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FM3, MB9BF506 Series, SPWM Generation

This application note describes the principle of SPWM and generation SPWM signal with 32-bit microcontroller MB9BF506.

Contents

1	Introduction.....	1	2.3	Harmonic Analysis of SPWM Inverter Circuit.....	6
1.1	Purpose	1	3	SPWM Application.....	7
1.2	Definitions, Acronyms and Abbreviations.....	1	3.1	Application of SPWM in Single-Phase Inverter Power	7
1.3	Document Overview.....	1	4	Additional Information.....	8
2	SPWM Algorithm	2		Document History.....	9
2.1	Overview	2			
2.2	SPWM Algorithm.....	2			

1 Introduction

1.1 Purpose

This application note describes the principle of SPWM and generation SPWM signal with 32-bit microcontroller MB9BF506.

1.2 Definitions, Acronyms and Abbreviations

SPWM - Sinusoidal Pulse Width Modulation

1.3 Document Overview

The rest of document is organized as the following :

Chapter 2 [SPWM Algorithm](#)

Chapter 3 [SPWM Application](#)

2 SPWM Algorithm

SPWM Algorithm

2.1 Overview

PWM technology utilizes the switch of whole-control component to convert voltage into voltage pulse sequences with the same breadth and different widths, thus to realize voltage transformation, frequency conversion control and harmonic wave cancellation. According to sampling control theory, the effects of narrow pulses with the same impulse and different shapes are basically the same when applied to inertia. SPWM control technology controls the switch of semiconductor switch components based on this theory; and the output end can obtain a series of pulses with equal breadth and expected pulse width. These pulses are used to substitute the expected output waveform. When this technology is applied in inverter, it not only can control the output voltage of inverter conveniently, but also control the frequency of output voltage.

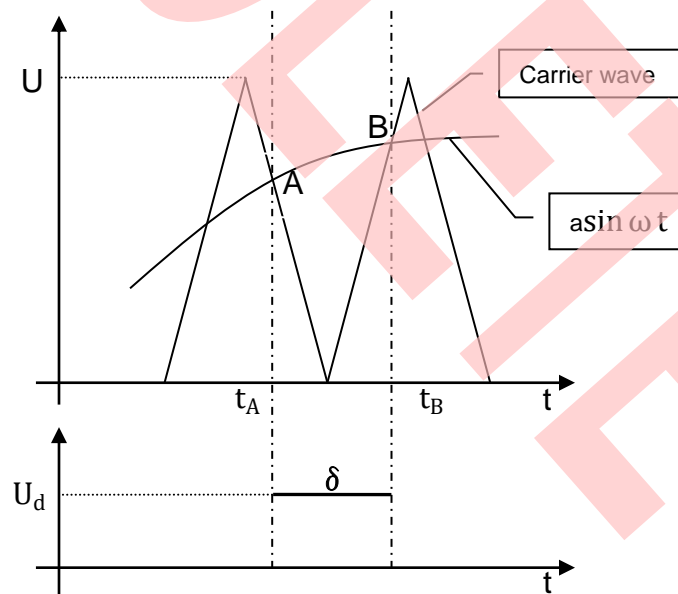
Though PWM control theory that has been raised long time ago, due to the limit in the development level of electronic component, it has not been widely applied until the rapid development of whole-control electronic components. PWM control technology develops considerably fast along with the development of electronics, semiconductor microelectronics and each control theory.

2.2 SPWM Algorithm

2.2.1 Natural Sampling

Use sinusoidal wave as the modulate wave, a high frequency triangular wave as the carrier wave, use sinusoidal wave modulate the carrier wave, the time of turn on or off switch is the natural point of intersections, we call it natural sampling, as show in Figure 1. With this manner, the obtained SPWM wave is very similar with sinusoidal wave, but the point of intersection has the random city, the center of the pulse in one cycle is not equidistant, so the equation of the pulse is exceed equations, calculate is very complexity, can't control in real-time.

