Performing ETM and ITM trace on PSOC™ Control C3 and PSOC™ Edge E8 MCUs

About this document

Scope and purpose

This application note introduces the trace features of the PSOC™ Control C3 and PSOC™ Edge E8 MCUs, helping you get started with performing instruction (ETM) and instrumentation (ITM) tracing on these devices. This application note also guides you to explore more features of trace and other resources available online to accelerate your learning. If you are new to the ModusToolbox™ software environment and these devices, see:

- AN238329 – Getting started with PSOC™ Control C3 MCU on ModusToolbox™ software
- AN235935 – Getting started with PSOC™ Edge E8 MCU on ModusToolbox™ software

Intended audience

This application note is intended for advanced engineers who want to use the trace capabilities of the PSOC™ Control C3 and PSOC™ Edge E8 MCUs.

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1 Introduction

This application note discusses the PSOC™ Control C3 and PSOC™ Edge E8 MCU trace architecture and the associated development tools with new features and limitations. It also covers various general aspects of Arm® trace architecture to help you understand and perform trace on PSOC™ Control C3 and PSOC™ Edge E8 MCUs to its full potential.

Although this application note focuses on demonstrating the ETM and ITM trace, third-party tools generally offer a wide range of additional trace features, including function profiling, data watchpoints, interrupt logging, and code coverage. Refer to the respective third-party tool documentation to understand all the features they offer and learn how to use them effectively for complex embedded application debugging and development.

1.1 Debug/trace features

Arm® CoreSight is a suite of tools for debugging and tracing software on Arm®-based devices. Debug capabilities let you observe or modify the state of system components, while trace capabilities continuously collect system information for later offline analysis.

Debug features include:

- Run Control of the processor allows you to start and stop programs.
- Single Step one source or assembler line.
- Set breakpoints while the processor is running.
- Read/write memory contents and peripheral registers on-the-fly.

Trace features include:

- Embedded Trace Macrocell (ETM)
- Instruction Trace Macrocell (ITM)
- Data Watchpoint and Trace (DWT)

ARM® CoreSight tracing is the architecture-level mechanism that streams execution and event information from the CPU in real time for debugging and analysis. Because it’s built into the core (ETM/DWT/ITM with ETB/TPIU via SWO/4-Pin Trace Output), it works without halting the target and without altering program behavior.

The CoreSight features are available via JTAG and Serial Wire Debug interfaces.

Introduction

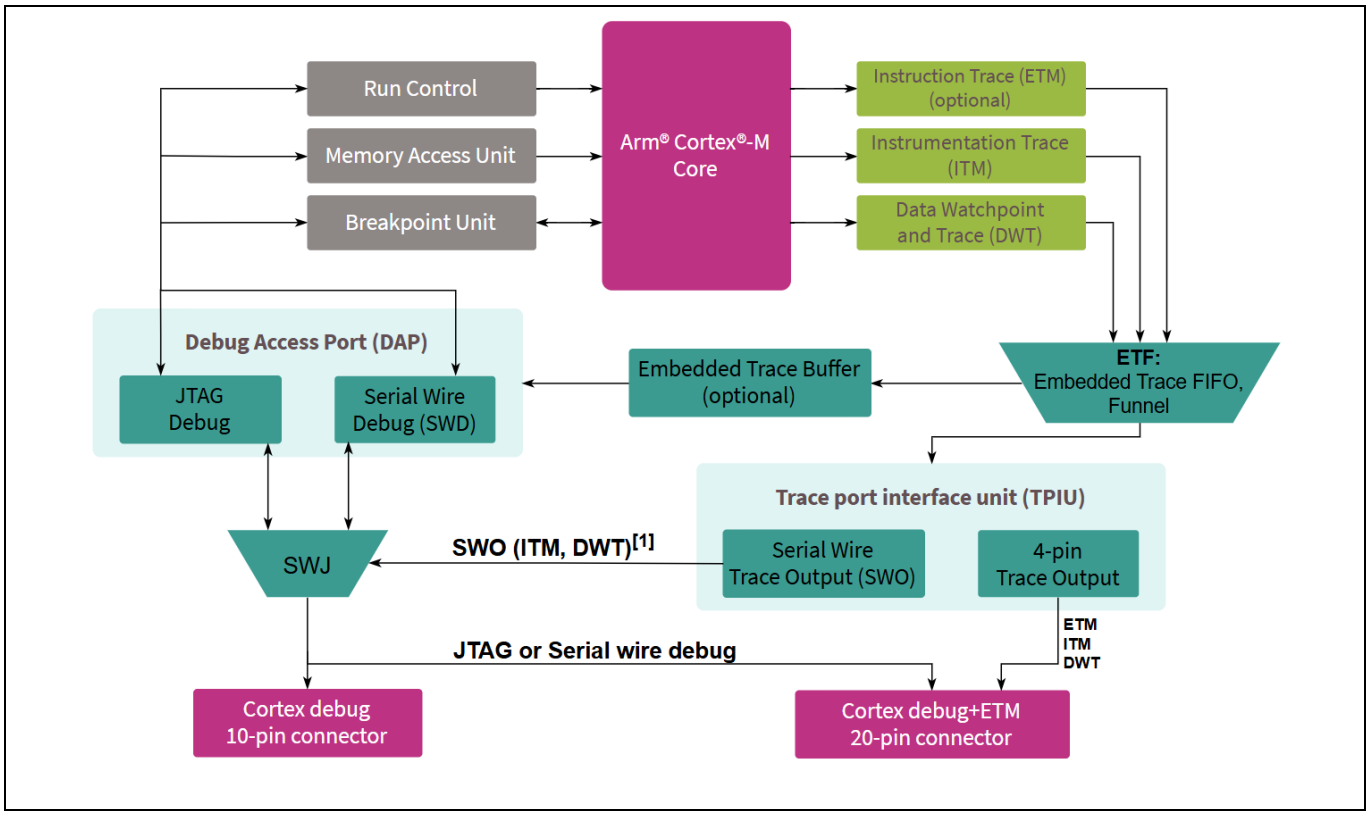

Figure 1 ARM® CoreSight Technology (Debug and Trace Support)

[1] The devices with Arm® CoreSight SoC-600 don't support SWO pin.

1.2 What are ETM and ITM tracing?

- **ETM (Embedded Trace Macrocell)** is one of the tracing types, that provides hardware program-flow trace. It records the actual instruction stream executed by the CPU (branches, exceptions, returns), allowing the debugger to reconstruct "where the core went" precisely, even across interrupts and context switches. ETM is ideal for runtime analysis, timing, software profiling, and code coverage.
- **ITM (Instrumentation Trace Macrocell)** is another of the tracing type, that provides software-generated trace. Your firmware writes small messages/events into ITM stimulus ports (0–31). These are timestamped and transported in the CoreSight trace stream, enabling non-intrusive printf, event logging, RTOS awareness, counters, and unit-test annotations. ITM also multiplexes DWT events (PC sampling, cycle counters, exceptions).

1.3 Benefits of ETM/ITM Tracing compared to breakpoints/logging

- **Non-intrusive:** trace runs continuously while the system executes at full speed — no instrumented UART, no blocking I/O, no periodic polling.
- **Deterministic:** ETM reconstructs the exact path, essential for intermittent faults, race conditions, and exception analysis.
- **Rich timing:** DWT (Data Watchpoint & Trace Unit) counters and timestamps correlate events; ITM can annotate domain-specific data in-line.
- **Profiling and coverage:** ETM enables function/line coverage and hot-path detection without recompiling with heavy instrumentation.

