

BGM1043N7

Front-End Module for Global Navigation  
Satellite Systems (GNSS) Applications  
with higher LTE Band-13 rejection

Application Note AN287

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**Application Note AN287**

**Revision History: 2012-06-19**

**Previous Revision: None**

Page	Subjects (major changes since last revision)

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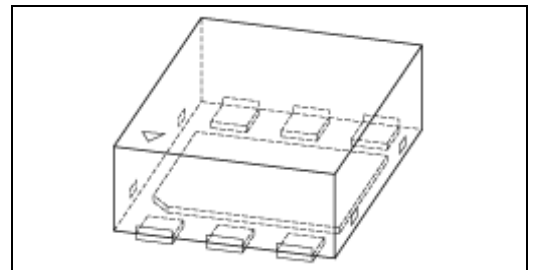
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## 1 BGM1043N7 GPS and GLONASS Front-End Module

### 1.1 Features

- Operating frequency: 1575.42 MHz and 1598.06-1605.38 MHz
- High Gain: 15.1 dB
- Low Noise Figure (GPS): 1.5 dB
- Low current consumption: 4.0 mA
- Out-of-band rejection in cellular bands: > 43 dBc
- Input compression point in cellular bands: 30 dBm
- Supply voltage: 1.5 V to 3.6 V
- Tiny TSNP-7-10 leadless package (2.3 x 1.7 x 0.73 mm<sup>3</sup>)
- RF output internally matched to 50 Ω
- IEC ESD contact discharge of RF input pin: 6 kV
- Only 3 external SMD parts
- RoHS compliant package (Pb-free)



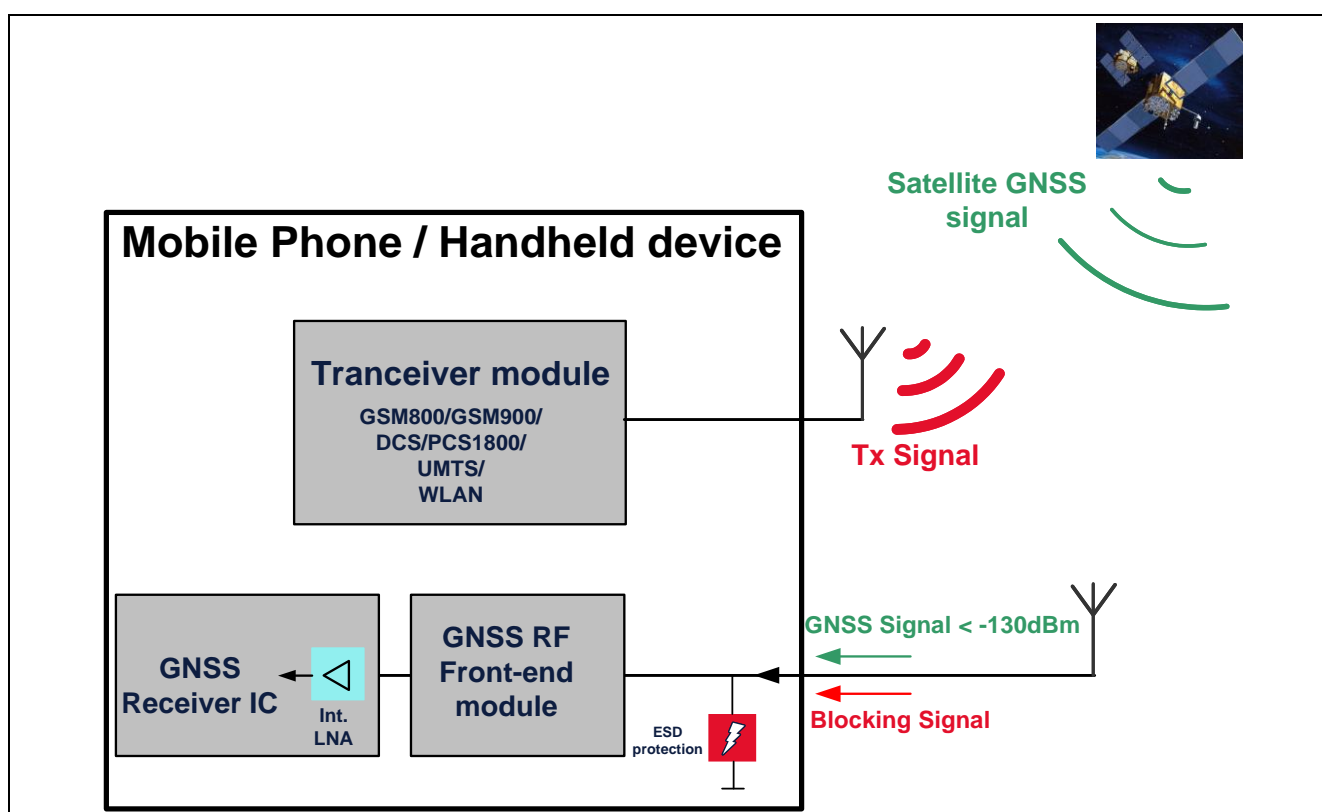
**Figure 1 BGM1043N7 in TSNP-7-10 Package**

### 1.2 Applications

- GPS (Global Positioning System) working in the L1 band at 1575.42 MHz
- GLONASS (Globalnaya Navigatsionnaya Sputnikovaya Sistema) working in the L1 band from 1598.06 MHz to 1605.38 MHz

## 2 Introduction

Global Navigation Satellite System or GNSS receiver, as we know, works on the reception of location based information from satellite signals. There are several standards worldwide like GPS, GLONASS, Galileo and COMPASS Bei Du. However, the power levels of the satellite signals received, can be lower than -130 dBm. This poses a challenge on the sensitivity of the GNSS receiver. Along with this, the ever growing disturbing or jamming signals in the adjacent cellular bands makes the design of the receiver front-end even more difficult. The rapidly growing market for GNSS systems is driving the design of advanced and high-performance GNSS receivers. A simple overview of the GNSS RF system in a mobile phone or other handheld devices is shown in Figure 2.

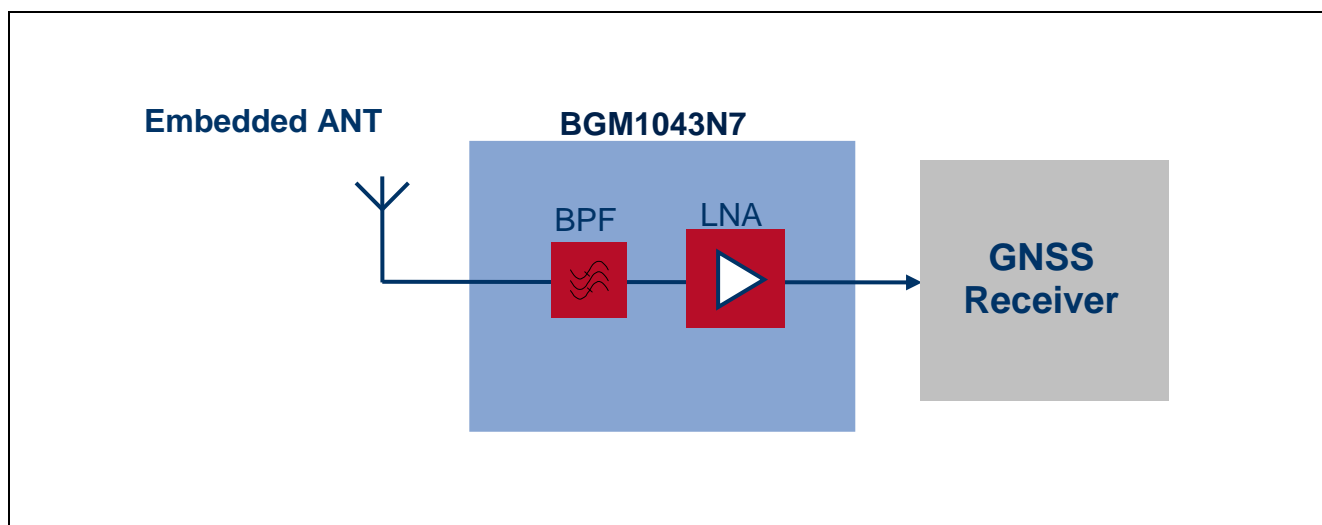


**Figure 2 RF System Overview: Mobile Phone**

GNSS receivers for mobile or handheld applications are always under the threat of high power cellular signals. Due to the coexistence of GNSS and Cellular services, there is a strong coupling of the DCS/PCS and Cellular signals to the GNSS receiver. The performance of a standard integrated GNSS receiver chip cannot meet the specifications required for the present systems. An external RF front-end is essential to achieve this required performance. The most important prerequisites for the front-end of a GNSS receiver are low noise figure and sufficient amplification of the desired signal together with high attenuation of the jamming signals.

## 2.1 Systems overview of a GNSS receiver

Several configurations can be adopted for a GNSS receiver chain. In all configurations, as mentioned earlier, a RF front-end like BGM1043N7 is placed between the antenna and the GNSS receiver chip. Mobile/portable devices as well as personal navigation devices request decreasing form factor used by the implementation of the GNSS function in the devices. BGM1043N7 supports the designers to minimize the area in the front-end. Such a configuration is shown in Figure 3. The BGM1043N7 can also be used for the active antenna module.



