

Please note that Cypress is an Infineon Technologies Company.

The document following this cover page is marked as "Cypress" document as this is the company that originally developed the product. Please note that Infineon will continue to offer the product to new and existing customers as part of the Infineon product portfolio.

Continuity of document content

The fact that Infineon offers the following product as part of the Infineon product portfolio does not lead to any changes to this document. Future revisions will occur when appropriate, and any changes will be set out on the document history page.

Continuity of ordering part numbers

Infineon continues to support existing part numbers. Please continue to use the ordering part numbers listed in the datasheet for ordering.



Objective

This example shows how to use the PSoC[®] Creator™ Timer Counter Pulse Width Modulator (TCPWM) Component configured as a PWM in a PSoC 4 device.

Requirements

Tool: PSoC Creator 4.2 Programming Language: C (Arm[®] GCC 5.4.1) Associated Parts: PSoC 4 family Related Hardware: CY8CKIT-042 PSoC 4 Pioneer Kit

Overview

This example contains two projects that use the PWM Component. The TCPWM_PWM_LED_RateSwap project demonstrates how PWM drives an LED with the option of changing the blink rate from slow to fast and vice versa. The TCPWM_PWM_ThreePhase project demonstrates three LEDs driven by three PWMs that are 120 degrees out-of-phase from one another.

Hardware Setup

No hardware setup is required for this code example.

Software Setup

No software setup is required for this code example.

Operation

- 1. Connect the USB cable between the PC and the PSoC 4 Pioneer Kit.
- 2. Build the project and program it into the PSoC 4 device. Choose **Debug** > **Program**. For more information on device programming, see PSoC Creator Help.
- 3. For the TCPWM_PWM_LED_RateSwap project: Each time SW2 is pressed, you will observe the LED's blink rate change.
- 4. For the TCPWM_PWM_ThreePhase project: The LED will cycle through colors to show the PWMs are 120 degrees out-ofphase.



Design and Implementation

There are two projects in this example:

TCPWM_PWM_LED_BlinkRateSwap

The TCPWM_PWM_LED_BlinkRateSwap example performs the following functions:

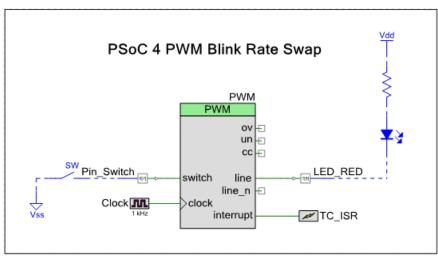
- 1. Configures the TC_ISR_Handler PWM interrupt handler function.
- 2. Starts PWM.
- 3. Initiates an interrupt when the count reaches terminal count.
- 4. When the switch (controlled by Pin_Switch) goes HIGH, the code example swaps the period register values. The period value controls the blink rate of LED_RED.

The TC_ISR_Handler function does the following:

- 1. Clears the interrupt for terminal count.
- 2. Toggles the LED ON/OFF state.

The top-level schematic of the PSoC Creator project is shown in Figure 1.

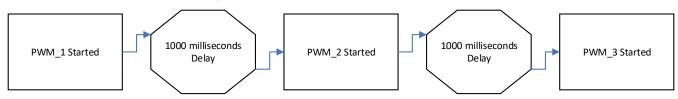
Figure 1. TCPWM_PWM_LED_RateSwap



TCPWM_PWM_ThreePhase

Figure 2 shows the functions performed in the TCPWM_PWM_ThreePhase example.





The top-level schematic of the PSoC Creator project is shown in Figure 3.

The delay between the start of PWMs creates the 120 degrees out-of-phase alignment in the waveform shown in Figure 4.

The delay is determined by 1/3 (120 out of 360 degrees) the period of PWM: 1/3*3000 = 1000 ms delay.

Note that varying the PWM period also varies the LED blink rate.



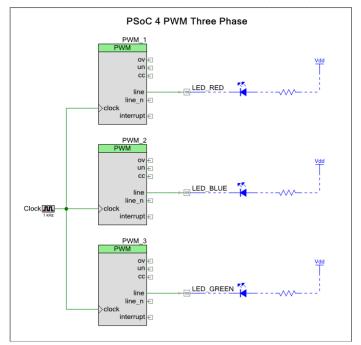
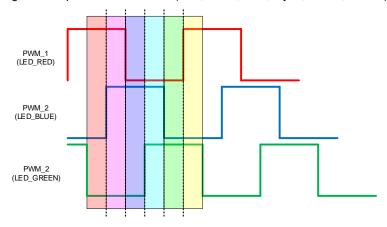


Figure 3. TCPWM_PWM_ThreePhase

Figure 4. Expected LED Pattern (Red, Violet, Blue, Cyan, Green, Yellow)





Components and Settings

Table 1 lists the PSoC Creator Components used in used in this example, how they are used in the design, and the non-default settings required so they function as intended.

