# GTM\_TOM\_PWM\_1 for KIT\_AURIX\_TC377\_TFT GTM TOM PWM generation

AURIX<sup>™</sup> TC3xx Microcontroller Training V1.0.0



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# GTM TOM is used to generate a PWM signal, which is driving the intensity of an LED.

The LED is driven by pin 0 of the port 13. The state of the pin is controlled by the PWM signal generated by the TOM timer of GTM.



## Introduction

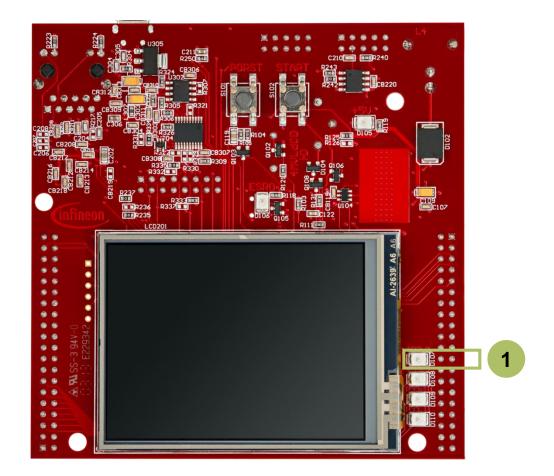
- The Generic Timer Module (GTM) is a modular timer unit designed to accommodate many timer applications.
- It has an in-built Timer Output Module (TOM) that can offer up to 16 independent channels to generate output signals.
- The Clock Management Unit (CMU) is responsible for clock generation of the GTM. The Fixed Clock Generation (FXU) is one of its subunits and it provides five predefined non-configurable clocks for GTM modules, including the TOM.



## Hardware setup

This code example has been developed for the board KIT\_A2G\_TC377\_5V\_TFT.

LED D107 (1) is used for this example.





## Implementation

#### Configuring the TOM

The configuration of the TOM is done by calling the initialization function *initGtmTomPwm()* containing the following steps:

- > Enable the GTM by calling the function *lfxGtm\_enable()*
- > Enable the FXU clocks by calling the function *lfxGtm\_Cmu\_enableClocks()*

The function *lfxGtm\_Tom\_Pwm\_initConfig()* initializes an instance of the structure *lfxGtm\_Tom\_Pwm\_Config* with its default values.

The *lfxGtm\_Tom\_Pwm\_Config* structure can be modified to set the following parameters to initialize the module:

- *tom* Selection of the TOM which is counting (TOM 2 in this example)
- *tomChannel* Selection of the channel which is driving the LED (Channel 5 in this example)
- > period Setting of the period for the PWM signal to the desired value
- > *pin.outputPin* Selection of the LED as output pin
- > synchronousUpdateEnable Enabling of synchronous update of the timer



## Implementation

### Configuring the TOM

After configuration, the function *lfxGtm\_Tom\_Pwm\_init()* initializes and activates the TOM with the user configuration.

Start the PWM with the function *lfxGtm\_Tom\_Pwm\_start()*.

#### Setting the duty cycle

The setting of the duty cycle is done by calling the function **setDutyCycle()**, which contains the following steps:

- Set the *dutyCycle* parameters of the configuration structure to set the duty cycle of the PWM signal to the desired value
- Call the function *lfxGtm\_Tom\_Pwm\_init()* to reconfigure the TOM with the new value of the duty cycle

All the functions used for the configuration of the TOM are provided by the iLLD header *lfxGtm\_Tom\_Pwm.h*.

## Fading the LED

The fading of the LED is done in the function *fadeLED()* by repeatedly adding or removing a step value to the duty cycle of the PWM.

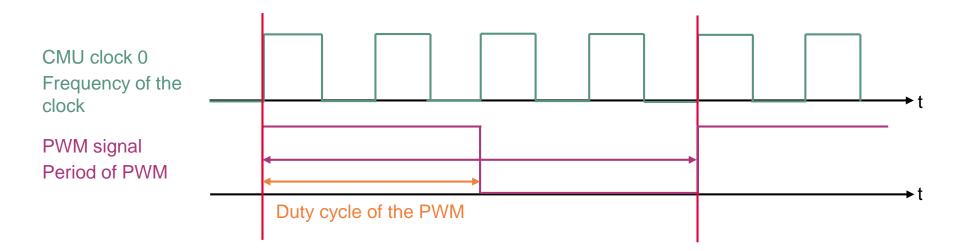


## **Calculation example**

The FXU clock 0 frequency ( $f_{fxclk0}$ ) is 100 MHz. The period value to have the desired PWM frequency ( $f_{PWM}$ ) is calculated with the following formula:

$$Period = \frac{f_{fxclk0}}{f_{PWM}}$$

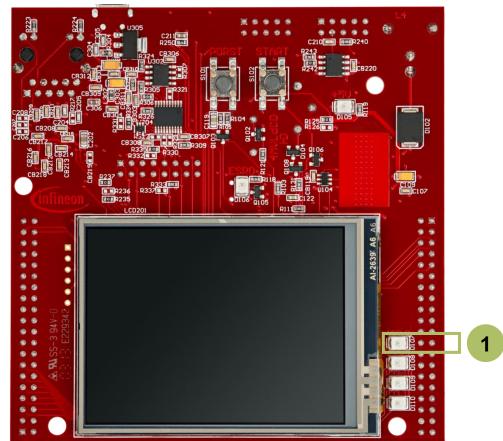
In this example:  $Period = \frac{100 MHz}{2 kHz} = 50000 ticks$ 





# Run and Test

After code compilation and flashing the device, observe the **LED D107** (1), which should be fading.



## References











- AURIX<sup>™</sup> Development Studio is available online: >
- https://www.infineon.com/aurixdevelopmentstudio
- Use the *"Import…"* function to get access to more code examples. >
- More code examples can be found on the GIT repository: >
- https://github.com/Infineon/AURIX code examples >
- For additional trainings, visit our webpage: >
- https://www.infineon.com/aurix-expert-training >
- For questions and support, use the AURIX<sup>™</sup> Forum: >
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Edition 2020-12 Published by Infineon Technologies AG 81726 Munich, Germany

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Document reference GTM\_TOM\_PWM\_1\_KIT\_TC377\_TFT

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