

# Quasi-resonant control with XMC1000 for LED ballast and SMPS

XMC™ Microcontrollers

June 2016



# Agenda

- 1 Overview
- 2 Introduction
- 3 Quasi-resonant control
- 4 Demonstration with Infineon Designer
- 5 XMC1000 implementation
- 6 Demo boards & virtual designs

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# Quasi-resonant control with XMC1000 - Overview



- › This training slides begin by introducing the losses in various power converter, especially the switching losses and how quasi-resonant control can be used to minimize switching losses
- › The second part of this training slides showcase the implementations of quasi-resonant control with XMC1000 using its peripherals and how they can be implemented on LED ballast and other SMPS

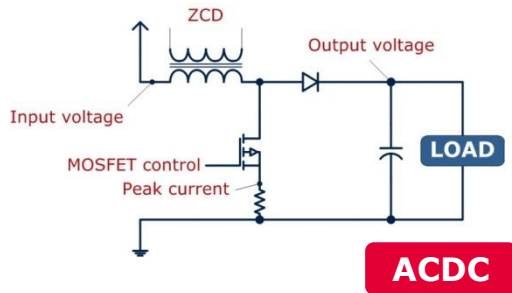
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# Introduction

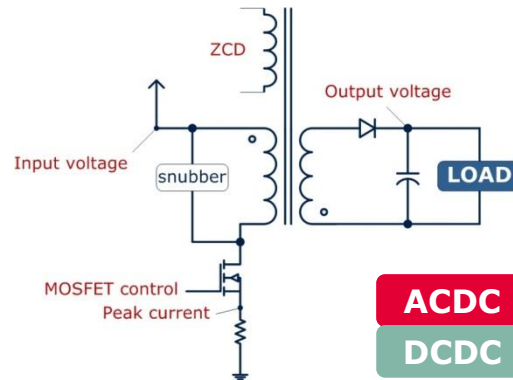
## Power topologies

### > Boost



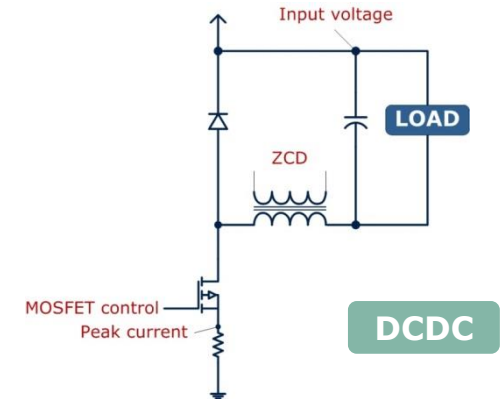
- $V_{out} > V_{in}$
- Power factor correction
- Constant ON time control

### > Flyback



- Buck/boost
- Galvanic isolation
- Power factor correction + constant current control

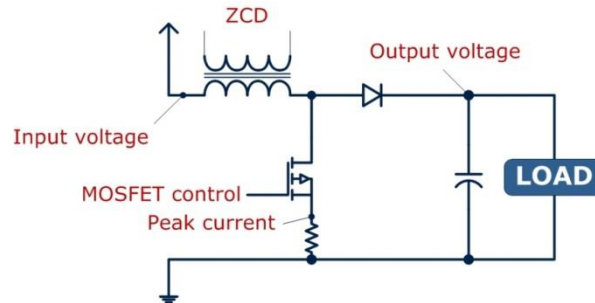
### > Buck



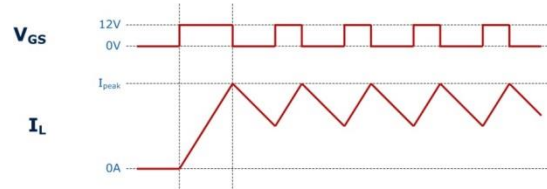
- $V_{out} < V_{in}$
- Peak current control
- Useful for LED driver stage

# Introduction

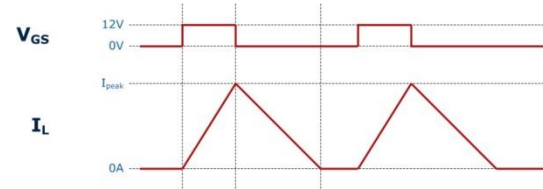
## Conduction mode



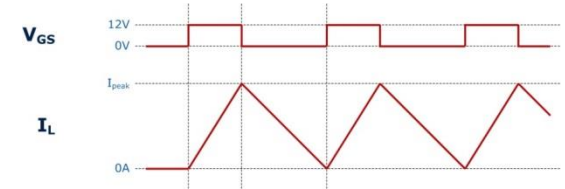
› Continuous conduction mode (CCM)



› Critical conduction mode (CrCM)



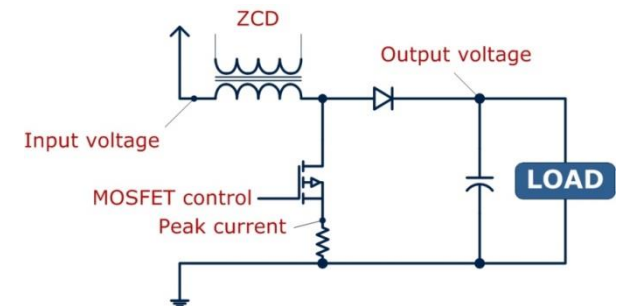
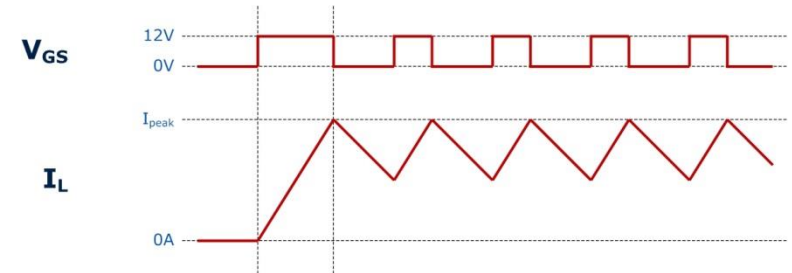
› Discontinuous conduction mode (DCM)



# Introduction

## Continuous conduction mode

- › MOSFET turned on while there is still current in the inductor
- › Maximum switching loss.  
“Hard switching”

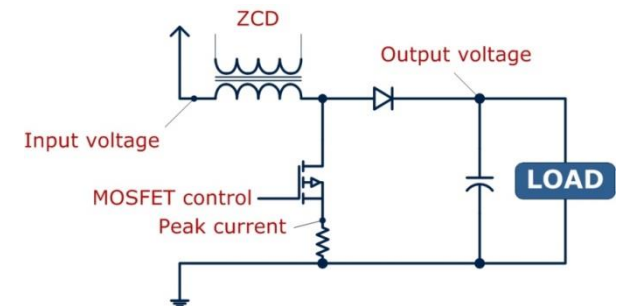
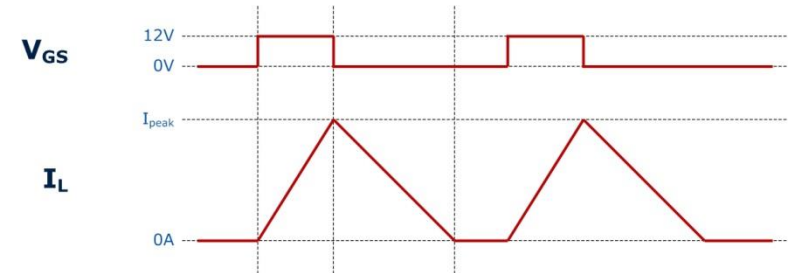




# Introduction

## Discontinuous conduction mode

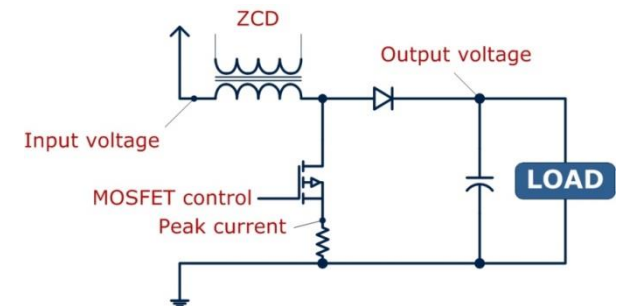
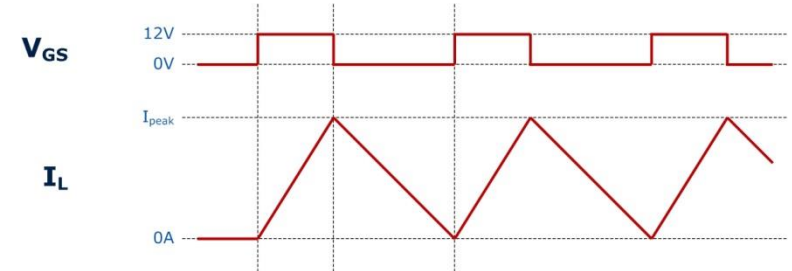
- › MOSFET turned on sometime after inductor current reaches zero
- › Zero current isn't detected
- ›  $V_{DS}$  oscillation is ignored
- › This is the simple way



# Introduction

## Critical conduction mode

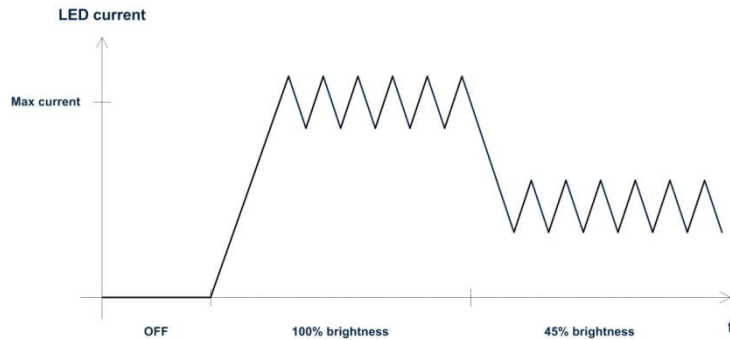
- › Aka boundary conduction mode
- › MOSFET turned on immediately as zero current is detected
  - Reduced turn-on loss



# Introduction

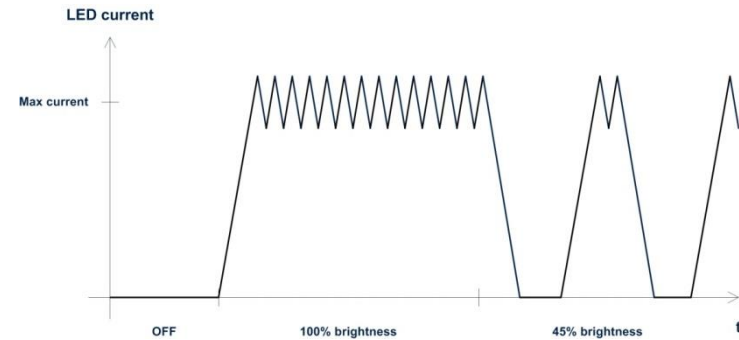
## LED dimming control

### › Analog dimming



- Need good DAC for accuracy
- Classical, straightforward method

### › Modulation dimming



- Simple DAC is sufficient.
- Need modulator. In XMC™: BCCU

### › Both dimming controls work on any conduction mode

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### › Conduction losses

- MOSFET:  $I_D^2 * R_{DS,on}$
- Diode:  $I_F * V_F$
- Shunt:  $I_D^2 * R$
- Inductor/transformer:  $I^2 * R_{series}$

