



Developer Day

Live session with DAVE
Hands-on: Get DAVE up and running



Basic Principles of DAVE

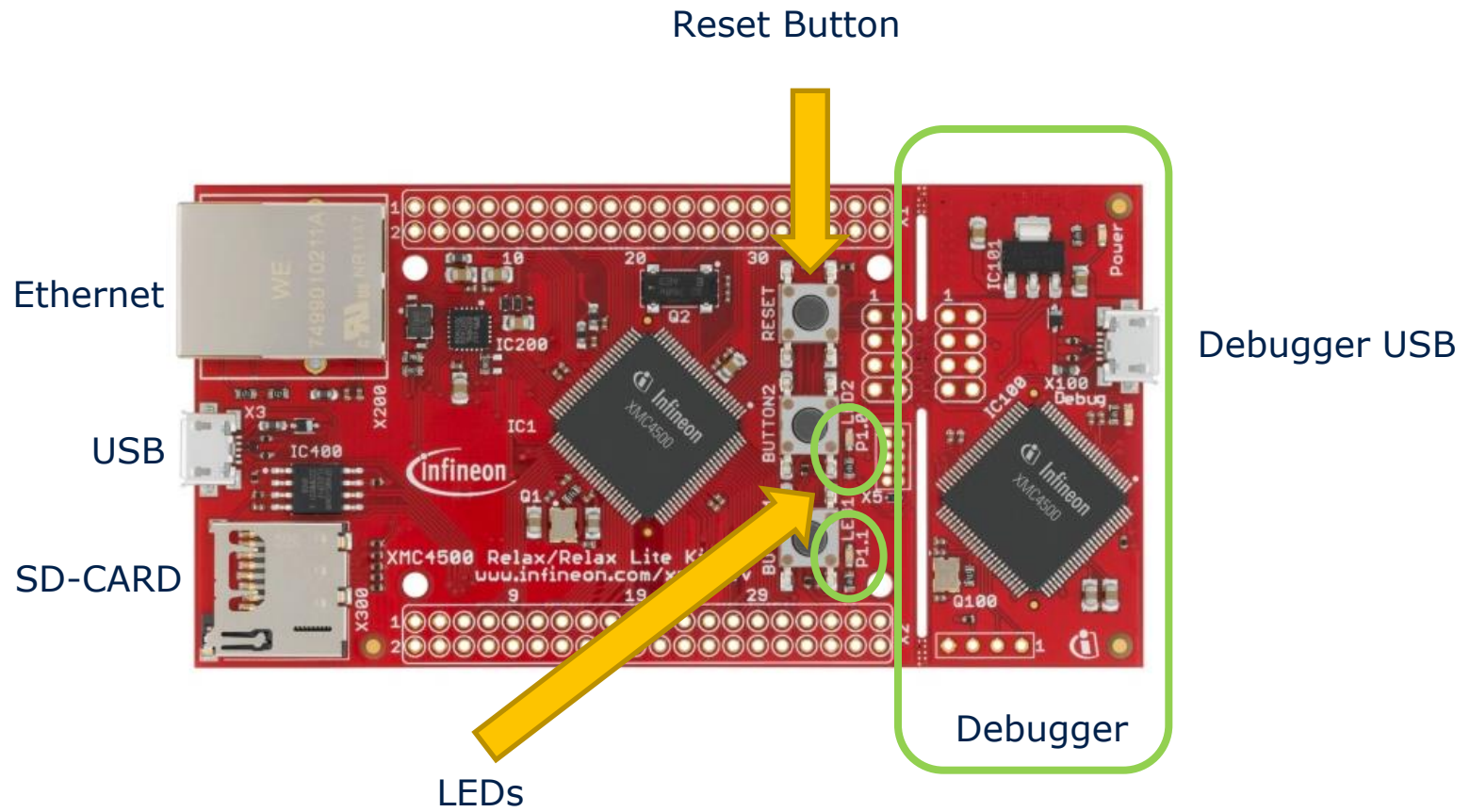
- example with how to...
 - Create first project
 - Handle DAVE surface
 - Configure Apps
 - Allocate Pins
 - Find the generated Code
 - Debug
 - Create more complex projects
 - Connect Apps with each other
 - Create Hardware Connections
 - Create Interrupt Service Routines
 - Use GPIO & API
 - Write own code into the projects

First Task

- Typically the first „Hello World“-like example for microcontrollers is blinking an LED:
- 1) Create a PWM signal with frequency 10 Hz
- 2) Output the PWM signal on a LED connected to P1.1 on the Relax Kit

