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## **SPI on SK-91F467-FlexRay**

This application note describes the necessary hardware modification at SK-91F467-FLEXRAY V1.1 to enable the SPI(Serial Peripheral Interface) communication mode between MB91F467D and MB88121B (FlexRay Communication Controller).

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## **1 Introduction**

This application note describes the necessary hardware modification at SK-91F467-FLEXRAY V1.1 to enable the SPI(Serial Peripheral Interface) communication mode between MB91F467D and MB88121B (FlexRay Communication Controller). The modification on PCB of the SK-91F467-FLEXRAY starter kit is necessary to free one data line (D19) of the external bus interface. Otherwise the external SRAM on the starter kit cannot be used.

## **2 General description**

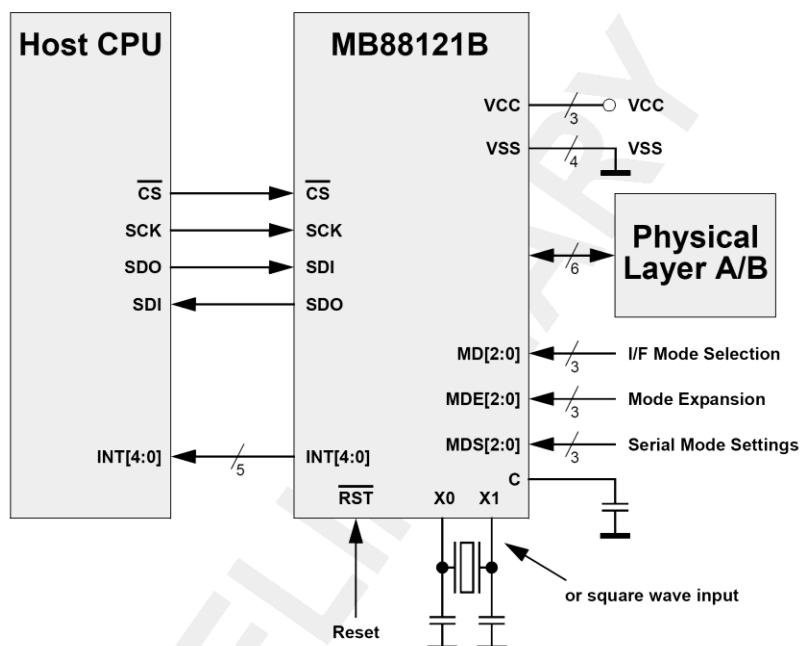
This chapter gives an overview of the modification.

### **2.1 Pin assignment of CC in SPI mode**

The evaluation board SK-91F467-FLEXRAY provides three communication modes between MCU and CC (communication controller). They are 16bit multiplexed parallel mode, 16bit non-multiplexed parallel mode and SPI serial mode.

The communication controller MB88121B has different pin assignment for each mode. For SPI mode the communication block diagram is shown below.

Figure 1. SPI communication mode



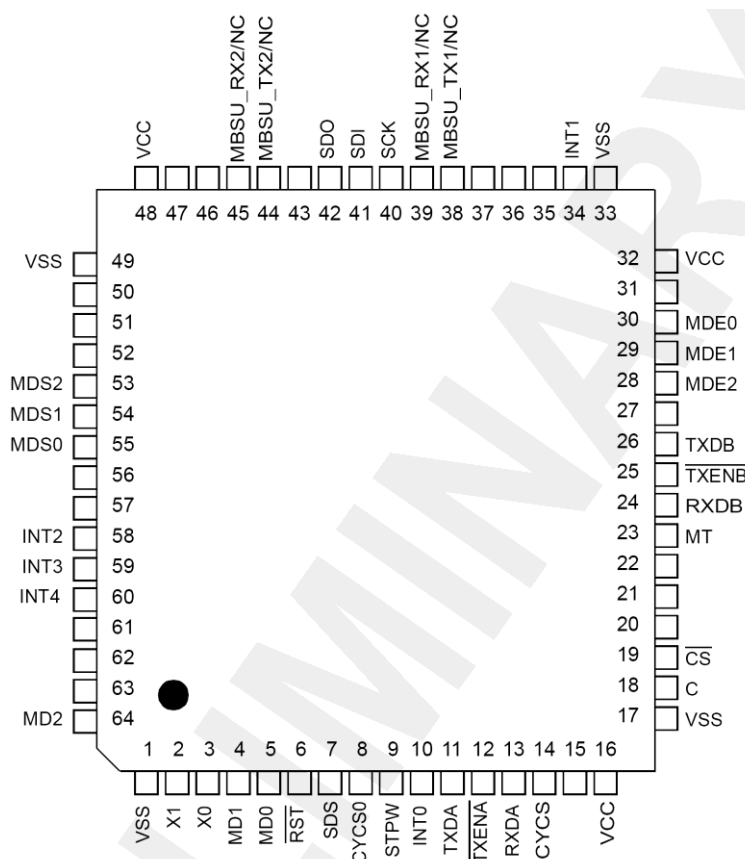
The pin usage of the communication controller is summarized in the following table.