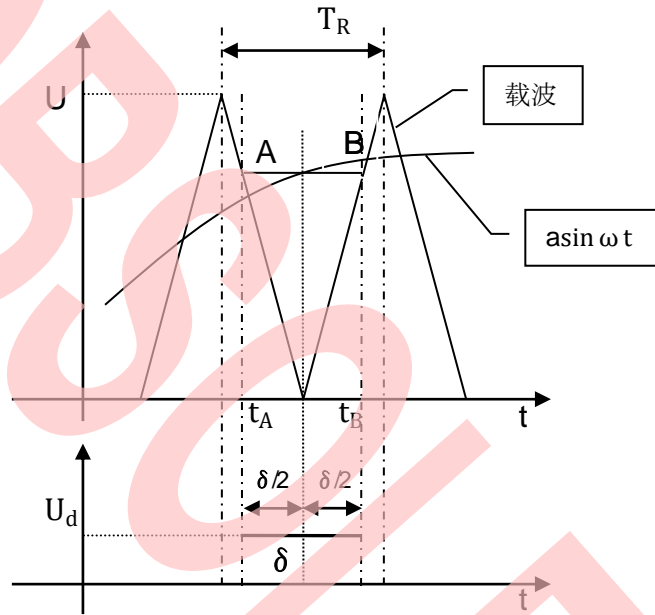
Figure 1. Natural sampling



2.2.2 Symmetric Regular Sampling

Symmetrical rule sample law is the improvement of nature sample method, it is made to be parallel by the triangular wave axis of symmetry and sine wave point of intersection in the time axis straight line, this parallel lines and triangular wave two waists' points of intersection take the SPWM This method only samples in the triangular wave apex or the basic point position to the sine wave, the principle of symmetrical rule sample method as shown in Figure 2.

Figure 2. Asymmetric Regular Sampling



If the sinusoidal wave is a $\sin \omega t$, the amplitude of the triangular wave is set to unit amount 1, the triangular wave and sinusoidal wave shift one unit amount upward, sample the sinusoidal wave at the bottom point of the triangular wave, then, the following formula can be got based on the Similar Triangles theory:

$$\frac{1 + a \sin \omega t}{\delta/2} = \frac{2}{T_R/2} \quad (1)$$

Simplify formula (1) to get the following:

$$\delta = T_R(1 + a \sin \omega t)/2$$

$$\text{In } \omega t = (k + 3/4)2\pi/N \quad (k=0, 1, 2, \dots, N-1)$$

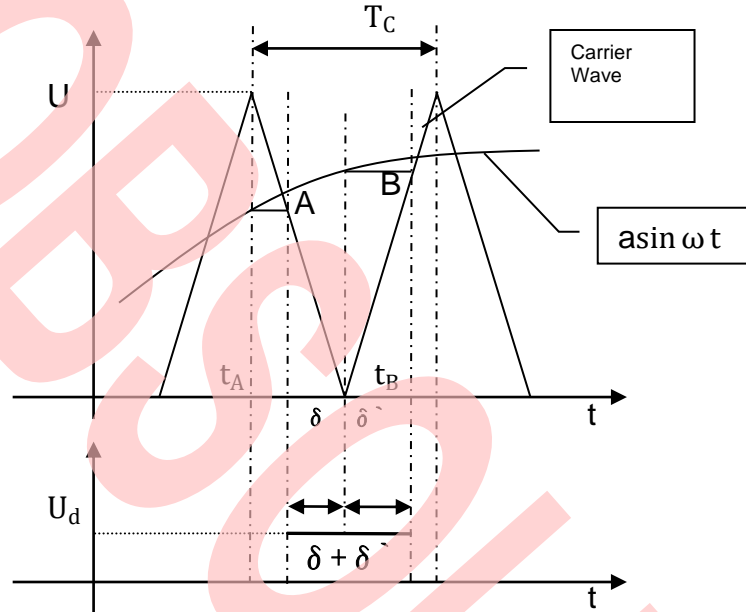
ω is the angular frequency of sinusoidal wave, δ is the pulse width of a certain phase enabling, and T_R is the cycle of the triangular wave. N refers to the carrier wave ratio, $2\pi/N$ refers to the amplitude corresponding to the triangular wave cycle T_R , K refers to the count of a cyclic sampling.

Because only needs to carry on a sample then in each triangle carrier cycle to be possible to obtain a switching signal, therefore simplified the formula, and may act according to the pulse width formula real-time computation the SPWM The WPWM wave and sine wave that approaching degree because forms has the big error, will thus create an error.