### › Optimization strategy:

- Use larger components
- Wider PCB trace

### › Switching losses

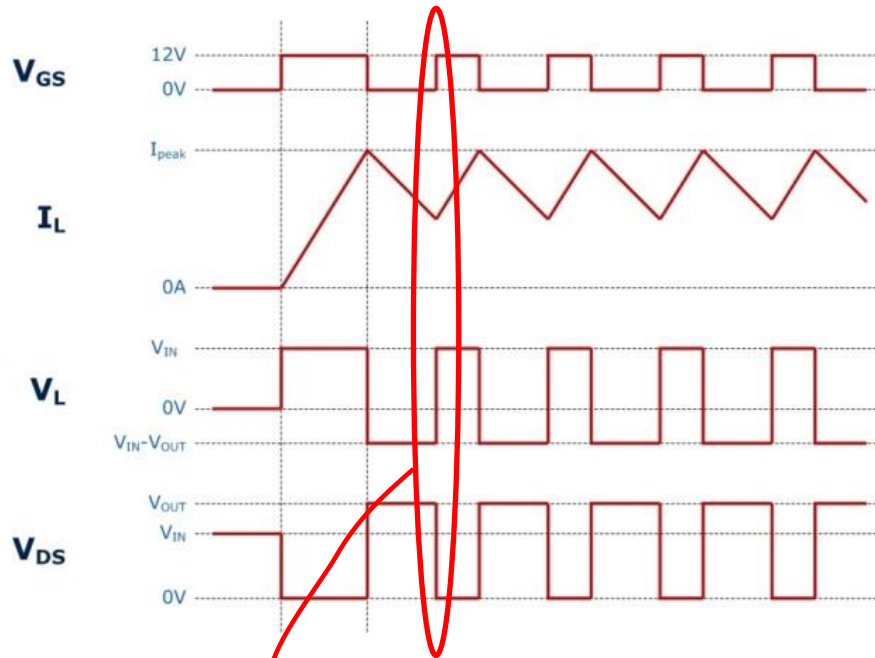
- MOSFET:  $C_{DS}, C_{GD}, C_{GS}, Q_{GD}, Q_{DS}$
- Diode:  $I_{RRM}, t_{RRM}$

### › Optimization strategy:

- Use faster components
- **Optimize the switching scheme**

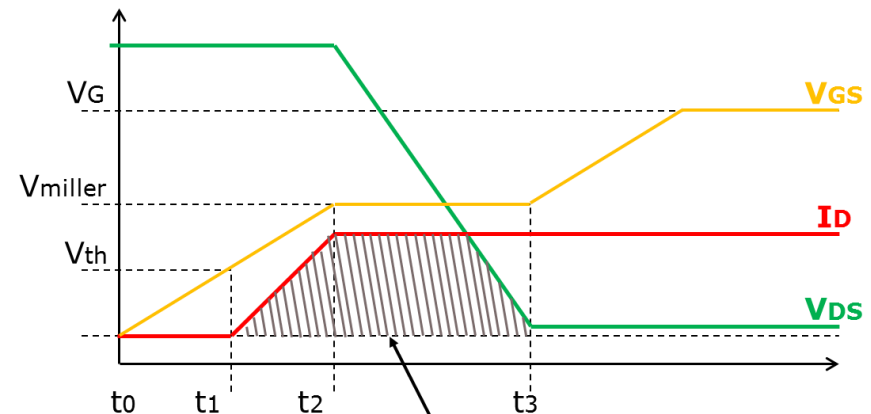
# Quasi-resonant control

## Losses & efficiency



In CCM steady state,  $I_D$  starts from previous current value.

- › T0-T1: Gate driver charges CGS.  $V_{GS}$  slope depends on gate driver current
- › T1-T2:  $V_{GS}$  passes gate threshold. Conducting channel available. Current starts flowing
- › T2-T3: Miller plateau. Depend on CGD and  $V_{DS}$ . **Longer plateau results in higher switching loss**
- › T3 onwards: MOSFET is conducting,  $V_{DS}$  depends on  $R_{DS(ON)}$  and  $I_D$

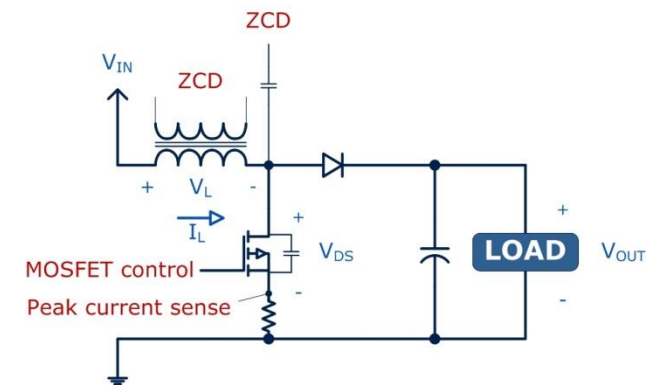
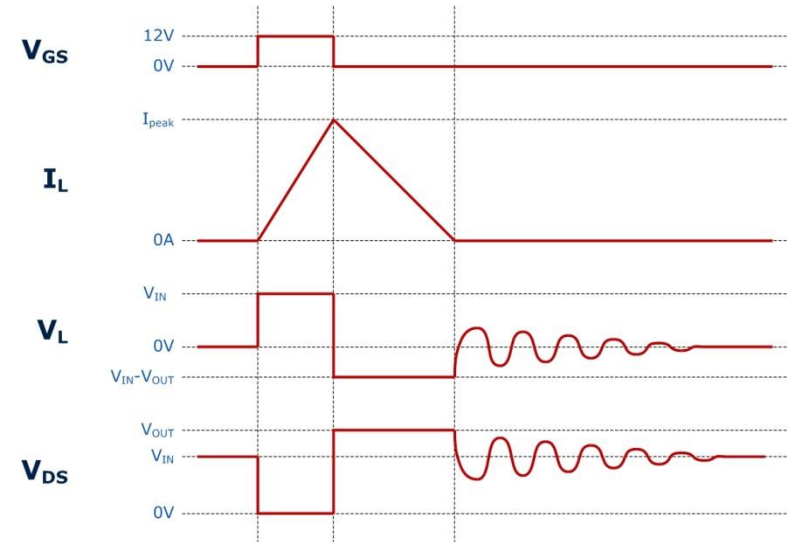


**Switching Loss**  
(area under the curve between  $I_D$  and  $V_{DS}$ )

# Quasi-resonant control

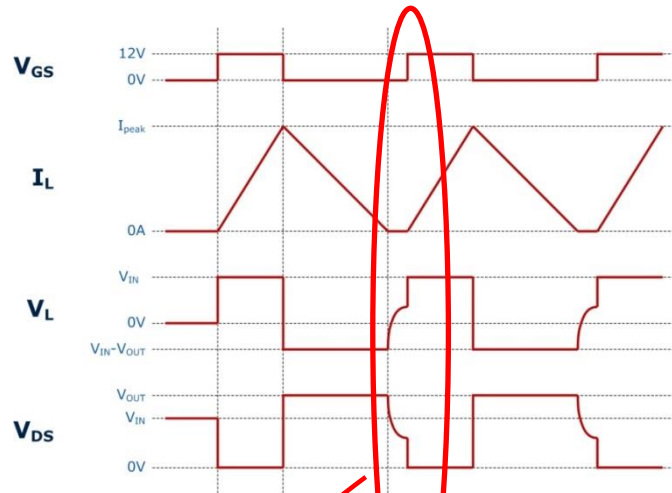
## One time switching

- › MOSFET turned on once
- ›  $V_L$  oscillates once the inductor current reaches zero
  - Frequency depends on main inductance and MOSFET output capacitance
  - High voltage oscillation that is easy to detect (ZCD)
    - Inductive coupling
    - Capacitive coupling
- › ZCD circuits don't measure the actual inductor current!

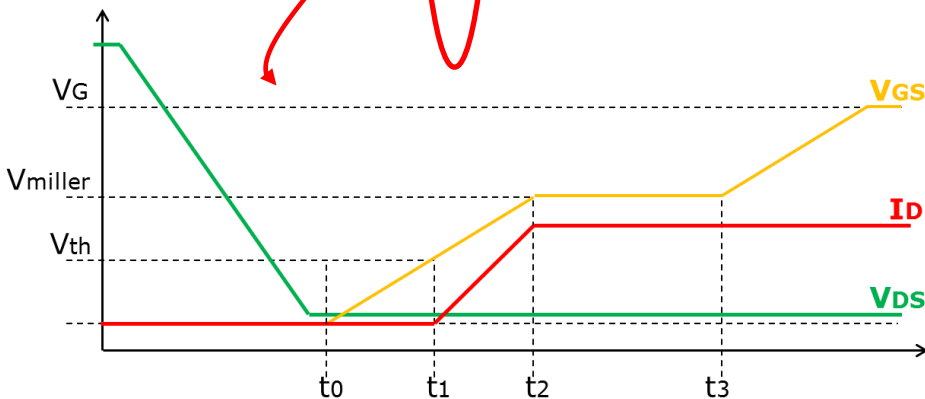


# Quasi-resonant control

## Valley switching



- › Wait for  $V_{DS}$  to fall when output current is fully discharged.
- › Start the next switching cycle at the “valley”
- › Known as “valley switching” or “soft switching”
- ›  $V_{DS}$  is ringing due to second order system behavior (LC)
- › The lower the valley, the lower the switching loss



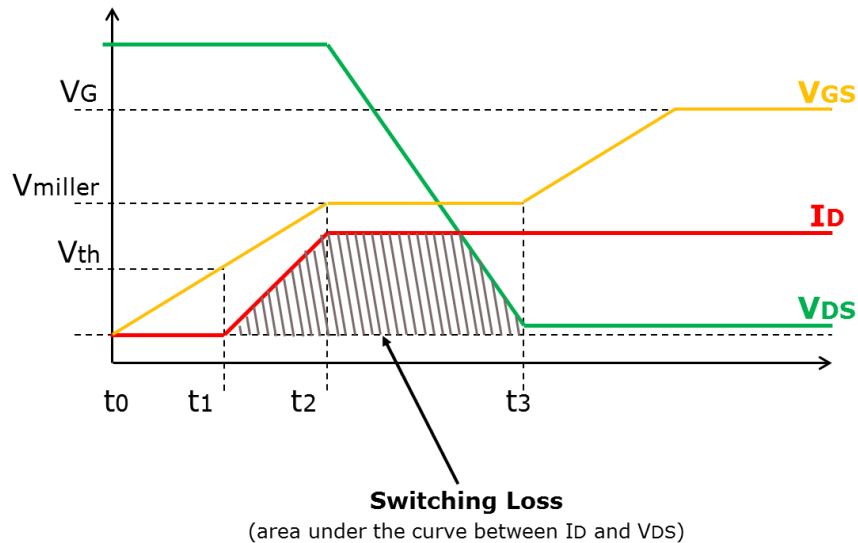
**No Switching Loss**  
(area under the curve between  $I_D$  and  $V_{DS}$ )