Table 1. CC pin usage in SPI mode

Pin No	Pin name	Description
1,17,33,49	VSS	Ground (0 V)
16,32,48	VCC	Power supply
2,3	X1,X0	Oscillation input/output pin
4,5	MD1,MD0	Mode selection
6	$\overline{RST}$	Reset input
7	SDS	Start of dynamic segment (debug pin)
8	CYCS0	Cycle 0 start output (debug pin)
9	STPWT	Stop watch trigger input
10	INT0	Interrupt 0 output
11	TXDA	Data output of channel A
12	$\overline{TXENA}$	Enable output of channel A
13	RXDA	Data input of channel A
14	CYCS	Cycle start output (debug pin)
18	C	Power supply stabilization capacitor pin
19	$\overline{CS}$	Chip select input
23	MT	Macrotick start output (debug pin)
24	RXDB	Data input of channel B

Pin No	Pin name	Description
25	$\overline{TXENB}$	Enable output of channel B
26	TXDB	Data output of channel B
28,29,30	MDE2,MDE1,MDE0	Extended mode selection
34	INT1	Interrupt 1 output
38	MBSU_TX1	Debug pin
39	MBSU_RX1	Debug pin
40	SCK	Serial clock input
41	SDI	Serial data input
42	SDO	Serial data output
44	MBSU_TX2	Debug pin
45	MBSU_RX2	Debug pin
53,54,55	MDS2,MDS1,MDS0	Specific settings for SPI mode
58,59,60	INT2,INT3,INT4	Interrupt 2,3,4 output
64	MD2	Mode selection

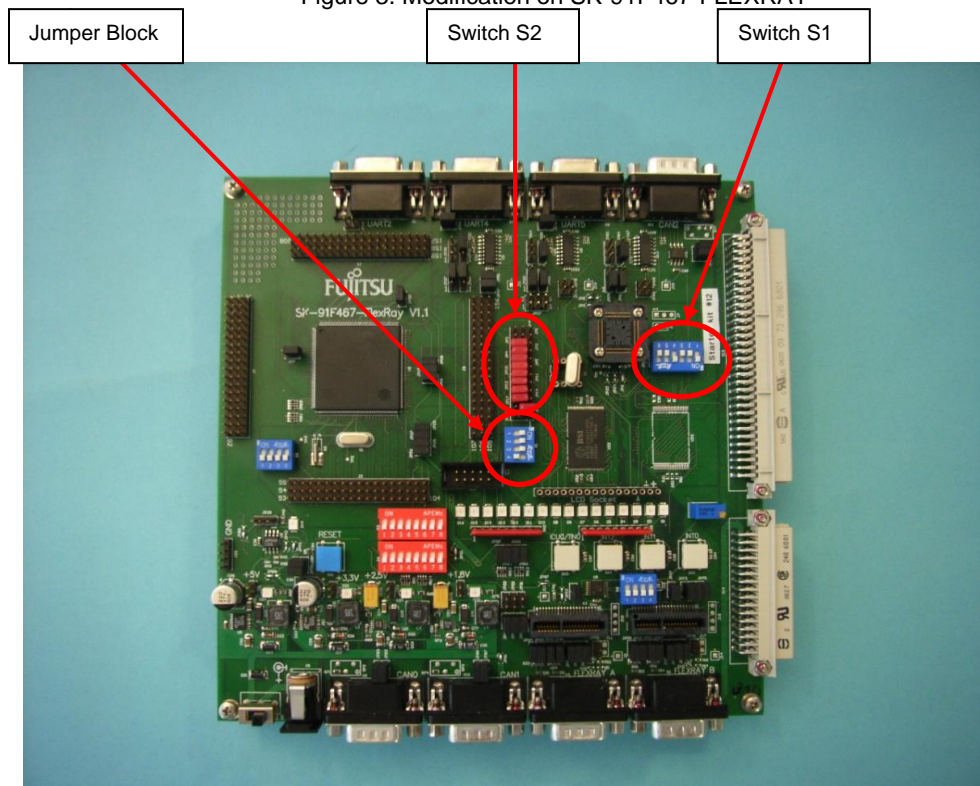
Figure 2. CC pin overview in SPI mode



## 2.2 Modification Summary

By default the evaluation board SK-91F467-FLEXRAY V1.1 is configured to realize 16bit non-multiplexed communication mode. To use the SPI mode **jumper block**, **switch S2** and **S1** need to be modified.

Figure 3. Modification on SK-91F467-FLEXRAY



The necessary modification is summarized in the following table. For details please see the next chapter.