2.2.3 Asymmetric Regular Sampling

Elements of Asymmetric Regular Sampling method is that to be namely in the apex position sample of triangular wave, and in the basic point position sample of triangular wave, hands over the triangular wave and A, B two spots along the time axis extension with the sine wave point of intersection, both samples to the sine wave in a triangle wave period two. As shown in Figure 3 is the start time and shutoff time of high level pulse.

Figure 3. Asymmetric Regular Sampling method.



Set the amplitude of triangular carrier wave to unit amount 1, the amplitude of sinusoidal modulation wave to a, the triangular carrier wave and sinusoidal wave shift one unit amount upward, as shown in Figure 3. The following formula can be got based on the Similar Triangles theory:

$$\frac{\delta}{T_c/2} = \frac{1 + a \sin \omega t_A}{2}$$

$$\frac{\delta'}{T_c/2} = \frac{1 + a \sin \omega t_B}{2}$$

Simplified as: $\delta = \frac{T_c(1 + a \sin \omega t_A)}{4}$

$$\delta' = \frac{T_c(1 + a \sin \omega t_B)}{4}$$

Inferred from the above, the SPWM pulse width is:

$$\delta + \delta' = \frac{T_c}{2} \left[1 + \frac{a}{2} (\sin \omega t_A + \sin \omega t_B) \right]$$

If the carrier wave ratio (the ratio between the triangular wave (carrier wave) frequency and sinusoidal wave (modulation wave) frequency) is N, since sampling modulation wave twice in each carrier wave cycle, as a result:

$$t_A = \frac{T_c}{2} K \quad (K = 0, 2, 4, \dots, 2N-2)$$

$$t_B = \frac{T_c}{2} K \quad (K = 1, 3, 5, \dots, 2N-1)$$

$$\text{Since } f_c/f_m = N = \frac{1}{T_c f_m}$$

$$\text{Then: } \omega t_A = 2\pi f_m t_A = 2\pi f_m \frac{T_c}{2} K = \frac{\pi}{N} K \quad (k=0, 2, 4 \dots 2N-2)$$

$$\omega t_B = 2\pi f_m t_B = 2\pi f_m \frac{T_c}{2} K = \frac{\pi}{N} K \quad (k=1, 3, 5 \dots 2N-1)$$

Therefore:

$$\delta = \frac{T_c}{4} (1 + a \sin \frac{\pi}{N} K) \quad (k=0, 2, 4 \dots 2N-2)$$

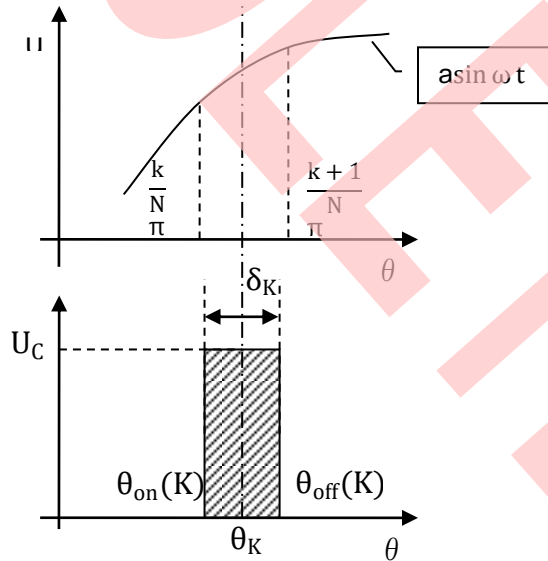
$$\delta' = \frac{T_c}{4} (1 + a \sin \frac{\pi}{N} K) \quad (k=1, 3, 5 \dots 2N-1)$$

The asymmetric regular sampling method samples the modulation wave at the symmetric places of the triangular carrier wave's peak and bottom, namely sampling twice in a carrier wave cycle. The similarity between the SPWM and the sinusoidal modulation wave is significantly raised compared with the symmetric rules sampling method, and the output waveform is closer to the natural sampling method. Therefore, this system adopts the asymmetric regular sampling method.

