SCU_Emergency_Stop_1 for KIT_AURIX_TC275_LK Emergency Stop via SCU

AURIX™ TC2xx Microcontroller Training V1.0.0





Scope of work

This example shows how to trigger an emergency stop via an external signal and how port pins can be set to a defined state in this case.

The LED1, which is driven by the port pin P00.5, is blinking until an external signal triggers an emergency stop and sets the pin to emergency stop mode.



Introduction

- The System Control Unit (SCU) contains miscellaneous control registers associated with other functions such as controlling Application Test Mode and chip identification
- The Emergency Stop (EMS) is one of these functions. It provides a fast reaction to an emergency without the intervention of the software
- An emergency stop can be triggered by a transition on the port pin state which is configured as the EMS input or by an alarm event
- The Emergency Stop control logic for the port pins can operate in two modes:
 - Synchronous Mode: emergency case is activated by hardware and released by software (default and used in this training)
 - Asynchronous Mode: emergency case is activated and released by hardware

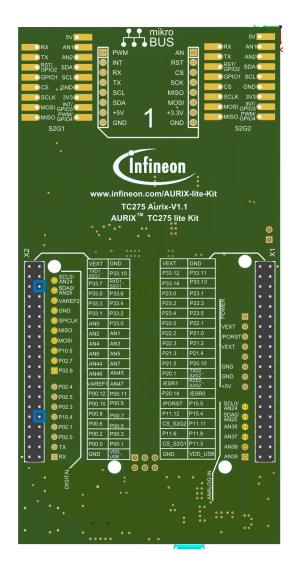


Hardware setup

This code example has been developed for the board KIT_AURIX_TC275_LITE.

Connect the emergency stop port pin P33.8 to the port pin P00.7 via a jumper.

```
VEXT
                         39 40
                                    GND
                         37 38
  TXD1 S2G1 - P33.9
                                  P33.10
                         35 36
               P33.7
                                   P33.8 - RXD1 S2G1
                         33 34
               P33.5
                                   P33.6
                         31 32
               P33.3
                                   P33.4
               P33.1
                         29 30
                                   P33.2
                         27 28
Potentiometer - ANO
                                   P33.0
                         25 26
               AN2
                                    AN1
                         23 24
                                    AN3
               AN4
                         21 22
               AN6
                                    AN<sub>5</sub>
                         19 20
               AN44
                                    AN7
                         17 18
                                   AN45
               AN46
               VAREF1
                         15 16
                                   AN47
               P00.12
                         13 14
                                  P00.11
                         11 12
               P00.10
                                   P00.9
                         9 10
               P00.8
                                   P00.7 - Button1
         LED2 - P00.6
                                   P00.5 - LED1
                         5 6
               P00.2
                                   P00.3
      TXDCAN - P00.0
                                   P00.1
                         1 2 VDD USB
               GND
```





Implementation

Configuring System Control Unit

Configuration of the System Control Unit (SCU) is done once in the setup phase by calling the initialization function *initScuEmergency()*, which contains the following steps:

- Call the iLLD function IfxScuWdt_clearSafetyEndinitInline() to disable the Safety Endinit protection in order to modify the SCU register
- > Set **SCU_EMSR.B.POL** to 0x0 to set input state as active high
- > Set **SCU_EMSR.B.MODE** to 0x0 to select the synchronous mode
- > Set **SCU_EMSR.B.PSEL** to 0x0 to select port A (pin P33.8) as emergency stop input
- > Set **SCU_EMSR.B.ENON** to 0x1 to enable emergency stop flag
- Call the iLLD function IfxScuWdt_setSafetyEndinitInline() to re-enable the Safety Endinit protection

The functions IfxScuWdt_clearSafetyEndinitInline() and IfxScuWdt_setSafetyEndinitInline() are contained in the iLLD header IfxScuWdt.h, while initScuEmergency() function is contained in SCU_Emergency_Stop.h.



Implementation

Configuring port pin

Configuration of the port pins for emergency stop input and for the LED are also done in the function *initScuEmergency()* with the following steps:

- Call the iLLD function IfxPort_setPinMode() with IfxPort_Mode_inputPullDown as parameter to configure the emergency stop pin as input
- Call the iLLD function IfxPort_setPinMode() with IfxPort_Mode_outputPushPullGeneral as parameter for the input to configure the LED as output
- Enable the emergency stop for the LED with the function IfxPort_setESR()

Toggling the LED

The LED is toggled in the function *toggleLED()*, which contains a call of the iLLD function *IfxPort_togglePin()*.

All of the above functions, called inside *initScuEmergency()* and *toggleLED()*, are contained in the iLLD header *IfxPort.h*.



Run and Test

After code compilation and flashing the device, perform the following steps:

- Observe the LED1 (1) which should be blinking
- Switch the emergency pin state P33.8
 by pressing the button (2)
- Observe the LED1 (1), which should be off







References





- > AURIX™ Development Studio is available online:
- https://www.infineon.com/aurixdevelopmentstudio
- Use the "Import…" function to get access to more code examples.



- More code examples can be found on the GIT repository:
- https://github.com/Infineon/AURIX code examples



- For additional trainings, visit our webpage:
- https://www.infineon.com/aurix-expert-training



- For questions and support, use the AURIX™ Forum:
- https://www.infineonforums.com/forums/13-Aurix-Forum

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