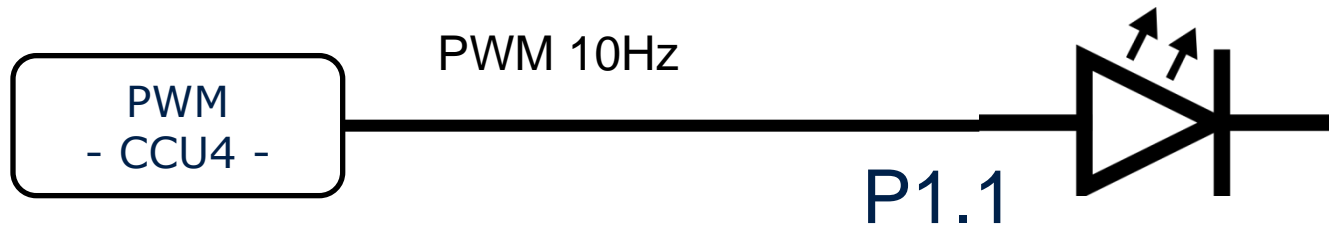
Relax Kit intro

- Relax-kit should be connected to your PC via Debugger USB



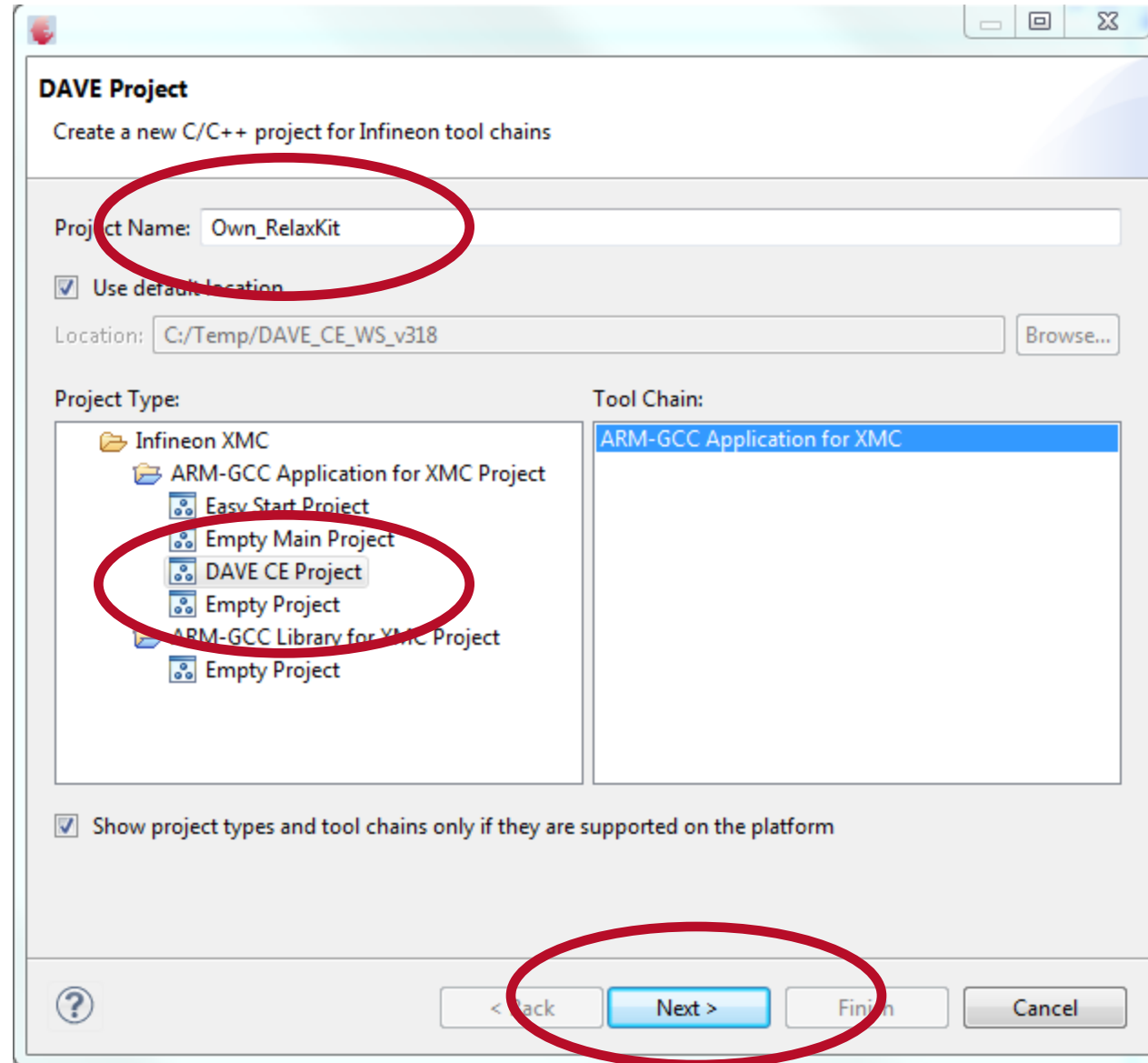
PWM to Blink an LED

- Creation of a PWM signal that control a LED



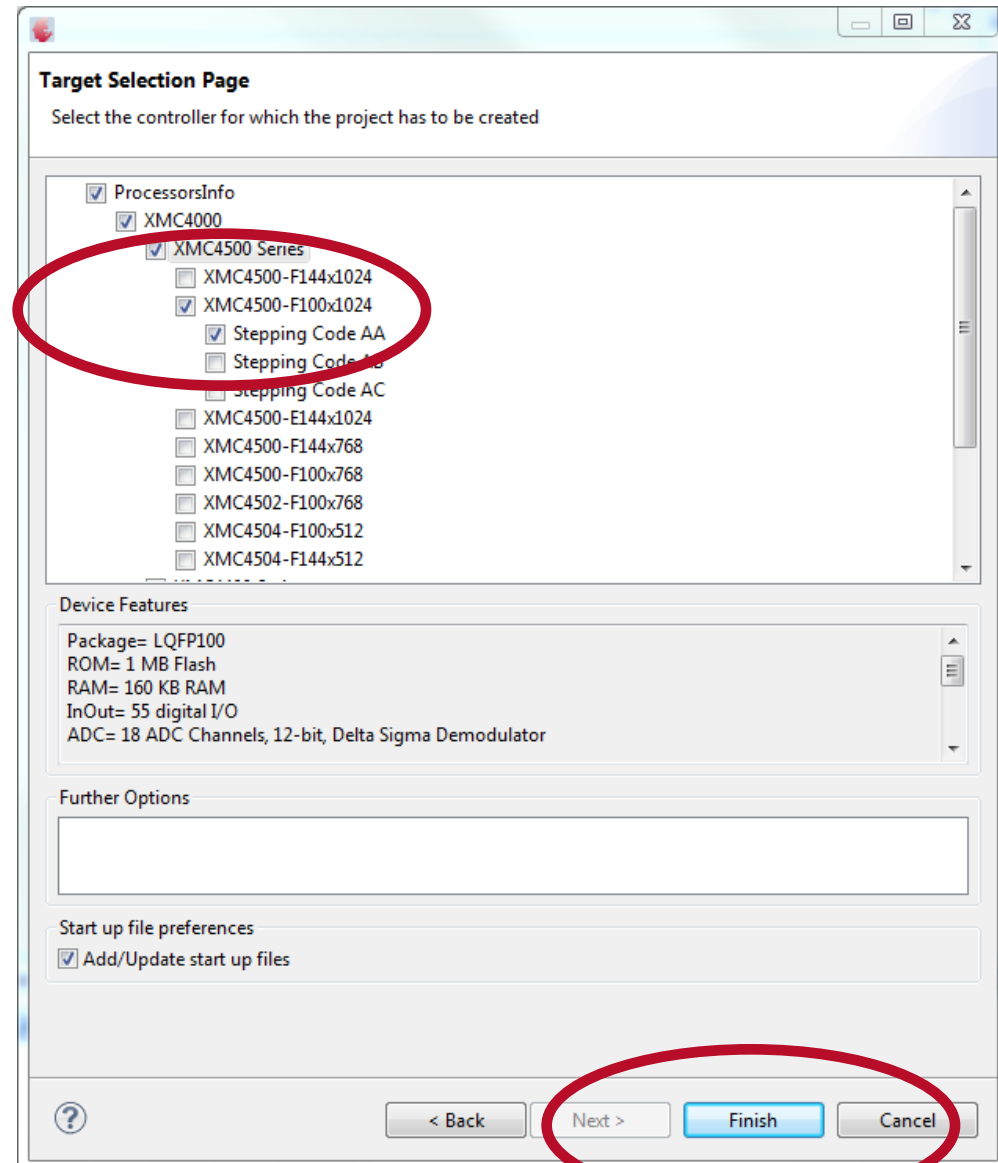
Create a new project

- Click "File"
- "New"
- "DAVE CE Project"
- Click "Next"

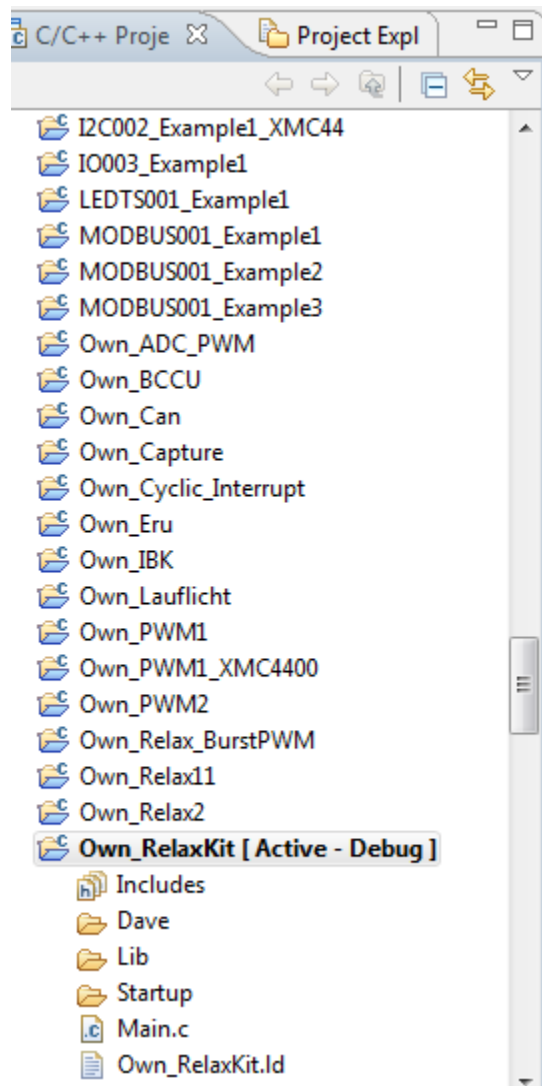


Select Microcontroller

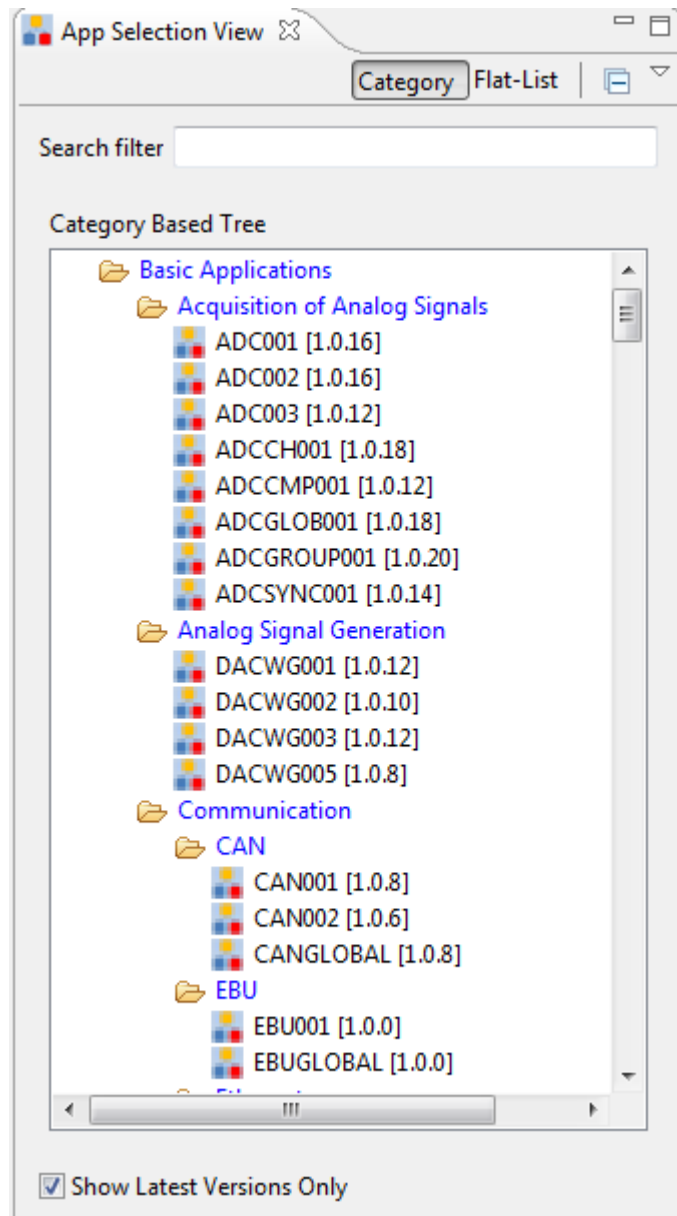
- Select the appropriate microcontroller
- In this case
 - XMC4500_F100x1024



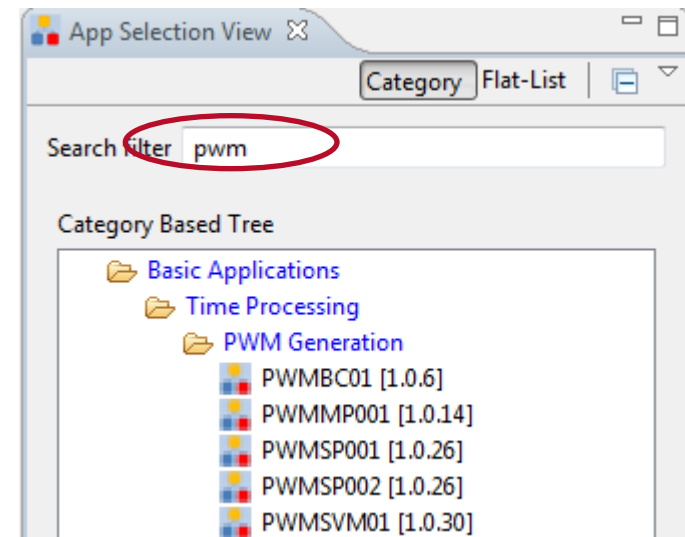
Project View



Adding an App

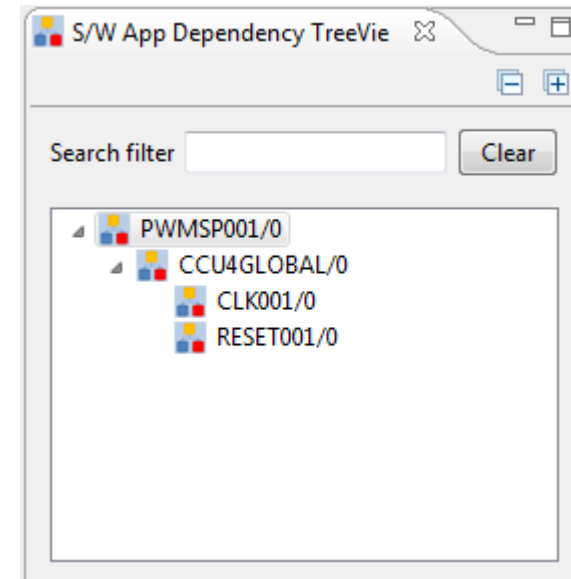
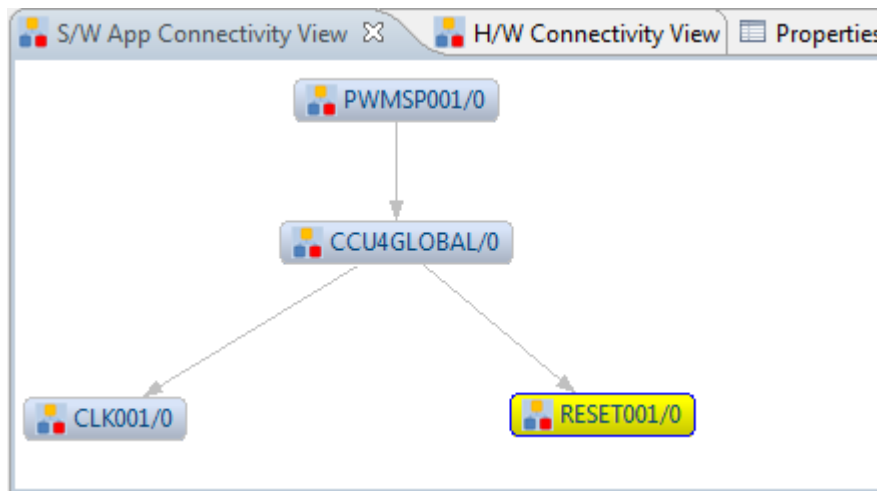


