SMU_Reset_Alarm_1
for KIT_AURIX_TC397_TFT
Reset triggered by an SMU alarm
Scope of work

The SMU triggers an alarm, which resets the device as preconfigured reaction.

The Safety Management Unit (SMU) is configured to trigger a reset if an internal software alarm occurs.
Introduction

- The Safety Memory Unit (SMU) is a central and modular component of the safety architecture providing a generic interface to manage the behavior of the microcontroller under the presence of faults.

- The SMU centralizes all the alarm signals related to the different hardware- and software-based safety mechanisms.

- Each alarm can be individually configured to trigger internal or external actions.

- The SMU in combination with the embedded safety mechanisms, is able to detect and report more than 99% of the critical failure modes.

- In this example, Software Alarm 0 is used to trigger a reset.
Hardware setup

This code example has been developed for the board KIT_A2G_TC397_5V_TFT.
Configure the SMU module

To trigger a reset with an SMU alarm, a few steps are required:

- To modify the SMU registers, the SMU module has to be unlocked with the function `IfxSmu_unlockConfigRegisters()`. After modification, the SMU registers have to be locked again using the function `IfxSmu_lockConfigRegisters()`.
- To modify SMU configuration registers, it is required to clear and set the Safety ENDINIT protection. This is done with the functions `IfxScuWdt_clearSafetyEndinit()` and `IfxScuWdt_setSafetyEndinit()`.
- To enable the SMU reset, the SMU field of the Reset Configuration Register (`RSTCON`) has to be set to 0x1 for a system reset or 0x2 for an application reset (`SCU_RSTCON.B.SMU = 0x1`).
The function `IfxSmu_setAlarmAction()` configures the alarm’s behavior by writing a 3-bit code to the three Alarm Configuration Registers associated to the specific alarm and its group. In this example, the software alarm 0 (`IfxSmu_Alarm_Software_Alarm0`) and the SCU reset (`IfxSmu_InternalAlarmAction_reset`) are selected. The iLLD function itself selects the group based on the above mentioned parameters.

- Start the SMU state machine (SSM) with the function `IfxSmu_activateRunState()`.

The functions above are provided by the iLLD headers `IfxSmu.h` and `IfxSrc.h`. 
Implementation

Triggering of the alarm

The Software Alarm 0 can be triggered with the function `IfxSmu_setAlarmStatus()` provided by the iLLD header `IfxSmu.h`. 
Run and Test

After code compilation and flashing the device, check if LED D106 (1) is turned on.

Note: If the debugger is disconnected, the LED D106 will blink very fast (continuous reset). In the case the debugger is connected, the LED D106 will blink once, due to the fact that after the reset the connection to the board was re-established.
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# Revision history

<table>
<thead>
<tr>
<th>Revision</th>
<th>Description of change</th>
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<tbody>
<tr>
<td>V1.0.1</td>
<td>Update of version to be in line with the code example’s version</td>
</tr>
<tr>
<td>V1.0.0</td>
<td>Initial version</td>
</tr>
</tbody>
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