**Figure 3** GNSS system with integrated GNSS FEM BGM1043N7 for mobile/portable and personal navigation devices

### 3 Description

The BGM1043N7 is a combination of a low-insertion-loss pre-filter with Infineon's high performance low noise amplifier (LNA) for Global Positioning System (GPS) and Globalnaya Navigatsionnaya Sputnikovaya Sistema (GLONASS) applications. Both, GPS and GLONASS frequency bands, can be used at the same time. Through the low insertion loss of the filter, the BGM1043N7 provides 15.1 dB gain, 1.5 dB noise figure and high linearity performance. In addition BGM1043N7 provides very high out-of-band attenuation in conjunction with a high input compression point. It can withstand IEC61000-4-2 ESD contact discharge at the RF input as high as 6 kV in the application circuit shown in Figure 5. Its current consumption is as low as 4.0 mA. It operates over the 1.5 V to 3.6 V supply voltage range.

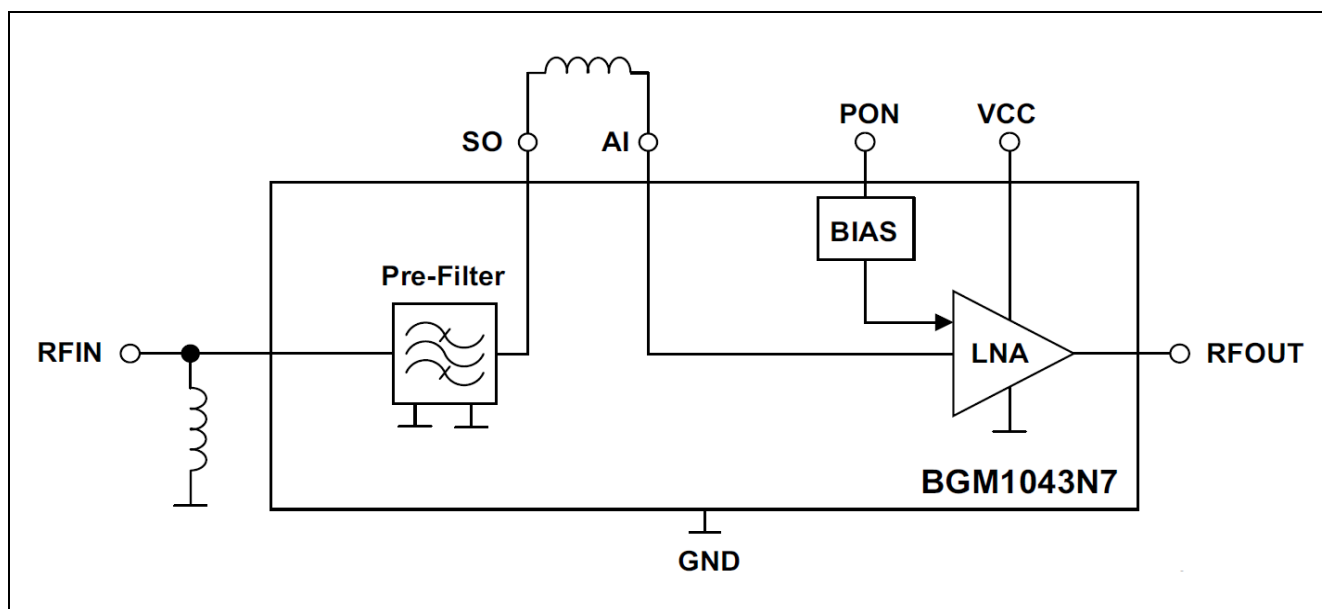


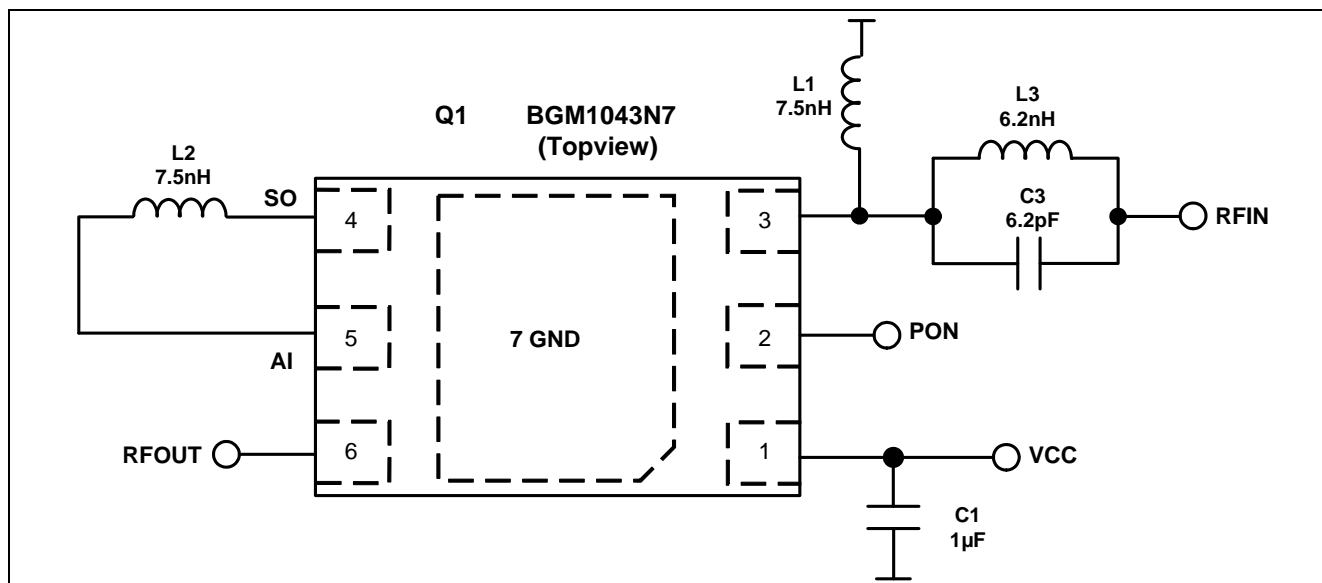
Figure 4 Block Diagram of BGM1043N7



## 4 Application Circuit and Block Diagram

The BGM1043N7 is internally matched at the output to 50 Ohm. The LNA bias circuitry is also integrated on chip. Therefore, only three external components are required in the application. The application schematic is shown in Figure 5 and the function of the external passives is listed in Table 2.

### 4.1 Application Schematic



**Figure 5** Schematic diagram of the BGM1043N7 application circuit

**Table 1** Pin Assignment of BGM1043N7

Pin No.	Symbol	Function
1	VCC	Power Supply
2	PON	Power ON/OFF
3	RFIN	RF Input
4	SO	Pre-Filter Output
5	AI	LNA Input
6	RFOUT	RF Output
7	GND	DC and RF ground

**Table 2** Bill-of-Materials

Symbol	Value	Unit	Size	Manufacturer	Comment
C1	1.0	µF	0201	Various	Supply filtering
C3	6.2	pF	0201	Various	787MHz Optimization
L1	7.5	nH	0201	Murata LQP Series	Matching/ESD protection Inductor
L2	7.5	nH	0201	Murata LQP Series	Matching Inductor
L3	6.2	nH	0201	Murata LQP Series	787MHz Optimization
Q1	BGM1043N7		TSNP-7-10	Infineon	GPS/GLONASS FEM

## 5 Measurement Results

Measurement results of the BGM1043N7 are presented in this section. The measurements are performed on the Infineon application board at room temperature. The performances of the BGM1043N7 are here provided for the voltage of 1.8V (Table 3) and 2.8V (Table 4). The data exclude PCB and SMA connector losses, unless otherwise mentioned.