Table 2. Modification Summary

Jumper	Setting
JP1	OPEN
JP2	OPEN
JP3	2-3
JP4	2-3
JP5	2-3
JP10	2-3
JP11	2-3
JP12	2-3
JP14	2-3
JP17	2-3
JP19	1-2
JP20	OPEN

Switch	Setting
S2-1	ON
S2-2	OFF
S2-3	OFF
S2-4	ON
S2-5	OFF
S2-6	OFF
S1	Application-specific settings
CC Pin No	setting
60	Manually remove its connection to SRAM

Figure 4. Modification details

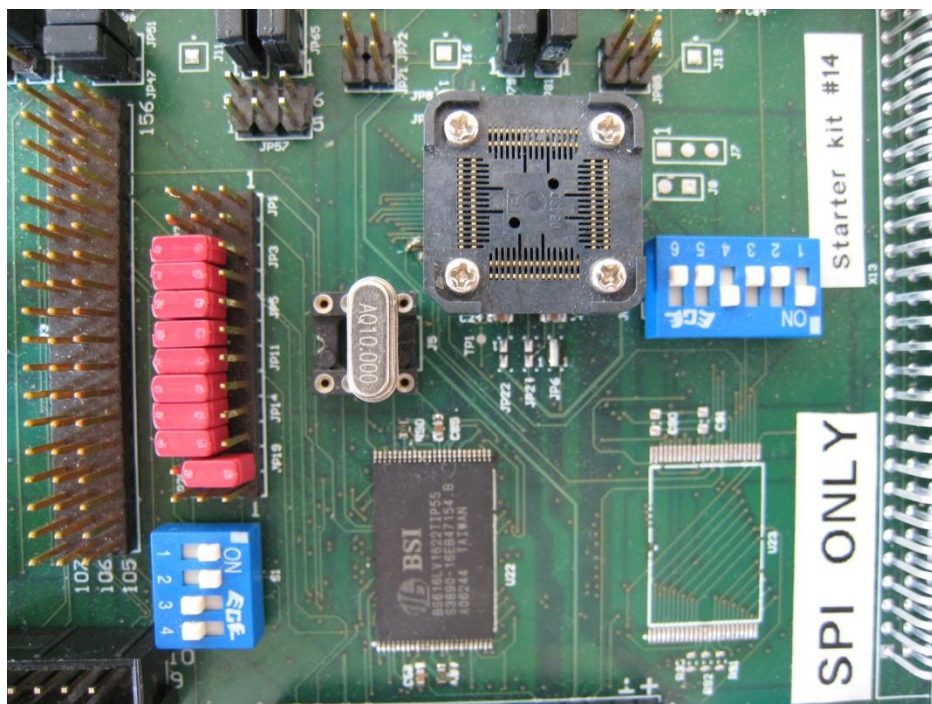
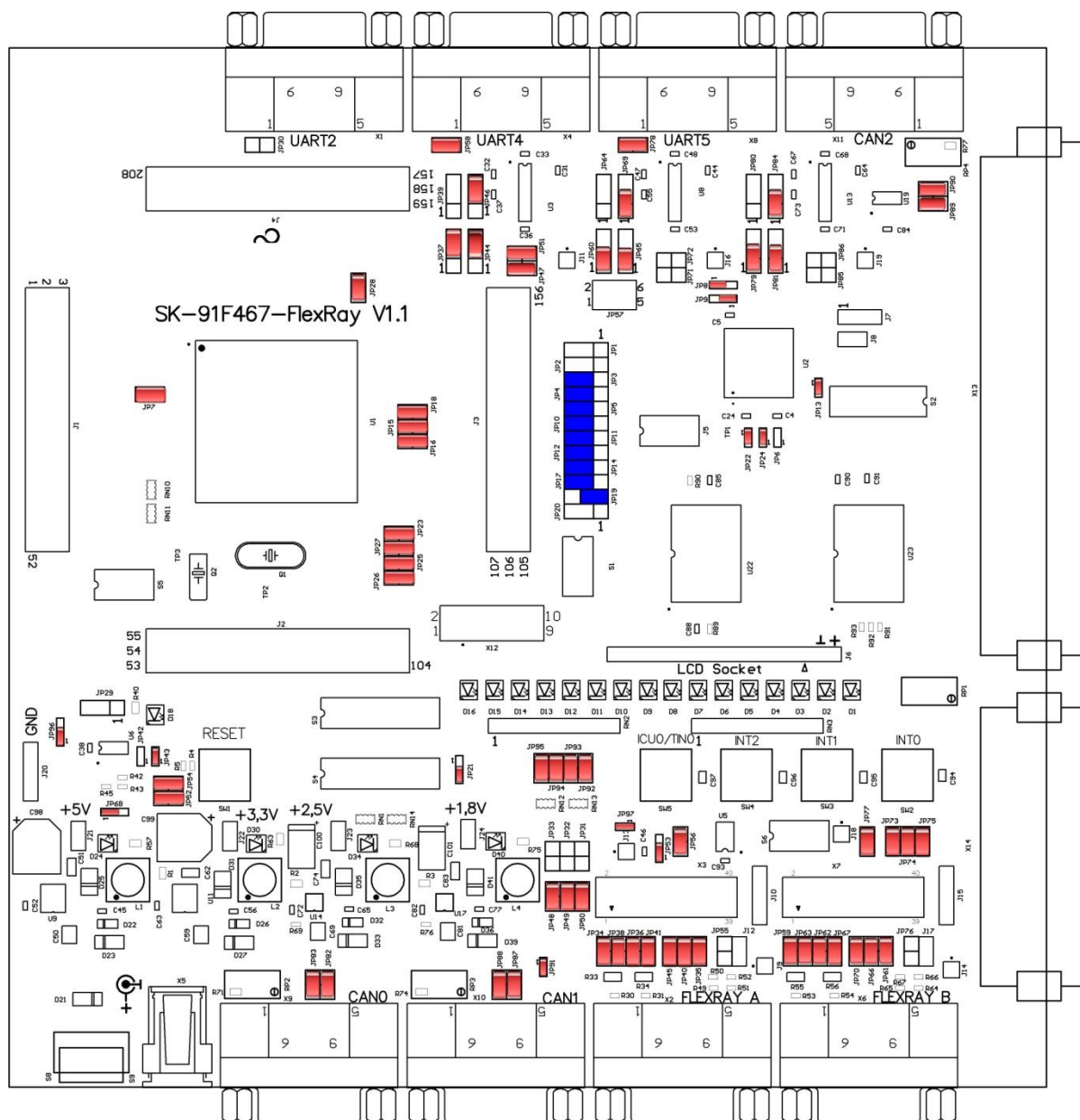


