

## Objective

This example demonstrates how to use a PSoC® 3 or PSoC 5LP device to measure temperature using a thermocouple and how to calibrate the signal chain to achieve 0.1% accuracy with 0.01°C resolution. For a basic project implementing temperature measurement using a thermocouple without calibration, see [CE219905](#).

## Overview

[AN75511](#) describes the theory of thermocouple operation and measurement. [CE219905](#) describes how to measure temperature with a thermocouple using either a PSoC 3 or PSoC 5LP device. This code example shows how to achieve the high-end accuracy described in [AN75511](#). Specifically, this code example shows how to achieve an accuracy of 0.1% with 0.01 °C precision. This accuracy is achieved through calibration. There are two types of calibration – an initial gain offset calibration and a drift calibration.

## Requirements

**Tool:** [PSoC Creator™](#) 4.2 or newer

**Programming Language:** C (Arm® GCC 5.4.1, Arm MDK 5.22, DP8051 Keil 9.51)

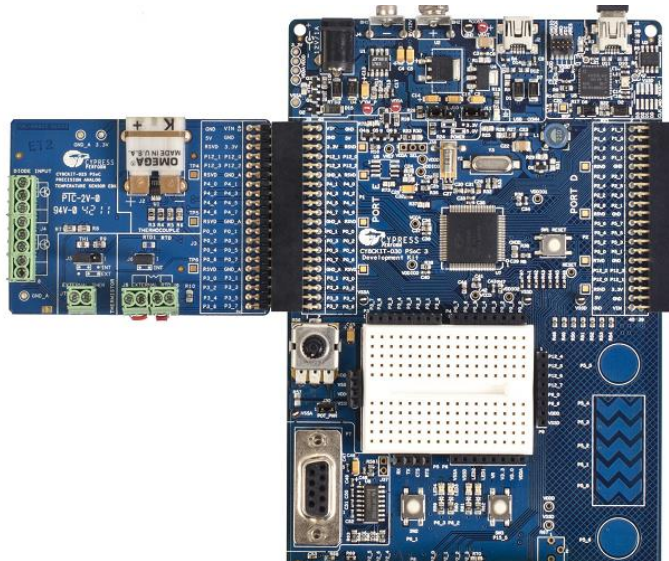
**Associated Parts:** All PSoC 3 and PSoC 5LP parts

**Related Hardware:** [CY8CKIT-050](#), [CY8CKIT-030](#), [CY8CKIT-025](#)

## Hardware Setup

1. Populate an LM4140 (3 ppm/°C) reference on [CY8CKIT-030](#) or [CY8CKIT-050](#) (position U6). Populate R34 (0 Ω), C24 (1 μF) and R37 (0 Ω) on [CY8CKIT-030](#) or [CY8CKIT-050](#). Now, a 1.024-V reference is available on pin 3[2]. It can also be used as an external reference.
2. In the prototyping space, add a resistor divider from pin 3[2] to ground to reduce 1.024 V down to 48.7 mV. Choose R1 = 20 kΩ (0.1%, 5 ppm/°C drift) and R2 = 1 kΩ (0.1%, 5 ppm/°C drift).
3. Connect the 48.7-mV input to pin 0[7]
4. Plug [CY8CKIT-025](#) into PORT E of either [CY8CKIT-030](#) or [CY8CKIT-050](#), as [Figure 1](#) shows.

Figure 1. CY8CKIT-025 Plugged into CY8CKIT-030



5. Plug the thermocouple provided in [CY8CKIT-025](#) into the thermocouple connector as [Figure 2](#) shows.

Figure 2. Thermocouple Section of the EBK



6. Connect an LCD to the LCD port on [CY8CKIT-030](#) or [CY8CKIT-050](#).
7. Plug a USB cable into a PC and then into the programming USB connector on the kit.

## Software Setup

In *main.h*, update the FULL\_SCALE define to match your full-scale calibration voltage.

```
/* Calibration input in microvolts */
#define FULL_SCALE 44760
```

In *main.h*, adjust the temperature threshold for doing a drift calibration by modifying the following code (this is in 100ths of a degree Celsius).

```
/* Temperature change for which gain correction has to be done in 100ths of a degree C. */
#define GAIN_CORRECT_THRESHOLD 500
```

To adjust the IIR filter coefficients, go to *removeOffsetNoise.c*. Adjust the initial values for feedforward, and filter\_coeff\_shift. Also, go to *main.h* and change the value of MAX\_FILTER\_COEFF\_SHIFT. For details, see [AN2099](#).