2.2.4 Unipolar Area Equivalence Method

According to an important theory in the sampling control: when the narrow pulse with equivalent impulse but different shape is added to the inertia segment, the effects are basically the same. The impulse refers to the area of the narrow pulse. Area Equivalence Method of the sinusoidal pulse width modulation uses a series of narrow pulses with the same amplitude but different width, to replace the area formed by the sinusoidal wave and time shaft in each sampling cycles. As shown in Figure 4: Divide the sinusoidal wave into N parts, the area formed by each part and the θ is replaced with the highly equivalent rectangle pulse. Combined N rectangle pulses with same amplitude and different width can be used to replace sinusoidal half wave.

Figure 4. Unipolar Area Equivalence method



If sine wave $u = a \sin \omega t = a \sin(\theta)$, divide the positive half wave of the sine wave into N parts, each part is π/N radian, the area of the K-th part is S_K , according to the area equivalence theory.

$$S_K = \delta_K U_C = a \int_{\frac{k}{N}\pi}^{\frac{k+1}{N}\pi} \sin(\theta) d(\theta) \quad (K=1, 2, 3 \dots N)$$

If the modulation ratio is $M = \frac{a}{U_C}$, then:

$$\delta_k = M[\cos(\frac{k}{N}\pi) - \cos(\frac{K+1}{N}\pi)]$$

According to the area center equivalence theory, get the following:

$$\int_{\frac{k}{N}\pi}^{\theta_k} a \sin(\theta) d(\theta) = \int_{\theta_k}^{\frac{K+1}{N}\pi} a \sin(\theta) d(\theta)$$

The center of the pulse is: $\theta_k = \arccos\{\frac{1}{2}[\cos(\frac{k}{N}\pi) - \cos(\frac{K+1}{N}\pi)]\}$

Therefore, the switching angle of the unipolar pulse is:

$$\left\{ \begin{array}{l} \theta_{on}(k) = \theta_k - \frac{\theta_k}{2} \quad (k=1,2,3...N) \\ \theta_{on}(k) = \theta_k + \frac{\theta_k}{2} \quad (k=1,2,3...N) \end{array} \right.$$

2.3 Harmonic Analysis of SPWM Inverter Circuit

The harmonic component size of the inverter output voltage and output current is the important indicator for measuring the inverter performance. The higher harmonic output by the inverter will increase the loss of inductive load, reduce the factor of efficiency and power, severely interfere with electronic devices, and affect the normal running of peripheral devices. Therefore, it is necessary to analyze and control the output harmonic of the SPWM inverter.

According to the Fourier Analysis:

$$f(\delta) = \sum_{k=1,3,5,...}^{\infty} V_{o_k} \sqrt{2} \sin K\omega t$$

$$V_{o_k} = \frac{4V_d}{\sqrt{2}K\pi} \sum_{i=1}^{N_2} ((-1)^{i-1} \cos k \delta_i)$$

δ_i is the switch angle, and t_i is the switch time. $\delta_i = \omega t_i$
 $k=1,3,5,...$

3 SPWM Application

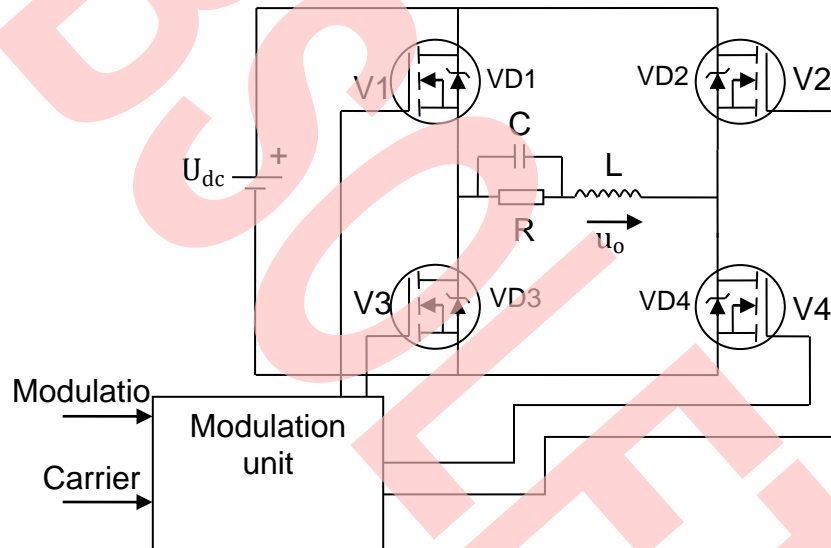
Application of SPWM algorithm in MB9BF506 inverter system

