SCU_Emergency_Stop_1
Emergency Stop via SCU
Scope of work

This example shows how to trigger an emergency stop via an external signal and how port pins can be set to a defined state in this case.

The LED D107, which is driven by the port pin P13.0, is blinking until an external signal triggers an emergency stop and sets the pin to emergency stop mode.
Introduction

- The System Control Unit (SCU) contains miscellaneous control registers associated with other functions such as controlling Application Test Mode and chip identification.

- The Emergency Stop (EMS) is one of these functions. It provides a fast reaction to an emergency without the intervention of the software.

- An emergency stop can be triggered by a transition on the port pin state which is configured as the EMS input or by an alarm event.

- The Emergency Stop control logic for the port pins can operate in two modes:
  - Synchronous Mode: emergency case is activated by hardware and released by software (default and used in this training)
  - Asynchronous Mode: emergency case is activated and released by hardware
Hardware setup

This code example has been developed for the board KIT_AURIX_TC297_TFT_BC-Step.

Connect the emergency stop port pin P33.8 to the ground via a jumper.
Implementation

Configuring System Control Unit

Configuration of the System Control Unit (SCU) is done once in the setup phase by calling the initialization function `initScuEmergency()`, which contains the following steps:

- Call the iLLD function `IfxScuWdt_clearSafetyEndinitInline()` to disable the Safety Endinit protection in order to modify the SCU register.
- Set `SCU_EMSR.B.POL` to 0x0 to set input state as active high.
- Set `SCU_EMSR.B.MODE` to 0x0 to select the synchronous mode.
- Set `SCU_EMSR.B.PSEL` to 0x0 to select port A (pin P33.8) as emergency stop input.
- Set `SCU_EMSR.B.ENON` to 0x1 to enable emergency stop flag.
- Call the iLLD function `IfxScuWdt_setSafetyEndinitInline()` to re-enable the Safety Endinit protection.

The functions `IfxScuWdt_clearSafetyEndinitInline()` and `IfxScuWdt_setSafetyEndinitInline()` are contained in the iLLD header `IfxScuWdt.h`, while `initScuEmergency()` function is contained in `SCU_Emergency_Stop.h`. 
Implementation

Configuring port pin

Configuration of the port pins for emergency stop input and for the LED are also done in the function `initScuEmergency()` with the following steps:

› Call the iLLD function `IfxPort_setPinMode()` with `IfxPort_Mode_inputPullDown` as parameter for the input to configure the pin as input.
› Call the iLLD function `IfxPort_setPinMode()` with `IfxPort_Mode_outputPushPullGeneral` as parameter for the input to configure the LED as output.
› Enable the emergency stop for the LED with the function `IfxPort_setESR()`.

Toggling the LED

The LED is toggled in the function `toggleLED()`, which contains a call of the iLLD function `IfxPort_togglePin()`.

All of the above functions, called inside `initSCUEmergency()` and `toggleLED()`, are contained in the iLLD header `IfxPort.h`.
Run and Test

After code compilation and flashing the device, perform the following steps:

› Observe the LED D107 (1) which should be blinking.
› Switch the emergency pin state P33.8 from low to high by connecting it to V_UC(+5V) via the jumper in order to trigger the emergency stop.
› Observe the LED D107 (1), which should be off.
References

› AURIX™ Development Studio is available online:
  › [https://www.infineon.com/aurixdevelopmentstudio](https://www.infineon.com/aurixdevelopmentstudio)
  › Use the „Import...“ function to get access to more code examples.

› More code examples can be found on the GIT repository:
  › [https://github.com/Infineon/AURIX_code_examples](https://github.com/Infineon/AURIX_code_examples)

› For additional trainings, visit our webpage:
  › [https://www.infineon.com/aurix-expert-training](https://www.infineon.com/aurix-expert-training)

› For questions and support, use the AURIX™ Forum:
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