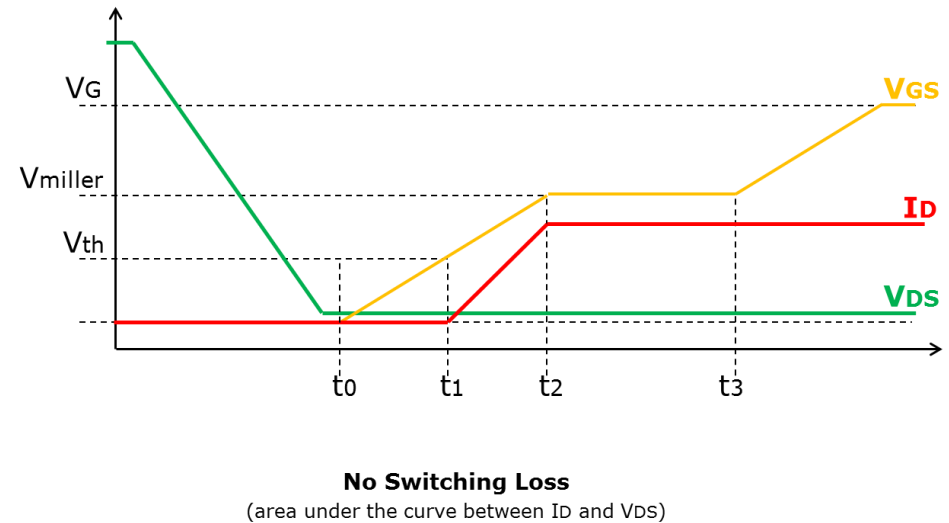
# Quasi-resonant control

## Hard switching vs soft switching

### › Hard switching



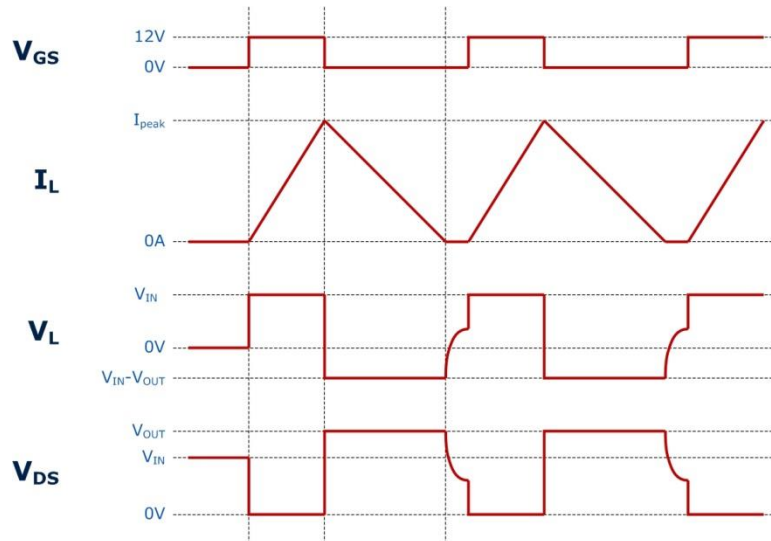
### › Soft switching



# Quasi-resonant control

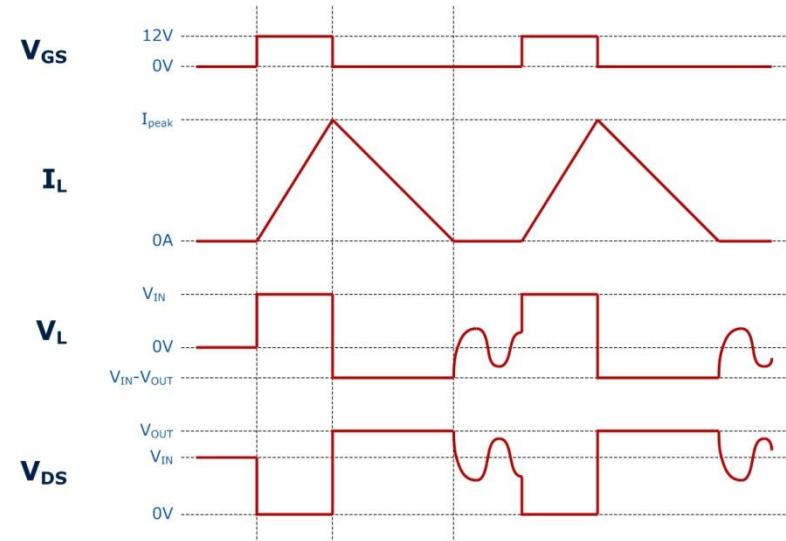
## Valley skipping

### › QR 1<sup>st</sup> valley



- › MOSFET turned on at the first lowest point of  $V_{DS}$  oscillation
  - MOSFET turn-on loss minimized to lowest possible level

### › QR 2<sup>nd</sup> valley



- › MOSFET turned on at the second lowest point of  $V_{DS}$  oscillation
  - MOSFET turn-on loss minimized
  - Switching frequency reduced

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# Infinite Designer Digital prototyping engine

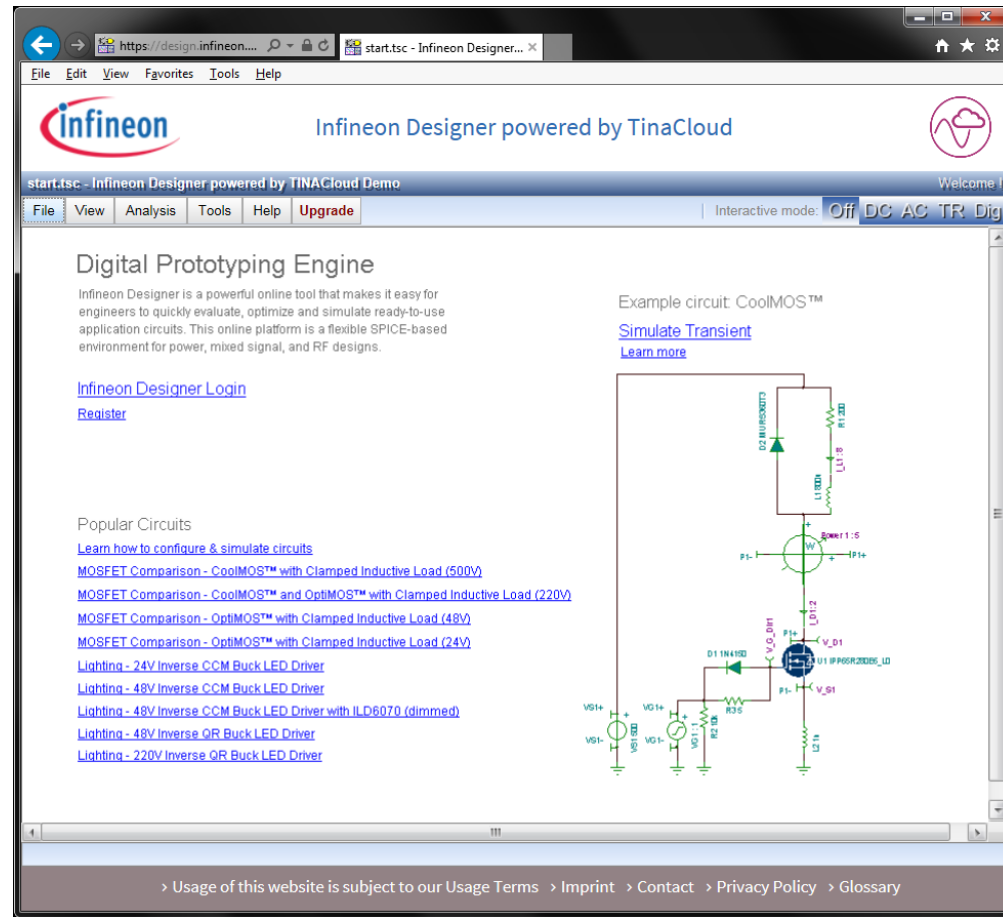


## › Features

- Circuit design
- Circuit behavior (simulation)
- Sharing
- No hassle

## › Infineon Designer is available to everyone:

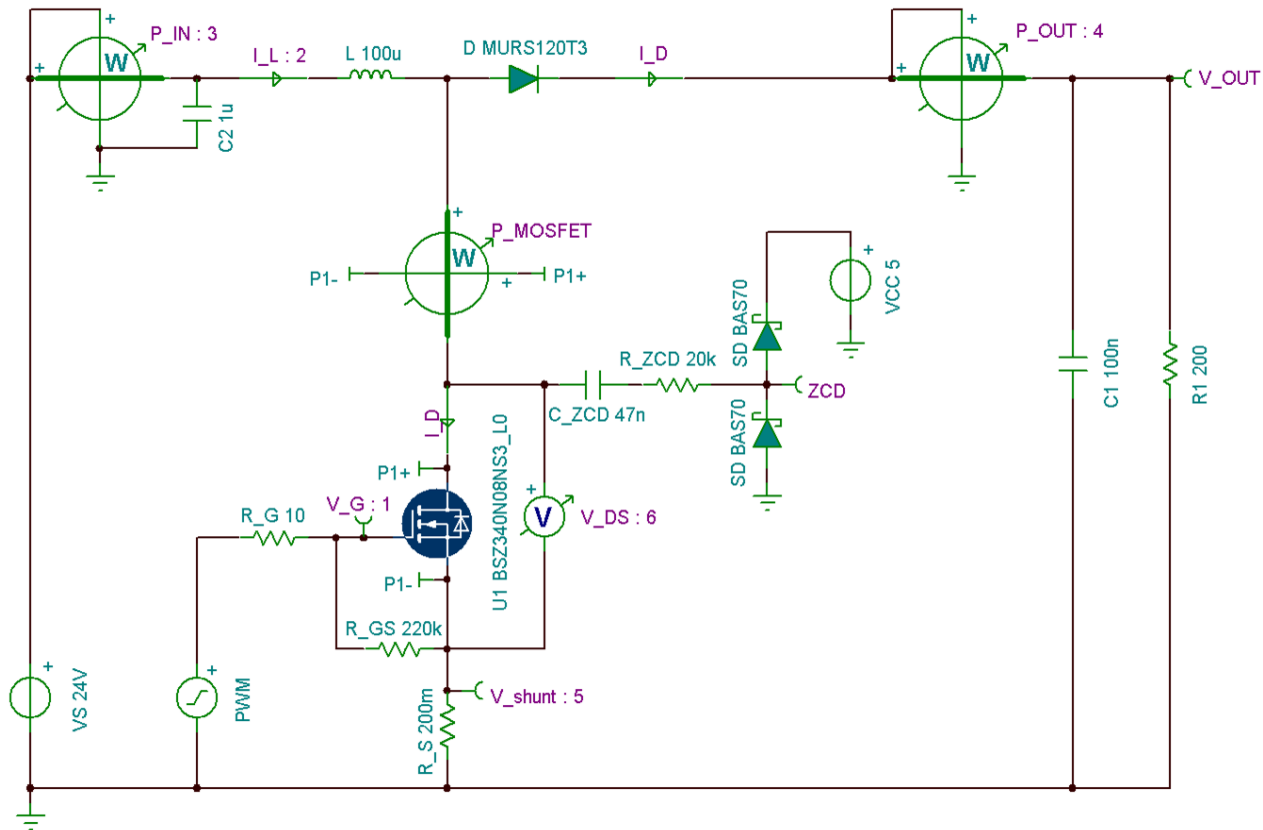
[www.infineon.com/ifxdesigner](http://www.infineon.com/ifxdesigner)  
(login with MyInfineon account)