1.4 Key differences

- **ETM** is hardware program-flow trace — high bandwidth, requires 4-Pin Trace Output via 20-pin Cortex Debug+ETM connector or ETB. Offers code coverage and detailed execution history.
- **ITM** is software trace over stimulus ports — lighter weight, designed for application messages. On PSOC™ Control C3 and PSOC™ Edge E8 MCU devices, ITM must go over the 4-pin Trace Port (or ETB).
- **DWT** is hardware events and sampling — can be included in the ITM/TPIU stream for timing and counters.

1.5 Typical use cases

Usually, ETM is used when you need exact instruction-level history and timing. ITM is used when you need lightweight, application-driven messages, timestamped annotations from firmware-messages, state changes, and counters—merged with DWT events in the same trace stream.

The items below illustrate common scenarios.

- **ETM**: crash reconstruction, timing across interrupts/tasks, function execution profiling, code coverage certification.
- **ITM:** printf-style logging without UART, RTOS task switching visibility, counters, unit test progress markers, app-specific telemetry. Use ITM to emit.

1.6 Additional information

For deeper architectural flow and background, recommend to see Infineon AN235279 (Performing ETM and ITM trace on PSOC™ 6 MCU), where the same CoreSight principles apply to PSOC™ Control C3 and PSOC™ Edge E8. However, PSOC™ Control C3 and PSOC™ Edge E8 MCU have some differences from the PSOC™ 6 MCU that you need to keep in mind before starting to work with them.

1.6.1 No SWO pin

The devices with Arm® CoreSight SoC-600 like PSOC™ Control C3 and PSOC™ Edge E8 MCU do not have **the SWO pin**.

Therefore, ITM must be routed **via the 4-Pin Trace Output or ETB**. Any “SWV console” expecting SWO will not work.

1.6.2 Probe capability

To work with **ETM**, we always must use probes that have a Cortex Debug + ETM Connector (ULINKpro and I-jet Trace) to output ETM via **the 4-Pin Trace Output**.

Now, this rule also applies to **ITM**, because basic probes (ULINK2 and I-jet) only have the capability to output ITM + DWT via SWO pin, **which has been removed**, as mentioned earlier.

Introduction

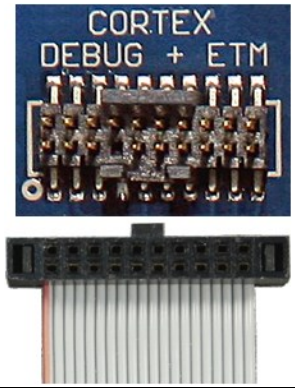

Figure 2 ARM® Cortex® Debug+ETM 20-pin connector

2 Getting started

Create a ModusToolbox™ application for a PSOC™ Control C3 or PSOC™ Edge E8 device that will be used with either IAR Embedded Workbench or Keil µVision. This application note will use a simple Empty_App application for demonstration purposes. For more information on creating applications targeting third-party IDEs, see:

- Keil µVision (MDK-ARM) – Keil µVision for ModusToolbox™ user guide
- IAR Embedded Workbench for ARM (EWARM) – IAR Embedded Workbench for ModusToolbox™ user guide

2.1 Software requirements

This application note uses the following software tools:

- ModusToolbox™ tools package: ModusToolbox™ tools package v3.6 is required to create or import a project for PSOC™ Control C3 and PSOC™ Edge E8 MCUs for use with IAR Embedded Workbench or Keil µVision.
- IAR Embedded Workbench for Arm®: IAR Embedded Workbench (tested with v9.70.1) and I-jet Trace can be used to perform tracing on PSOC™ Control C3 and PSOC™ Edge E8 MCUs.
- Keil µ Vision: Keil µVision (tested with v5.43) and ULINKpro can be used to perform tracing on PSOC™ Control C3 and PSOC™ Edge E8 MCUs.

2.2 Hardware requirements

Trace probes (external debugger)

This application note uses the following trace probes:

- **I-jet Trace for Arm® Cortex®-M:** This probe is used with IAR Embedded Workbench software tools. For more information, see I-jet Trace for Arm® Cortex® -M.
- **ULINKpro debug and trace unit:** This probe is used with Keil µVision software tools. For more information, see ULINKpro.

Development board

This application note uses the following kits:

- For PSOC™ Control C3 MCUs – PSOC™ Control C3M5 Evaluation Kit;
- For PSOC™ Edge E8 MCUs – PSOC™ Edge E84 Evaluation Kit

Typically, on evaluation kits, the trace pins are multiplexed with other peripherals due to limited I/Os.

For instance, for PSC3M5-EVK, open the KIT-PSC3M5-EVK schematics file and search for the term "trace". You will find a box with trace pins, as shown in Figure 3.

Getting started

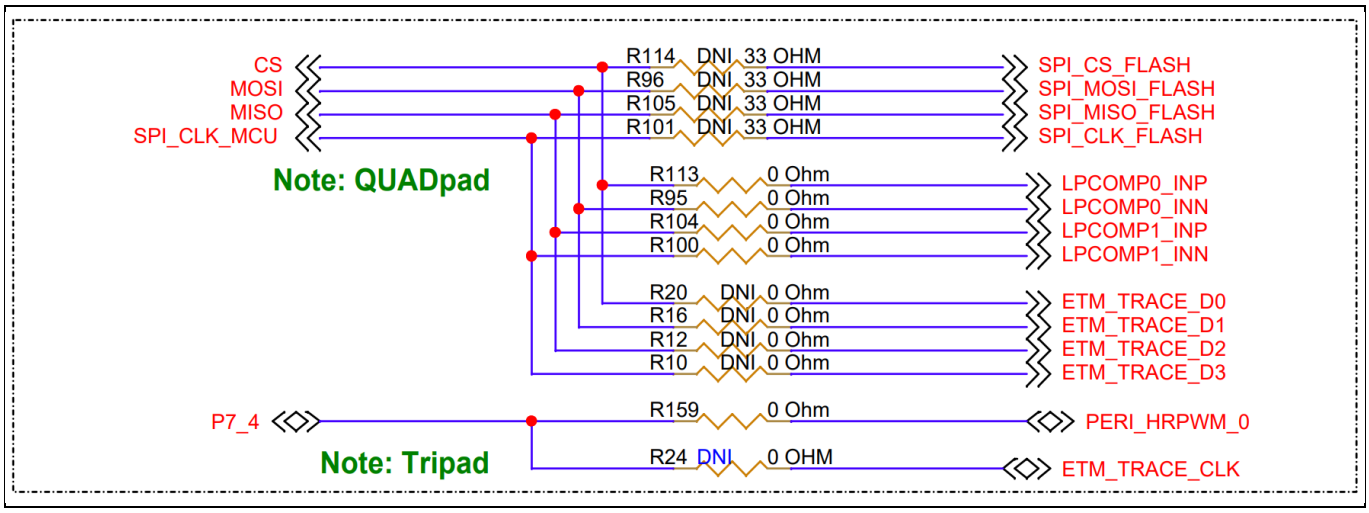

Figure 3 KIT-PSC3M5-EVK kit trace pin schematics

To expose the trace pins to the J14 ETM header, do the following:

1. Unload the resistances R113, R95, R104, R100, and R159.
2. Load 0 Ω resistances to R20, R16, R12, R12, and R24.
3. Solder the ETM header (20-pin FRC male connector) in place.

2.3 General Limitations and constraints

MCU security and access:

TrustZone/security policies can block trace/debug until unlocked (device option bytes, debug authentication). If trace stays empty, verify the device is in an unlocked debug state.