**Table 3 Electrical Characteristics (at room temperature), Vcc = Vpon = 1.8 V**

Parameter	Symbol	Value		Unit	Comment/Test Condition
DC Voltage	Vcc	1.8		V	
DC Current	Icc	4.1		mA	
Navigation System	Sys	GPS	GLONASS		
Frequency Range	Freq	1575.42	1598-1606	MHz	
Gain	G	14.5	14.1	dB	
Noise Figure	NF	1.68	2.06	dB	PCB and SMA connectors of 0.12 dB losses subtracted
Input Return Loss	RLin	10.9	14.6	dB	
Output Return Loss	RLout	16.3	25.0	dB	
Reverse Isolation	IRev	22.1	22.4	dB	
Input P1dB	IP1dB	-8.9	-7.7	dBm	$f_{\text{gps}} = 1575.42 \text{ MHz}$ $f_{\text{GLONASS}} = 1605 \text{ MHz}$
Output P1dB	OP1dB	4.6	5.4	dBm	
Input IP3 In-band	IIP3	-6.93	-5.43	dBm	
Output IP3 In-band	OIP3	7.57	8.67	dBm	$f_{1\text{gps}} = 1575 \text{ MHz}$ , $f_{2\text{gps}} = 1576 \text{ MHz}$ $f_{1\text{GLONASS}} = 1602 \text{ MHz}$ , $f_{2\text{GLONASS}} = 1603 \text{ MHz}$ $P_{1\text{IN}} = P_{2\text{IN}} = -30 \text{ dBm}$
Rejection 750MHz <sup>1)</sup>	Rej <sub>750M</sub>	64.7		dBc	$f = 750 \text{ MHz}$
Rejection 900MHz <sup>1)</sup>	Rej <sub>900M</sub>	44.4		dBc	$f = 806 \text{ MHz} - 928 \text{ MHz}$
Rejection 1800MHz <sup>1)</sup>	Rej <sub>1800M</sub>	43.0		dBc	$f = 1710 \text{ MHz} - 1980 \text{ MHz}$
Rejection 2400MHz <sup>1)</sup>	Rej <sub>2400M</sub>	47.2		dBc	$f = 2400 \text{ MHz} - 2500 \text{ MHz}$
Input P1dB	IP1dB <sub>900M</sub>	29.6		dBm	$f = 900 \text{ MHz}$
Input P1dB	IP1dB <sub>1710M</sub>	31.5		dBm	$f = 1710 \text{ MHz}$
LTE band-13 2 <sup>nd</sup> Harmonic	H2	-69.8		dBm	$f_{\text{IN}} = 787.76 \text{ MHz}$ , $P_{\text{IN}} = +15 \text{ dBm}$ ; $f_{\text{H2}} = 1575.52 \text{ MHz}$
Input IP3 out-of-band	IIP3 <sub>OOB</sub>	64.2		dBm	$f_1 = 1712.7 \text{ MHz}$ , $f_2 = 1850 \text{ MHz}$ $P_{1\text{IN}} = +10 \text{ dBm}$ , $P_{2\text{IN}} = +10 \text{ dBm}$ ; $f_{\text{IIP3}} = 1575.4 \text{ MHz}$
Stability	k	>1		--	Unconditionnally Stable from 0 to 10GHz

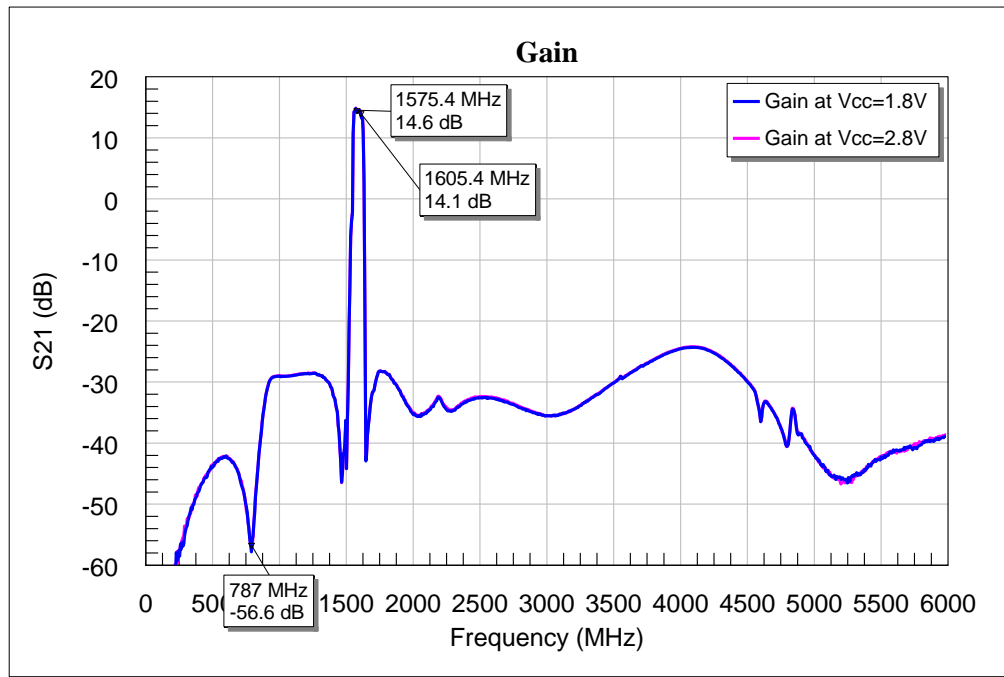
<sup>1)</sup> Rejection is defined as following: [Gain at 1575.42 MHz] – [Attenuation@stopband frequency]

**Table 4 Electrical Characteristics (at room temperature), Vcc = Vpon = 2.8 V**

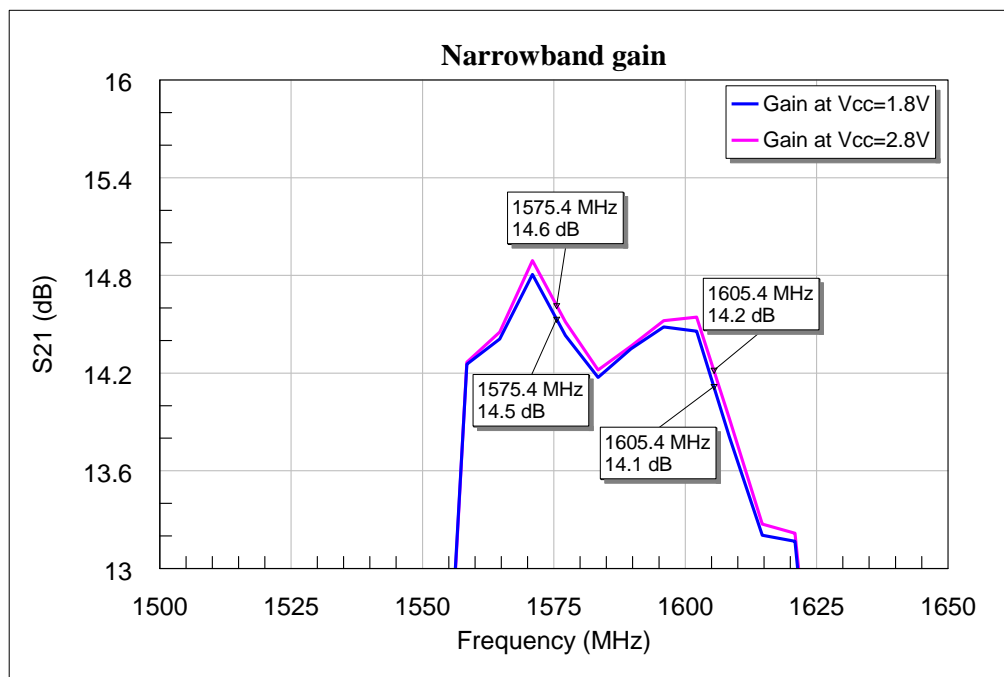
Parameter	Symbol	Value		Unit	Comment/Test Condition
DC Voltage	Vcc	2.8		V	
DC Current	Icc	4.2		mA	
Navigation System	Sys	GPS	GLONASS		
Frequency Range	Freq	1575.42	1598-1606	MHz	
Gain	G	14.6	14.2	dB	
Noise Figure	NF	1.69	2.07	dB	PCB and SMA connectors of 0.12 dB losses subtracted
Input Return Loss	RLin	11.4	15.6	dB	
Output Return Loss	RLout	15.0	20.7	dB	
Reverse Isolation	IRev	22.5	22.8	dB	
Input P1dB	IP1dB	-6.5	-5.1	dBm	f <sub>gps</sub> = 1575.42 MHz f <sub>GLONASS</sub> = 1605 MHz
Output P1dB	OP1dB	7.1	8.1	dBm	
Input IP3 In-band	IIP3	-6.86	-5.35	dBm	
Output IP3 In-band	OIP3	7.74	8.85	dBm	f <sub>1gps</sub> = 1575 MHz, f <sub>2gps</sub> = 1576MHz f <sub>1GLONASS</sub> = 1602 MHz, f <sub>2GLONASS</sub> = 1603 MHz Input power = -30 dBm
Rejection 750MHz <sup>1)</sup>	Rej <sub>750M</sub>	64.7		dBc	f = 750 MHz
Rejection 900MHz <sup>1)</sup>	Rej <sub>900M</sub>	44.4		dBc	f = 806 MHz - 928 MHz
Rejection 1800MHz <sup>1)</sup>	Rej <sub>1800M</sub>	43.0		dBc	f = 1710 MHz - 1980 MHz
Rejection 2400MHz <sup>1)</sup>	Rej <sub>2400M</sub>	47.2		dBc	f = 2400 MHz - 2500 MHz
Input P1dB	IP1dB <sub>900M</sub>	30.1		dBm	f = 900 MHz
Input P1dB	IP1dB <sub>1710M</sub>	32.2		dBm	f = 1710 MHz
LTE band-13 2 <sup>nd</sup> Harmonic	H2	-69.9		dBm	f <sub>IN</sub> = 787.76 MHz, P <sub>IN</sub> = +15 dBm; f <sub>H2</sub> = 1575.52 MHz
Input IP3 out-of-band	IIP3 <sub>OOB</sub>	64.3		dBm	f <sub>1</sub> = 1712.7 MHz, f <sub>2</sub> = 1850 MHz P <sub>1IN</sub> = +10 dBm, P <sub>2IN</sub> = +10 dBm; f <sub>IIP3</sub> = 1575.4 MHz
Stability	k	>1		--	Unconditionnally Stable from 0 to 10GHz