# Infineon Designer

## Boost converter

- › BSZ340N08NS3 G (OptiMOS™)
- › MURS120T3G
  - Ultrafast recovery diode



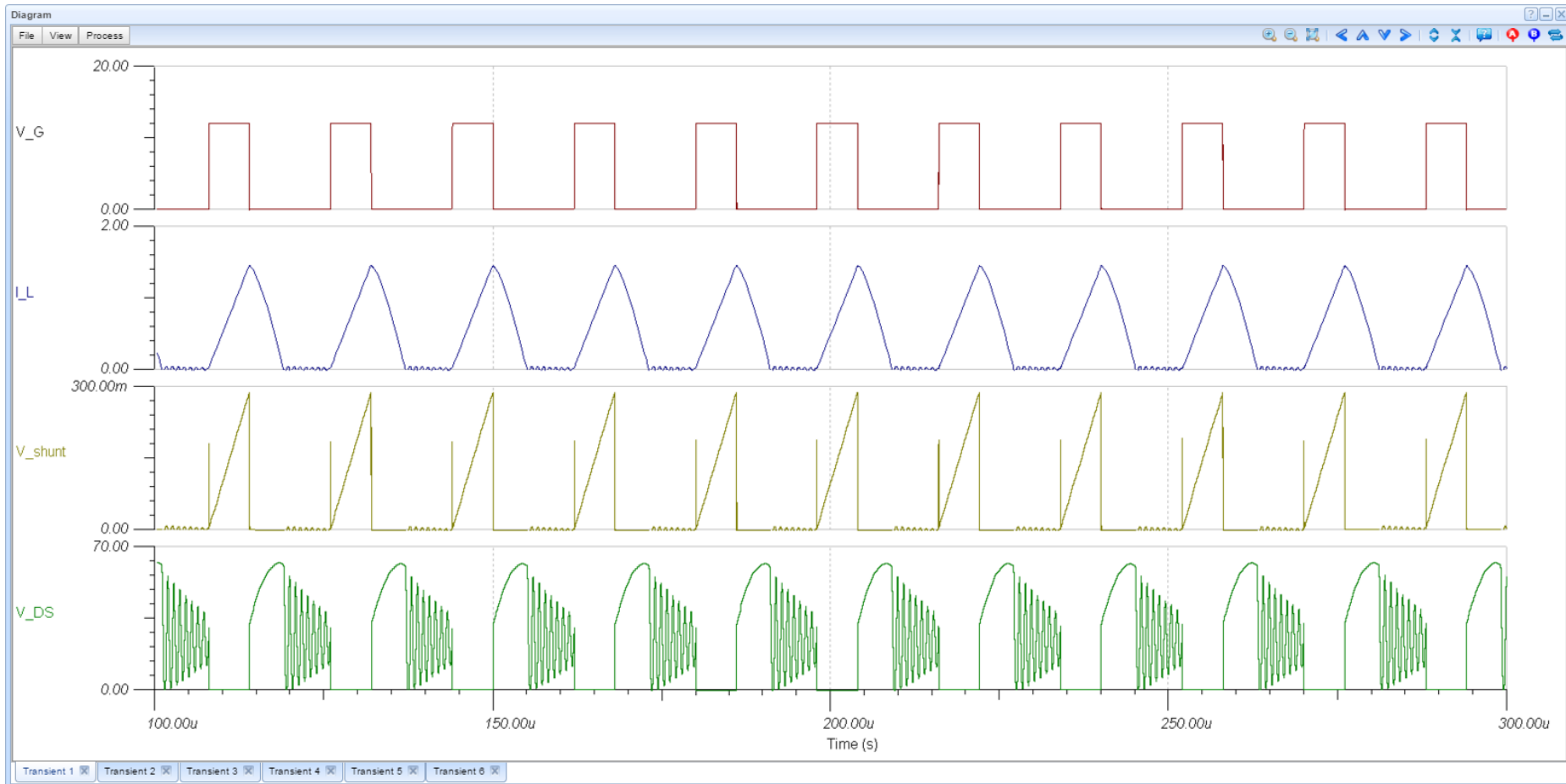
# Infineon Designer

## One time only



Efficiency: NA

Frequency: 56 kHz



[power\\_optimos\\_24V\\_boost\\_1\\_onetime.tsc](#)

# Infineon Designer

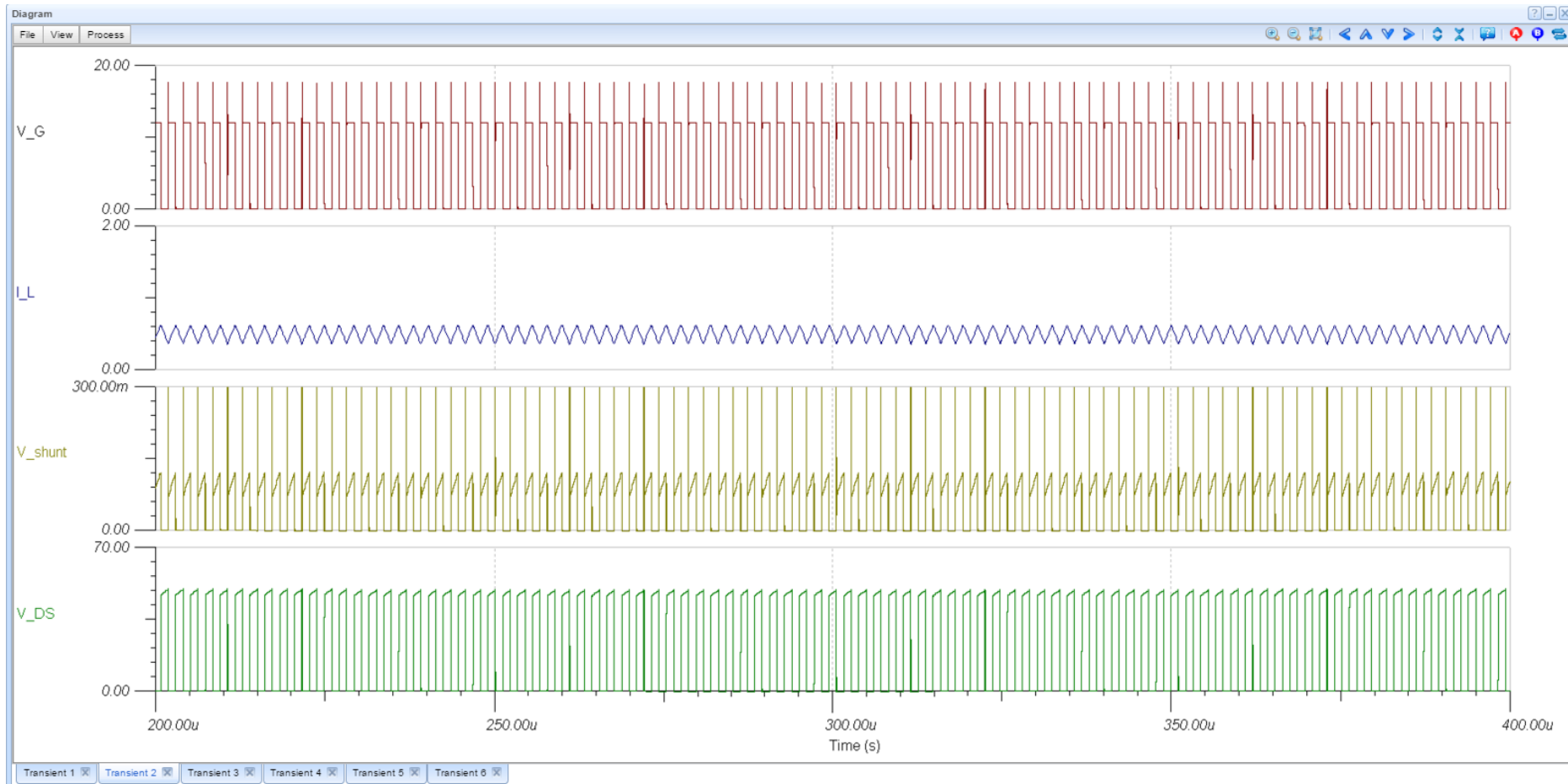
## Continuous conduction mode



Efficiency: 92.7%

Frequency: 456 kHz

Large spikes



[power\\_optimos\\_24V\\_boost\\_2\\_CCM.tsc](#)

# Infineon Designer

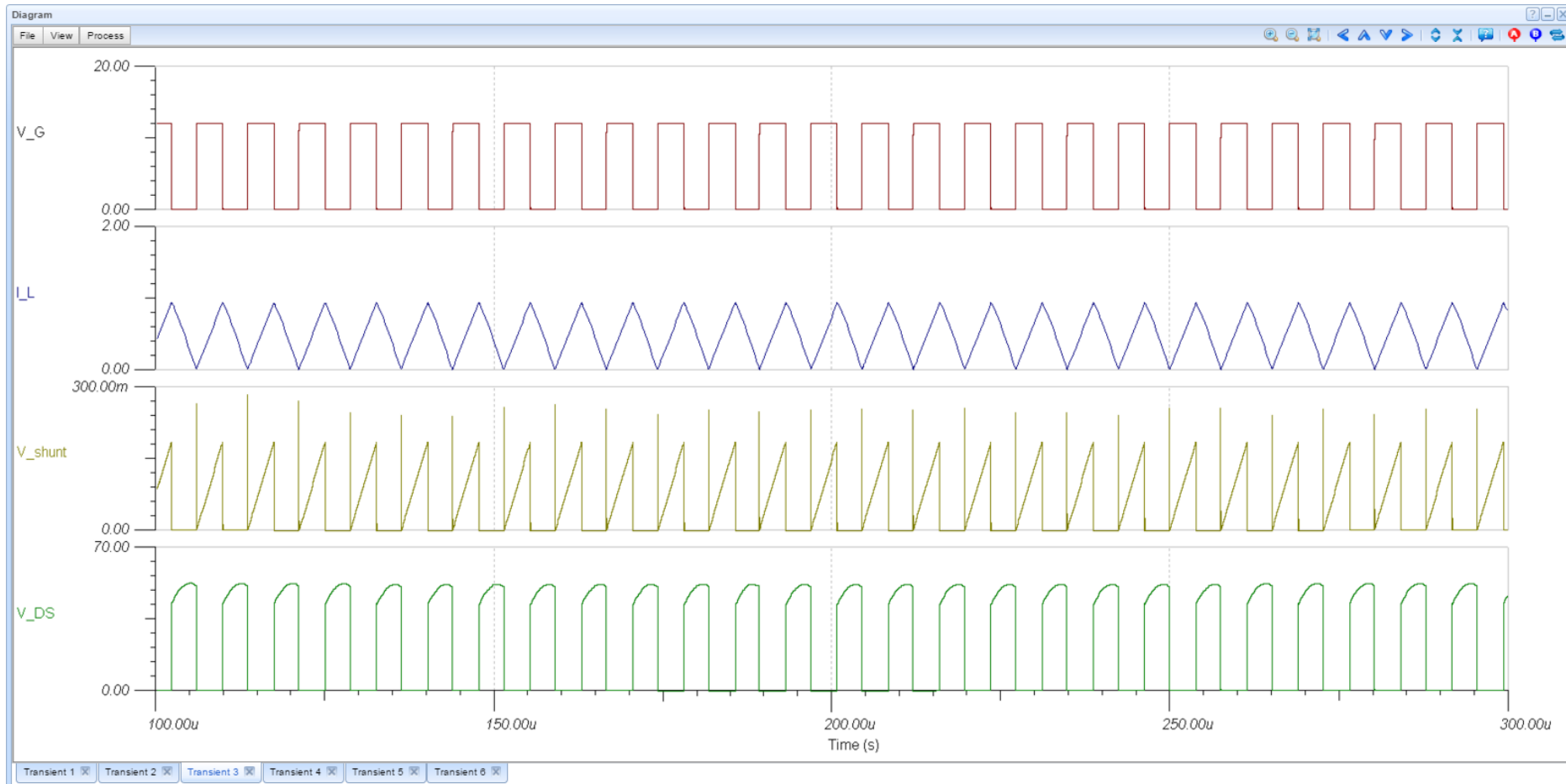
## Critical conduction mode



Efficiency: 97.6%

Frequency: 132 kHz

Medium-sized spikes



[power\\_optimos\\_24V\\_boost\\_3\\_CrCM.tsc](#)