- Type „pwm“ in the search filter field
- Double-click on PWMSP001

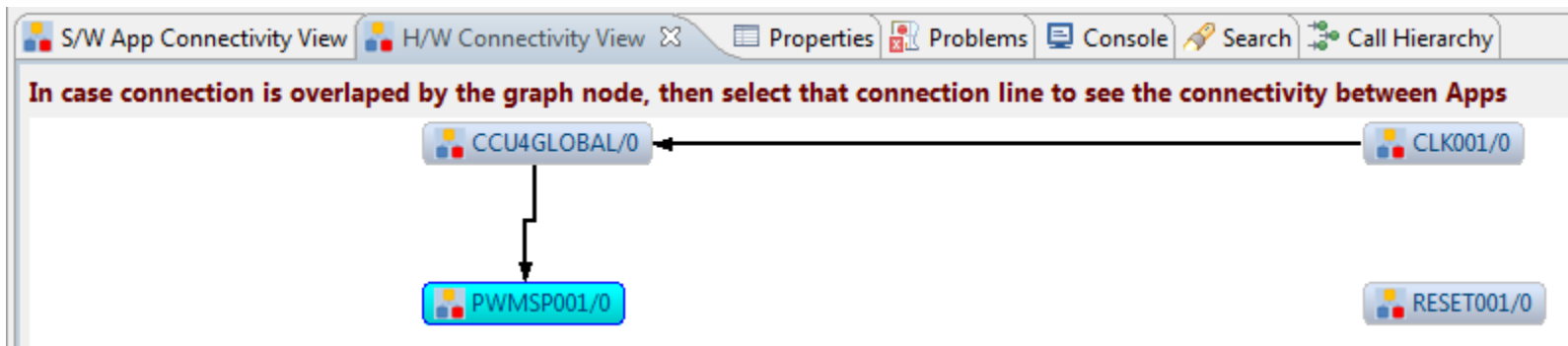


More Project Views

- All Apps in included into one Project are displayed in different Views:

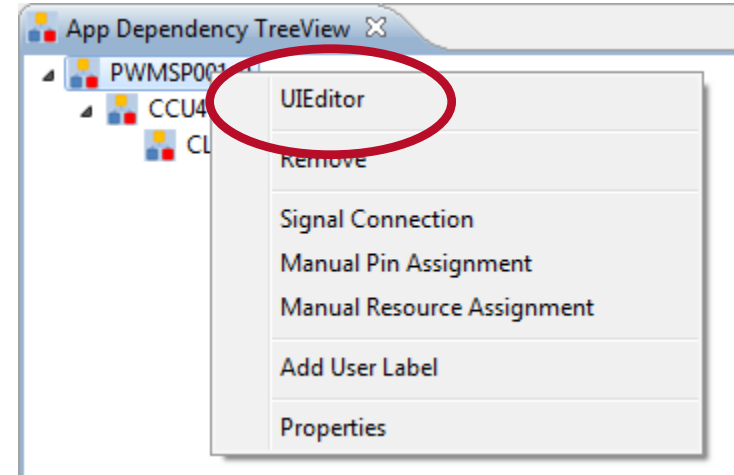


- The number behind the „/“ identifies the instance of an App

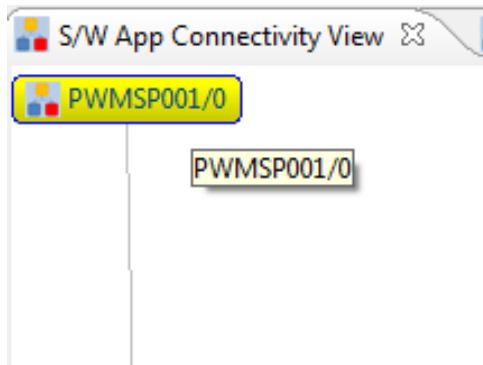


Configuring Apps

- Perform right-click on App name in the App Dependency TreeView
- Select UIEditor

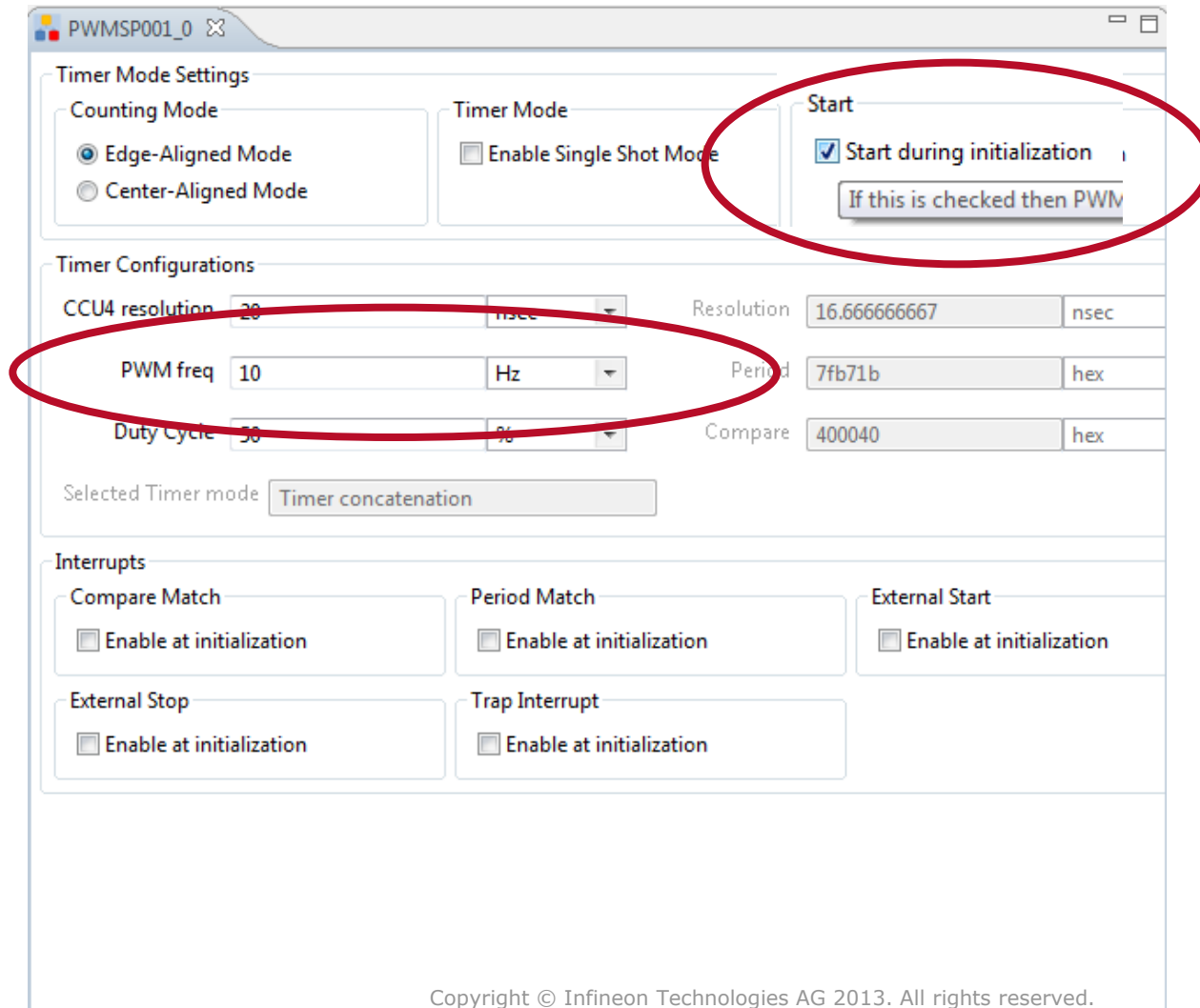


- Second Possibility:
- Double-click on App Name in S/W App Connectivity View



Configure PWMSP001 App for a 10 Hz signal

- Open the UIEditor of PWMSP001 and configure:



Timer Mode Settings

Counting Mode

- ☒ Edge-Aligned Mode
- ☐ Center-Aligned Mode

Timer Mode

- ☐ Enable Single Shot Mode

Start

- ☒ Start during initialization

If this is checked then PWM

Timer Configurations

CCU4 resolution 20 nsec Resolution 16.666666667 nsec

PWM freq 10 Hz Period 7fb71b hex

Duty Cycle 50 % Compare 400040 hex

Selected Timer mode Timer concatenation

Interrupts

Compare Match

- ☐ Enable at initialization

Period Match

- ☐ Enable at initialization

External Start

- ☐ Enable at initialization

External Stop

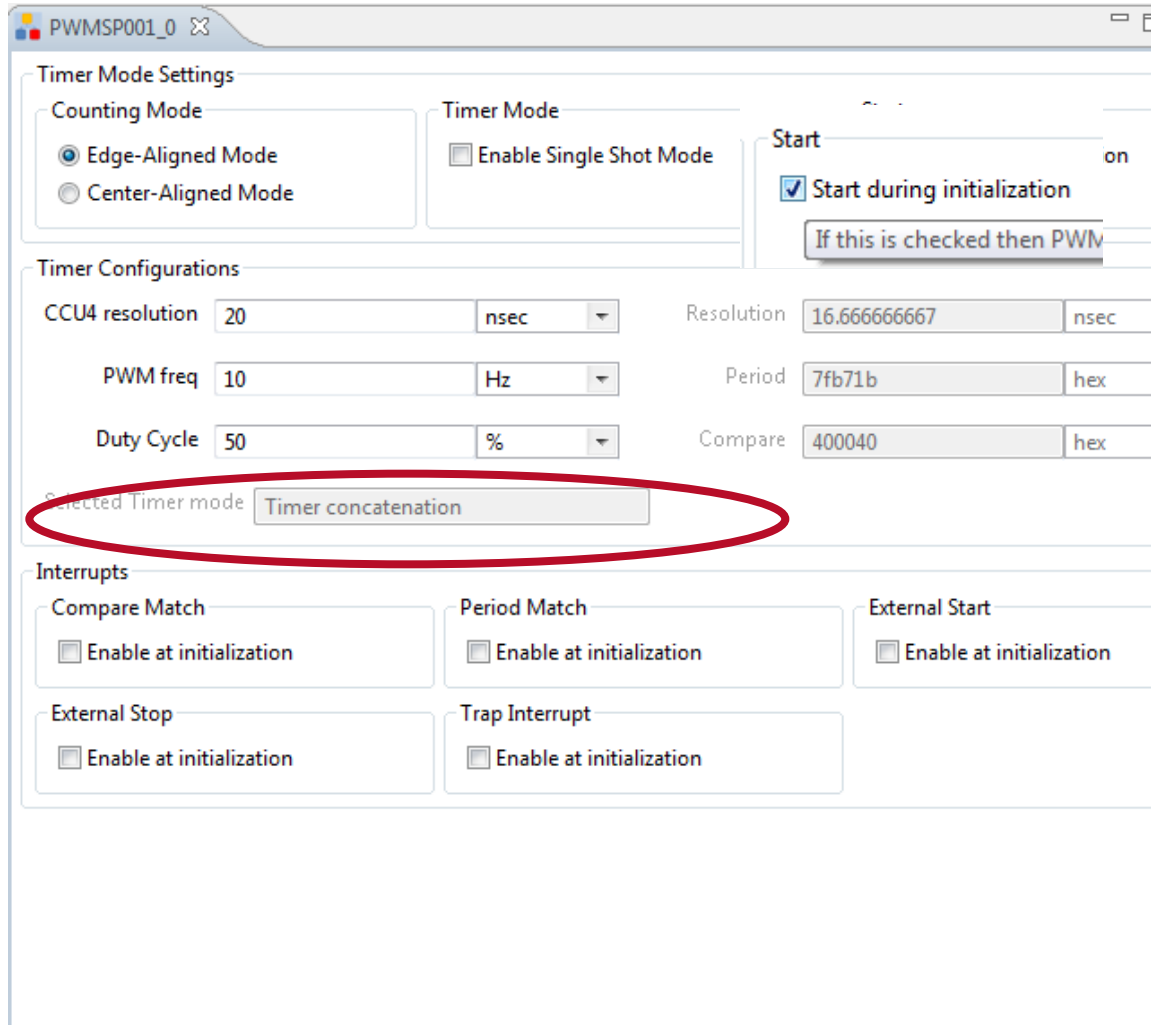
- ☐ Enable at initialization

Trap Interrupt

- ☐ Enable at initialization

Hint

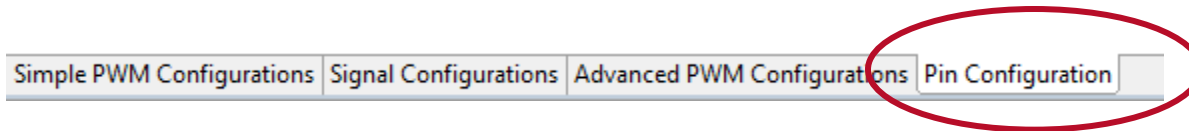
- Please note that the Tool automatically concatenates timers



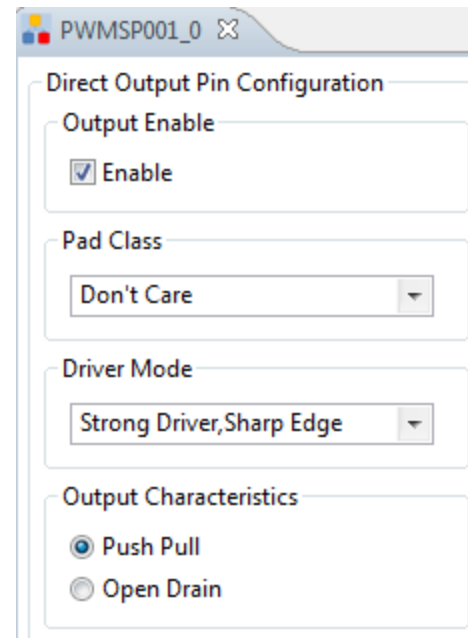
The screenshot shows the configuration window for PWMSP001_0. The 'Timer Mode Settings' section includes 'Counting Mode' (Edge-Aligned Mode selected), 'Timer Mode' (Enable Single Shot Mode unchecked), and 'Start' (Start during initialization checked). The 'Timer Configurations' section shows 'CCU4 resolution' (20 nsec), 'PWM freq' (10 Hz), 'Duty Cycle' (50 %), 'Resolution' (16.66666667 nsec), 'Period' (7fb71b hex), and 'Compare' (400040 hex). The 'Selected Timer mode' is set to 'Timer concatenation', which is highlighted with a red oval. The 'Interrupts' section includes 'Compare Match', 'Period Match', 'External Start', 'External Stop', and 'Trap Interrupt', all with 'Enable at initialization' unchecked.

Output Settings

- From the selection of the subviews of the UIEditor select „Pin Configuration“

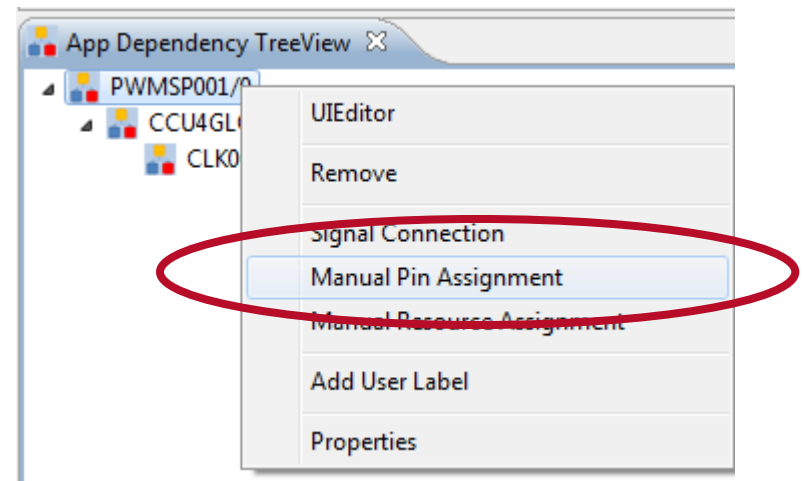


- Check „Output Enable“



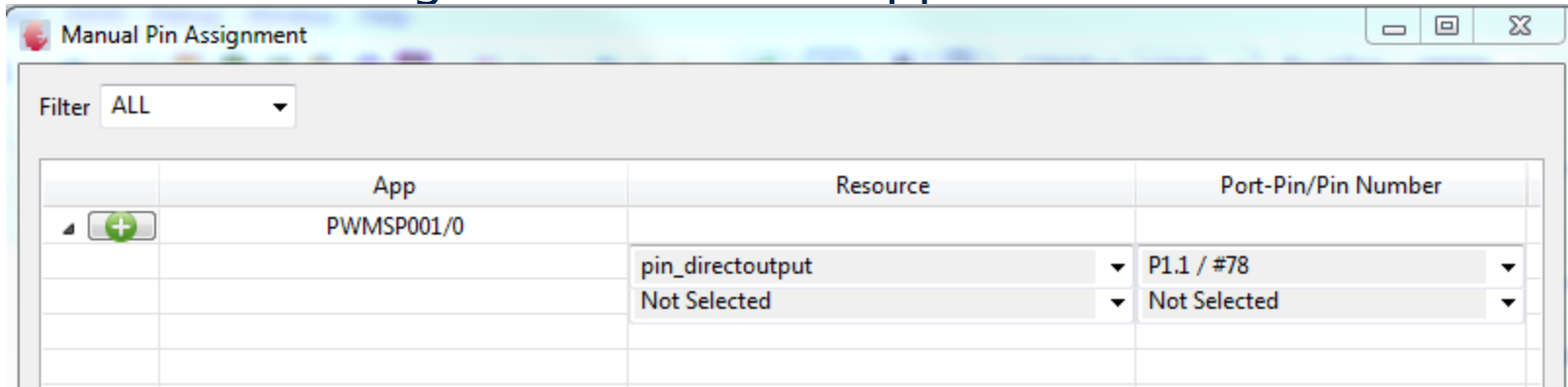
Pin Configuration

- Now to direct the PWM signal we just configured out of the P1.2 we have to assign this pin to the PWM signal output
- Right-click on PWMSP001/0
- Select „Manual Pin Assignment“

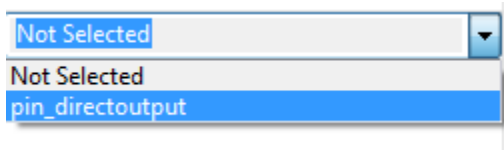


Pin Configuration

- Manual Pin Assignment Window appears:

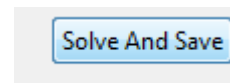
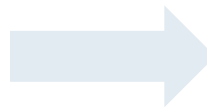


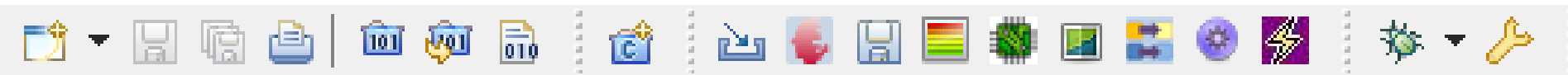
- From the Drop-down menu select „pin_directoutput“



- From the second Drop-down menu select „P1.1 / #78“

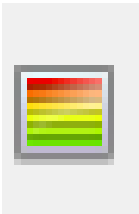
- Click „Solve and Save“





Check Correct function of the Timer Module

- Open the Resource Overview in DAVE CE perspective



Reports

Resource Mapping Pin Assignment Signal Assignment Apps

App	Resource	Mapped Resource
CCU4GLOBAL/0	global	ccu4/0/global
CLK001/0	ccu	scu/0/clkctrl/0/ccu
	clk_extpin	
	cpu	scu/0/clkctrl/0/cpu
	ebu	scu/0/clkctrl/0/ebu
	hibernate	scu/0/pwrctrl/0/hibernate
	mmc	scu/0/clkctrl/0/sdmmc
	perbridge	scu/0/clkctrl/0/perbridge
	pll	scu/0/clkctrl/0/pll
	rgextclk	scu/0/clkctrl/0/extclk
	rtccksel	scu/0/rtccksel
	sys	scu/0/clkctrl/0/sys
	usb	scu/0/clkctrl/0/usb
	wdt	scu/0/clkctrl/0/wdt
DAVESupport/0		
DBG001/0		
LIBS/0		
MOTORLIBS/0		
PWMSP001/0		
	pin_directoutput	p/1/pad/1
	slice	ccu4/0/cc4/2
	slice1	ccu4/0/cc4/1
RESET001/0		