<sup>1)</sup> Rejection is defined as following: [Gain at 1575.42 MHz] – [Attenuation@stopband frequency]

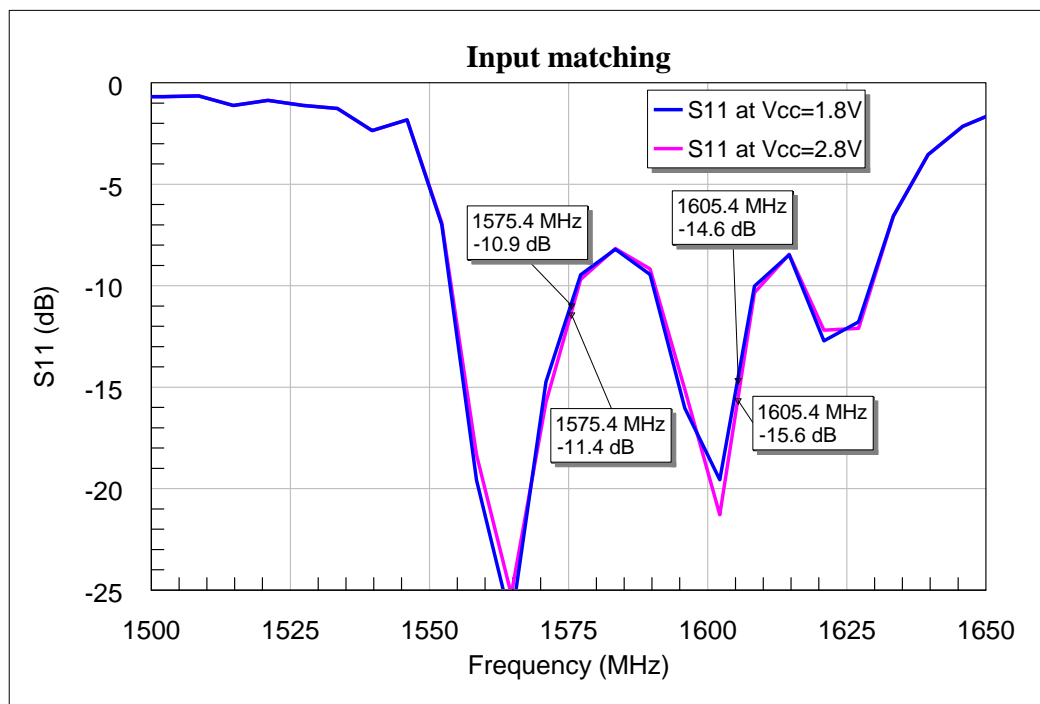
## 6 Measured Graphs for GPS and GLONASS Bands



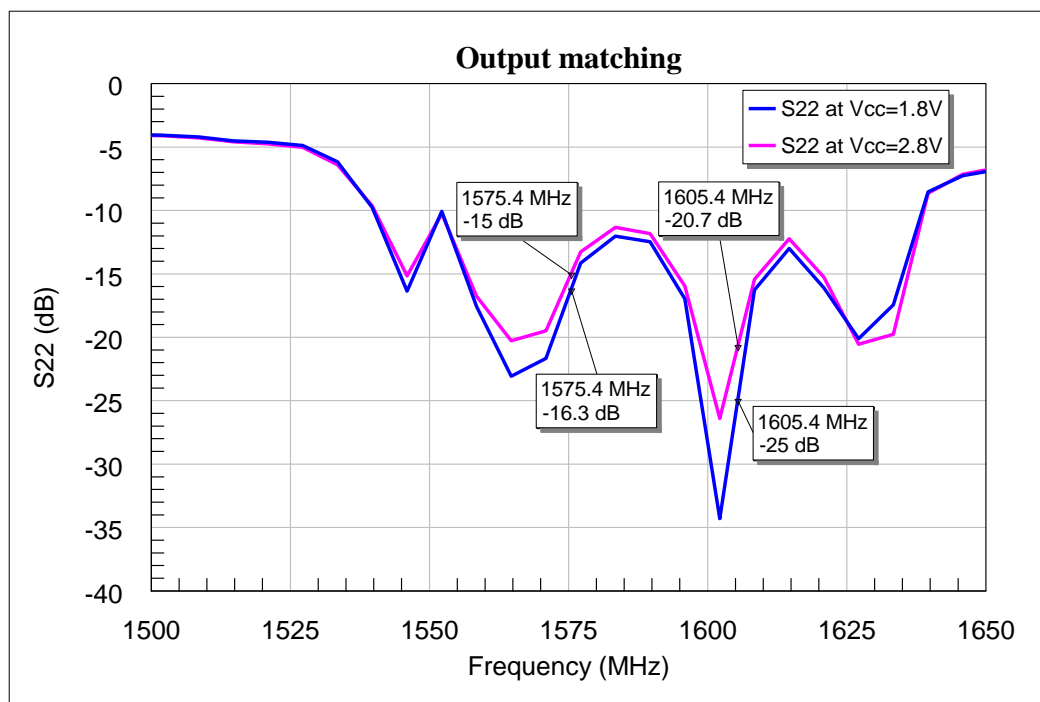
**Figure 6 Wideband Insertion Power Gain of BGM1043N7**