3.1 Application of SPWM in Single-Phase Inverter Power

3.1.1 System topology

The single-phase full-bridge inverter circuit as shown in Figure 5, the carrier wave u_c is the high frequency triangular wave generated by the MCU, modulation wave u_m is the internal benchmark sine modulation signal of the MCU, the modulation unit generates 4-channel high-frequency switch pulse through different SPWM algorithm (asymmetric regular sampling or area equivalence method) to control the sine voltage with high-frequency component output by the full-bridge inverter. Through the smooth filter of the LC low-pass filter, eliminate the harmonic component to get pure sine wave from the load R.

Figure 5. Single-phase full-bridge inverter topology



3.1.2 System algorithm

MB9BF506 is a 32-bit low-cost and high-performance micro-controller launched by Fujitsu, based on ARM Cortex-M3, providing on-chip Flash memory and SRAM. MB9BF506 contains a Multifunction Timer, which facilitates generating PWM signals of any cycle/pulse width.

For easier calculation, the system adopts symmetric regular sampling method to implement the SPWM waveform. The harmonic component of the symmetric regular sampling method is greater than that of the asymmetric regular sampling method, but if the carrier wave frequency is high enough, the effect is not severe enough.

To eliminate the even harmonic, the modulation ratio is better to be an odd integer and the multiples of three. In addition, the slopes of the triangular wave and the sine wave should have opposite polarity at the zero passage convergence. Namely, the sampling points for the modulation wave are symmetric about $\frac{\pi}{2}$ and π , as shown in Figure 6. The amplitude of the triangular wave varies between $0 \sim U_R$, if the amplitude modulation is M, the sine wave is expressed as:

$$U_s = \left(\frac{1}{2} + \frac{1}{2} M \sin \theta \right) U_R$$

If use the peak sampling, the enabling time of the upper bridge arm is :

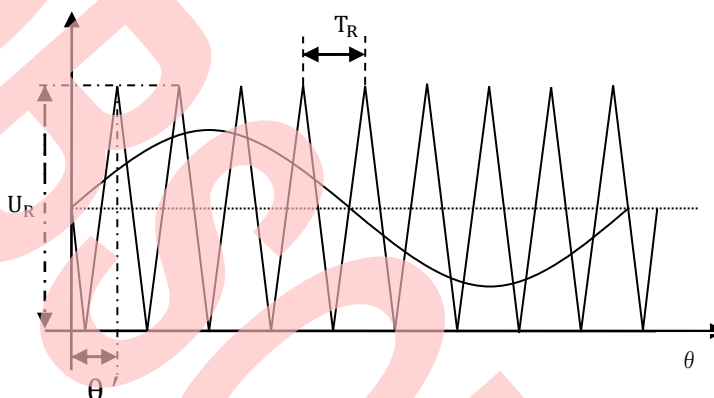
$$t_{on} = \frac{1}{4} T_R (1 + M \sin \theta')$$

T_R is the cycle of the carrier wave, θ' is the sampling time of the triangular wave for the sine wave, θ' is expressed as :

$$\theta' = \left(K + \frac{3}{4} \right) \frac{2\pi}{N}$$

N is the modulation ratio, $\frac{2\pi}{N}$ is the amplitude corresponding to the carrier wave cycle of the triangular wave T_R , K is the counting value in a sine cycle, $K = 1, 2, 3, \dots, N-1$.

Figure 6. System Modulation Schematic



In the system, the carrier wave frequency is 30KHz, and the carrier wave ratio $N=600$, namely the system samples the base waves for 600 times in a sine cycle. The MCU calculates the 0 ~ 599 discrete values of the sine function $\sin \left(K + \frac{3}{4} \right) \frac{2\pi}{N}$ with the amplitude 1 of the 600 sampling values. The values are made into a table to save in the memory. The system repeatedly invokes the values in the table and loads them into the count counter in multifunction timer of the MCU, and the SPWM waveforms are generated.

4 Additional Information

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*A	5279145	CBZH	06/23/2016	Migrated Spansion Application Note "MCU-AN-510101-E-02" to Cypress format.
*B	5842070	AESATMP9	08/02/2017	Updated logo and copyright.
*C	6329249	SSAS	10/02/2018	Obsoleted

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