# Infineon Designer

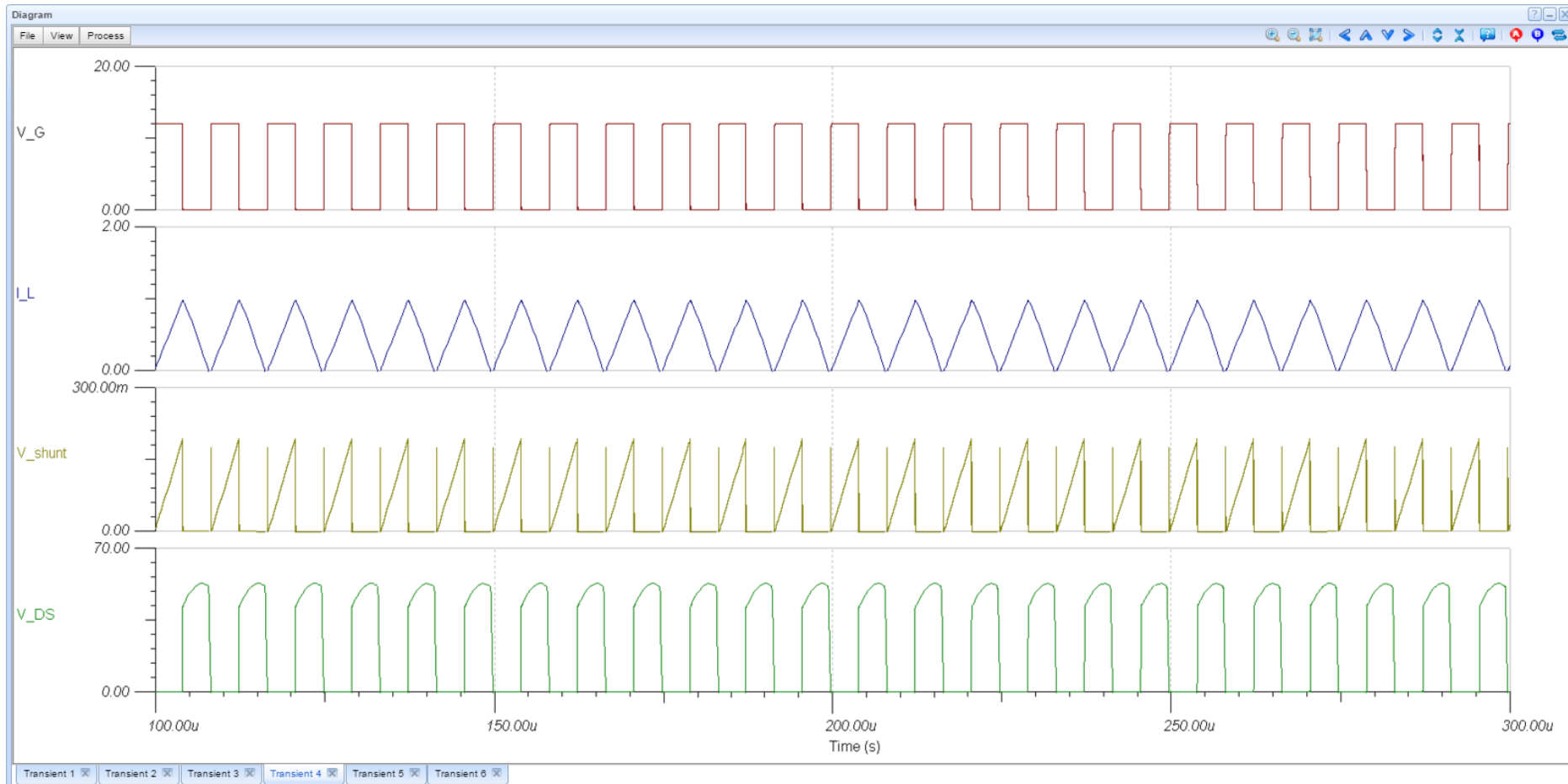
## Quasi-resonant conduction mode – 1<sup>st</sup> valley



Efficiency: 97.9%

Frequency: 120 kHz

Small spikes



[power\\_optimos\\_24V\\_boost\\_4\\_QR\\_1v.tsc](#)

# Infineon Designer

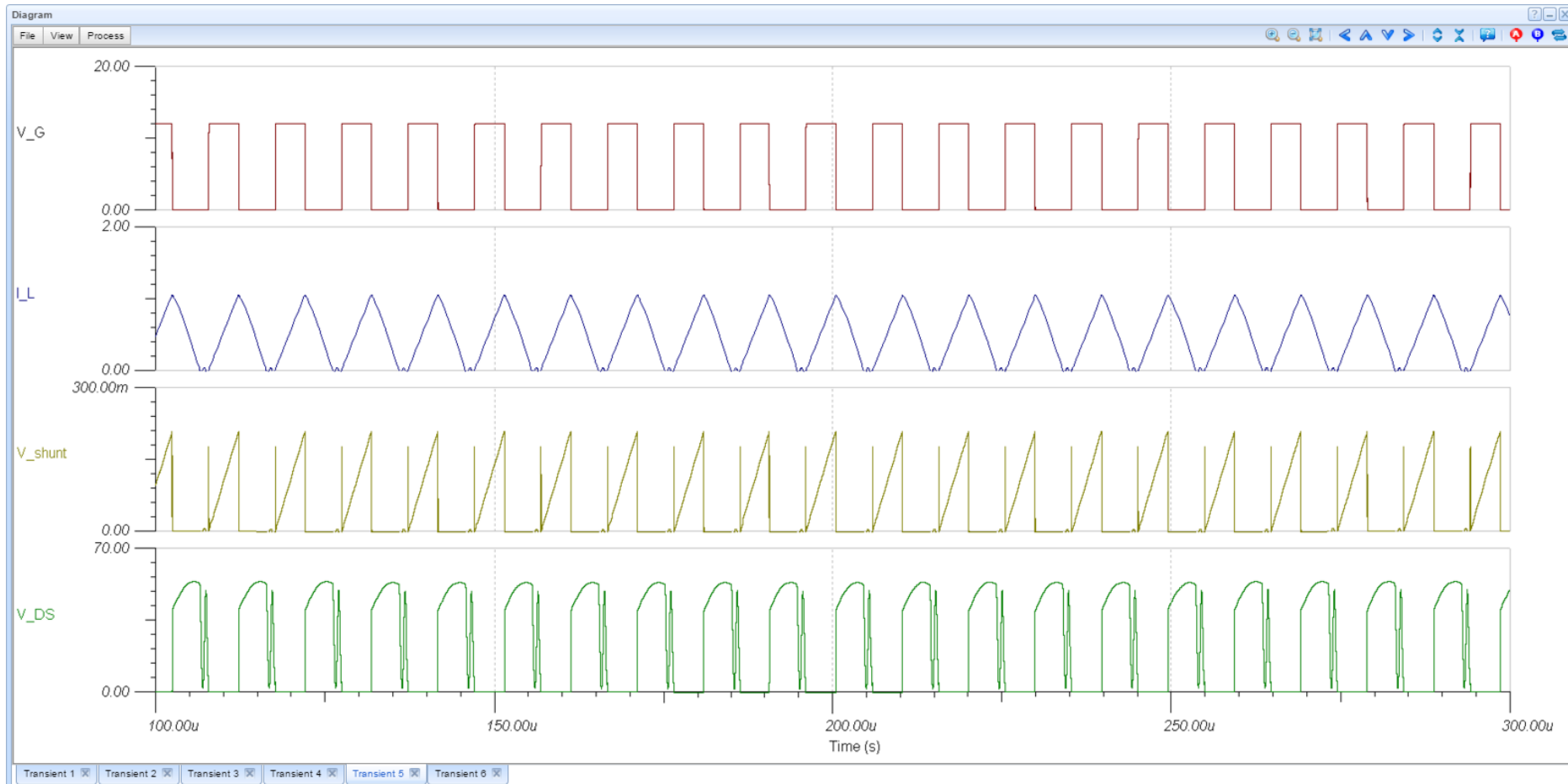
## Quasi-resonant conduction mode – 2<sup>nd</sup> valley



Efficiency: 97.9%

Frequency: 102 kHz

Small spikes



[power\\_optimos\\_24V\\_boost\\_4\\_QR\\_2v.tsc](#)