Note: For details about PSOC™ Control C3 and PSOC™ Edge E8 MCU security, refer to Application Notes:

- *AN240106 – Getting started with PSOC™ Control C3 security*
- *AN237849 – Getting started with PSOC™ Edge security*

2.4 Keil µVision limitations and constraints

2.4.1 ULINKpro

Debug interface:

- **Issue:** JTAG is **not supported** by ULINKpro.
- **Impact:**
  - JTAG connection and JTAG-chain workflows (boundary-scan, multi-device daisy chain) are not available.
  - Debug and trace must use SWD with the parallel trace port; any setup expecting JTAG will fail.
- **Resolution/Status:** N/A.
- **Recommended action:** Use SWD as the only supported interface.

Getting started

Tracing of Cortex-M55 (for PSOC™ Edge E8 MCU):

- **Issue:** ETM, DWT, and ITM are not supported for Cortex-M55 on **Keil µVision v5.43.0.**
- **Impact:**
  - Instruction trace (ETM), hardware events/timing (DWT), and ITM messages from Cortex-M55 cannot be captured/decoded.
  - Features relying on these (code coverage, profiling, timelines, ITM consoles) are unavailable on Cortex-M55 for PSOC Edge E8 with v5.43.0.
- **Resolution/Status:** N/A. Monitor Keil µVision release notes for future support changes.
- **Recommended action:** N/A.

2.5 IAR Embedded Workbench limitations and constraints

2.5.1 I-jet Trace

To use the I-jet Trace probe from IAR, it is recommended to use IAR EWARM version 9.60.3 or later, as this version provides full trace support for the PSOC™ Control C3 and PSOC™ Edge E8 MCU.

ITM Tracing:

- **Issue:** You cannot enable ITM via ETB or the 4-pin Trace output in **IAR Embedded Workbench through version 9.70.1.**
- **Impact:**
  - ITM output cannot be routed via ETB or the 4-pin parallel trace port; SWO is not available on these MCUs, so ITM logging is effectively not possible in the affected IAR versions.
  - Any workflows depending on ITM over ETB or 4-pin (runtime logs, profiling, visualization) will not function.
- **Resolution/Status:** N/A. Monitor IAR release notes for future support changes.
- **Recommended action:** Use alternative channels (UART, semihosting, RTT).

Performing trace on PSOC™ Control C3 and PSOC™ Edge E8 MCU

3 Performing trace on PSOC™ Control C3 and PSOC™ Edge E8 MCU

ETM and ITM are supported on the CM33 core for PSOC™ Control C3 MCUs and the CM33/CM55 for PSOC™ Edge E8 MCUs.

3.1 Keil µVision

3.1.1 Configure the debugger script and debugger

The debugger configures the TPIU port and necessary clocks before starting the trace. The CMSIS CAT1B and PSE8XXX packs have the necessary files to perform this configuration. The DBGCONF files in the DebugConfig folder, located under the project directory, contain the TPIU port selection information and clock trace clock prescaler option.

3.1.2 Configure the debugger script with ULINKpro Cortex®

To override the default values in the DBGCONF file, do the following:

1. In Keil µVision, select **File > Open**.
2. Navigate to the DebugConfig folder in the Empty App project directory, select the DBGCONF file, and click **Open**.

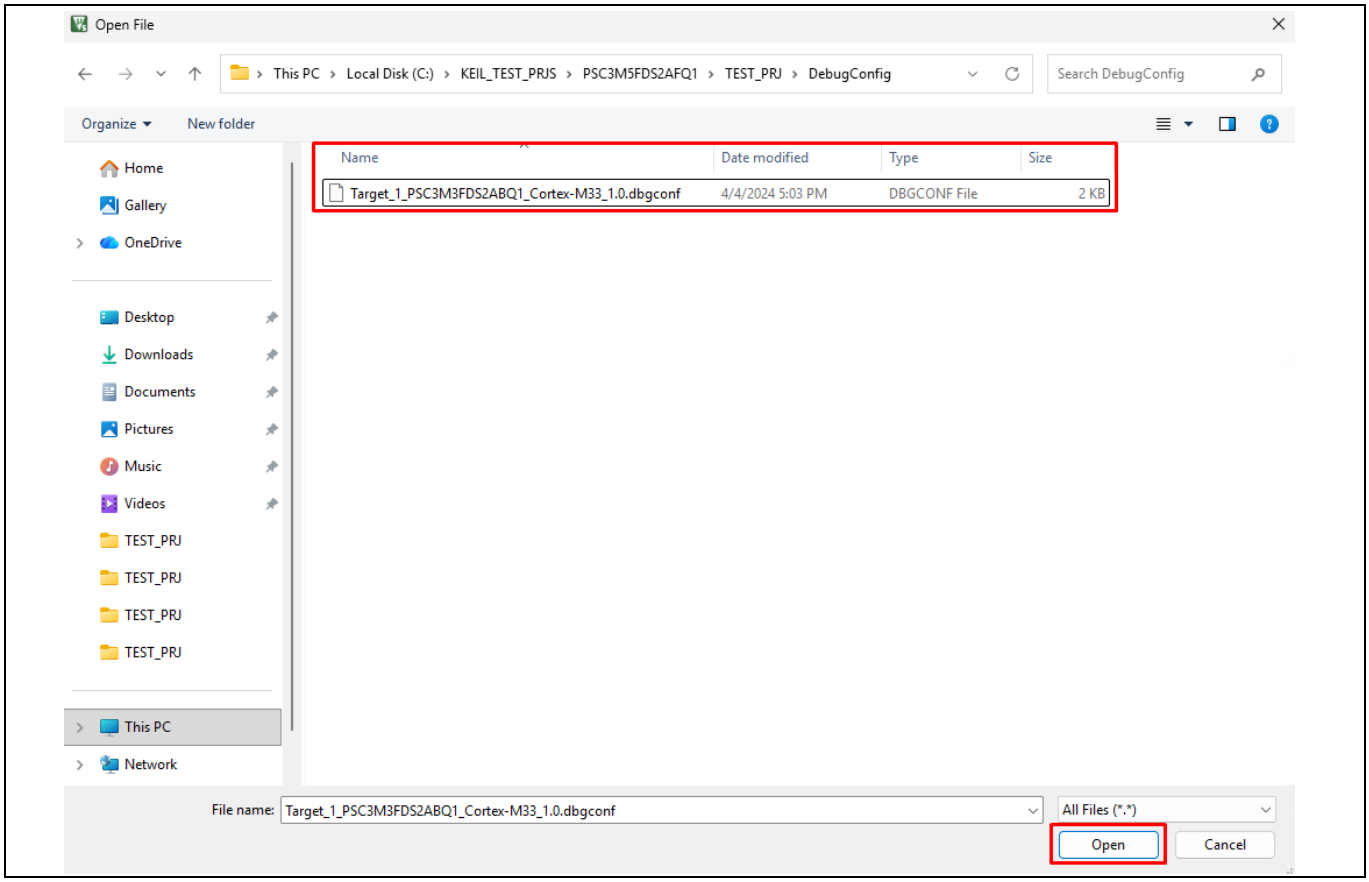

Figure 4 DBGCONF file for PSOC™ Control C3 project.