**Important:** If you create this project from an empty project, go to the **System** tab and change the heap size from 0x80 to 2048. This is needed for the sprintf function.

**Important:** If you create this project from an empty project, right-click on the project and select **Build Setting**. Go to **Linker > command line** and add “-u\_printf\_float” without quotes.

## Math Library

The Thermistor Calculator Component used in this design requires the math library to be linked into the design. That step is already done for you in the attached example.

If you are creating a new PSoC Creator project and using the Thermistor Calculator Component, right-click on your project, and then select **Build Settings....** Expand the compiler group by pressing the **+** button. The name of the compiler will depend on the compiler used in the design; for PSoC Creator 4.2, it is **ARM GCC 5.4-2016-q2-update**. Click on **Linker**, in **Additional Libraries** add **m**, and then click **Apply**.

When using third-party IDEs, the math library will need to be added as well. The steps to do this are specific to each IDE and not described in this document. See your IDE's Help.

## Operation

1. Complete the steps in the [Hardware Setup](#) section.
2. In *main.h*, change `#define FULL_SCALE 63777` to match the voltage of your gain calibration in  $\mu\text{V}$ .
3. Build the project, and program it into the kit.
4. If you wish to calibrate, press SW2.
  - a. To calibrate out temperature offset short the terminals of the thermocouple connector together. After this is done, press SW2. If you don't wish to calibrate just wait.
  - b. Next connect a full-scale  $\sim 64\text{-mV}$  signal across the thermocouple connector. After this is done, press SW2.
  - c. Wait for calibration to complete
5. The LCD displays the thermocouple temperature and cold junction temperature.
6. Press SW2 on the DVK to toggle the cold junction temperature source between the thermistor and the IC.
7. Change the temperature of the thermocouple and observe the measurement change on the LCD.

## Design

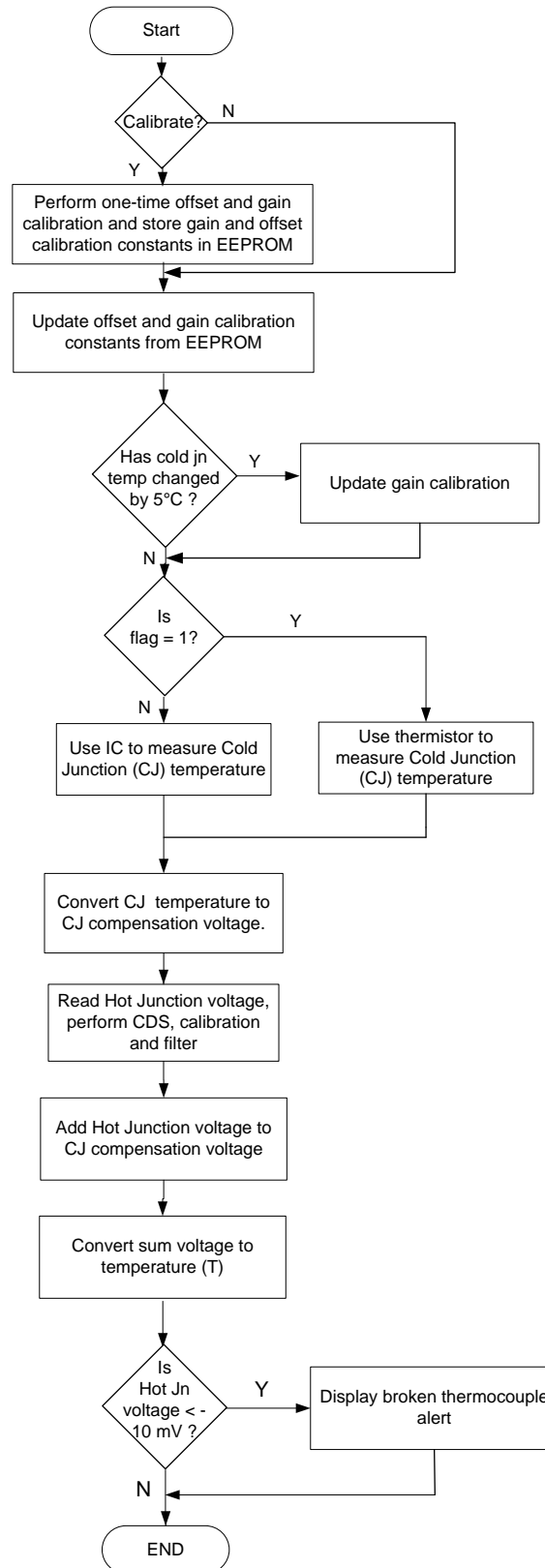
This document describes only how the calibration works. For detailed explanation of how the project works, see [CE219905](#).