Export

OK Cancel

Generate & Compile Code

- Start the Solver by clicking „the disc“ in the tool panel

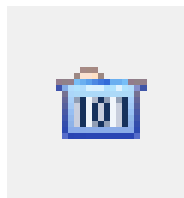


- If the solver does not show an error, there is none and everything that is configured it possible



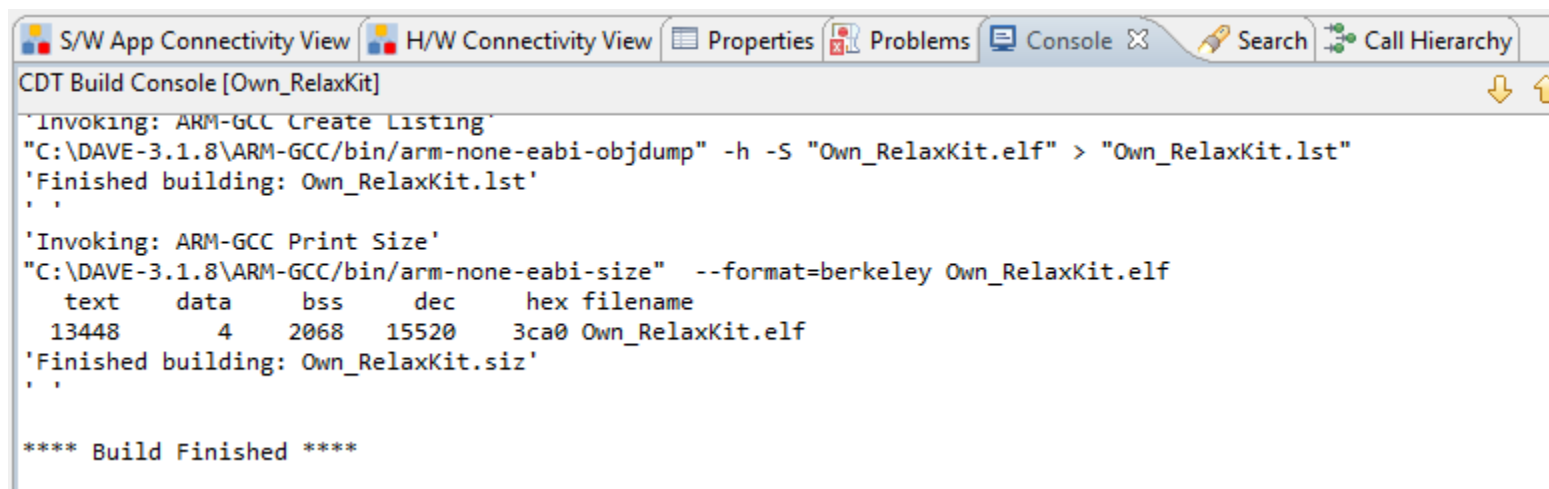
- Start the Code generator by clicking the „Lightning“ in the tool panel

- Start the compiler by clicking the „build“ symbol in the tool panel



Check Compiler Results

- Ensure that Compiler finished regularly in Console window



The screenshot shows the CDT Build Console window for a project named 'Own_RelaxKit'. The console displays the output of two ARM-GCC commands. The first command is 'Invoking: ARM-GCC Create Listing', which runs 'C:\DAVE-3.1.8\ARM-GCC/bin/arm-none-eabi-objdump' to create 'Own_RelaxKit.lst'. The second command is 'Invoking: ARM-GCC Print Size', which runs 'C:\DAVE-3.1.8\ARM-GCC/bin/arm-none-eabi-size' to print the size of 'Own_RelaxKit.elf'. The output shows the size of the text, data, bss, and dec sections in decimal and hexadecimal, along with the filename. The console ends with '**** Build Finished ****'.

```

CDT Build Console [Own_RelaxKit]

'Invoking: ARM-GCC Create Listing'
"C:\DAVE-3.1.8\ARM-GCC/bin/arm-none-eabi-objdump" -h -S "Own_RelaxKit.elf" > "Own_RelaxKit.lst"
'Finished building: Own_RelaxKit.lst'
', '

'Invoking: ARM-GCC Print Size'
"C:\DAVE-3.1.8\ARM-GCC/bin/arm-none-eabi-size" --format=berkeley Own_RelaxKit.elf
  text    data    bss    dec    hex filename
13448      4   2068   15520   3ca0 Own_RelaxKit.elf
'Finished building: Own_RelaxKit.siz'
', '

**** Build Finished ****

```

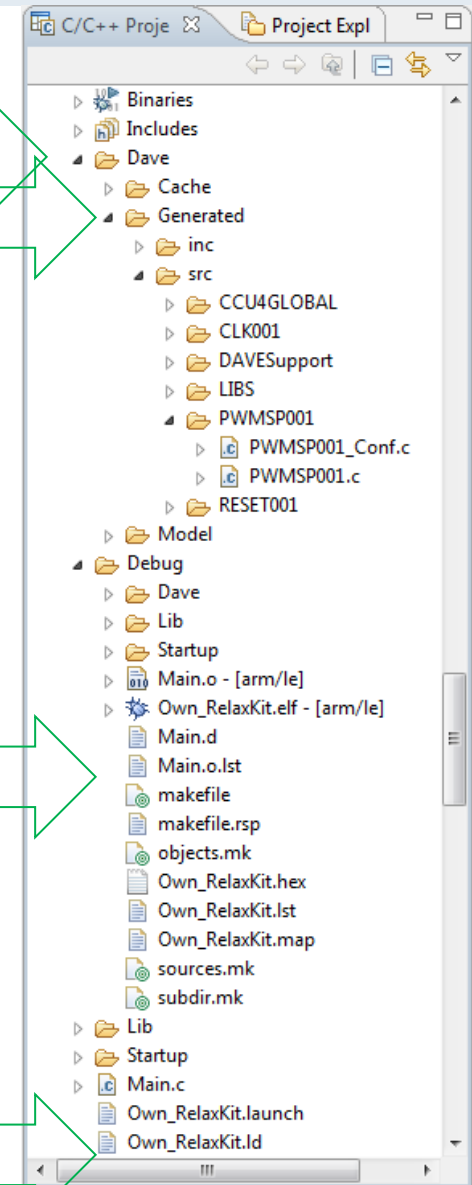
The Project Folder

Folder which is used exclusively by DAVE
Generated code goes in here

Code Templates can be found in here

Compiler output files

Linker Script file

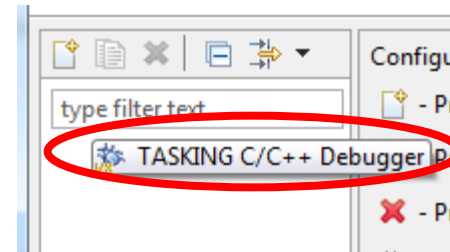


Flash and Debug

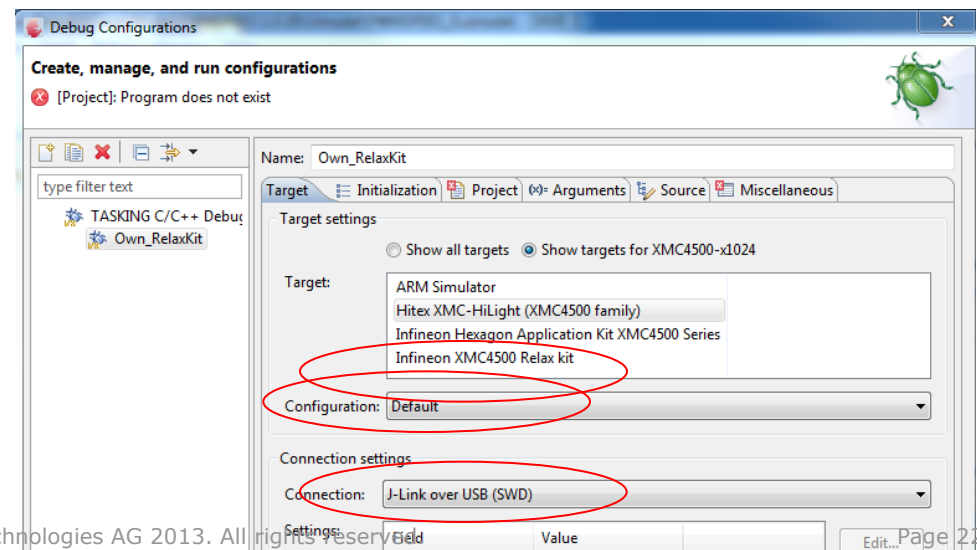
- Start the Debug Session by clicking on „the bug“ in the tool panel



- Create a new Debug Configuration by double-clicking on „Tasking C/C++ Debugger“

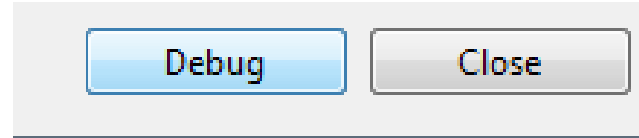


- Select „Infineon XMC4500 Relax kit“
Configuration: Default
Connection: J-Link over USB (SWD)