**Figure 7 Narrowband Insertion Power Gain of BGM1043N7 for GPS and GLONASS bands**



**Figure 8** Input Matching of BGM1043N7 for GPS and GLONASS bands



**Figure 9** Output Matching of BGM1043N7 for GPS and GLONASS bands

Measured Graphs for GPS and GLONASS Bands

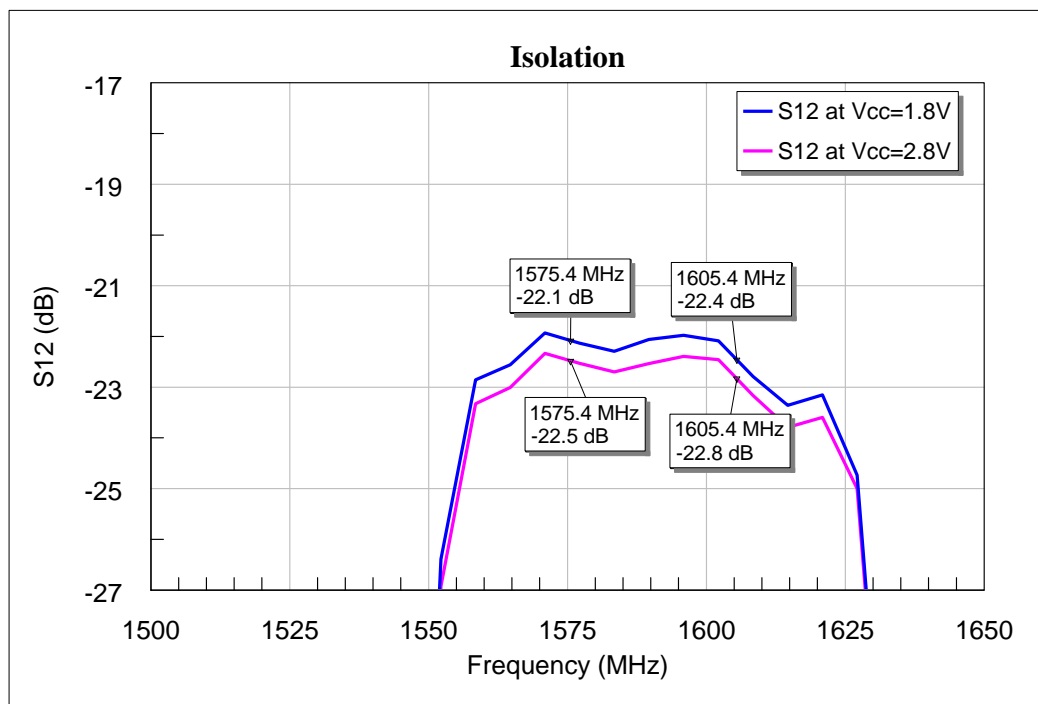


Figure 10 Reverse Isolation of BGM1043N7 for GPS and GLONASS bands

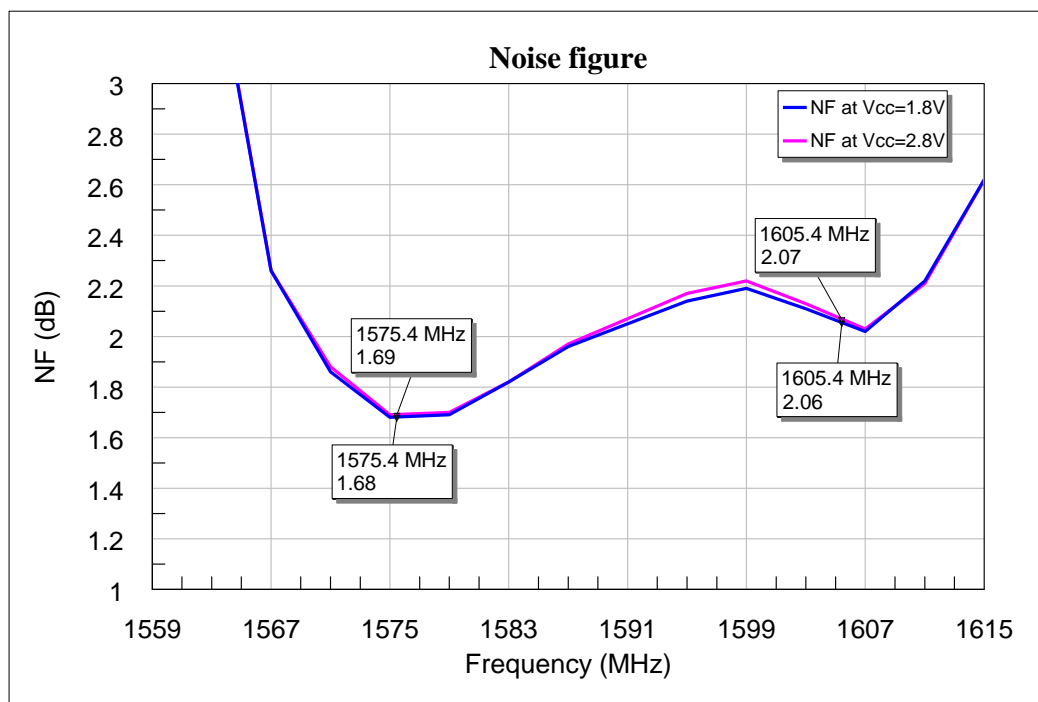
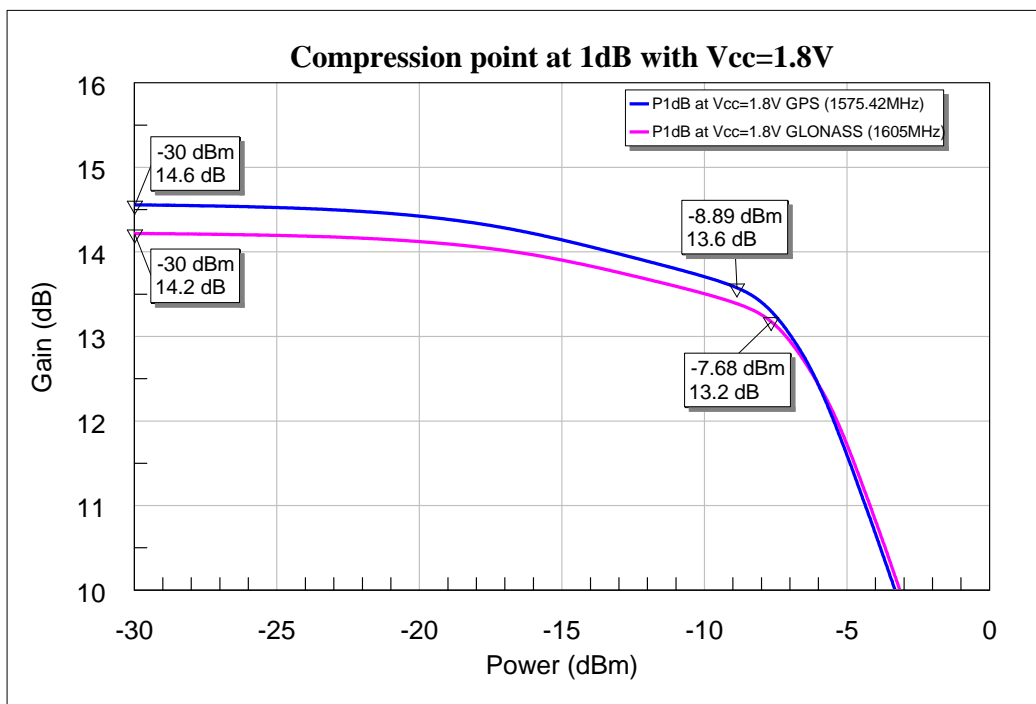
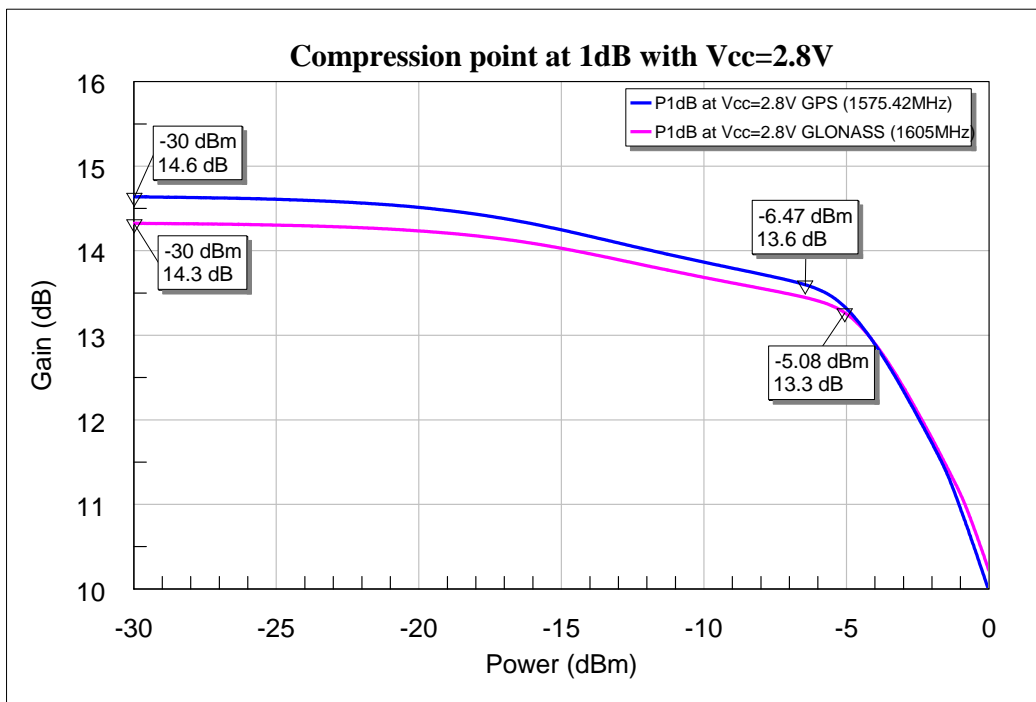


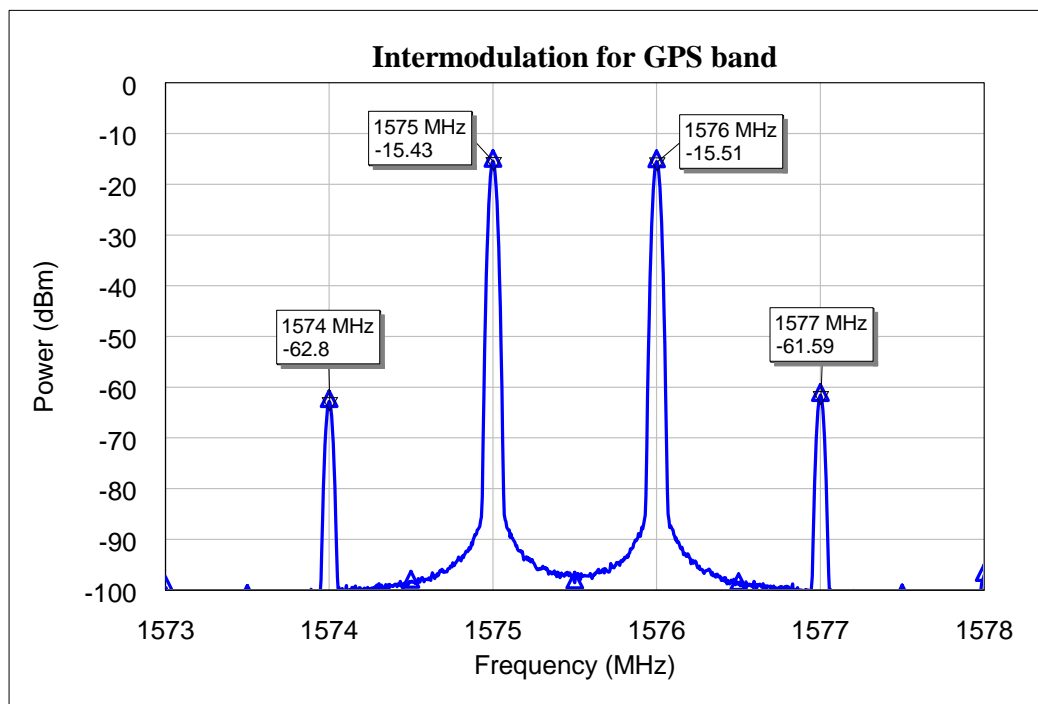
Figure 11 Noise Figure of BGM1043N7 for GPS and GLONASS bands