To meet the performance of high-end temperature controllers, a one-time gain and offset calibration is required. In some cases, a temperature drift calibration is also required. This code example performs both calibrations.

[Figure 3](#) provides the firmware flowchart of the project. This has the same flow as that of [CE219905](#) with two additional steps:

1. One-time gain and offset calibration
2. Gain drift calibration

Figure 3. CE219929\_PSoC3\_5\_Thermocouple\_Calibration Project Flowchart



Gain drift calibration is performed if the ambient temperature changes by 5 °C. The condition for performing temperature calibration can be changed to periodically performing it based on a timer interrupt, or a combination of temperature or time, or always, or whatever is desired.

## Gain and Offset Calibration

The gain and offset calibration first asks for 0 V to be applied to the thermocouple input. The best way to do this is to short the two inputs of the thermocouple connector together. Because the negative input of the thermocouple is biased at 15 mV, this can be done with the assurance that the value will not float.

Next, the calibration asks for a full-scale input. Because the ADC is configured for ±64 mV, supply an accurate calibration voltage of less than 64 mV. This calibration voltage should be applied across the thermocouple inputs. Remember that the negative input of the thermocouple is tied to 15 mV.

You also need to change the define `FULL_SCALE` to match the value of your calibration reference. This is defined in `main.h`. If, for example, your calibration voltage is 63.209 mV, then change the define to the following:

```
/* Calibration input in microvolts */
#define FULL_SCALE          63209
```

After you have completed the zero and full-scale calibration, the system asks if you want to do Gain Drift Calibration.

## Gain Drift Calibration

The total ADC gain drift (ADC reference + modulator) is characterized at 50 ppm/°C when using an internal reference. The internal reference drift is 20 ppm/°C. You can calibrate out the gain drift using the following procedure:

1. Using a 1.024-V external reference (LM4140), generate a ~50-mV voltage using a low-temperature-coefficient resistor divider (10 ppm/°C).
2. Measure the generated 50 mV ( $V_r$ ) immediately after the gain and offset calibration.
3. Store the value of  $V_r$  in EEPROM.
4. Whenever the temperature increases by 5 °C, measure the 50-mV reference ( $V_t$ ) and compute  $V_r/V_t$ . The cold junction sensor can be used to measure the internal board temperature. (The condition in Step 4 can be anything such as whenever the temperature increases by 1 °C or at periodic duration based on a timer interval, or always)
5. Multiply all subsequent ADC readings with  $V_r/V_t$ .

## Calculations

Use 1-kΩ and 20-kΩ resistances to generate the reference voltage of ~50 mV.

$$V_r = 1.024 * R1 / (R1 + R2) \\ = 48.7 \text{ mV}$$

For the worst-case tempco error, consider a temperature deviation of ±60 °C from the room temperature.

For a 10 ppm/°C (0.001%) resistor, the worst-case error at 60 °C deviation from the room temperature is 0.06%.

The worst-case voltage reference error happens when the tempco is 10 ppm/°C for  $R_1$  and -10 ppm/°C for  $R_2$ .

At 60 °C, the worst-case reference drift = 0.11%.

With 10 ppm/°C resistors, you can achieve a 0.11% gain drift with temperature.

With 5 ppm/°C resistors, you can achieve a 0.057% gain drift with temperature.

## Filtering the Thermocouple Output

The firmware IIR filter used has an attenuation factor of 64. From Table 1 in [AN2099](#), you can see that the temperature settling time (0.1%) is 441 cycles. For this code example, the cycle time is about 50 ms, resulting in a temperature settling time of 22 s.

The IIR filter has a feed forward term that ensures that the temperature settles to within 2 °C in 50 ms. That is, if the source temperature changes from 50 °C to 150 °C, the temperature shown by PSoC will reach 148 °C in 50 ms and 149.9 °C in 22 s.

## Components

Table 1 lists the PSoC Creator Components used in this example, as well as the hardware resources used by each.

Table 1. List of PSoC Creator Components

Component	Hardware Resources
Delta Sigma ADC	1 Delta Sigma ADC
Opamp	1 Opamp
Thermocouple	Firmware
Thermistor	Firmware
AMux	Analog Routing
Debouncer	1 UDB
Character LCD	7 Pins
Emulated EEPROM	Flash

## Parameter Settings

The following tables list the Component parameters that have been changed from their default configuration.