Figure 5. Overview of the Jumper Block Modification in SPI Mode



### 3 Detailed description

This chapter explains each individual modification.

#### 3.1 Switch S2

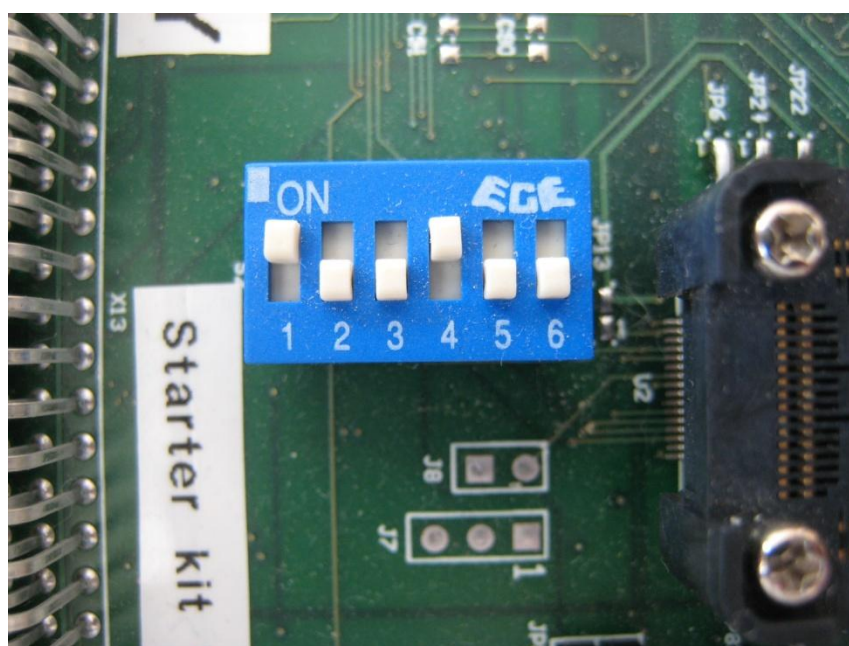
Switch S2 specifies the operation mode of the communication controller. Its configuration in SPI mode is fixed for the evaluation board SK-91F467-FLEXRAY.



Table 3. Switch S2 settings

Switch	Setting	Function	Description
S2-1	ON	MD0 = 0	Serial communication mode selected
S2-2	OFF	MD1 = 1	
S2-3	OFF	MD2 = 1	
S2-4	ON	MDE0 = 0	SPI interface
S2-5	OFF	MDE1 = 1	10MHz external clock
S2-6	OFF	MDE2 = 1	

Figure 6. Switch S2 overview



### 3.2 Switch S1 and Jumper JP10, JP11, JP12

Switch S1 is responsible for the application specific settings in SPI mode. All functions are listed in the following table. An example of switch S1-3 for the bit direction is also provided. User should set the switch according to the application.