Performing trace on PSOC™ Control C3 and PSOC™ Edge E8 MCU

3. In the editor that opens with the file content, select **Configuration Wizard** at the bottom of the editor.

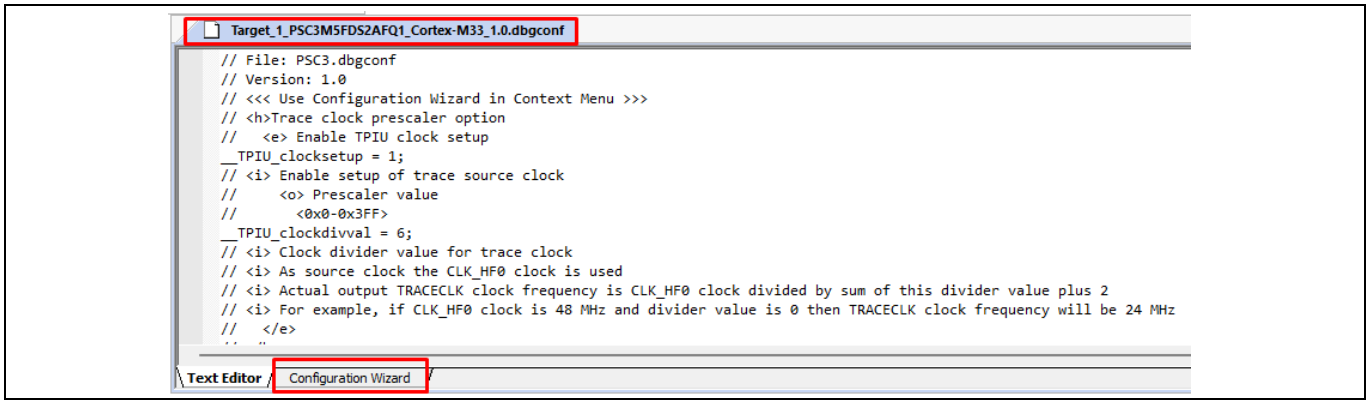

Figure 5 Opening the DBGCONF file in Configuration Wizard

4. Select **Trace Pin Setup > TPIU Pin Location > Pin Location 1** from the drop-down list. Details about the drop-down options are provided at the end of the editor.

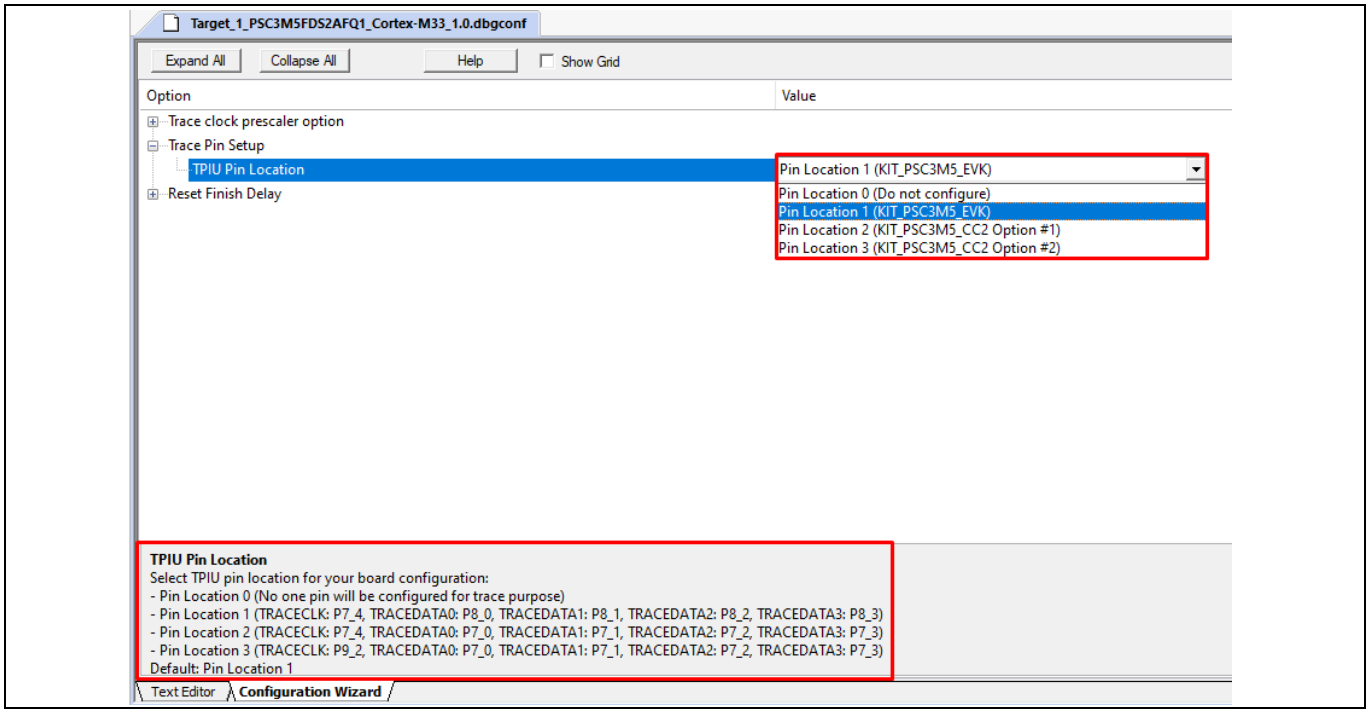

Figure 6 Select the TPIU Pin Location

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5. Enable the **TPIU clock setup** using the check box and set a **prescaler value** if you do not want to use the default. Once the setup is complete, save and close the file.

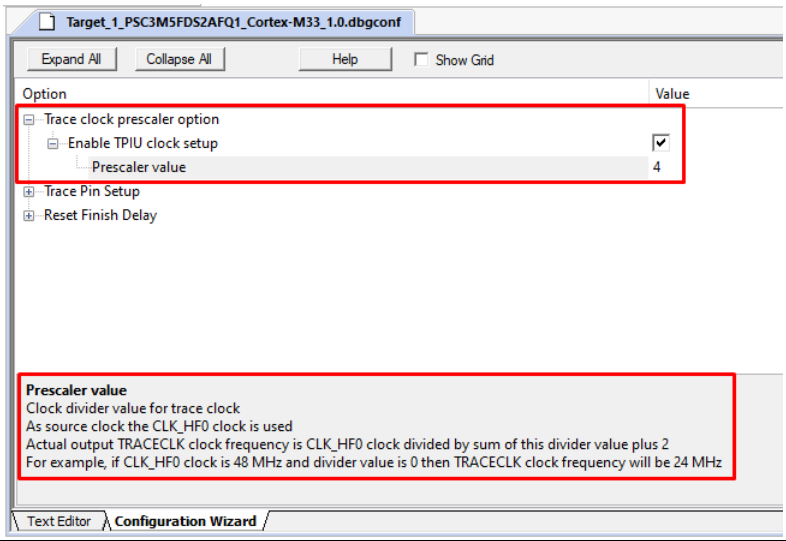

Figure 7 Enable the TPIU clock with prescaler value

To select and configure the debugger in µVision, do the following:

1. Open the project options.
2. Select the **Debug** tab and choose **ULINK Pro ARMv8-M Debugger** from the drop-down menu.
3. Click the **Settings** button next to it.