# Infineon Designer

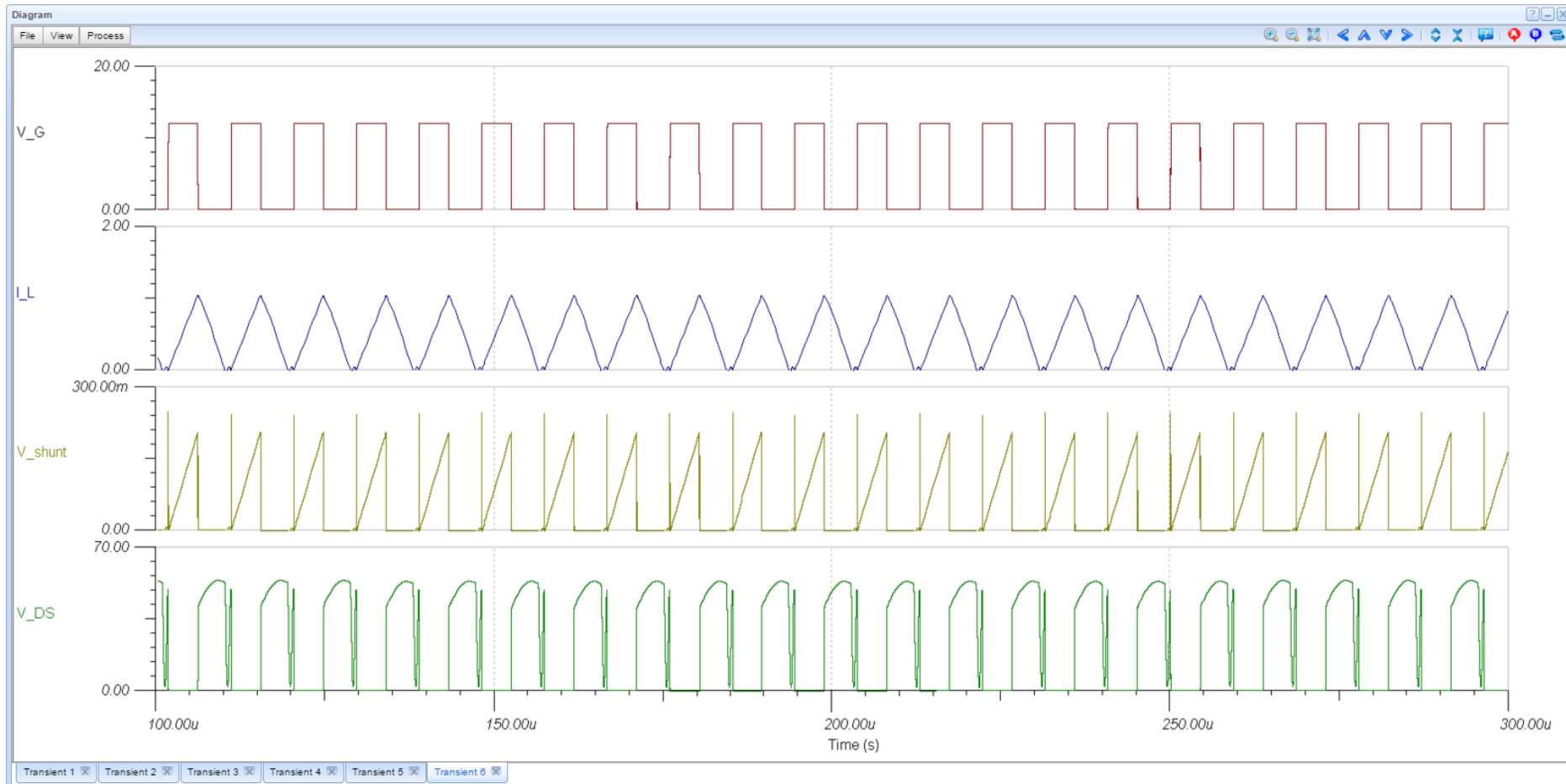
## Discontinuous conduction mode



Efficiency: 97.5%

Frequency: 108 kHz

Medium-sized spikes



[power\\_optimos\\_24V\\_boost\\_5\\_DCM.tsc](#)

# Infineon Designer – [www.infineon.com/ifxdesigner](http://www.infineon.com/ifxdesigner)

## Different conduction modes



Mode	Effic.	Freq.	Link
One time	NA	56 kHz	<a href="#">power_optimos_24V_boost_1_onetime.tsc</a>
CCM	92.7%	456 kHz	<a href="#">power_optimos_24V_boost_2_CCM.tsc</a>
CrCM	97.6%	132 kHz	<a href="#">power_optimos_24V_boost_3_CrCM.tsc</a>
QR-1	97.9%	120 kHz	<a href="#">power_optimos_24V_boost_4_QR_1v.tsc</a>
QR-2	97.9%	102 kHz	<a href="#">power_optimos_24V_boost_4_QR_2v.tsc</a>
DCM	97.5%	108 kHz	<a href="#">power_optimos_24V_boost_5_DCM.tsc</a>

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# XMC1000 implementation

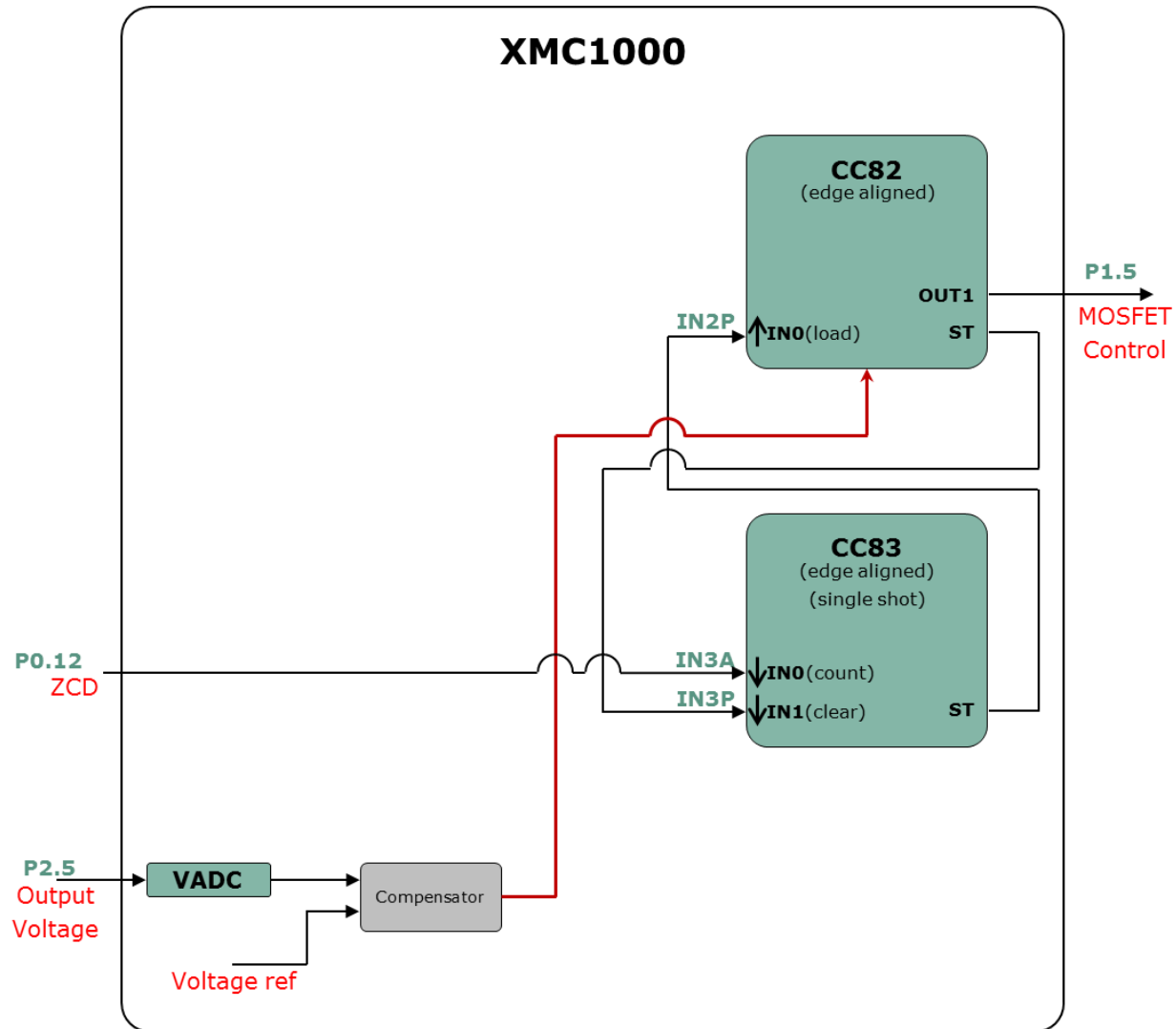
## Quasi-resonant control



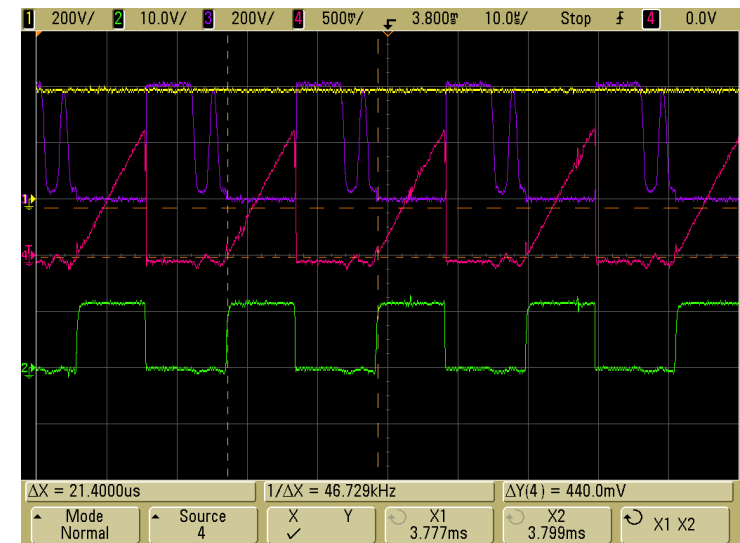
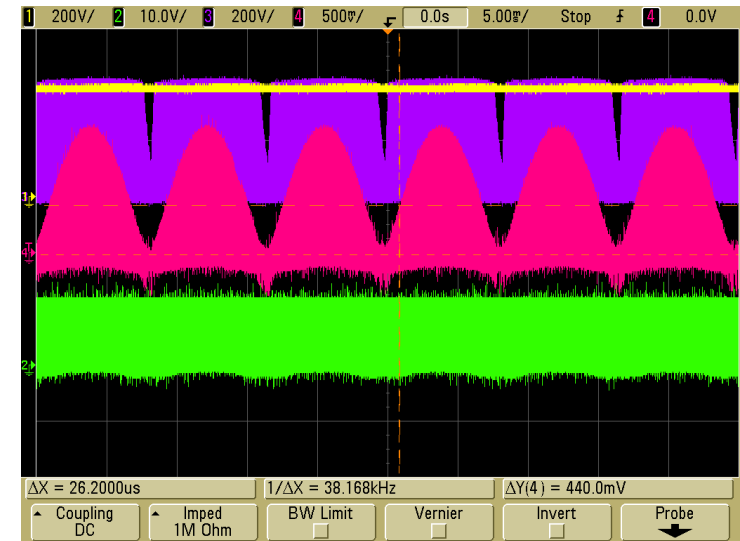
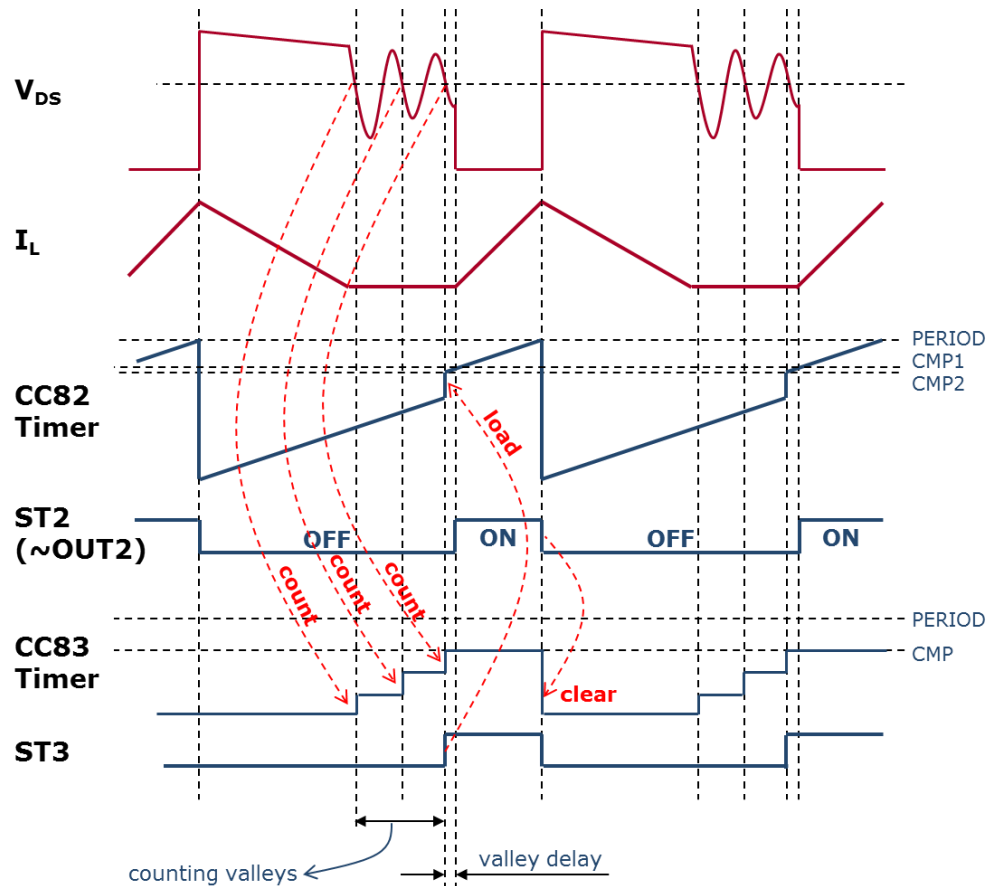
- › XMC1000 peripherals + interconnects for quasi-resonant control
  - CCU8/CCU4, ACMP, ERU, BCCU
  - Fully hardware dependent: minimum CPU load
  - Full functionality including valley skipping, leading edge blanking
  