Table 4. Switch S1 settings

Switch	Setting	Function	Description
S1-1	ON	MDS0=0	Sample data at odd edges of SCK
	OFF	MDS0=1	Sample data at even edges of SCK
S1-2	ON	MDS1=0	SCK is active-high
	OFF	MDS1=1	SCK is active-low
S1-3	ON	MDS2=0	Most significant bit first (MSB)
	OFF	MDS2=1	Least significant bit first (LSB)
S1-4	ON	\	Not used
	OFF	\	Not used



Figure 7. Least Significant Bit First By Data Transfer

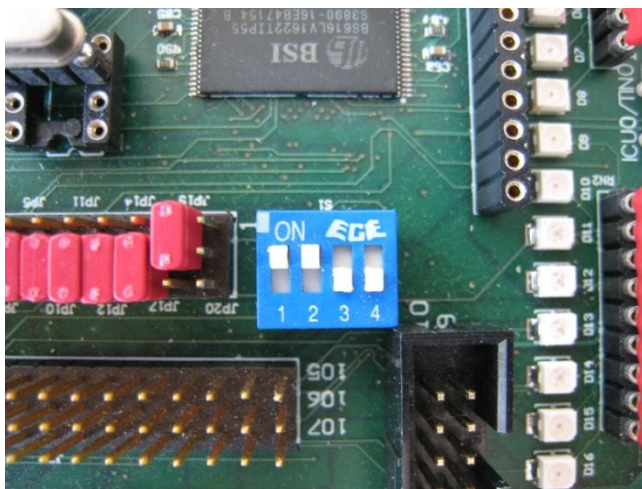
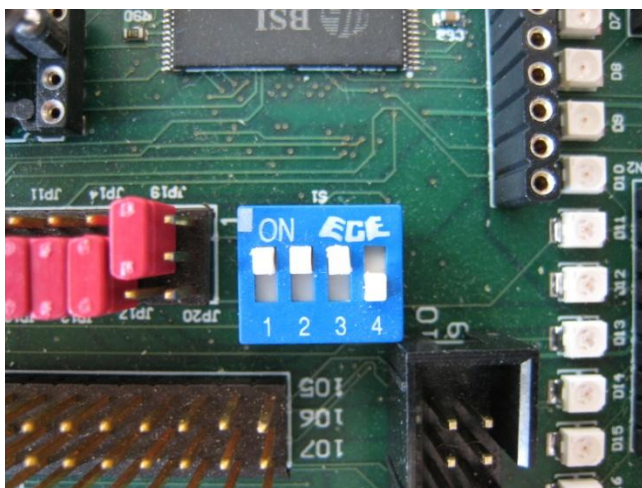


Figure 8. Most Significant Bit First By Data Transfer



By default jumper JP10, JP11 and JP12 connect pin1 and pin2 for parallel communication mode between MCU and CC. Therefore switch S1 is separated from CC MDS[2:0] pins. To use the switch S1 in SPI mode it is necessary to connect pin2 and pin3 of the jumpers.