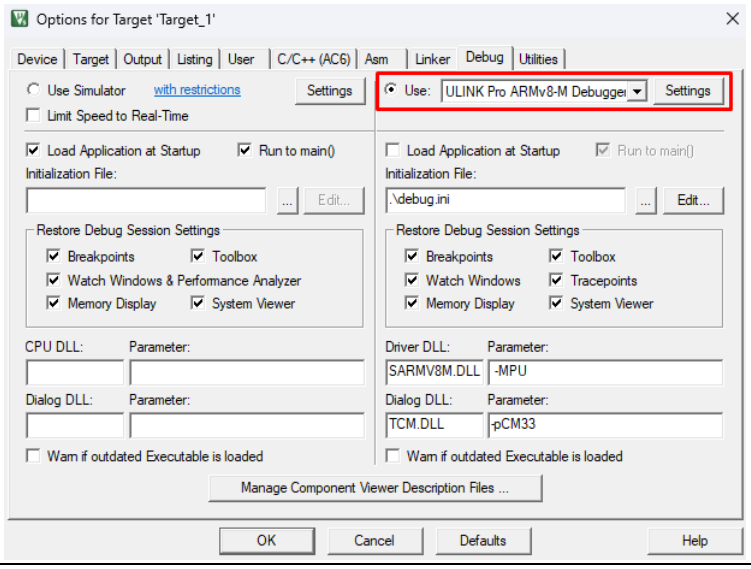

Figure 8 Configurations in Debug tab

4. In the new window, configure the settings for the **Debug** tab to match Figure 9.
   - **Serial No.**: Any
   - **Port**: SW
   - **Max Clock**: 1MHz
   - **Connect**: Normal

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- **Reset**: SYSRESETREQ
- **Reset after Connect**: selected

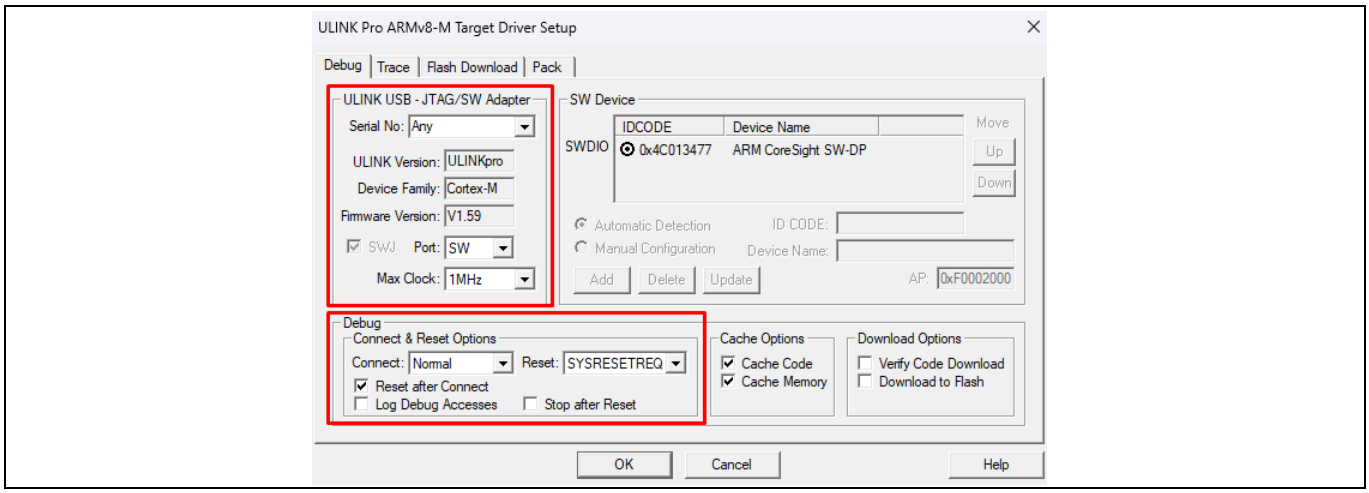

Figure 9 Configurations in Debug > Debug tab

5. Select the **Trace** tab and configure the settings to match Figure 10.
   - **Trace Enable**: selected
   - **ETM Trace Enable**: selected
   - **Trace Port**: Sync Trace Port with 1/2/4-bit Data
   - **ITM Stimulus Ports**: 0 selected

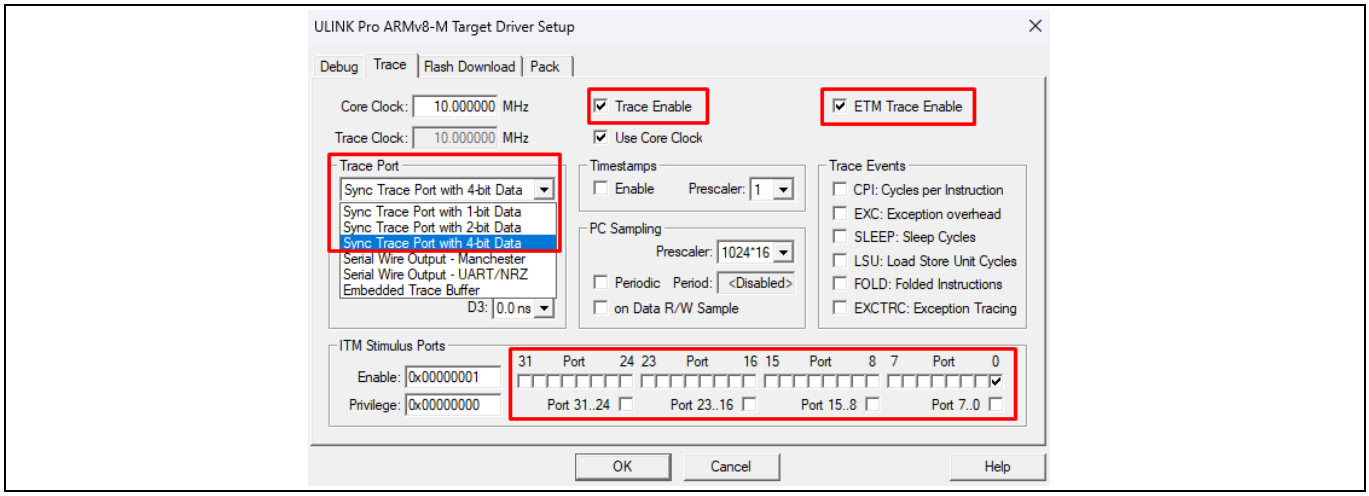

Figure 10 Configurations in Debug > Trace tab

6. Select the **Flash Download** tab and select the check boxes for **Program, Verify, Reset,** and **Run**.
7. Select the **Pack** tab and **Enable** check box, and then click **OK**.

Performing trace on PSOC™ Control C3 and PSOC™ Edge E8 MCU

3.1.3 Perform ETM trace

In the *main.c* file, modify the main function as follows. This modification will toggle the user LED on the kit every second.

```
int main(void)
{
    cy_rslt_t result;

    /* Initialize the device and board peripherals */
    result = cybsp_init();

    /* Board init failed. Stop program execution */
    if (result != CY_RSLT_SUCCESS)
    {
        CY_ASSERT(0);
    }

    /* Enable global interrupts */
    __enable_irq();

    /* Initialize the User LED */
    mtb_hal_gpio_t led;
    mtb_hal_gpio_setup(&led, CYBSP_USER_LED_PORT_NUM, CYBSP_USER_LED_PIN);
    mtb_hal_gpio_configure(&led, MTB_HAL_GPIO_DIR_OUTPUT, MTB_HAL_GPIO_DRIVE_STRONG);
    mtb_hal_gpio_write(&led, CYBSP_LED_STATE_OFF);


    for (;;)
    {
        mtb_hal_system_delay_ms(1000);

        /* Invert the USER LED state */
        mtb_hal_gpio_toggle(&led);
    }
}
```

To perform an ETM trace, do the following:

1. Click the **Build** icon on the µVision toolbar to rebuild the code.
2. Click the **Start or Stop Debug Session** icon on the µVision toolbar to program the image and start the debug perspective.
3. To open the ETM trace window, select **View > Trace > Trace Data**.
4. Click the **Run** icon on the toolbar to start the execution and collection of ETM trace data.