Flash and Debug

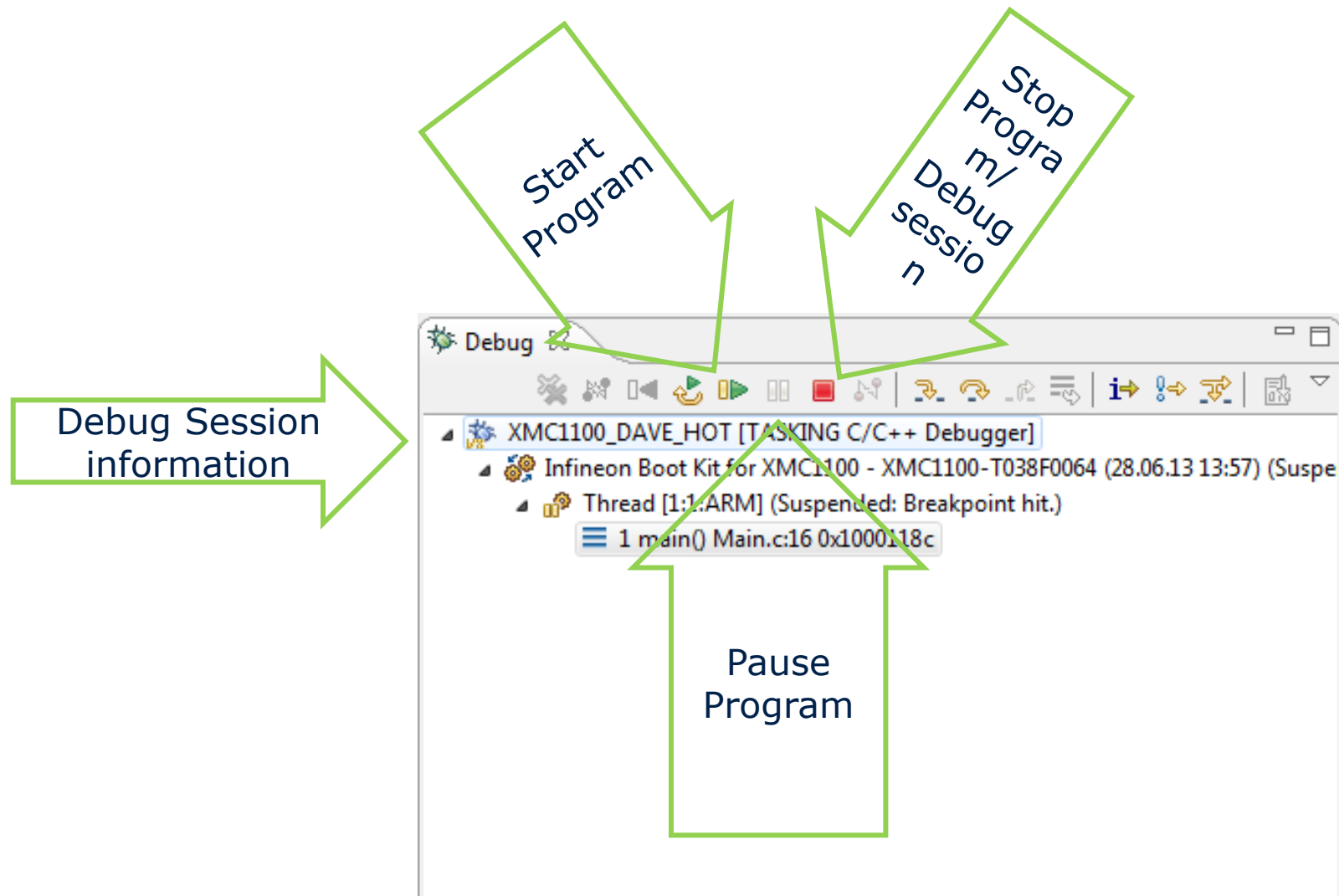
- Click on „Debug“



- The flashing process is started automatically and DAVE automatically switches to the Debug Perspective
- You can switch back to the Project Workspace Perspective using this button in the upper right corner of your window:

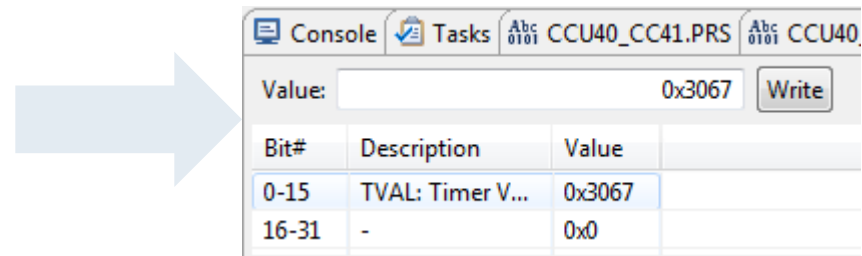
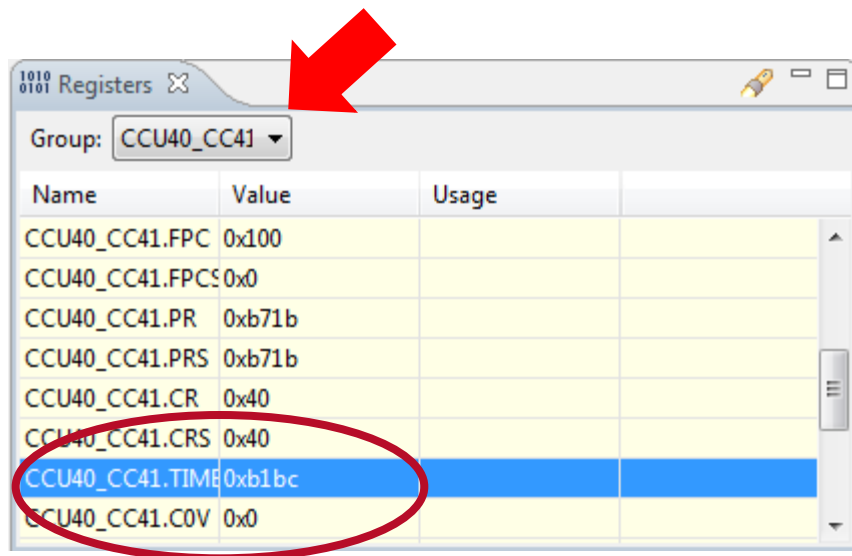


The Debug Perspective - Debug Window



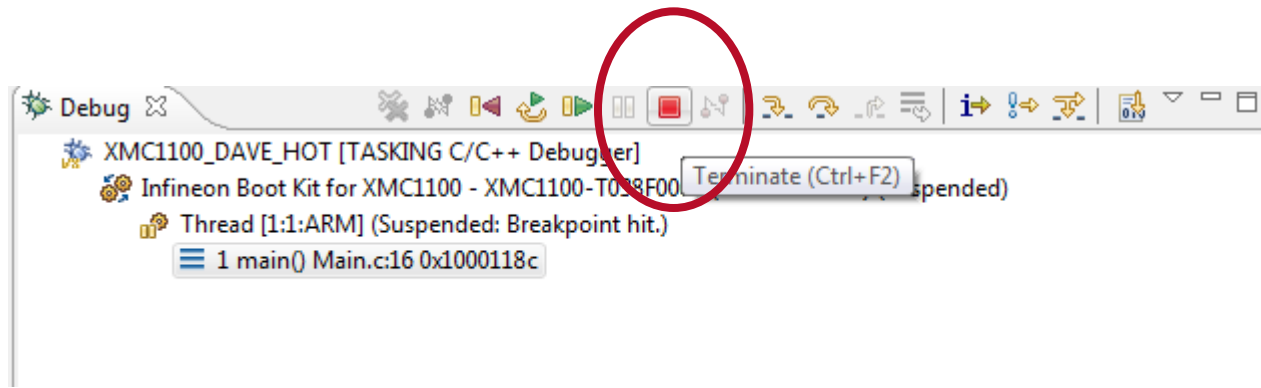
The Debug Perspective – Register Views

- Registers
- Drop-down list with modules
- For detailed register view right-click on the register name and select „Symbolic Representation“



The Debug Perspective – End Debug Session

- Always end a debug session by clicking the „Stop“ Button



Connecting Apps

- Task: Additional PWM with 5Hz shall be output on P1.0
- Generated by Counter Event = 20
- Counter incremented by PWM
- ISR: Resetting Counter and Toggling P1.0



Add and configure a Counter App

CNT001_0

Counter Configurations

Active Edge for Counting: Rising Edge

Gating signal Configuration: Disable

Low Pass filter: Disable

Event Count match: 20 dec

Start: ☒ Start During initialization

Interrupts

Count Match: ☒ Enable at initialization

Rollover: ☐ Enable at initialization

Input event edge: ☐ Enable at initialization

Gating: ☐ Enable at initialization

EventCounter

App Selection View

Category: Flat-List

Search filter: cnt

Category Based Tree

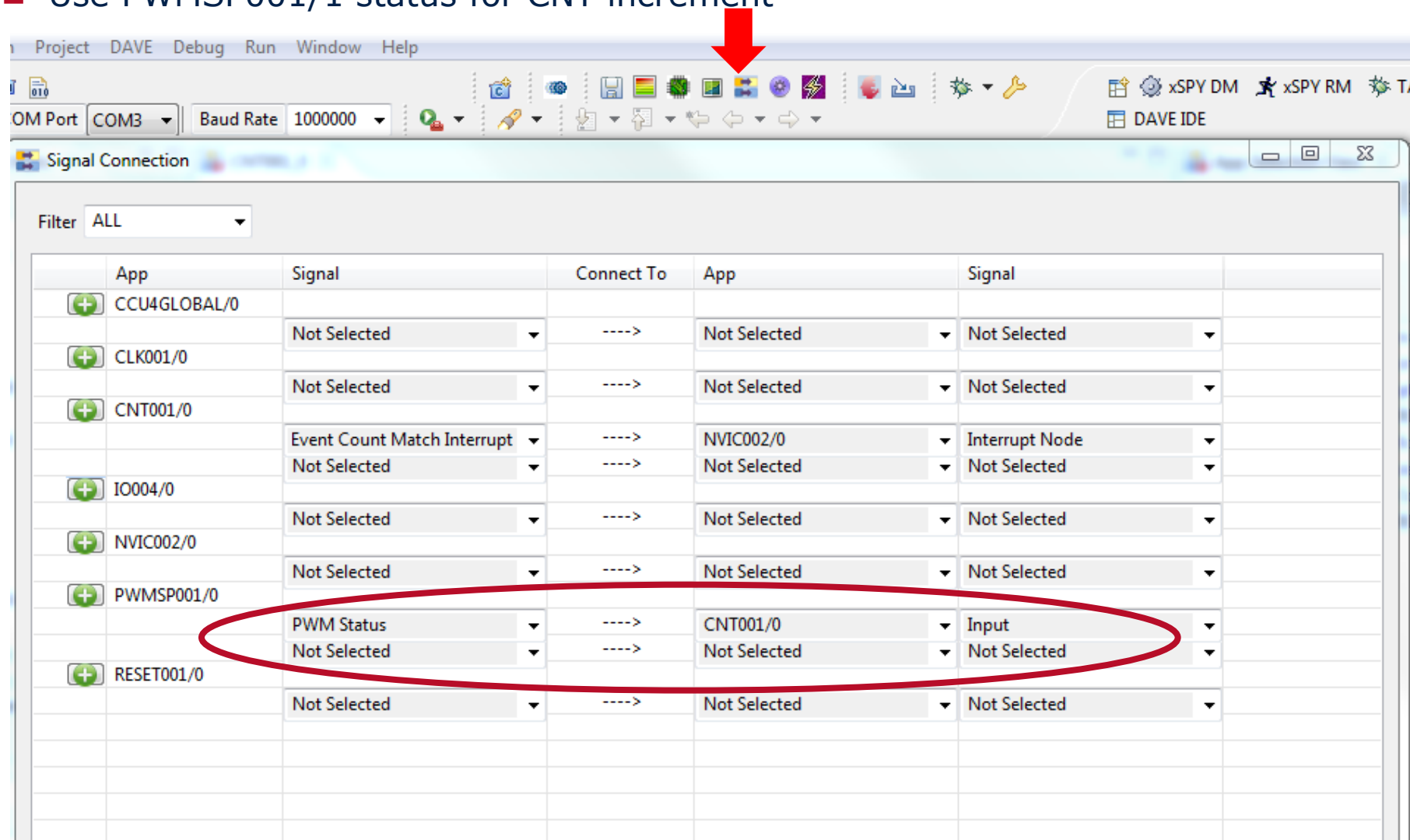
- Basic Applications
- Time Processing
 - Signal Capture
 - CNT001 [1.0.24]
- Peripheral Specific Apps
 - Timer/Capture-Compare
 - Capture/Compare Unit 4 (CAPCOM4)
 - CNT001 [1.0.24]

