SCR 8-Bit Standby Controller

AURIX[™] TC3xx Microcontroller Training V1.0 2020-12



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SCR 8-Bit Standby Controller





Highlights

- > The SCR is an 8-bit microcontroller that can continue to run during the standby mode.
- It is based on the XC800 core, which is compatible with the industry standard 8051 processor.
- The microcontroller has an embedded 8 KB XRAM for program code and data.

Key Features	Customer Benefits
16-bit General Purpose Timer	> Digital signal generation
Real Time Clock (RTC)	> Periodic wake-up in standby mode
Power Saving Modes	 Various power saving techniques can be implemented



- One of the features of the SCR is the 16-bit T2CCU, which contains three timers: Timer 0, Timer 1:
 - Timer or counter operation
 - 16-bit auto-reload mode
 - Selectable up or down counting
- > Additionally, a 6-channel Capture/Compare Unit is included:
 - 16-bit resolution
 - Six compare channels
 - Four capture channels
- > The timers can be used for digital signal generation or periodic interrupt generation, ensuring high flexibility of the module.

SCR Real Time Clock (RTC)



- One of the SCR's peripherals is the Real Time Clock (RTC), which, once started, can work independently of the state of the rest of the microcontroller.
- The Real Time Clock (RTC) with the on-chip oscillator support the periodic wake-up in standby mode.
- The periodic Wake-up Mode is using either the 70 kHz clock or the 100 MHz /DIV clock.



SCR Power Saving Modes



- > The different Power Saving Modes ensure a very flexible configuration, using either the idle mode or the clock gating control to each peripheral.
- > With only one silicon, two separate core domains are supported:
 - A "high performance" domain (TriCore[™]): this is needed for example, only when the engine is on
 - A "low power" domain (SCR):
 - It is permanently on
 - All features needed for supervising tasks are available
 - Wake-up of high performance domain can be done only when needed (e.g. when the car is started)

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SCR System integration

- The SCR is connected to multiple modules of the AURIX[™] microcontroller:
 - Power Management System: it controls the changes between different power domains
 - Interrupt Router: it triggers different interrupt signals
 - Clock Control Unit: it selects the correct clock source
 - Reset Control Unit: it ensures that the SCR receives the request for reset
 - Debug: SCR has its own debug interface separately from the AURIX[™], which allows parallel debugging of both TriCore[™] and SCR
 - Port Pins: the timers contained in SCR can generate digital signals on these port pins







- > The microcontroller shall perform periodic communication with external components through one of the LIN channels (up to 30 channels).
- The system receives a communication request for the channel through a change in the logical state on one of the TX lines.
- The system respond time for the communication shall not exceed 200 ms and the system current in this mdoe shall not exceed 7 mA, given the total budget of the microcontroller average current of 5 mA.
- The standby mode together with the total amount of pins (the high-end devices have a total amount of 16 pins) fits all the requirements:
 - The periodic wake-up of the TriCore[™] cluster in a minimal configuration can take place in order to acquire the necessary amount of signals.
 - Even though the TriCore[™] domain requires a relatively high current, the average current remains low since most of the time only the SCR with a minimum functionality remains active.

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