Performing trace on PSOC™ Control C3 and PSOC™ Edge E8 MCU

You should see the user LED toggling every second. When you pause the program execution, the collected trace data will populate in the ETM trace data window, as shown in Figure 11.

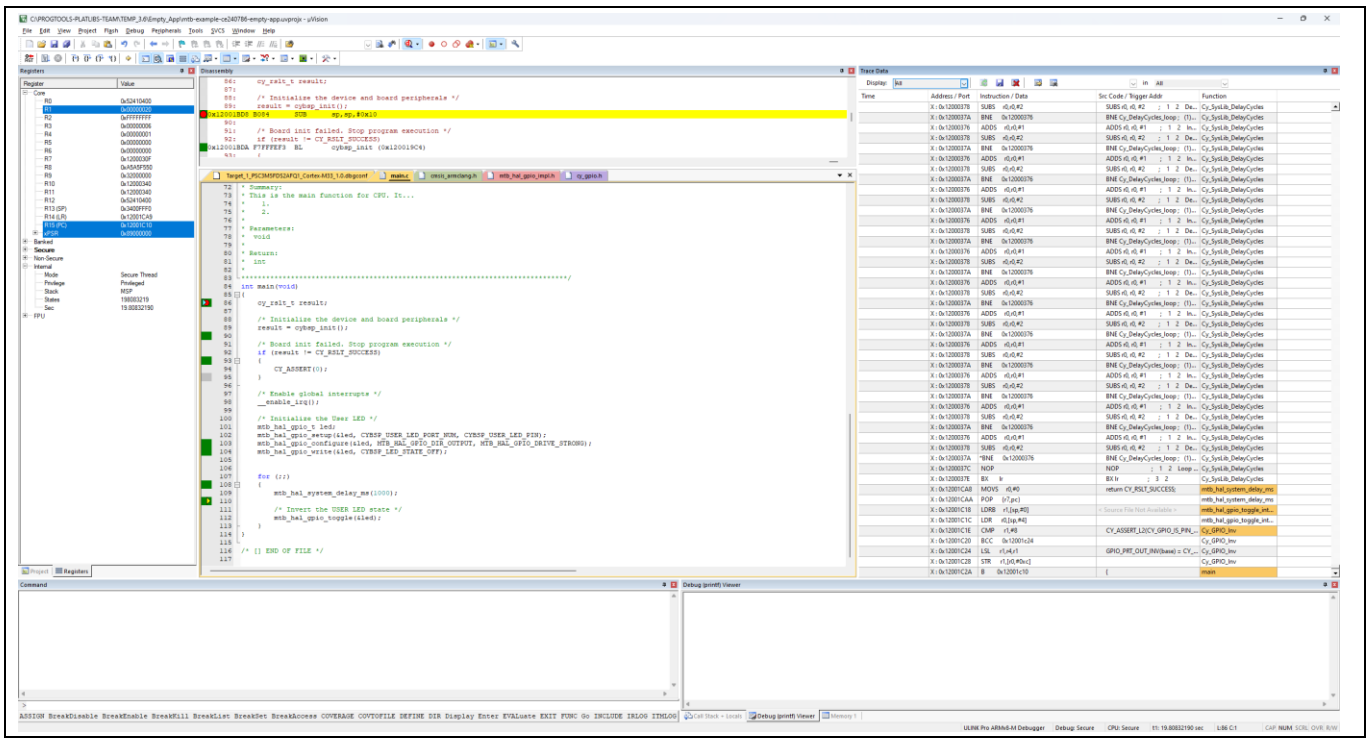

Figure 11 µVision trace data windows showing the ETM data

The ULINKpro debugger automatically calibrates to the new trace clock if the trace clock changes during code execution.

3.1.4 Perform ITM trace (printf-style debugging)

To configure for printf-style debugging, do the following:

1. In µVision, go to **Project > Manage > Run-Time Environment**.
2. Once the Manage Run-Time Environment window opens, select **Compiler > IO**, and then select the check boxes for **STDIN** and **STDOUT**. In the drop-down list for STDIN and STDOUT, select **ITM**.
3. In the *main.c* file, modify the main function and header list as follows:

Performing trace on PSOC™ Control C3 and PSOC™ Edge E8 MCU

```c
#include "mtb_hal.h"
#include "cybsp.h"
#include "stdio.h"

int main(void)
{
    cy_rslt_t result;

    /* Initialize the device and board peripherals */
    result = cybsp_init();

    /* Board init failed. Stop program execution */
    if (result != CY_RSLT_SUCCESS)
    {
        CY_ASSERT(0);
    }

    /* Enable global interrupts */
    __enable_irq();

    /* Initialize the User LED */
    mtb_hal_gpio_t led;
    mtb_hal_gpio_setup(&led, CYBSP_USER_LED_PORT_NUM, CYBSP_USER_LED_PIN);
    mtb_hal_gpio_configure(&led, MTB_HAL_GPIO_DIR_OUTPUT, MTB_HAL_GPIO_DRIVE_STRONG);
    mtb_hal_gpio_write(&led, CYBSP_LED_STATE_OFF);

    int a = 0;
    int b = 1;
    printf("Fibonacci Sequence:\n");

    for (;;)
    {
        mtb_hal_system_delay_ms(1000);

        /* Invert the USER LED state */
        mtb_hal_gpio_toggle(&led);

          /* printf-style debugging */
        printf("%d, %d, ", a, b);
        a += b;
        b += a;
    }
}
```

4. If not already done, follow the steps described in the Configure the debugger script with ULINKpro Cortex® section.
5. Click the **Build** icon on the µVision toolbar to rebuild the code.
6. Click the **Start or Stop Debug Session** icon on the µVision toolbar to program the image and start the debug perspective.
7. Select **View > Serial Windows > Debug (printf) Viewer**.
8. Click the **Run** icon on the toolbar to start the execution and collection of ITM data.

Performing trace on PSOC™ Control C3 and PSOC™ Edge E8 MCU

You should see the user LED toggling every second. The Debug Viewer displays logs as shown in Figure 12.

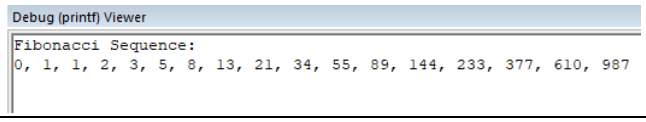

Figure 12 µVision Debug Viewer showing printf outputs

3.2 IAR Embedded Workbench for ARM

3.2.1 Configure the debugger script and debugger

The debugger configures the TPIU port and necessary clocks before starting the trace. This configuration is done through functions listed in a debugger script. The debugger scripts for PSOC™ Control C3 and PSOC™ Edge E8 MCUs are located in the IAR EW installation directory in accordance:

- <IAR Installation path> \Embedded Workbench\arm\config\debugger\Infineon\CAT1B.
- <IAR Installation path> \Embedded Workbench\arm\config\debugger\Infineon\CAT1D.

The debugger scripts with .dmac extension have default values for the TPIU port and clock divider selection. However, the default value for the TPIU port is usually not applicable for all development kits. Therefore, the script file must be edited to choose the correct TPIU port.

The PSOC™ Edge E84 Evaluation Kit uses CAT1D_trace.dmac files for configuration of TPIU port. To configure the TPIU port, open this debugger script from the IAR EWARM installation directory. In the file, search for the following parameters:

- __param _TRACE_d0_path – parameter, that define the TRACEDATA[0] pin.
- __param _TRACE_d1_path – parameter, that define the TRACEDATA[1] pin.
- __param _TRACE_d2_path – parameter, that define the TRACEDATA[2] pin.
- __param _TRACE_d3_path – parameter, that define the TRACEDATA[3] pin.
- __param _TRACE_clk_path – parameter, that define the TRACECLK pin.