☒ Show Latest Versions Only

20

Connect PWM App with CNT App

- Use PWMSP001/1 status for CNT increment

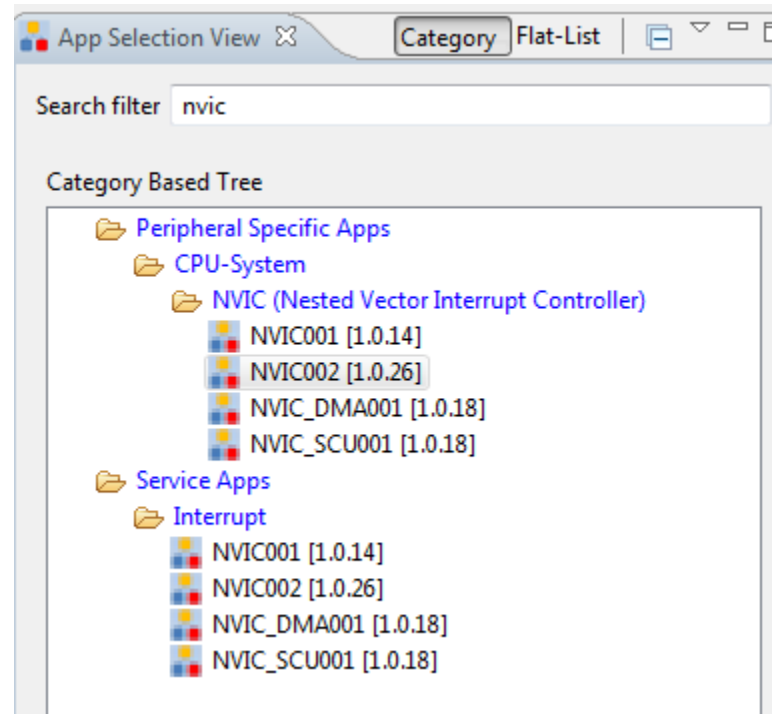


The screenshot shows the DAVE IDE interface with the 'Signal Connection' window open. The window displays a table of signal connections between various applications. A red arrow points to the 'Signal Connection' tab. A red oval highlights the connection between PWMSP001/0 and CNT001/0.

App	Signal	Connect To	App	Signal
CCU4GLOBAL/0	Not Selected	----	Not Selected	Not Selected
CLK001/0	Not Selected	----	Not Selected	Not Selected
CNT001/0	Event Count Match Interrupt	----	NVIC002/0	Interrupt Node
IO004/0	Not Selected	----	Not Selected	Not Selected
NVIC002/0	Not Selected	----	Not Selected	Not Selected
PWMSP001/0	PWM Status	----	CNT001/0	Input
RESET001/0	Not Selected	----	Not Selected	Not Selected

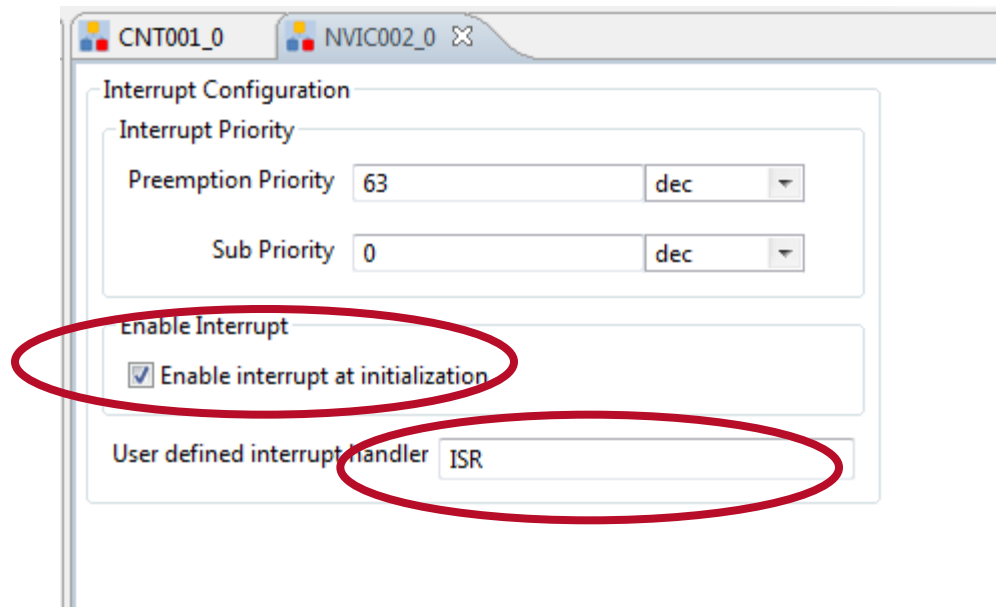
Add a Nested Vector Interrupt App - Solution

- Select the NVIC002 app which allows to configure an interrupt node
- Add this app to the project



Configure Interrupt Node

- Open the UIEditor of the added NVIC002 App
- Check „Enable interrupt at initialization“
- Type a name for the User defined interrupt handler
 - Note that this is the C function name used in the code



Signal Connection

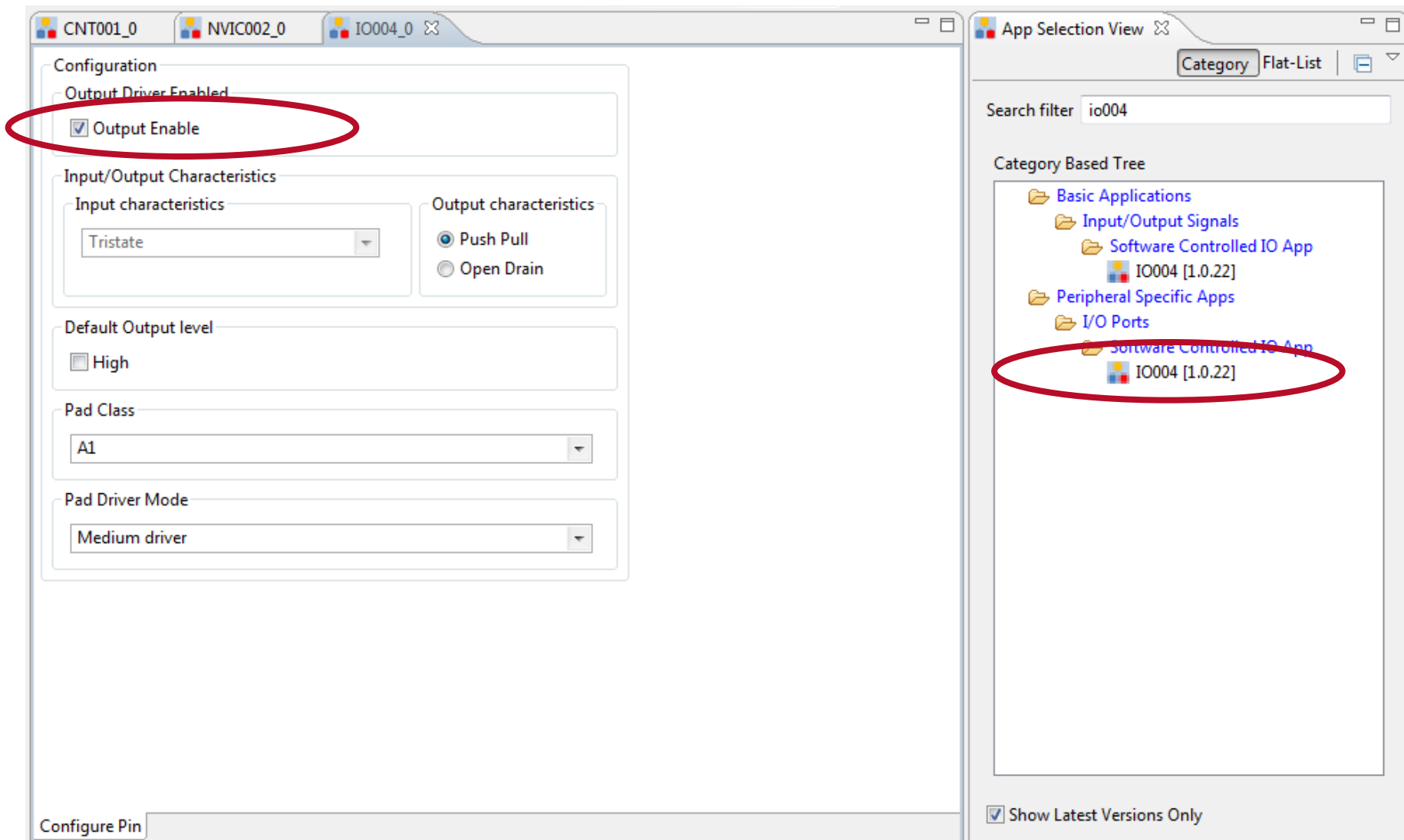
- Select the signal „Event Count Match Interrupt“
- Route the signal to NVIC002/0
- Click „Solve and Save“ and „Close“

Signal Connection

Filter: ALL

App	Signal	Connect To	App	Signal
CCU4GLOBAL/0	Not Selected	----	Not Selected	Not Selected
CLK001/0	Not Selected	----	Not Selected	Not Selected
CNT001/0	Not Selected	----	Not Selected	Not Selected
	Event Count Match Interrupt	----	NVIC002/0	Interrupt Node
	Not Selected	----	Not Selected	Not Selected
IO004/0	Not Selected	----	Not Selected	Not Selected
NVIC002/0	Not Selected	----	Not Selected	Not Selected
PWMSP001/0	PWM Status	----	CNT001/0	Input
	Not Selected	----	Not Selected	Not Selected
RESET001/0	Not Selected	----	Not Selected	Not Selected

Add and configure IO App



The screenshot displays two windows from the Infineon configuration tool. The left window, titled 'IO004_0', shows the configuration for the IO004_0 pin. The 'Output Driver Enabled' section is circled in red, with the 'Output Enable' checkbox checked. The 'Input/Output Characteristics' section shows 'Input characteristics' set to 'Tristate' and 'Output characteristics' set to 'Push Pull'. The 'Default Output level' is set to 'High'. The 'Pad Class' is set to 'A1' and the 'Pad Driver Mode' is set to 'Medium driver'. The right window, titled 'App Selection View', shows a search filter 'io004' and a category-based tree. The 'Software Controlled IO App' is circled in red, with the 'IO004 [1.0.22]' version selected. The 'Show Latest Versions Only' checkbox is checked at the bottom.