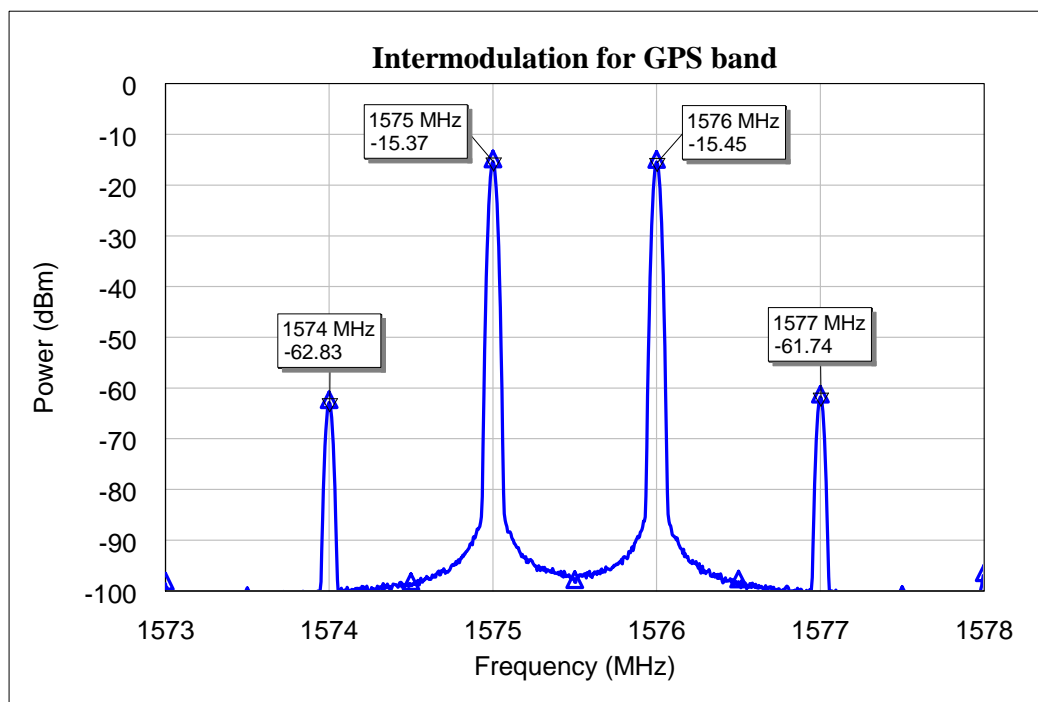
**Figure 12** Input 1dB Compression Point of BGM1043N7 at supply voltage of 1.8V for GPS and GLONASS bands



