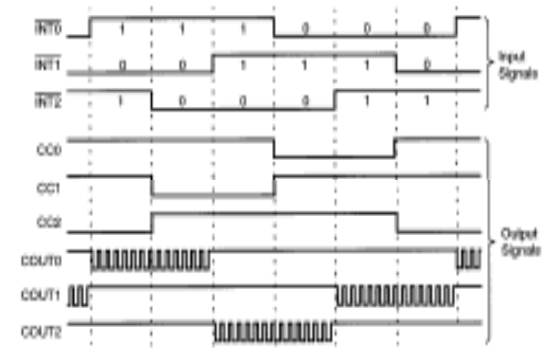


XC800 Product Presentation

May 2006



Capture Compare Unit CC6



Never stop thinking.

Table of contents

Introduction – Why such a CC6?

Special Features of XC8xx's CC6 with Application Examples

Practical Usage – Software Examples

Target Application for XC8xx – Electronic Motor Control

- Drives need **realtime performance**
 - control loop must run faster than 2-4 PWM periods (e.g. 100-200us)
 - **CPU performance is valuable and must be saved for key tasks**
 - **Question:** How to offload the CPU?
 - **Answer:** Build intelligent and autonomous peripherals!

- CC6 in a Drive application:
 - generate PWM patterns for all kind of motors
 - operate always in a safe state – even in an error condition
 - interact with ADC for sensorless control of motors

- **CC6 is used intensively – the more it works autonomous the more CPU load can be saved for control algorithms**