Configuration Window (IO004_0):

- Configuration:**
 - Output Driver Enabled: ☒ Output Enable
- Input/Output Characteristics:**
 - Input characteristics: Tristate
 - Output characteristics: ☒ Push Pull, ☐ Open Drain
- Default Output level:** ☒ High
- Pad Class:** A1
- Pad Driver Mode:** Medium driver

App Selection View:

- Search filter: io004
- Category Based Tree:
 - Basic Applications
 - Input/Output Signals
 - Software Controlled IO App
 - IO004 [1.0.22]
 - Peripheral Specific Apps
 - I/O Ports
 - Software Controlled IO App
 - IO004 [1.0.22]

☒ Show Latest Versions Only

Assign the P1.0 - Solution

Manual Pin Assignment

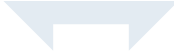
Filter: ALL

	App	Resource	Port-Pin/Pin Number
+	PWMSP001/0	pin_directoutput	P1.1 / #78
		Not Selected	Not Selected
+	IO004/0	pin	Not Selected
			Not Selected
			P0.0 / #2
			P0.1 / #1
			P0.2 / #100
			P0.3 / #99
			P0.4 / #98
			P0.5 / #97
			P0.6 / #96
			P0.7 / #89
			P0.8 / #88
			P0.9 / #4
			P0.10 / #3
			P0.11 / #95
			P0.12 / #94
			P1.0 / #79
			P1.2 / #77
			P1.3 / #76
			P1.4 / #75
			P1.5 / #74
			P1.6 / #83
			P1.7 / #82

Include the Interrupt Service Routine

- The interrupt service routine has to be written by the user because DAVE has no access to the user code parts of the project workspace.
- Therefore one has to write this:

```
void ISR(void)
{
    IO004_TogglePin(IO004_Handle0);
    CNT001_ResetCounter((CNT001_HandleType*)&CNT001_Handle0);
}
```



- Use App Help Functionality (see next slide)
- Make sure that the name of the function matches the one that is configured in the NVIC-App!

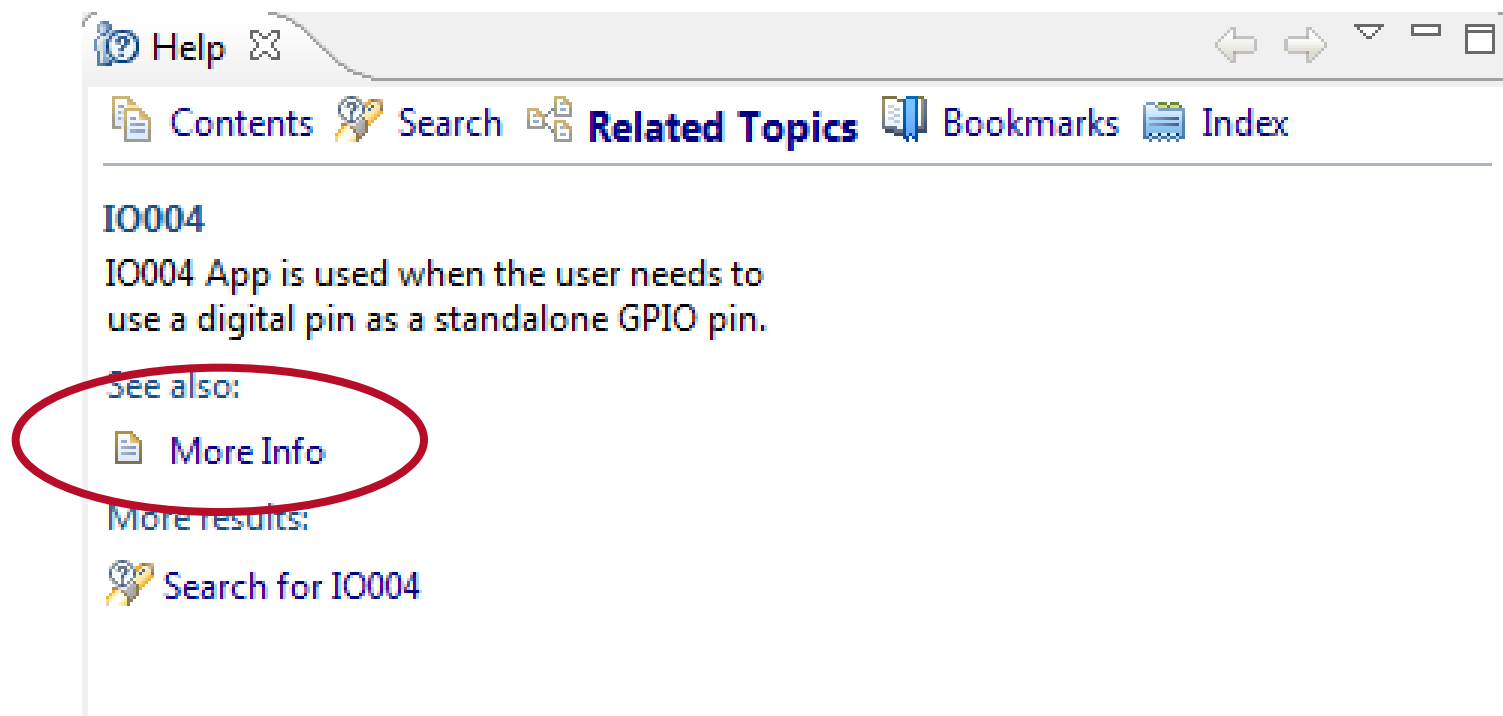
How to use App HELP function

- Each App has a dedicated help file which includes
 - Description
 - Parameter description
 - Variables
 - API description

- Press „F1“ on your keyboard and left-click the IO004 App in your project view

The Help

■ Click „More Info“



Find the function you search for

- Select „API Documentation“

Modules

Copyright and Licensing Information
Introduction
Overview
File Structure
App Configuration Documentation
App Public structures
API Documentation
Release History

v1.0.16 Generated on Mon Apr

- Select „IO004_TogglePin“; copy & paste into main.c

Example:

```
#include <DAVE3.h>

int main(void)
{
    DAVE_Init(); // IO004_Init() is called within DAVE_Init()
    IO004_TogglePin(IO004_Handle0);
    return 0;
}
```

Main.c

```
// global variable to be used for debugger demo
PWMSP001_TimerRegsType TimerVal;

// global variable to be used for debugger demo
uint32_t CountVal;

-----

while(1)
{
    PWMSP001_GetTimerRegsVal(&PWMSP001_Handle0, &TimerVal); // writing to global variable
    CNT001_GetEvtCountValue(&CNT001_Handle0, &CountVal);      // writing to global variable
}

-----

// ISR Handler for Count match interrupt to toggle the LED and reset the counter
void ISR (void){
    IO004_TogglePin(IO004_Handle0);
    CNT001_ResetCounter(&CNT001_Handle0);
}
```



Main.c

Compile

Task:

Save everything

Generate Code

Build

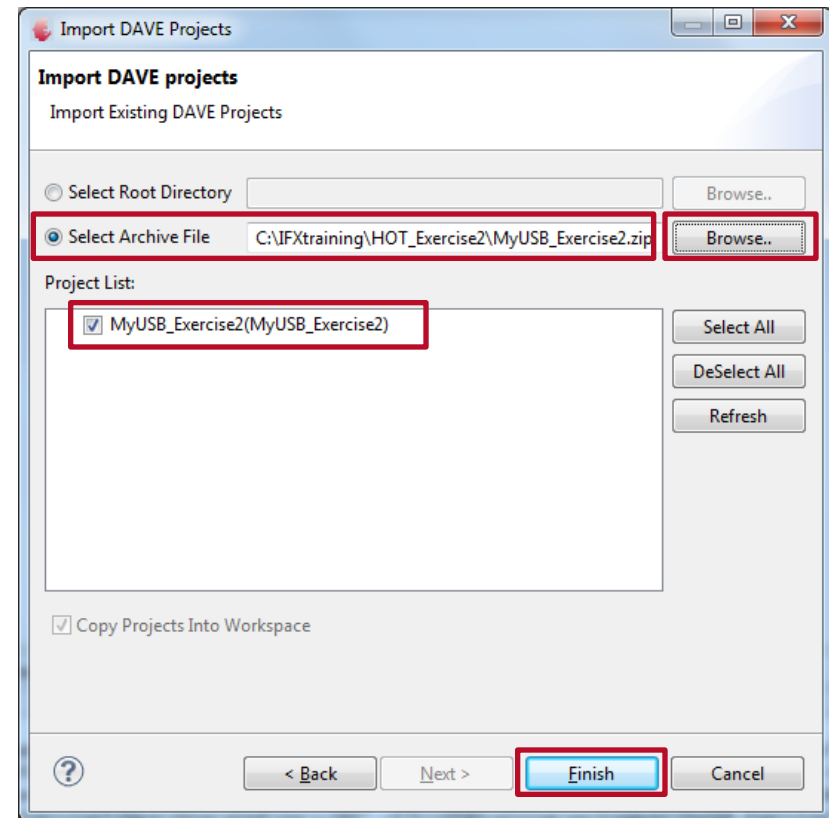
Start Debug

Pause the program in the
interrupt service routine

DAVE™ Project Management

■ **Import** a project (RelaxKit_XMC_DevDay):

- File > Import > Infineon > DAVE Project
- Click "Next >"
- Select "Select Archive File"
- Browse to
 `..\RelaxKit_XMC_DevDay.zip`
- Check the project
 Project RelaxKit_XMC_DevDay
- Click "Finish"



ENERGY EFFICIENCY MOBILITY SECURITY

Innovative semiconductor solutions for energy efficiency, mobility and security.