The parameters and their comments are shown in Figure 13.

```
25  //
26  //  Trace pins route path - determine the route path for each trace pin.
27  //  _TRACE_xx_path = ( PORT_NUM << 8 ) + PIN_NUM
28  //  Default values are suitable for PSoC EDGE E8 EVALUATION KIT
29  //
30  __param _TRACE_d0_path = 0x1404;   // default - P20_4 (0x1404), alternate - P4_4 (0x404)
31  __param _TRACE_d1_path = 0x1403;   // default - P20_3 (0x1403), alternate - P4_5 (0x405)
32  __param _TRACE_d2_path = 0x1402;   // default - P20_2 (0x1402), alternate - P4_6 (0x406)
33  __param _TRACE_d3_path = 0x1401;   // default - P20_1 (0x1401), alternate - P4_7 (0x407)
34  __param _TRACE_clk_path = 0x1400;  // default - P20_0 (0x1400), alternate - P4_3 (0x403)
35
```

Figure 13 IAR debugger script snapshot for PSOC™ Edge E8 MCU

Trace data pins are routed to Port 20 of the kit, which is the default setting. However, if you want to override the parameter values in the debugger script without directly editing the file, please follow these steps:

1. In the IAR Embedded Workbench, go to **Project > Options > Debugger > Extra Options** and select **Use command line options**.

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2. In the text box, enter the following command:

```
--macro_param _TRACE_d0_path=0x404
--macro_param _TRACE_d1_path=0x405
--macro_param _TRACE_d2_path=0x406
--macro_param _TRACE_d3_path=0x407
--macro_param _TRACE_clk_path=0x403
```

Note: This command is space-sensitive; extra spaces should not be added around the equals sign.

You can modify any other parameter in the script in a similar way if required. For the flow followed in this application note, modifying the trace path is sufficient.

To select the debugger, in the IAR EWARM, go to **Project > Options > Debugger > Setup** and select **Driver(I-jet)** from the **Driver** drop-down menu.

3.2.2 Perform ETM trace

In the main.c file, modify the code as described in the Perform ETM trace section. This modification will toggle the user LED on the kit every second.

To start the ETM trace, follow these steps:

1. Click one of the buttons:
   - **Download and Debug** icon on the IAR EW toolbar to program the image and start the debug perspective.
   - **Debug without Downloading** icon on the IAR EW toolbar to start the debug perspective without programming of MCU.
2. To open ETM Trace Window for I-jet, select **I-jet > ETM trace**. The ETM trace window appears.
3. Right-click the ETM trace window and select **Enable**.
4. Click the **Go** icon on the toolbar to start the execution and collection of ETM trace data You should see the user LED toggling every second. The debug log window is shown in Figure 14.

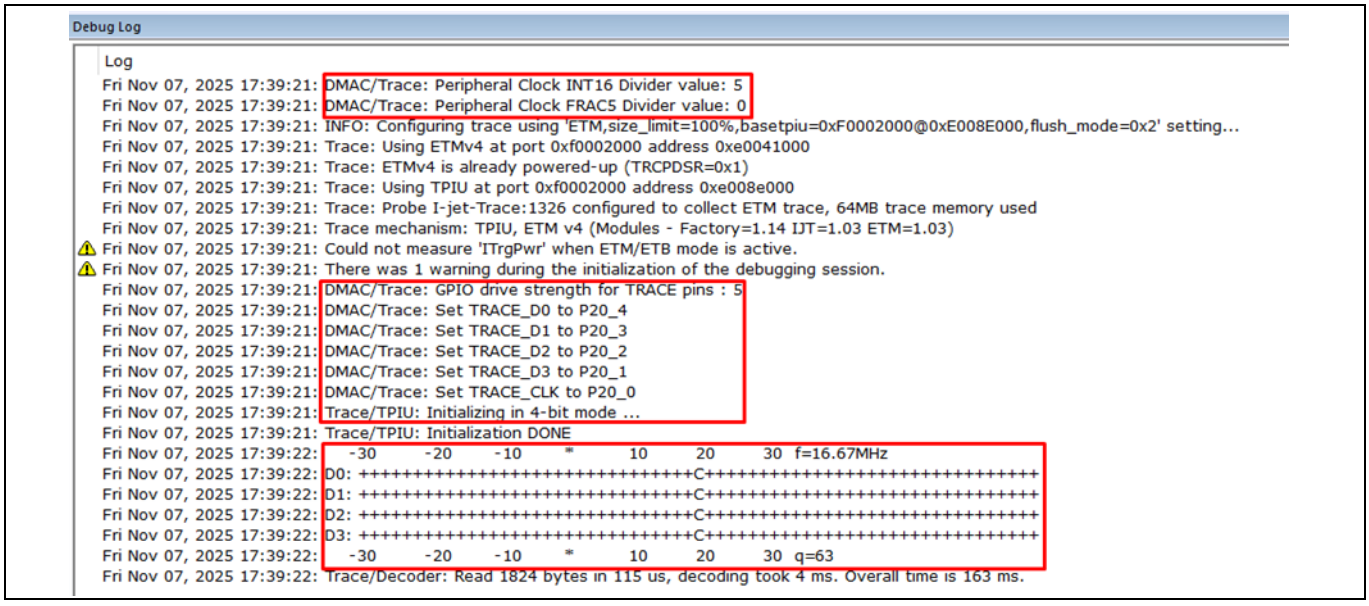

Figure 14 IAR debug log for ETM trace for first initialization

Performing trace on PSOC™ Control C3 and PSOC™ Edge E8 MCU

Sometimes the trace clock can have another clock after the first initialization, so we recommend recalibrating the trace clock by changing the number of pins.

The ideal way to trace is to set a breakpoint right after the cybsp_init() function. Once the breakpoint is hit, tracing stops. If you then restart the trace, the debugger recalibrates to the new frequency and starts capturing data correctly. See Figure 15.

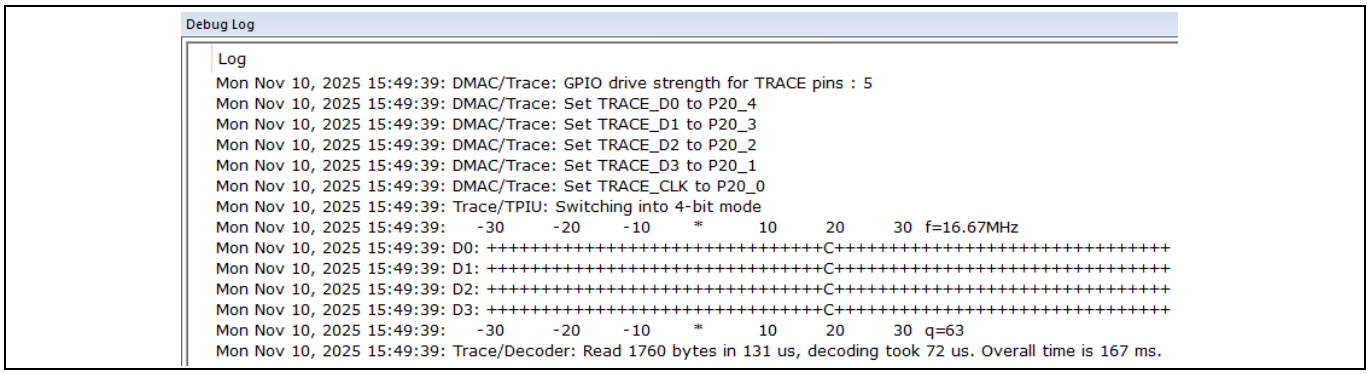

Figure 15 IAR debug log for ETM trace recalibration

If you pause the program execution, the trace data collected will be populated in the ETM trace window as shown in Figure 16.