Table 2. ADC IC Temp Config

Parameter	Change
Resolution	16 → 20
Conversion rate (SPS)	10000 → 180
Buffer Mode	“Rail to Rail” → “Level Shift”

Table 3. ADC Thermocouple Config

Parameter	Change
Conversion Mode	Continuous → Single Sample
Resolution	16 → 20
Conversion rate (SPS)	10000 → 59
Input Range	+/-1.024V → ± 0.064V
Buffer Mode	“Rail to Rail” → “Level Shift”

Table 4. ADC Thermistor Config

Parameter	Change
Buffer Mode	“Rail to Rail” → “Level Shift”

Figure 4. OpAmp Settings

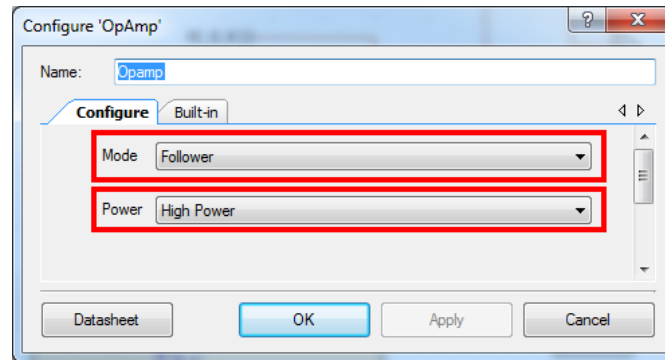
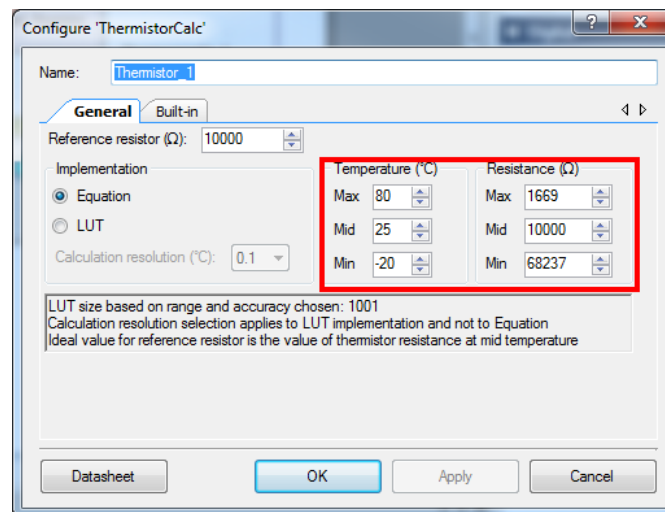


Figure 5. ThermistorCalc Settings



## Design-Wide Resources

Table 5. Pin Locations for PSoC 3 and PSoC 5LP Devices

Pin Name	PSoC 3/ PSoC 5LP Pin Location
LCD	P2[6:0]
CJTemp	P6[1]
IC	P0[6]
TcHotJnNeg	P0[5]
TcHotJnPos	P0[4]
VSSA_REF	P0[3]
VThermPos	P0[0]
VThermNeg	P0[1]
Calib_In_0_7	P0[7]

## Related Documents

Code Example		
<a href="#">CE219905</a>	Thermocouple Measurement	Explains how to measure a thermocouple
Application Notes		
<a href="#">AN75511</a>	Temperature Measurement with Thermocouples	Describes how PSoC 3 and PSoC 5LP devices can be used to measure a thermocouple.
<a href="#">AN66444</a>	Correlated Double Sampling to Reduce Offset, Drift, and Low Frequency Noise	Describes how to implement correlated double sampling on a PSoC device.
<a href="#">AN2099</a>	Single Pole Infinite Impulse Response (IIR) Filters	Describes how to implement a software IIR filter.
PSoC Creator Component Datasheets		
<a href="#">Thermocouple Component</a>	Thermocouple Calculator	
<a href="#">Thermistor Component</a>	Thermistor Calculator	
<a href="#">Delta Sigma ADC</a>	Precision ADC component	
Device Documentation		
<a href="#">PSoC 3 Datasheets</a>	<a href="#">PSoC 3 Technical Reference Manuals</a>	
<a href="#">PSoC 5LP Datasheets</a>	<a href="#">PSoC 5LP Technical Reference Manuals</a>	
Development Kit (DVK) Documentation		
<a href="#">PSoC 3 and PSoC 5LP Kits</a>		
<a href="#">CY8CKIT-025</a>		



## Document History

Document Title: CE219929 - PSoC 3 and PSoC 5LP Thermocouple Calibration

Document Number: 002-19929

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	5791122	TDU	09/15/2018	New spec

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