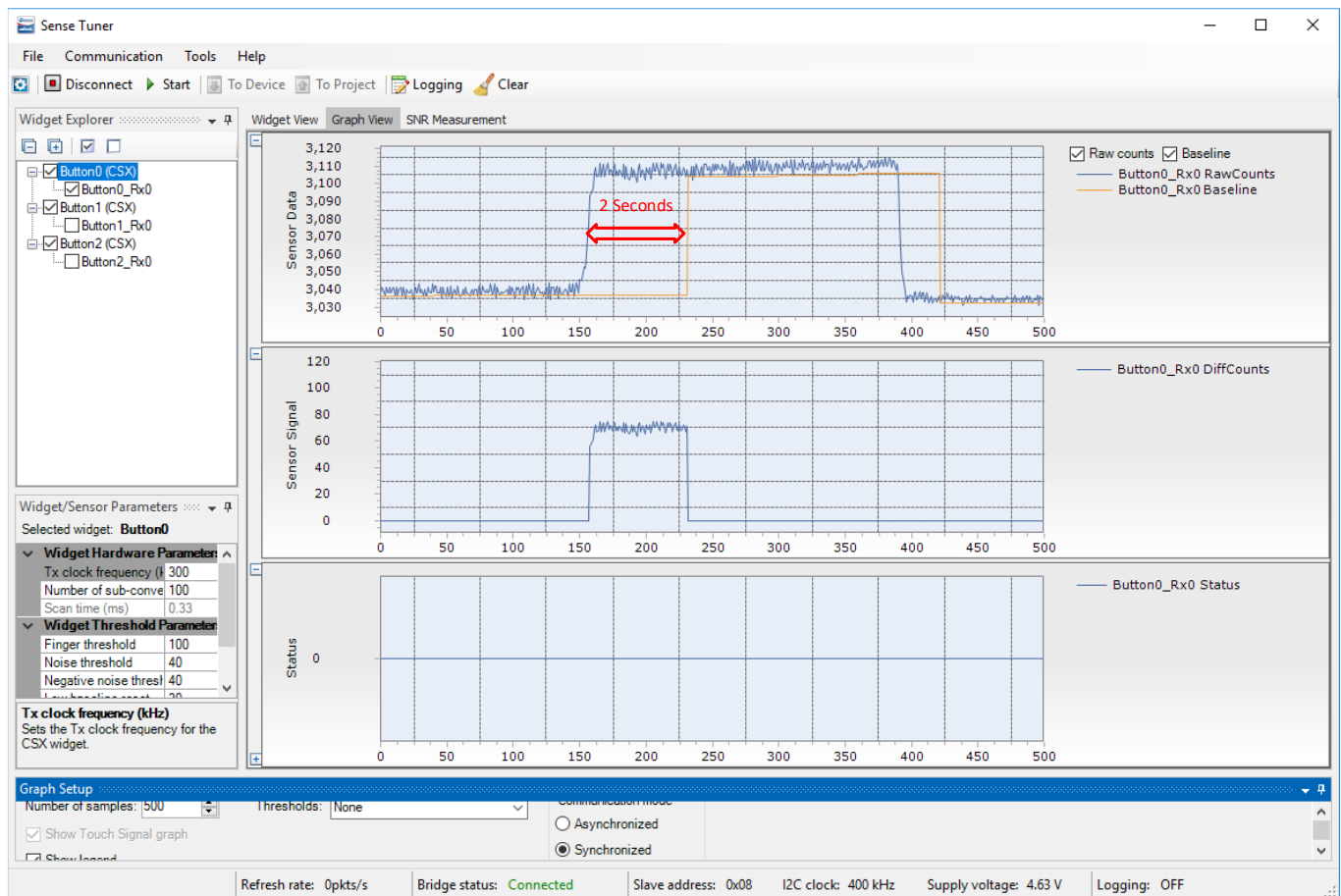
3. Define SENSOR_STUCK_NT_FT_TIMEOUT and SENSOR_STUCK_AT_ONE_TIMEOUT to set the reset timeout in 100 milliseconds or in number of samples based on the reset configuration.

```
/* Sensor Stuck Timeout in 100 milliseconds or in number of samples */
#define SENSOR_STUCK_NT_FT_TIMEOUT    (20u)
#define SENSOR_STUCK_AT_ONE_TIMEOUT    (20u)
```


- Build the project CE229140_CapSense_CustomBaselineReset and program it into the PSoC 4100S Plus device. Choose **Debug > Program**. For more information on device programming, see PSoC Creator Help.
- Launch the tuner GUI and monitor data in the tuner GUI. To set up the tuner GUI, see the CapSense Tuner section of the [CapSense Component Datasheet](#).