- › Constant ON-time (CON)
  - ON-time is proportional to the amount of power transfer
- › Peak current control (PCC)
  - Twofold functionality: power transfer and protection
  - Dynamic OCP

# XMC1000 implementation

## QR CON



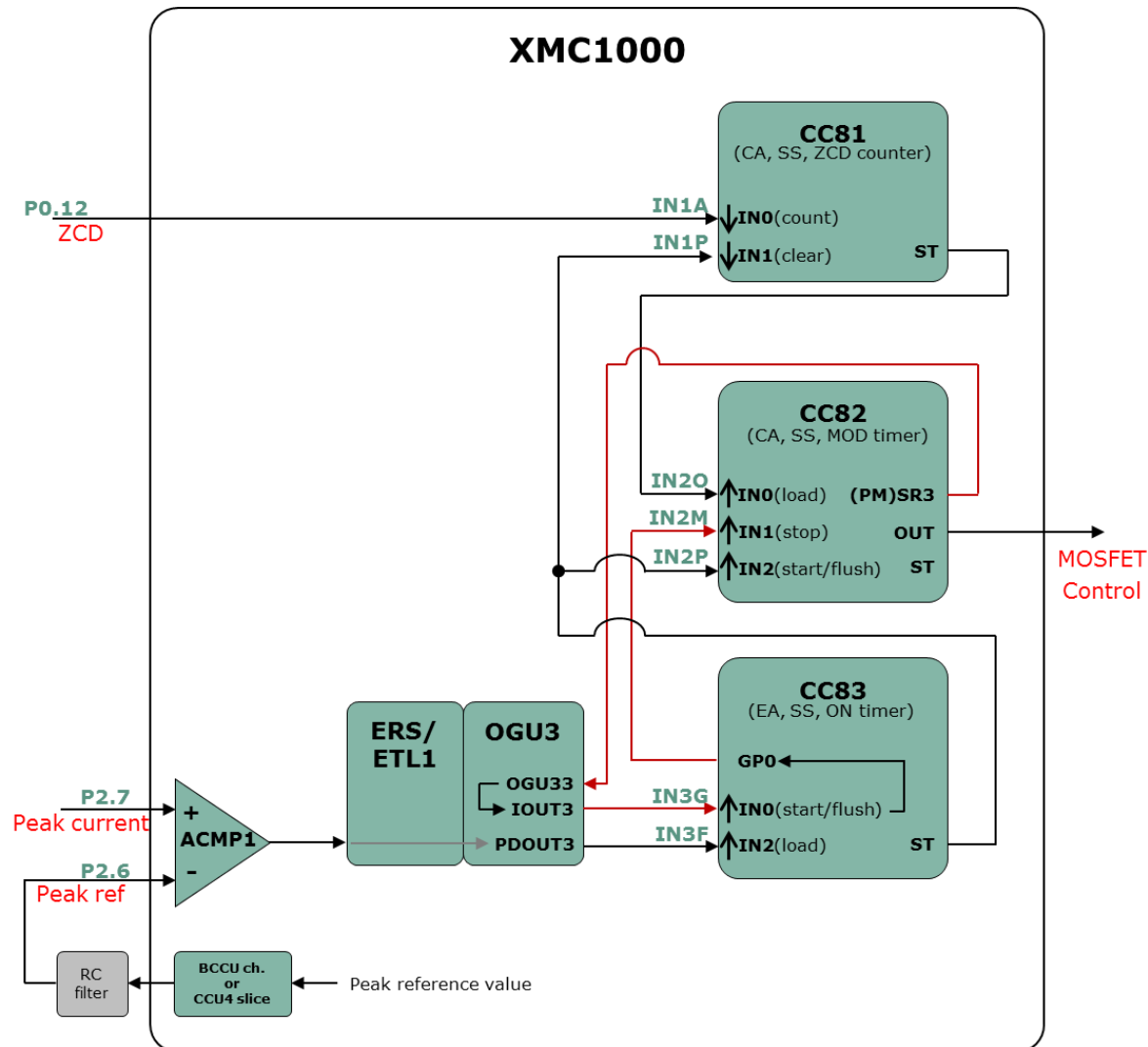
# XMC1000 implementation QR CON





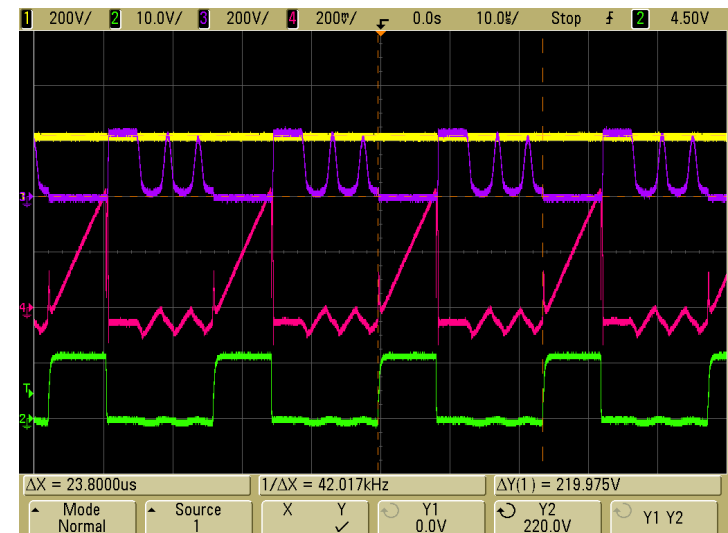
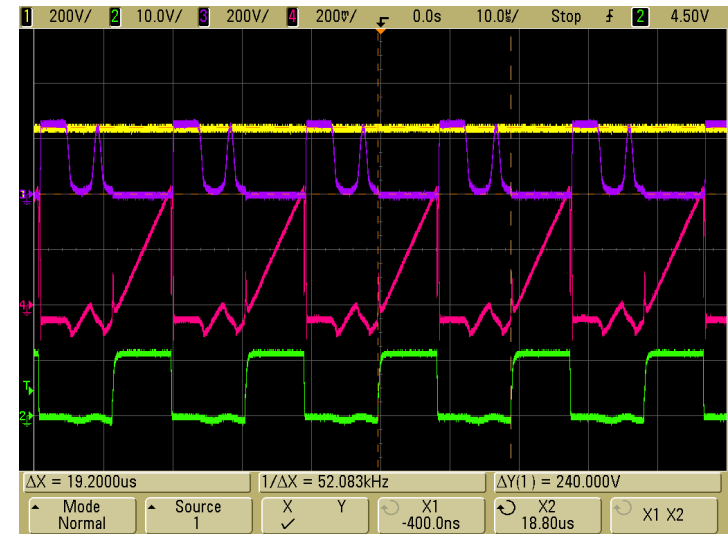
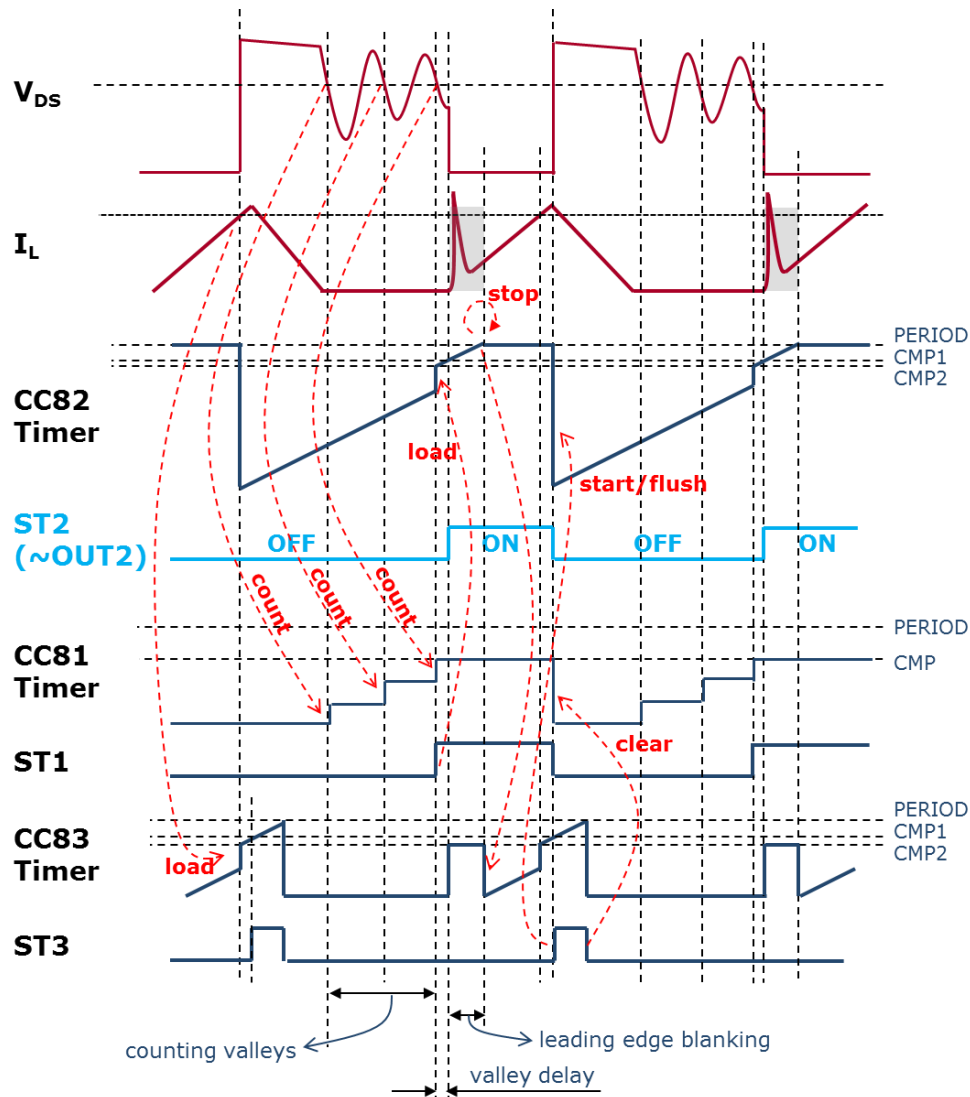
# XMC1000 implementation