Figure 9. Pin Jumper With Label '1' For The Pin One On The PCB

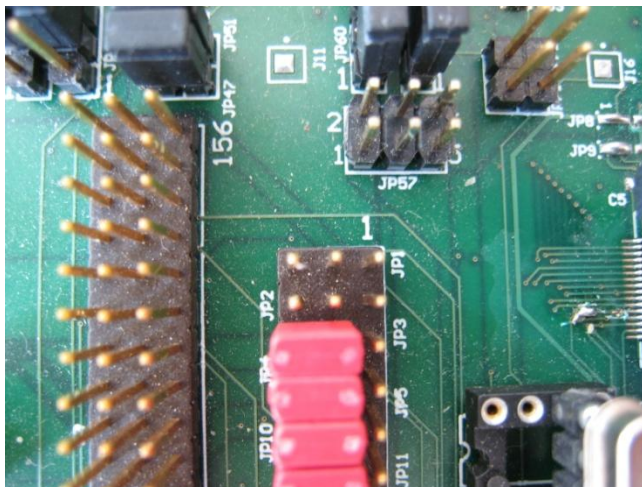
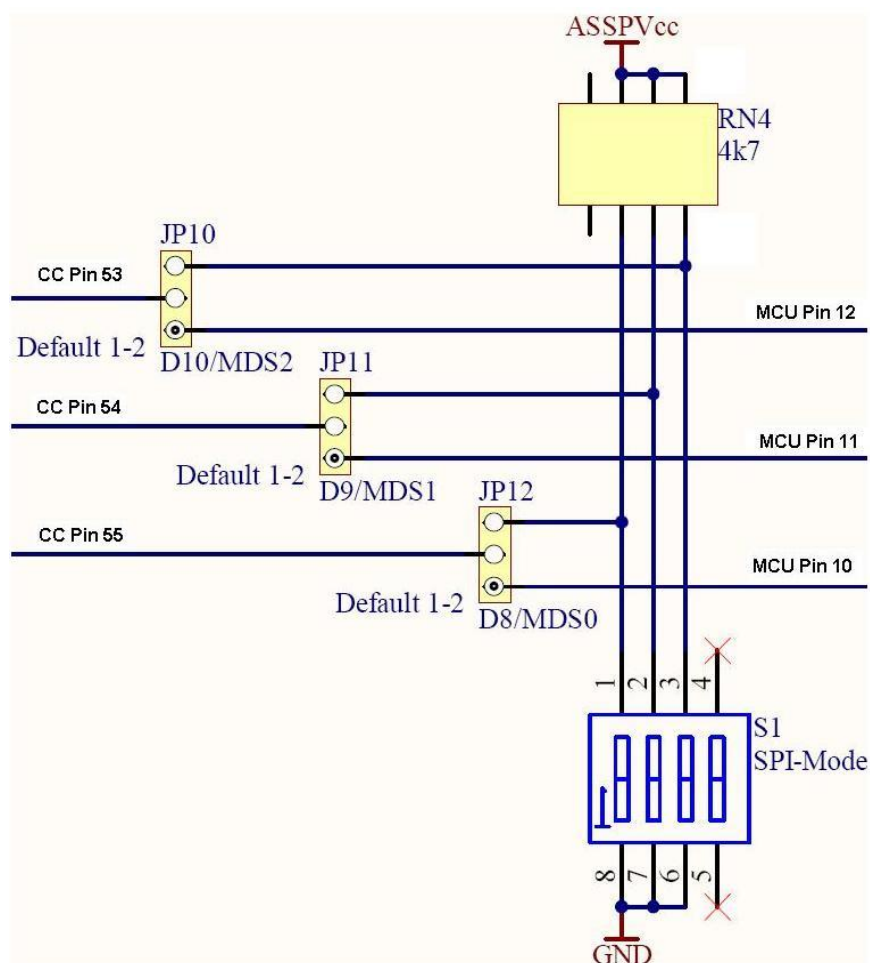


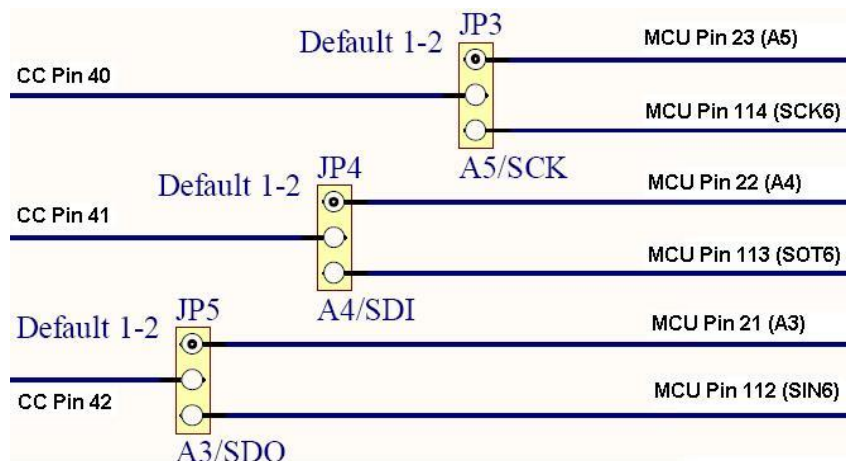
Figure 10. Schematic view of S1, JP10, JP11 and JP12



### 3.3 Jumper JP3, JP4, JP5

CC pin 40, 41 and 42 have different function for parallel mode and SPI mode. In SPI mode they are the clock and data lines. Jumper JP3, JP4 and JP5 connect pin2 and pin3 to select SPI function.

Figure 11. Schematic View Of Jumper 3,4,5



### 3.4 Jumper JP1, JP2, JP14, JP17, JP20

The communication controller has five interrupt outputs INT[4:0]. Among them INT0 and INT1 have fixed connection to MCU pin87 and pin88. Other interrupts however have different pin assignment for parallel mode and SPI mode. Therefore jumpers should be configured properly.

