

SMU_IR_Alarm_1 for KIT_AURIX_TC297_TFT

Interrupt triggered by an SMU alarm

AURIX™ TC2xx Microcontroller Training
V1.0.1



Scope of work

The SMU triggers an alarm, which has, as preconfigured reaction, an interrupt. The interrupt turns on an LED.

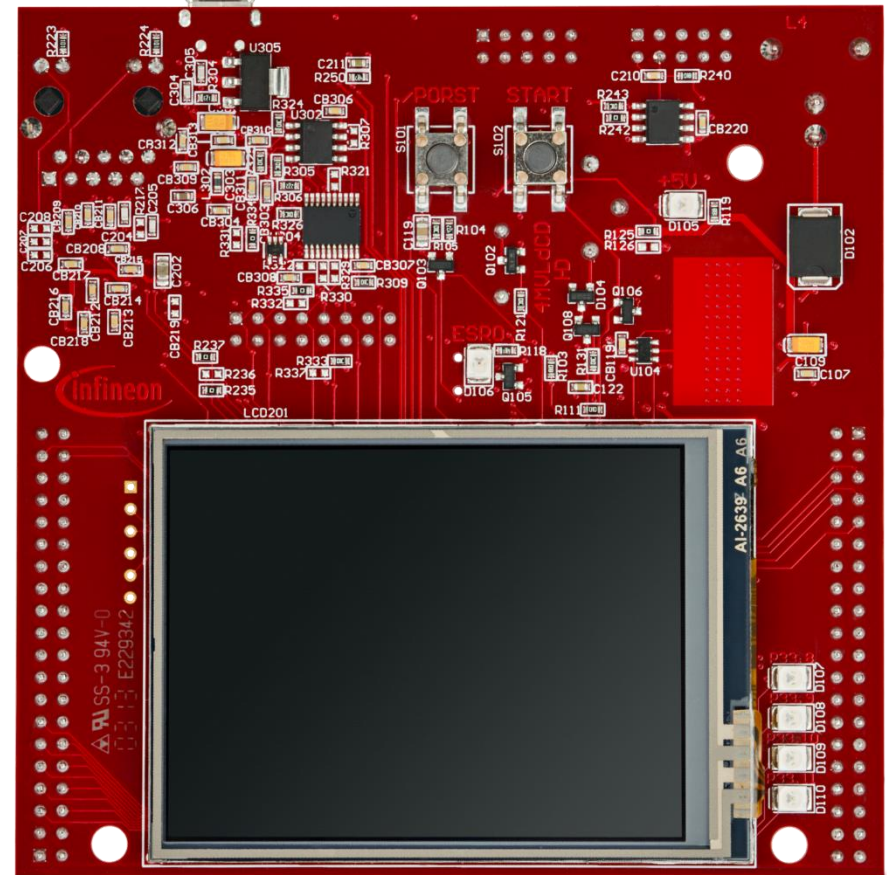
The Safety Management Unit (SMU) is configured to trigger an interrupt if an internal software alarm occurs. In case of an alarm, an LED will be turned on inside the Interrupt Service Routine.

Introduction

- › The Safety Management Unit (SMU) is a central and modular component of the safety architecture, providing a generic interface to manage the behavior of the microcontroller under the presence of faults.
- › The SMU centralizes all the alarm signals related to the different hardware- and software-based safety mechanisms.
- › Each alarm can be individually configured to trigger internal or external actions.
- › The SMU, in combination with the embedded safety mechanisms, is able to detect and report more than 99% of the critical failure modes.
- › In this example, Software Alarm 0 is used to trigger an interrupt.

Hardware setup

This code example has been developed for the board
KIT_AURIX_TC297_TFT_BC-Step.



Implementation

Configure the SMU module

- › To trigger an interrupt with an SMU alarm, a few steps are required:
 - To modify the SMU registers, the SMU module has to be unlocked with the function ***IfxSmu_unlock()***. After the modification is finished, the SMU registers should be locked again using the function ***IfxSmu_lock()***.
 - Additionally, it is required to clear and set the Safety ENDINIT protection before and after the modification of the SMU configuration registers. This is done with the functions ***IfxScuWdt_clearSafetyEndinit()*** and ***IfxScuWdt_setSafetyEndinit()***.
 - The Alarm Global Configuration register (**SMU_AGC**) provides the software interface to control how the SMU triggers interrupt requests to the interrupt router. By setting the **IGCS0** bitfield to **1**, SMU Interrupt Request 0 is triggered.
 - The function ***IfxSmu_setAlarmConfig()*** configures the alarm's behavior by writing a 3-bit code to the three Alarm Configuration Registers associated to the specific alarm and its group. In this example, the software alarm 0 (***IfxSmu_Alarm_SoftwareAlarm0***) and the Interrupt Generation Configuration Set 0 (***IfxSmu_AlarmConfig_interruptSet0***) are selected. The iLLD function itself selects the group based on the above mentioned parameters.
 - Configure and enable the SMU Service Request 0 with the functions ***IfxSrc_init()*** and ***IfxSrc_enable()***.
 - Start the SMU state machine (SSM) with the function ***IfxSmu_cmd()*** and the parameter ***IfxSmu_Cmd_start***.

The functions above are provided by the iLLD headers ***IfxSmu.h*** and ***IfxSrc.h***.

Implementation

LED configuration

- › The port pin with the connected LED is configured to push-pull output mode by calling the function ***IfxPort_setPinMode()*** with the parameter ***IfxPort_Mode_outputPushPullGeneral*** (enumerated type value).
- › With the function ***IfxPort_setPinState()***, using the enumerated type value ***IfxPort_State_high***, the LED is turned off as default state.

All functions above are provided by the iLLD header ***IfxPort.h***.

Triggering of the alarm

- › The Software Alarm 0 can be triggered with the function ***IfxSmu_triggerAlarm()*** provided by the iLLD header ***IfxSmu.h***.

Implementation

The Interrupt Service Routine (ISR)

- › The alarm status flag reset is implemented inside the ISR triggered by the SMU (*IfxSmu_clearAlarm()*). In order to enable the clearing of the alarm, the command *IfxSmu_cmd(IfxSmu_Cmd_enableClearAlarmStatus)* is required. Both functions are provided by the iLLD header *IfxSmu.h*.
- › The LED is turned on inside the ISR to indicate the successful configuration of the SMU and the triggering of the interrupt. This is done by setting the port pin of the connected LED by using the function *IfxPort_setPinState()* from the iLLD header *IfxPort.h*.
- › The method implementing the ISR needs to be assigned a **priority** and a **CPU core** responsible for its execution. This is done with the macro *IFX_INTERRUPT(isr, vectabNum, priority)*.

References



- › AURIX™ Development Studio is available online:
- › <https://www.infineon.com/aurixdevelopmentstudio>
- › Use the „Import...“ function to get access to more code examples.



- › More code examples can be found on the GIT repository:
- › https://github.com/Infineon/AURIX_code_examples



- › For additional trainings, visit our webpage:
- › <https://www.infineon.com/aurix-expert-training>



- › For questions and support, use the AURIX™ Forum:
- › <https://www.infineonforums.com/forums/13-Aurix-Forum>

Revision history

Revision	Description of change
V1.0.1	Update of version to be in line with the code example's version
V1.0.0	Initial version

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