Go to the **Graph View** table of the Tuner GUI. As shown in [Figure 2](#), when the raw count is stuck between Noise threshold (40) and Finger threshold (100), a baseline reset is applied after 2 seconds as per the user configuration.

Figure 2. Tuner: Graph View



Components and Settings

[Table 1](#) lists the PSoC Creator Components used in this example, how they are used in the design, and the non-default settings required so they function as intended.

Table 1. PSoC Creator Components

Component	Instance Name	Purpose	Non-default Settings
CapSense	CapSense	The CapSense Component is configured to scan 3 – CSX buttons	For Basic Setting, see Figure 3 . CapSense Basic Settings
			For Widget Settings, see Figure 4 and Figure 5 .
EZI2C	EZI2C	To establish communication with the Tuner application	Data Rate (kbps): 400 Sub-address size (bits): 16

For information on the hardware resources used by a Component, see the Component datasheet.

Figure 3 highlights the non-default settings for the CapSense Component.

Figure 3. CapSense Basic Settings

Configure 'CapSense' ? X

Load configuration Save configuration Export Register Map

Name: CapSense

Basic Advanced Gestures Built-in

Move up Move down Delete CSD tuning mode: SmartSense (Hardware parameters only)

Type	Name	Sensing mode	Sensing element(s)				Finger capacitance
<input checked="" type="radio"/>	Button0	CSX (Mutual-cap)	1	Rx	1	Tx	N/A
<input type="radio"/>	Button1	CSX (Mutual-cap)	1	Rx	1	Tx	N/A
<input type="radio"/>	Button2	CSX (Mutual-cap)	1	Rx	1	Tx	N/A
+							