Component	Instance Name	Purpose	Non-default Settings
Digital Input Pin	Pin_Switch	Handle the SW2 connection on device	See Figure 5
PWM (TCPWM mode) [v2.10]	PWM	Handle the PWM operation	See Figure 6
Digital Output Pin	LED_RED	Handle any LED color on device	Make sure external terminal is checked.
PWM (TCPWM mode) [v2.10]	PWM_1 (_2 & _3)	Handle the PWM operation	See Figure 7

Table 1. PSoC Creator Components

Figure 5. Pi	n_Switch	Parameter	Settings
--------------	----------	-----------	----------

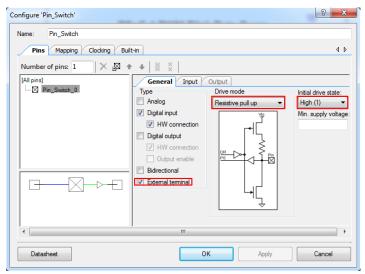




Figure 6. PWM Parameter Settings

Configure 'PWM'								<u>२</u> ×
Name: PWM								
Configuration P	WM Built-in							4 Þ
Prescaler:	1x 🔹		Input	Present	Mode		_	1
PWM align:	Left align 👻		reload		Rising edge		•	
PWM mode:	PWM	•	start		Rising edge		•	
Dead time cycle:		•	stop		Rising edge		•	
Stop signal event:	Don't stop on kill 🔻		switch	V	Rising edge	_	•	
Kill signal event:			count		Level		•	
Output line signal:				Regis		Register	Buf	
	Direct output		Period Compare	1500		500 65535	-	
Output line_n signal:	Direct output		compare	U		00000		1
 On terminal count 								
On compare/capt	ure count							
								_
	PWM, left	aligned, b	uffered					
cou								
cou		500					1	
	0V		÷.					
(interrupt only)		+ +	¥				1	
	line	• •						
lin	e n		1					
]
Datasheet							ſ	OK Apply Cancel
Datasheet							l	OK Apply Cancel

Figure 7. PWM Parameter Settings

			4
Configuration	PWM Built-in		V
Prescaler:	1x •	Input Present Mode	
PWM align:	Left align 🔻	reload Rising edge	
PWM mode:	PWM	▼ start Rising edge ▼	
Dead time cycle:	0	stop Rising edge v switch Rising edge v	
Stop signal event:	Don't stop on kill 🔻	switch V Rising edge	
Kill signal event:	Asynchronous		
Output line signal:	Direct output	Register Swap RegisterBuf Period 1500	
		Period 1500 💟 500 Compare 0 🗇 65535	
Output line_n signal:	Direct output	Compare 0	
Interrupt On terminal cour			
On compare/cap			
	Auto count		
	PWM, left aligr	ned, buffered	
col	1500 unter 500	7 7 7	
	0V	+ + +	
		+ + +	
(interrupt only			
(interrupt only	CC + +	* *	
) TC + CC +	**	
	CC + +	**	

For information on the hardware resources used by a Component, see the Component datasheet.



Reusing this Example

This example is designed for the CY8CKIT-042 pioneer kit. To port this design to a different PSoC 4 device, kit, or both, do the following:

- 1. In PSoC Creator, select **Project** > **Device Selector** to change the target device. Select your device as listed in Table 2.
- 2. Make sure that the **SysClk Desired frequency** is set to 24 MHz after the device is changed.
- 3. In the PSoC Creator Workspace Explorer, select the Clocks interface listed under Design Wide Resources.
- 4. Set the **SysClk Desired Frequency** to 24 MHz, if it is not already.

Development Kit	Device
CY8CKIT-041	CY8C4146AZI-S433
CY8CKIT-042	CY8C4245AXI-483
CY8CKIT-042-BLE	CY8C4247LQI-BL483
CY8CKIT-044	CY8C4247AZI-M485
CY8CKIT-046	CY8C4248BZI-L489
CY8CKIT-048	CY8C4A45AZI-483

In some cases, a resource used by a code example (for example, a Universal Digital Block) is not supported on another device. In that case, the example will not work. If you build the code targeted at such a device, you will get errors. See the device datasheet for information on what a device supports.



