GTM_TOM_PWM_1
for KIT_AURIX_TC375_SB
GTM TOM PWM generation

AURIX™ TC3xx Microcontroller Training V1.0.0





Scope of work

GTM TOM is used to generate a PWM signal, which is driving the intensity of an LED.

The LED is driven by pin 2 of the port 10. The state of the pin is controlled by the PWM signal generated by the TOM timer of GTM.



Introduction

- The Generic Timer Module (GTM) is a modular timer unit designed to accommodate many timer applications.
- It has an in-built Timer Output Module (TOM) that can offer up to 16 independent channels to generate output signals.
- The Clock Management Unit (CMU) is responsible for clock generation of the GTM. The Fixed Clock Generation (FXU) is one of its subunits and it provides five predefined non-configurable clocks for GTM modules, including the TOM.

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Hardware setup

This code example has been developed for the board KIT_A2G_TC375_ARD_SB.

LED (1) is used for this example.



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Implementation

Configuring the TOM

The configuration of the TOM is done by calling the initialization function *initGtmTomPwm()* containing the following steps:

- Enable the GTM by calling the function IfxGtm_enable()
- > Enable the FXU clocks by calling the function *IfxGtm_Cmu_enableClocks()*

The function *IfxGtm_Tom_Pwm_initConfig()* initializes an instance of the structure *IfxGtm_Tom_Pwm_Config* with its default values.

The *IfxGtm_Tom_Pwm_Config* structure can be modified to set the following parameters to initialize the module:

- > tom Selection of the TOM which is counting (TOM 0 in this example)
- > tomChannel Selection of the channel which is driving the LED (Channel 2 in this example)
- > period Setting of the period for the PWM signal to the desired value
- > pin.outputPin Selection of the LED as output pin
- synchronousUpdateEnable Enabling of synchronous update of the timer

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Implementation

Configuring the TOM

After configuration, the function *IfxGtm_Tom_Pwm_init()* initializes and activates the TOM with the user configuration.

Start the PWM with the function IfxGtm_Tom_Pwm_start().

Setting the duty cycle

The setting of the duty cycle is done by calling the function **setDutyCycle()**, which contains the following steps:

- Set the dutyCycle parameters of the configuration structure to set the duty cycle of the PWM signal to the desired value
- Call the function IfxGtm_Tom_Pwm_init() to reconfigure the TOM with the new value of the duty cycle

All the functions used for the configuration of the TOM are provided by the iLLD header *IfxGtm Tom Pwm.h*.

Fading the LED

The fading of the LED is done in the function *fadeLED()* by repeatedly adding or removing a step value to the duty cycle of the PWM.



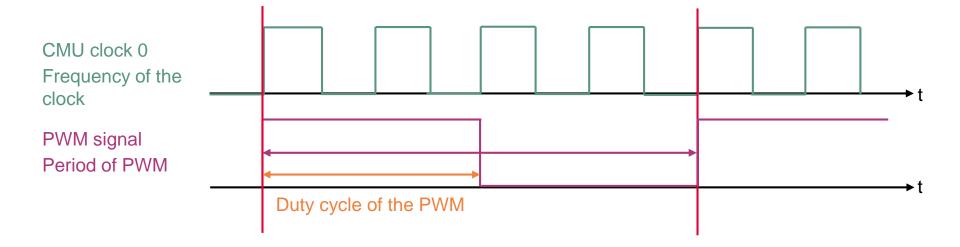


Calculation example

The FXU clock 0 frequency (f_{fxclk0}) is 100 MHz. The period value to have the desired PWM frequency (f_{PWM}) is calculated with the following formula:

$$Period = \frac{f_{fxclk0}}{f_{PWM}}$$

In this example:
$$Period = \frac{100 \, MHz}{2 \, kHz} = 50000 \, ticks$$



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Run and Test

After code compilation and flashing the device, observe the **LED** (1), which should be fading.



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References





- > AURIX™ Development Studio is available online:
- https://www.infineon.com/aurixdevelopmentstudio
- Use the "Import…" function to get access to more code examples.



- More code examples can be found on the GIT repository:
- https://github.com/Infineon/AURIX code examples



- For additional trainings, visit our webpage:
- https://www.infineon.com/aurix-expert-training



- For questions and support, use the AURIX™ Forum:
- https://www.infineonforums.com/forums/13-Aurix-Forum

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