Table 5. Jumpers for CC interrupt output in SPI mode

Jumper	Settings for SPI mode	Description
JP1	OPEN	CC pin35 is unused in SPI mode
JP2	OPEN	CC pin36 is unused in SPI mode
JP14	2-3	CC pin58 is INT2 in SPI mode connected to MCU pin 89 and
JP17	2-3	CC pin59 is INT3 in SPI mode connected to MCU pin 90 and
JP20	OPEN	CC pin22 is unused in SPI mode

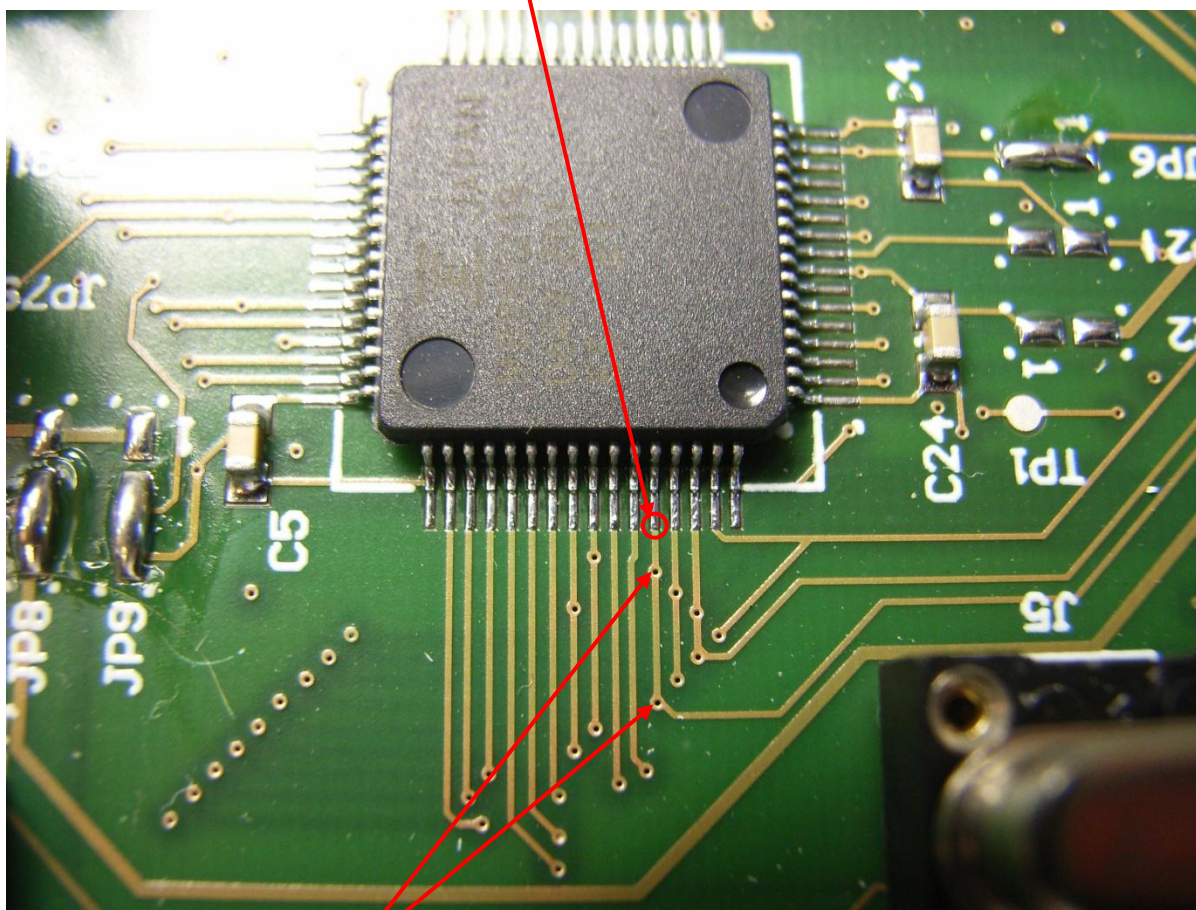
Modification for interrupt INT4 is special and will be introduced in the next chapter.

### 3.5 CC Pin 60 (INT4)

In SPI mode CC pin60 is assigned to interrupt output INT4 and should be connected to MCU pin91. However in the current PCB version (v1.1) of the evaluation board there is no dedicated jumper for this pin. Instead CC pin60 has a fixed connection to the MCU pin5 and SRAM pin10 (with label U22 on PCB). This connection prevents the monitor debugger in SPI mode, so that the evaluation board is only suitable for STANDALONE mode in SOFTUNE workbench.

To overcome this defect user should manually cut off this connection between CC pin60 and SRAM.

Figure 12. CC Pin60 before Modification for SPI Mode



It is noticed that there are two **via** in connection with CC pin60. In order to cut off the connection the opening must be located between the CC pin and the first via. Please see the following figures.