**Figure 13** Input 1dB Compression Point of BGM1043N7 at supply voltage of 2.8V for GPS and GLONASS bands

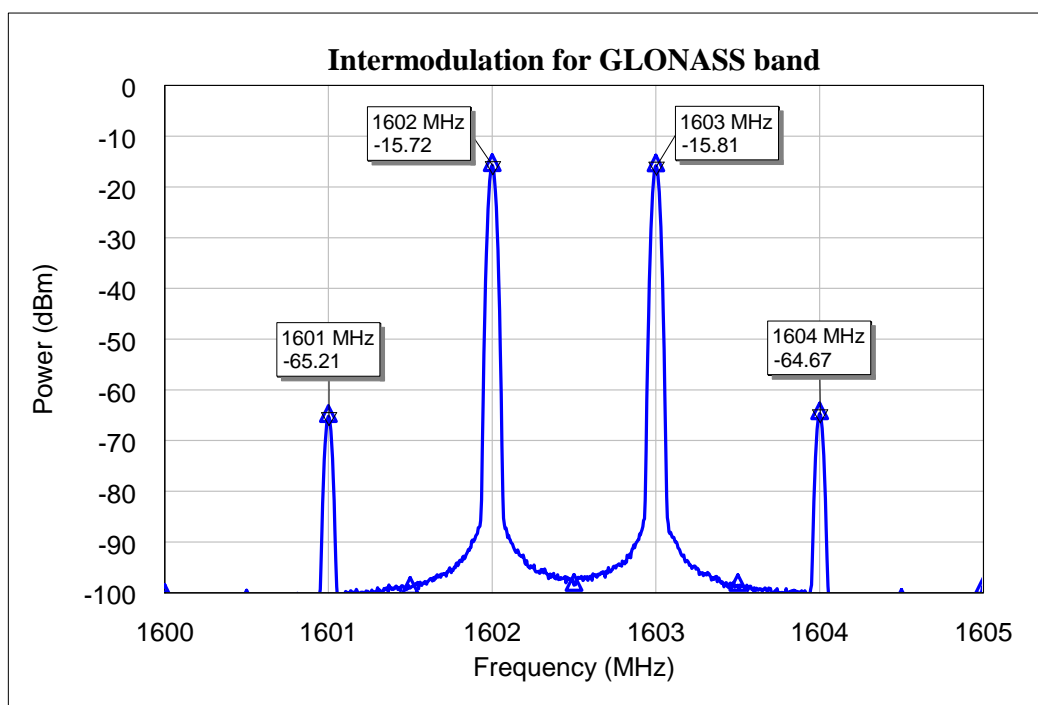


**Figure 14** Carrier and intermodulation products of BGM1043N7 for GPS band at  $V_{cc}=1.8V$

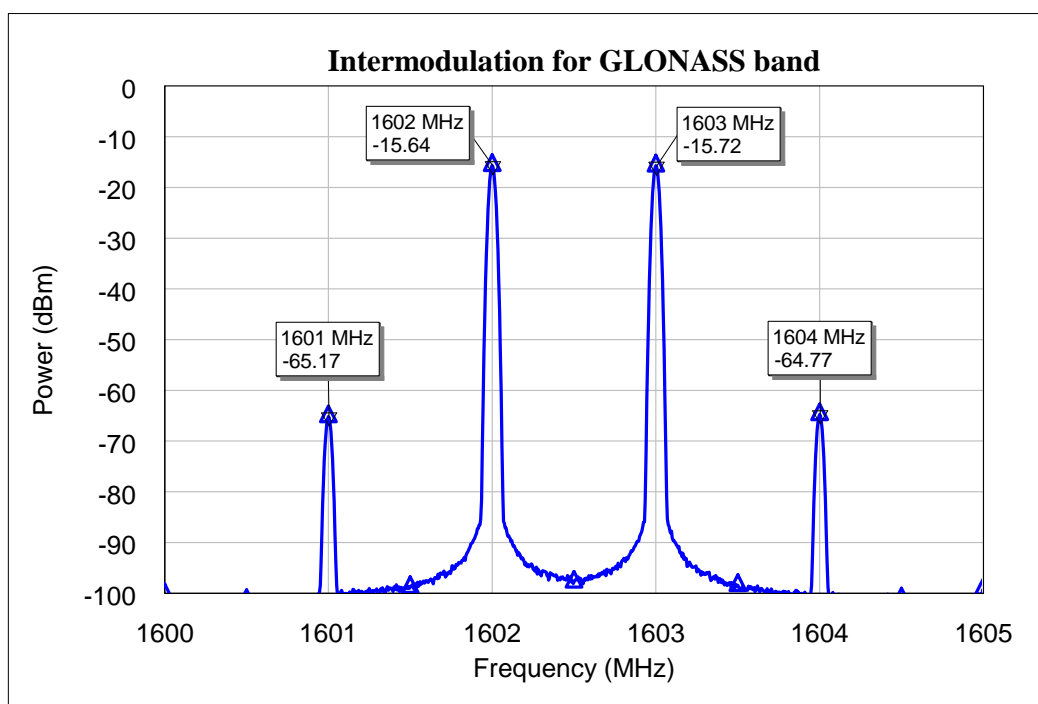


**Figure 15** Carrier and intermodulation products of BGM1043N7 for GPS band at  $V_{cc}=2.8V$



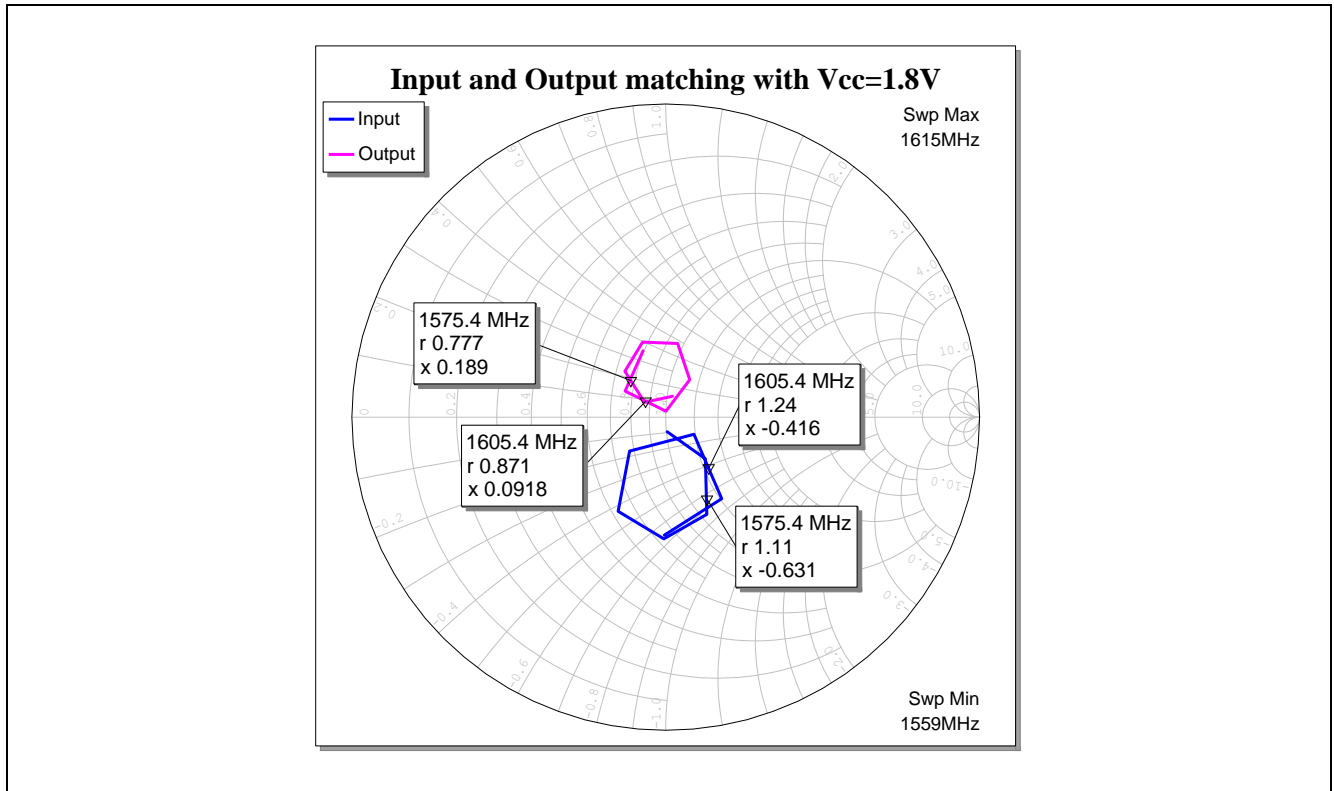


**Figure 16** Carrier and intermodulation products of BGM1043N7 for GLONASS band at  $V_{cc}=1.8V$

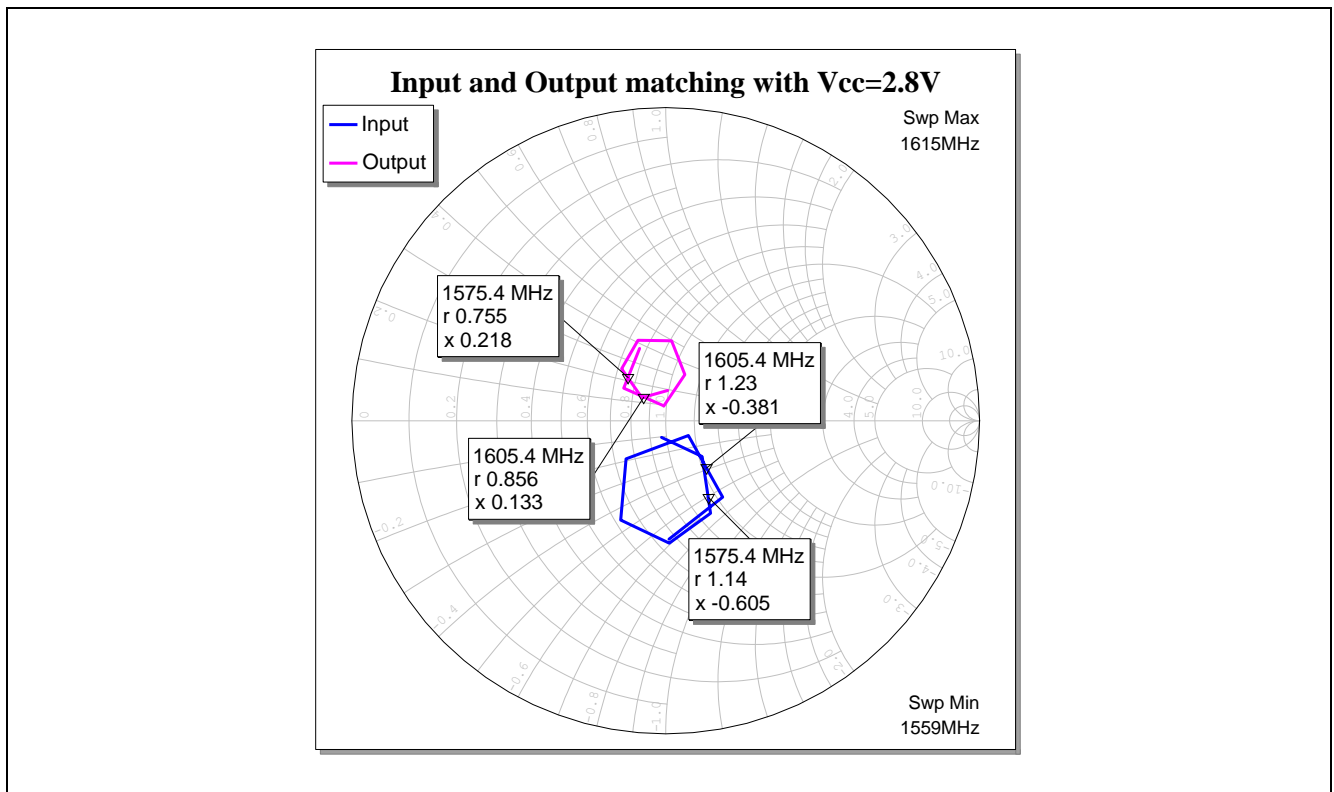


**Figure 17** Carrier and intermodulation products of BGM1043N7 for GLONASS band at  $V_{cc}=2.8V$

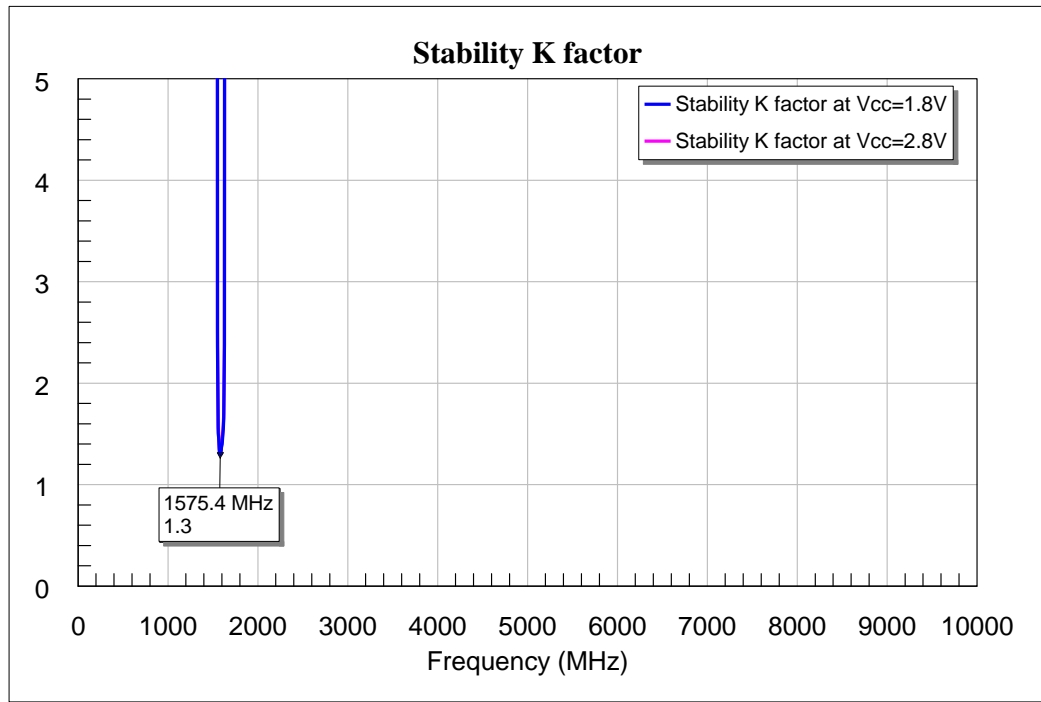
## 7 Miscellaneous Measured Graphs



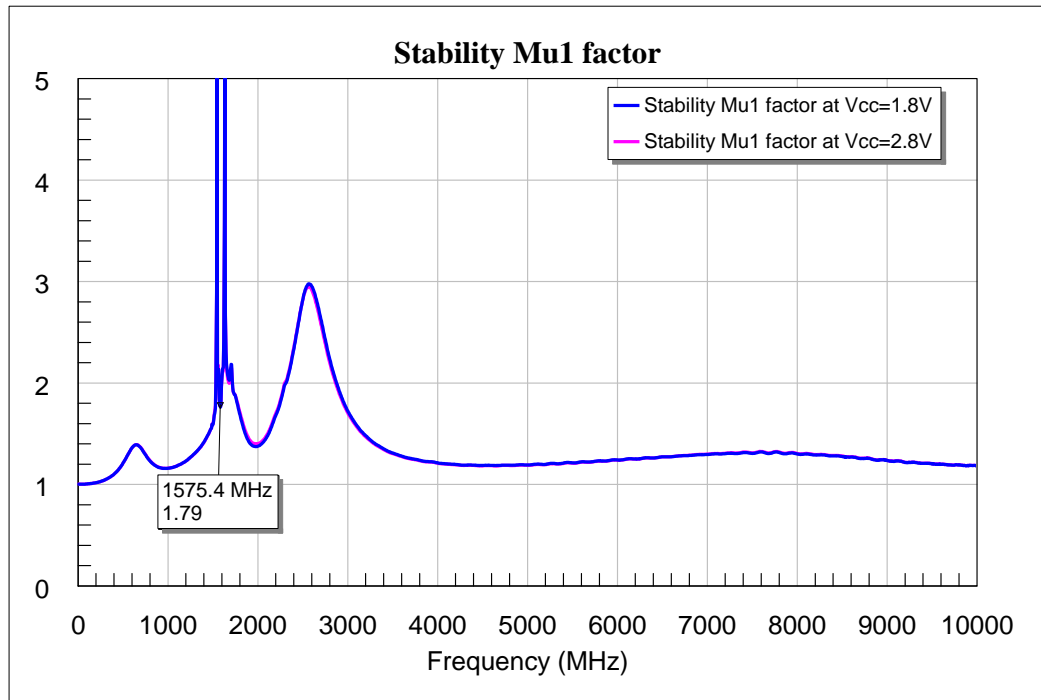
**Figure 18** Input and Output Matching of BGM1043N7 for GPS and GLONASS bands with Vcc=1.8V