Sensor resources

CSD electrodes: 0 CSX electrodes: 6 Pins required: 6 Pins available: 54

Datasheet OK Apply Cancel

Figure 4. CapSense Button1 Widget Settings

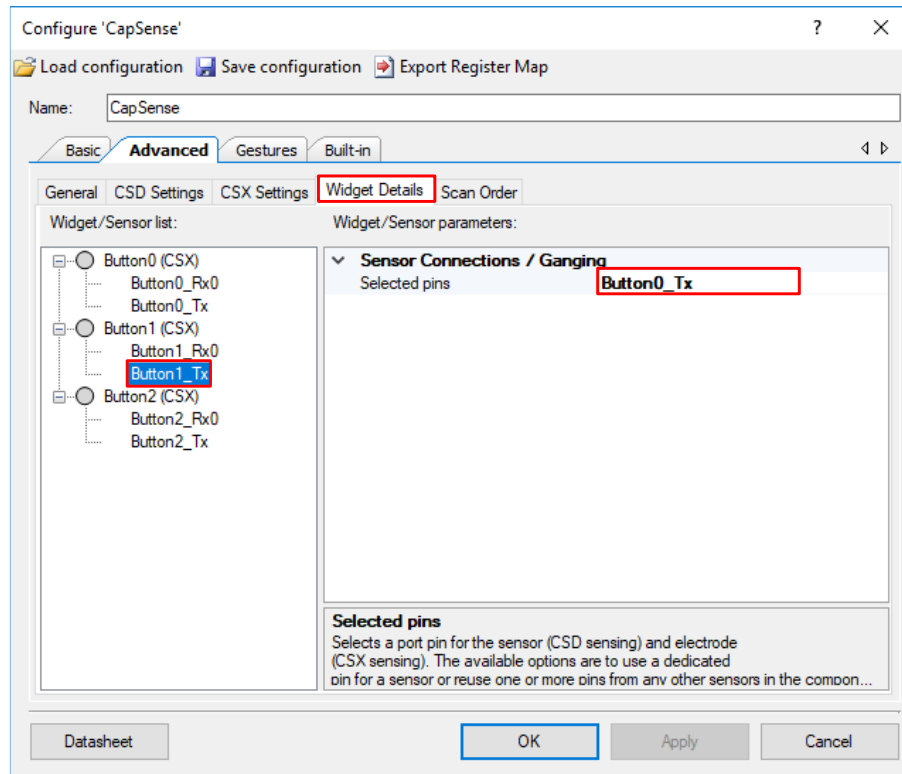


Figure 5. CapSense Button2 Widget Settings

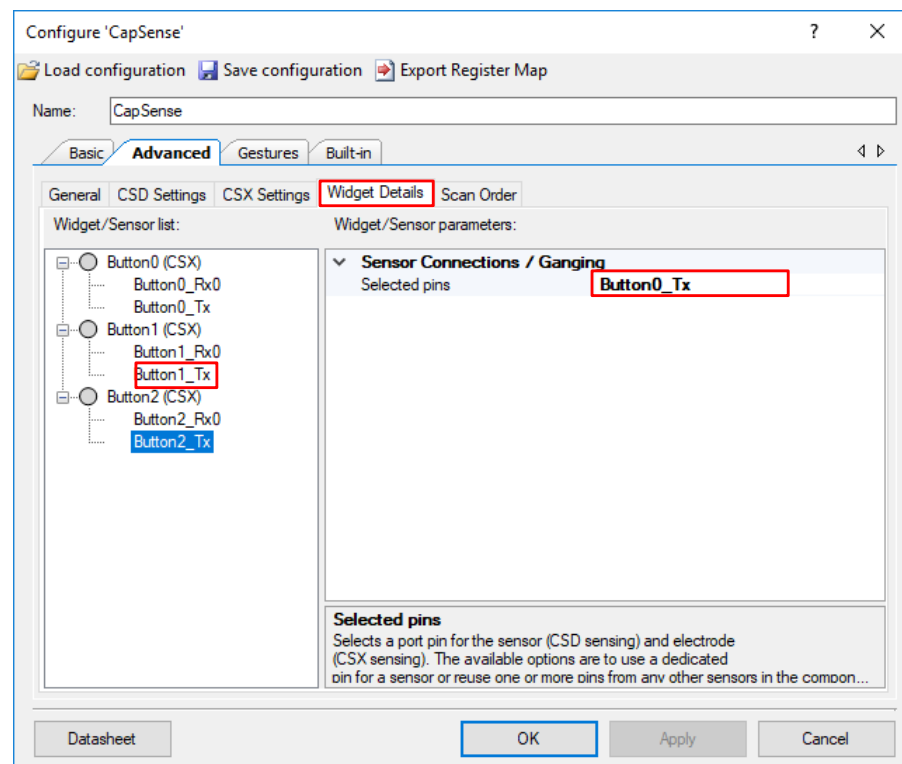


Table 2 shows the pin assignments for the project done in the **Pins** tab of the **Design Wide Resources** window for this code example. These assignments are compatible with the CY8CKIT-149 kit.

Table 2. Pin Assignments

Pin Name	CY8CKIT-149	CY8CKIT-145
CapSense:CintA	P4[2]	P4[2]
CapSense:CintB	P4[3]	P4[3]
CapSense:Rx[0]	P4[6]	P1[4]
CapSense:Rx[1]	P4[5]	P1[4]
CapSense:Rx[2]	P4[4]	P1[6]
CapSense:Tx	P0[2]	P1[3]
EZI2C:scl	P3[0]	P1[0]
EZI2C:sda	P3[1]	P1[1]

Reusing This Example

This example is designed for [CY8CKIT-149 PSoC 4100S Plus Prototyping Kit](#) and [CY8CKIT-145-40XX PSoC 4000S CapSense Prototyping Kit](#). To port the design to a different PSoC 4 MCU device and/or kit, change the target device using the Device Selector and pin assignments in the Design Wide Resources Pins settings as needed.

Related Documents

For a comprehensive list of PSoC 3, PSoC 4, and PSoC 5LP resources, see [KBA86521](#) in the Cypress community.

Application Notes	
AN85951 - PSoC 4 and PSoC 6 MCU CapSense Design Guide	Describes how to design capacitive touch sensing applications with PSoC 4 and PSoC 6
AN79953 - Getting Started with PSoC 4	Introduces the PSoC 4 device and explains how to build a PSoC Creator project
PSoC Creator Component Datasheets	
CapSense	Supports various interfaces such as Button, Matrix Buttons, Slider, Touchpad, and Proximity Sensor
EZI2C Slave	Supports one or two address decoding with independent memory buffers
Pins	Supports connection of hardware resources to physical pins
SysTick	Supports a down counter with the capability to generate an interrupt
Device Documentation	
PSoC 4100S Plus Datasheet	PSoC 4 Technical Reference Manuals
Development Kit Documentation	
CY8CKIT-149 PSoC 4100S Plus Prototyping Kit	
CY8CKIT-145-40XX PSoC® 4000S CapSense Prototyping Kit	
Tool Documentation	
PSoC Creator	Look in the downloads tab for Quick Start and User Guides

Document History

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Document Number: 002-29140

Revision	ECN	Submission Date	Description of Change
**	6756887	01/20/2020	New code example

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