Figure 13. In Modification

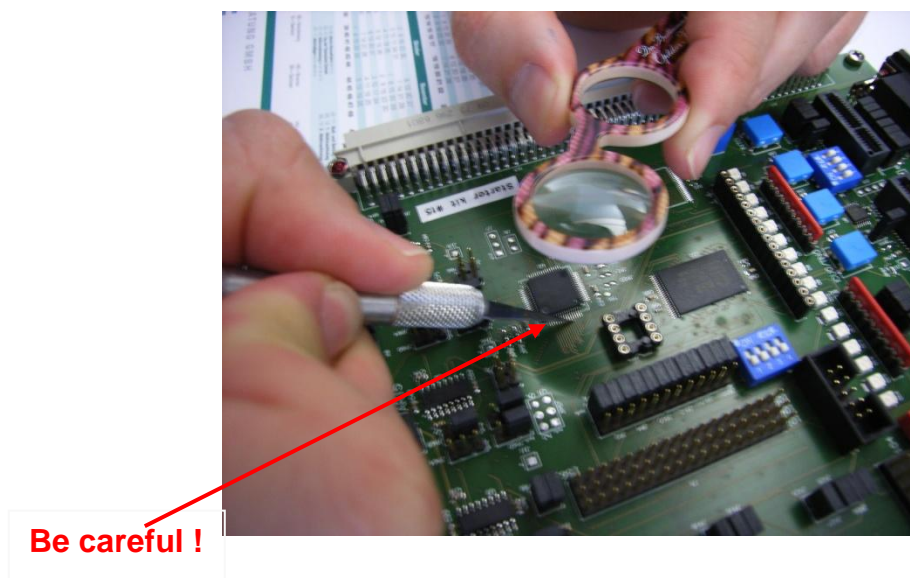
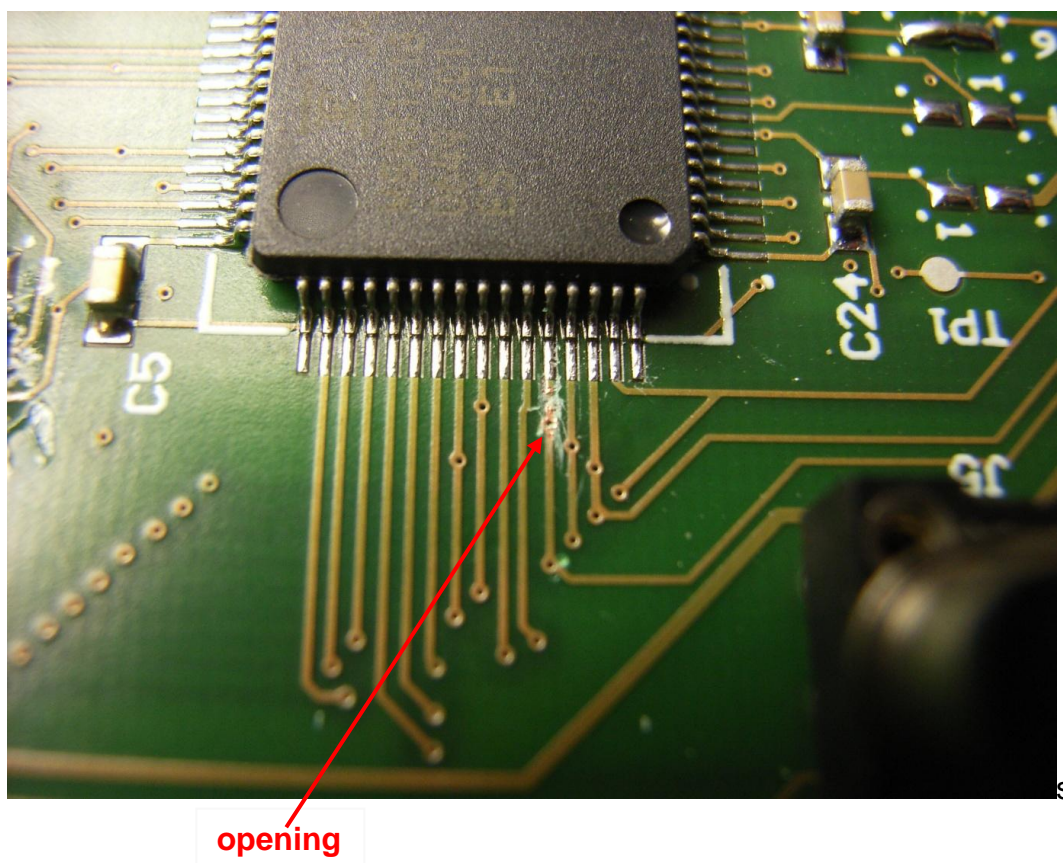


Figure 14. CC Pin60 after Modification







## 4 Document History

Document Title: AN205154 - SPI on SK-91F467-FlexRay

Document Number: 002-05154

Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	-	NOFL	08/31/2007	Initial Release
			02/19/2008	Description in chapter introduction added
*A	5082278	NOFL	01/12/2016	Migrated Spansion Application Note from MCU-AN-300014-E-V11 to Cypress format
*B	5844614	AESATP12	08/30/2017	Updated logo and copyright.

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