## QR PCC



# XMC1000 implementation

## QR PCC

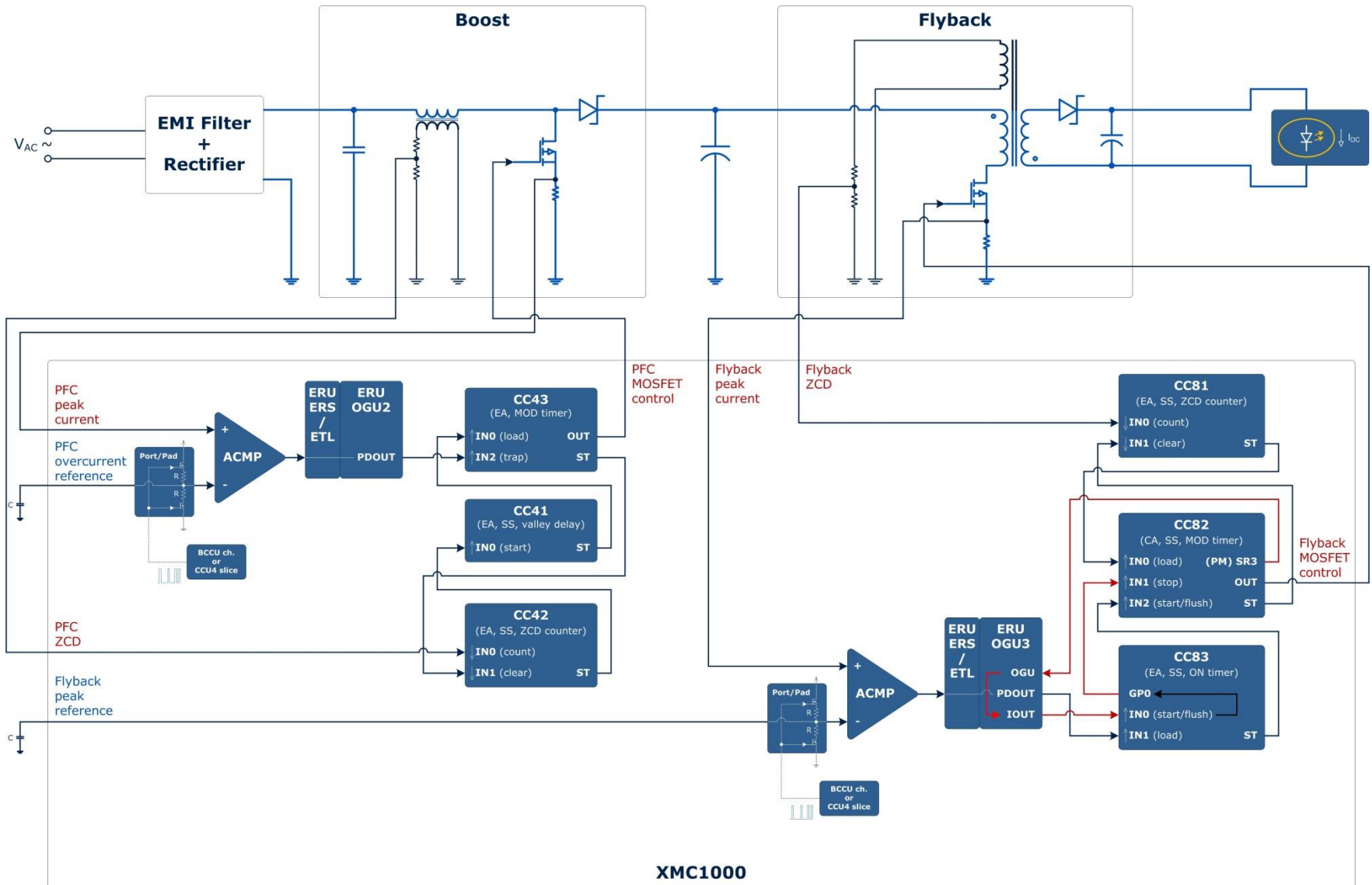


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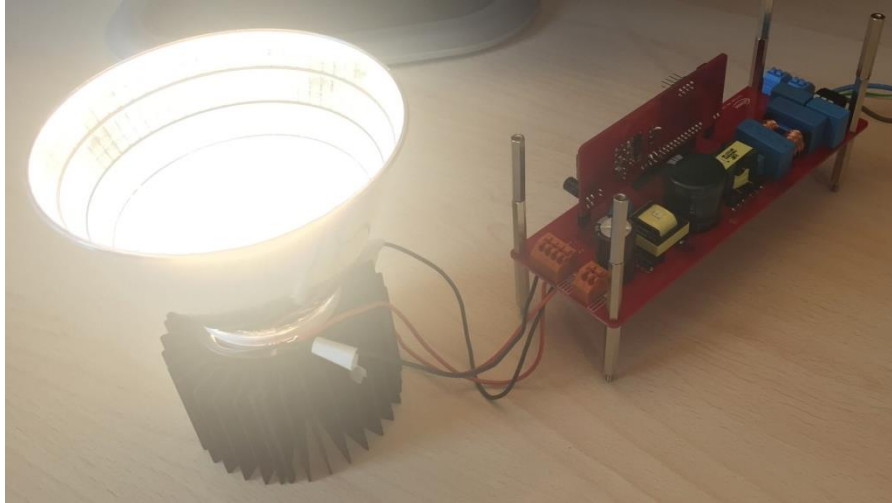
# Demo board

## Two-stage LED ballast with XMC1300



# Demo board

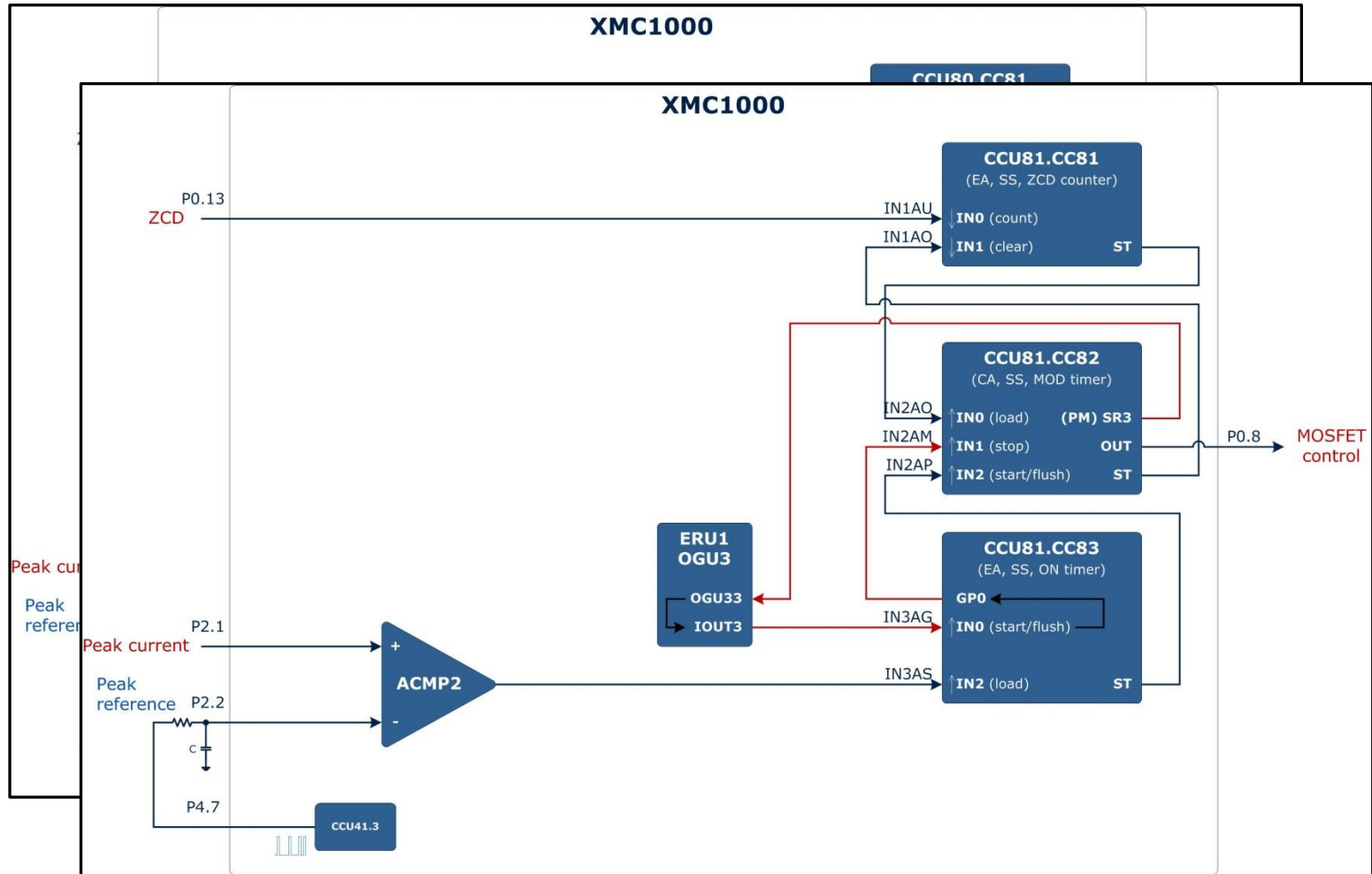
## Two-stage LED ballast with XMC1300



- › Specification:
  - Rated power = 40 W
  - Input voltage = 90 V<sub>AC</sub> to 277 V<sub>AC</sub>
  - Output voltage = 60 V<sub>DC</sub> max
  - Output current = 1 A max
- › Two-stage LED ballast:
  - AC/DC boost PFC for power factor correction
  - DC/DC flyback for LED current and dimming control
- › Quasi-resonant constant ON-time on PFC boost
- › Quasi-resonant peak current control on flyback
- › Tuneable white LED light
- › Communication:
  - DALI, 10 V dimming, LEDset

# Virtual designs

## QR buck LED driver with XMC1400



# Support material:

## Collaterals and Brochures



- › Product Briefs
- › Selection Guides
- › Application Brochures
- › Presentations
- › Press Releases, Ads

› [www.infineon.com/XMC](http://www.infineon.com/XMC)

## Technical Material



- › Application Notes
- › Technical Articles
- › Simulation Models
- › Datasheets, MCDS Files
- › PCB Design Data

› [www.infineon.com/XMC](http://www.infineon.com/XMC)

› [Kits and Boards](#)

› [DAVE™](#)

› [Software and Tool Ecosystem](#)

## Videos



- › Technical Videos
- › Product Information Videos

› [Infineon Media Center](#)

› [XMC Mediathek](#)

## Contact



- › Forums
- › Product Support

› [Infineon Forums](#)

› [Technical Assistance Center \(TAC\)](#)

# Glossary abbreviations

› CON	Constant ON-time
› DAVE™	Free development IDE for XMC™
› OCP	Over Current Protection
› PCC	Peak Current Control
› PF	Power Factor
› PFC	Power Factor Correction
› PWM	Pulse Width Modulation
› QR	Quasi Resonant
› SMPS	Switched-Mode Power Supplies
› THD	Total Harmonics Distortion
› ZCD	Zero Crossing Detection



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