Related Documents

Application Notes				
AN79953 Getting Started with PSoC® 4		Describes PSoC 4 devices and shows how to build the associated code example		
Code Examples				
CE224564 PSoC 4 TCPWM Counter/Timer		Demonstrates the use of a counter to keep track of the number of button presses to measure the frequency and duty cycle of an input waveform.		
CE224595 PSoC 4 TCPWM QuadDec		Demonstrates the use of a Quadrature Decoder to detect the rotational direction as one waveform leads the other. Two PWMs are used to simulate input waveforms.		
PSoC Creator Component Datasheets	5			
ТСРШМ	A multifunctional Component that can implement the following functionalities: PWM, Timer/Counter, and Quadrature Decoder.			
General Purpose Input/Output (GPIO)	A multifunctional Component that allows hardware resources to connect to a physical port-pin and provides access to external signals through an appropriately configured physical I/O pin.			
Interrupt	The Interrupt Component defines hardware-triggered interrupts. There are three types of system interrupt waveforms that can be processed by the interrupt controller: Level, Pulse, and Edge.			
Device Documentation				
PSoC 4 Datasheets PSoC 4 Technical Reference Manuals				
Development Kit (DVK) Documentation				
CY8CKIT-042 PSoC [®] 4 Pioneer Kit				
PSoC 4 Kits				
Tool Documentation				
PSoC Creator		Go to the Downloads tab for Quick Start and User Guides		



Document History

Document Title: CE224593 - PSoC 4 PWM

Document Number: 002-24593

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	6290692	SYAO	08/31/2018	New code example
*A	6672859	NRSH	09/13/2019	Updated document layout and small changes for clarity.





Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at Cypress Locations.

Products

Arm® Cortex® Microcontrollers	cypress.com/arm
Automotive	cypress.com/automotive
Clocks & Buffers	cypress.com/clocks
Interface	cypress.com/interface
Internet of Things	cypress.com/iot
Memory	cypress.com/memory
Microcontrollers	cypress.com/mcu
PSoC	cypress.com/psoc
Power Management ICs	cypress.com/pmic
Touch Sensing	cypress.com/touch
USB Controllers	cypress.com/usb
Wireless Connectivity	cypress.com/wireless

PSoC[®] Solutions

PSoC 1 | PSoC 3 | PSoC 4 | PSoC 5LP | PSoC 6 MCU

Cypress Developer Community

Community | Code Examples | Projects | Videos | Blogs | Training | Components

Technical Support

cypress.com/support

All other trademarks or registered trademarks referenced herein are the property of their respective owners.



Cypress Semiconductor 198 Champion Court San Jose, CA 95134-1709

© Cypress Semiconductor Corporation, 2018-2019. This document is the property of Cypress Semiconductor Corporation and its subsidiaries ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress hardware products. Any other use, reproduction, modification, translation, or compilation of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. No computing device can be absolutely secure. Therefore, despite security measures implemented in Cypress hardware or software products, Cypress shall have no liability arising out of any security breach, such as unauthorized access to or use of a Cypress product. CYPRESS DOES NOT REPRESENT, WARRANT, OR GUARANTEE THAT CYPRESS PRODUCTS, OR SYSTEMS CREATED USING CYPRESS PRODUCTS, WILL BE FREE FROM CORRUPTION, ATTACK, VIRUSES, INTERFERENCE, HACKING, DATA LOSS OR THEFT, OR OTHER SECURITY INTRUSION (collectively, "Security Breach"). Cypress disclaims any liability relating to any Security Breach, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from any Security Breach. In addition, the products described in these materials may contain design defects or errors known as errata which may cause the product to deviate from published specifications. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. "High-Risk Device" means any device or system whose failure could cause personal injury, death, or property damage. Examples of High-Risk Devices are weapons, nuclear installations, surgical implants, and other medical devices. "Critical Component" means any component of a High-Risk Device whose failure to perform can be reasonably expected to cause, directly or indirectly, the failure of the High-Risk Device, or to affect its safety or effectiveness. Cypress is not liable, in whole or in part, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from any use of a Cypress product as a Critical Component in a High-Risk Device. You shall indemnify and hold Cypress, its directors, officers, employees, agents, affiliates, distributors, and assigns harmless from and against all claims, costs, damages, and expenses, arising out of any claim, including claims for product liability, personal injury or death, or property damage arising from any use of a Cypress product as a Critical Component in a High-Risk Device. Cypress products are not intended or authorized for use as a Critical Component in any High-Risk Device except to the limited extent that (i) Cypress's published data sheet for the product explicitly states Cypress has qualified the product for use in a specific High-Risk Device, or (ii) Cypress has given you advance written authorization to use the product as a Critical Component in the specific High-Risk Device and you have signed a separate indemnification agreement.

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.