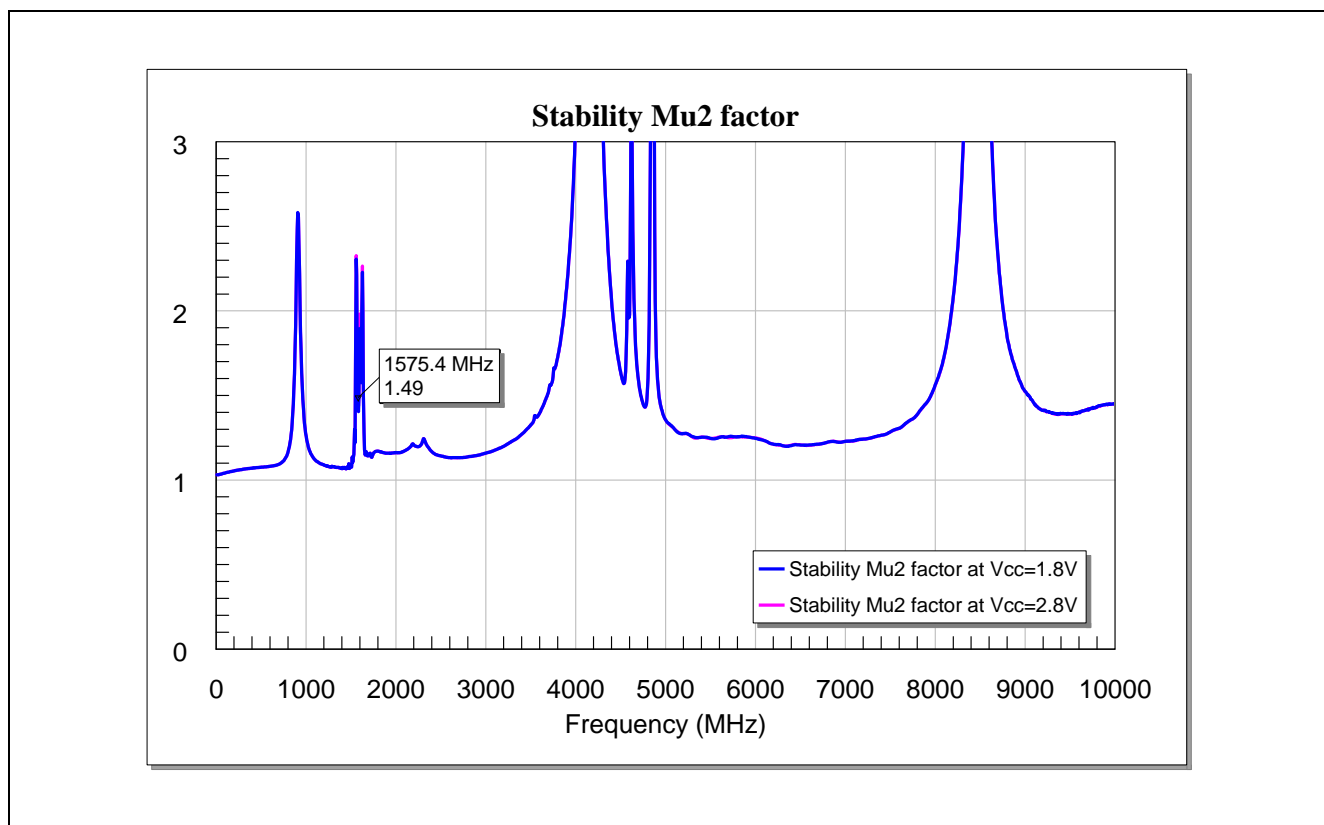
**Figure 19** Input and Output Matching of BGM1043N7 for GPS and GLONASS bands with Vcc=2.8V



**Figure 20** Stability Factor K of BGM1043N7 upto 10 GHz



**Figure 21** Stability Factor  $\mu_1$  of BGM1043N7 upto 10 GHz



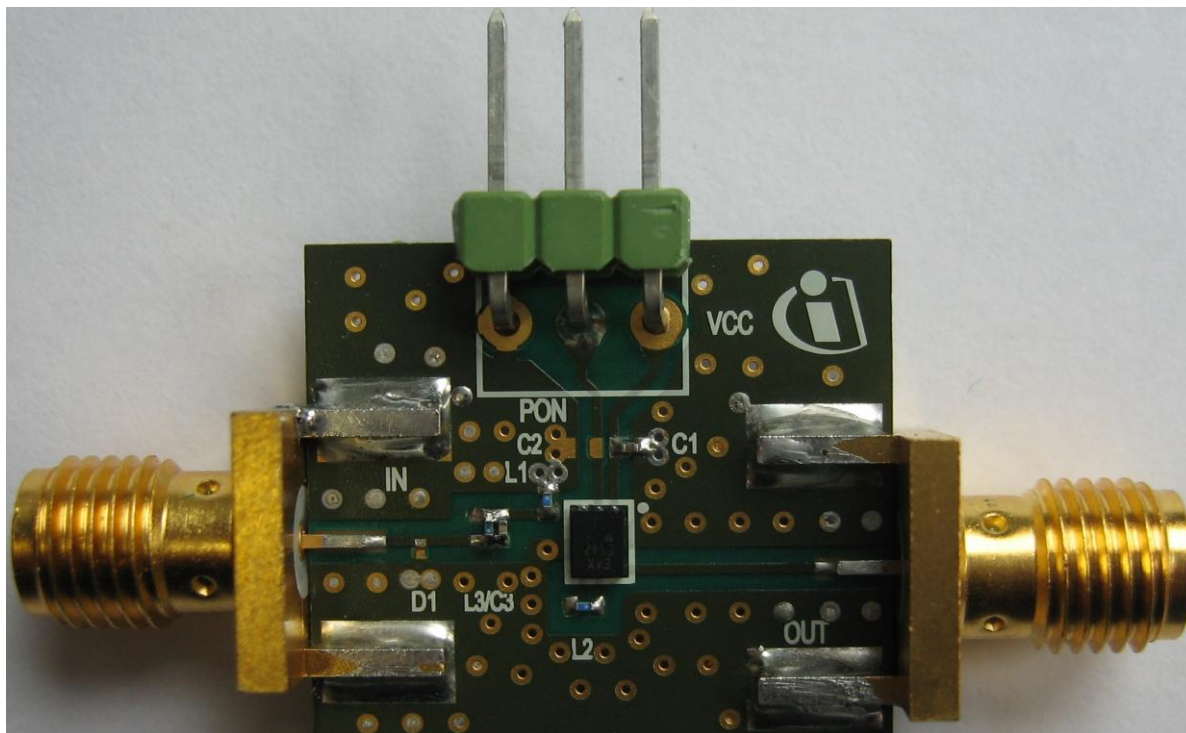
**Figure 22** Stability Factor  $\mu_2$  of BGM1043N7 upto 10 GHz

## 8 Evaluation Board and Layout Information

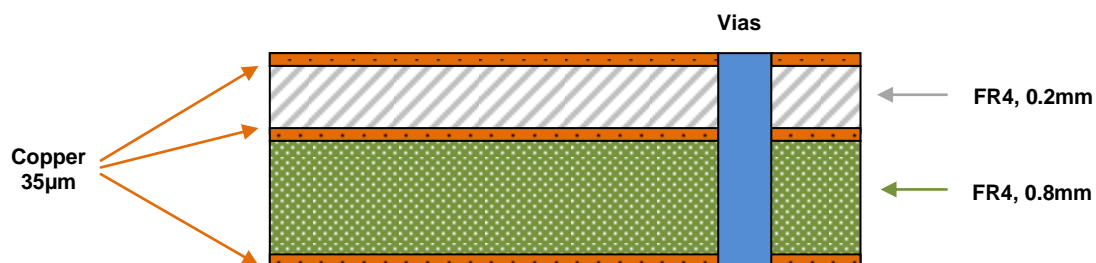
In this application note, the following PCB is used:

PCB Marking: V3.0 M110416

PCB material: FR4



**Figure 23** Picture of Evaluation Board for BGM1043N7



**Figure 24** PCB Layer Information

## **9 Authors**

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