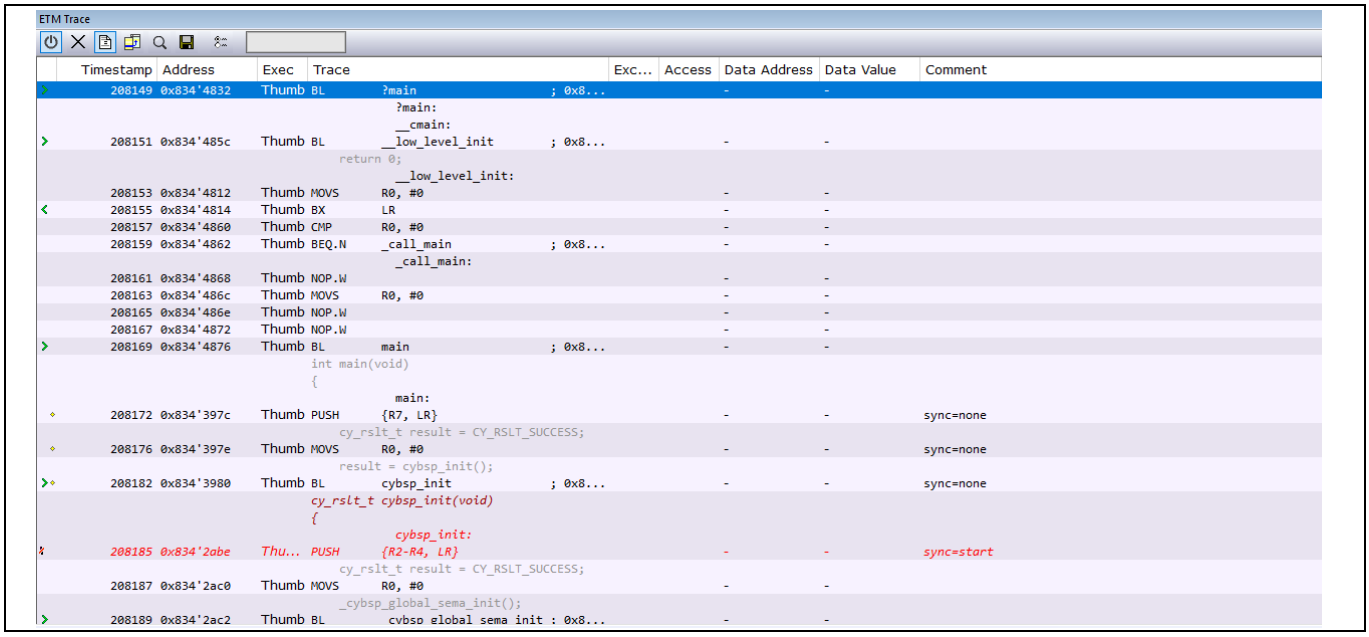

Figure 16 IAR ETM trace window showing ETM data

3.2.3 Perform ITM trace (printf-style debugging)

As previously stated, at this moment IAR Embedded Workbench does not provide support for ITM Trace (printf-style debugging) via 4-pin Trace Output or over ETB/MTB.

4 Troubleshooting

In this section, we will examine how we can resolve common issues encountered while performing ETM and ITM tracing on the PSOC™ Control C3 and PSOC™ Edge E8 MCU.

4.1 Keil µVision

During of debugging you can meet some common µVision Trace Status errors when using parallel 4-pin trace on PSOC™ Control C3 and PSOC™ Edge E8 MCUs:

- Communication Error
- No Synchronization
- Data Stream Error
- Data Overflow
- Processing aborted

Note: *Detailed definitions are available at Arm's page:* https://developer.arm.com/documentation/101416/0100/-Vision-Windows/Trace-Status?lang=en

Before applying fixes, we recommend to look this items:

1. Ensure cybsp_init() did not reconfigure or clear the trace pins. Confirm TRACECLK and TRACEDATA[0..3] remain routed, enabled, and in trace mode after board initialization.
2. In Options for **Target > Debug > Settings > Trace**, verify:
   - Trace Port is Sync Trace Port with 1/2/4-bit Data (Parallel). Do not select SWO.
   - Enter the correct prescaler value for TRACECLK.
   - ETM is enabled; ITM/DWT are enabled if needed.

4.1.1 Recommended fixes

Reduce the number of active trace data pins

If the MCU supports configurable TPIU port size, set the trace port width from 4 to 2 or 1 bit. This lowers bandwidth and eases signal integrity and timing.

Increase compensating signal delays for Sync Trace Port

The default is 0.0 ns and often works, but if you see No Synchronization or Data Stream Error, increase these delays to move the sampling point toward the center of the valid window and compensate cable/board skew. Tune in small steps (for example, +0.5 to +2.0 ns). Start with the same value for D0..D3; if one data lane is still unstable, fine-tune it individually.

In ULINKpro Trace settings, adjust the input sampling delays as defined by Keil:

- CLK: signal delay (ns) applied to TRACECLK.
- D0..D3: signal delay (ns) applied to TRACEDATA[0]..[3].

Troubleshooting

Note: For more information, see Arm® guidance on compensating signal delays: https://developer.arm.com/documentation/101416/0100/Troubleshooting/Compensate-Signal-Delays?lang=en

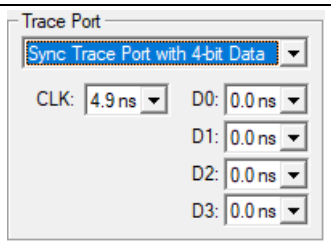

Figure 17 Sync Trace Port setting for ULINKpro probe

Adjust the trace clock divider

Lower the TPIU TRACECLK using the device's trace clock divider or reduce system clock feeding TPIU. If synchronization fails, try stepping down in increments.

If the probe reports underflow or stalls, you can also try modestly increasing TRACECLK to improve synchronization.

Change the 20-pin ribbon cable

Use a shorter shielded trace cable; verify correct orientation and a solid ground reference. Avoid long fly-wires or adapters without ground stitching.

Attach after the system is fully running

Use the **Start Debug Session**, but configure µVision to avoid a reset on connect. Got to **Project > Options > Debug > Settings** and deselect **Reset after connect**. This attaches without resetting the device, so late trace-clock initialization is preserved and helps prevent issues.

5 References

[1] AN235279: Performing ETM and ITM trace on PSOC™ 6 MCU

[2] AN238329: Getting started with PSOC™ Control C3 MCU on ModusToolbox™ software

[3] 630-60703-01: PSOC CONTROL C3M5 EVALUATION KIT Schematic

[4] AN235935 : Getting started with PSOC™ Edge E8 MCU on ModusToolbox™ software

[5] ModusToolbox™ tools package user guide (v3.6)

[6] Learn the architecture: Understanding trace by Arm® Developer

[7] IAR Embedded Workbench for ModusToolbox™ user guide

[8] Keil µVision for ModusToolbox™ user guide

[9] AN240106: Getting started with PSOC™ Control C3 security

[10] AN237849: Getting started with PSOC™ Edge security

References

Revision history

Document revision	Date	Description of changes
**	2025-11-20	New document.

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