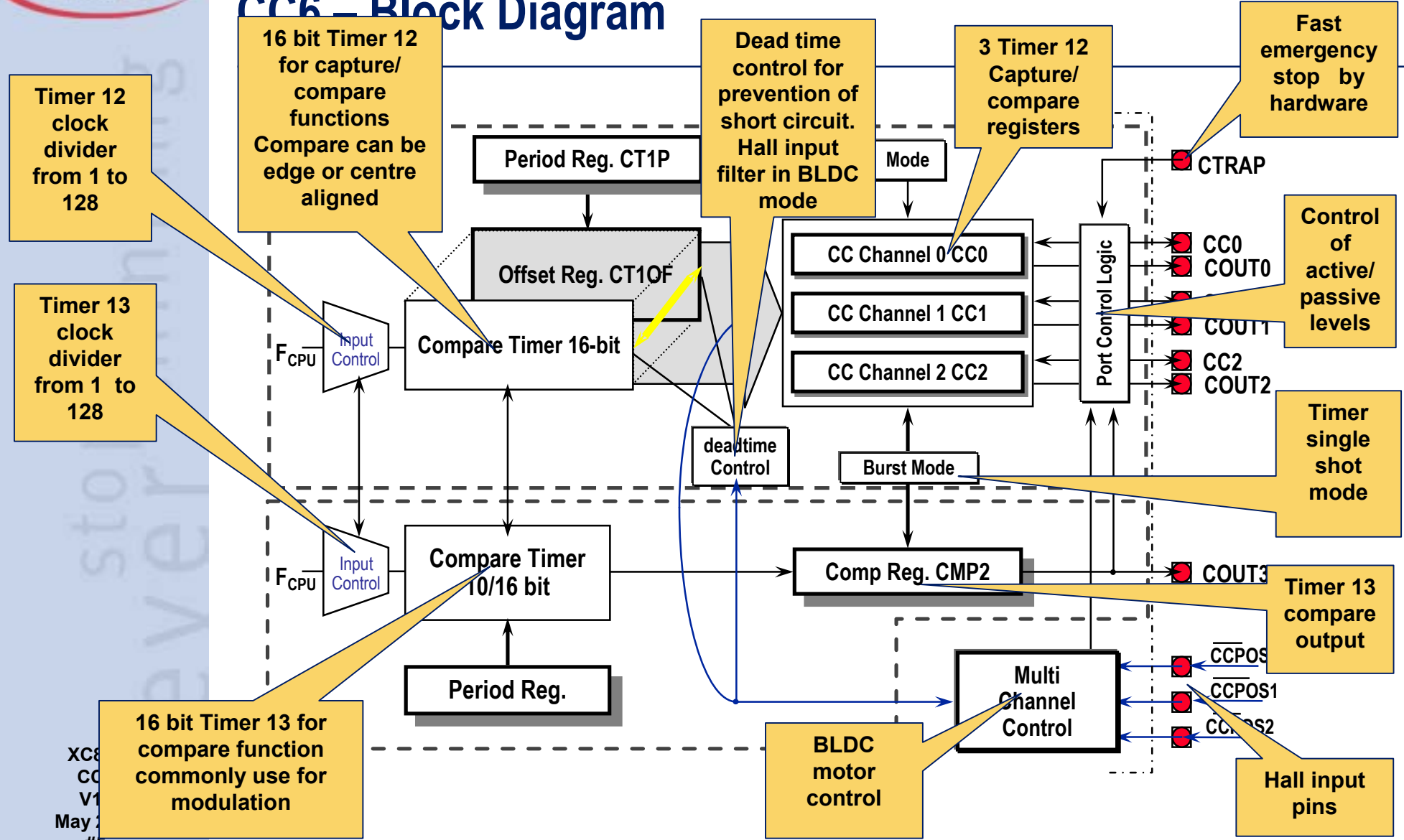
Table of contents

■ Introduction – Why such a CC6?

■ **Special Features of XC8xx's CC6 with Application Examples**

■ Practical Usage – Software Examples

CC6 - Block Diagram



CC6 – The Register Map

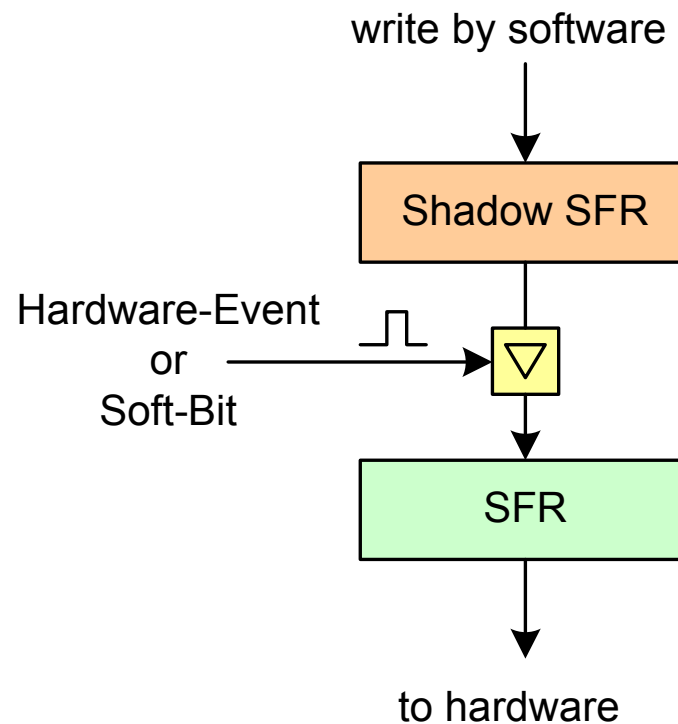
- The CC6 has **61 SFRs** in 4 SFR pages
- Switching between pages for configuration
- Running from a **working page** after configuration

Page 0	Page 1	Page 2	Page 3
CC63SRL	CC63RL	T12MSELL	MCMOUTL
CC63SRH	CC63RH	T12MSELH	MCMOUTH
TCTR4L	T12PRL	IENL	ISL
TCTR4H	T12PRH	IENH	ISH
MCMOUTSL	T13PRL	INPL	PISEL0L
MCMOUTSH	T13PRH	INPH	PISEL0H
ISRL	T12DTCL	ISSL	PISEL2
ISRH	T12DTCH	ISSH	–
CMPMODIFL	TCTR0L	PSLR	–
CMPMODIFH	TCTR0H	MCMCTR	–
CC60SRL	CC60RL	TCTR2L	T12L
CC60SRH	CC60RH	TCTR2H	T12H
CC61SRL	CC61RL	MODCTRL	T13L
CC61SRH	CC61RH	MODCTRH	T13H
CC62SRL	CC62RL	TRPCTRL	CMPSTATL
CC62SRH	CC62RH	TRPCTRH	CMPSTATH

CC6 – Shadow Register

Shadow Register

- All SFRs which have to be updated in runtime (realtime) are shadowed
- Software (CPU) accesses are decoupled from hardware
- Safe operation in all conditions
- Fully utilized PWM (0-100%)
- Hardware event controls shadow transfer



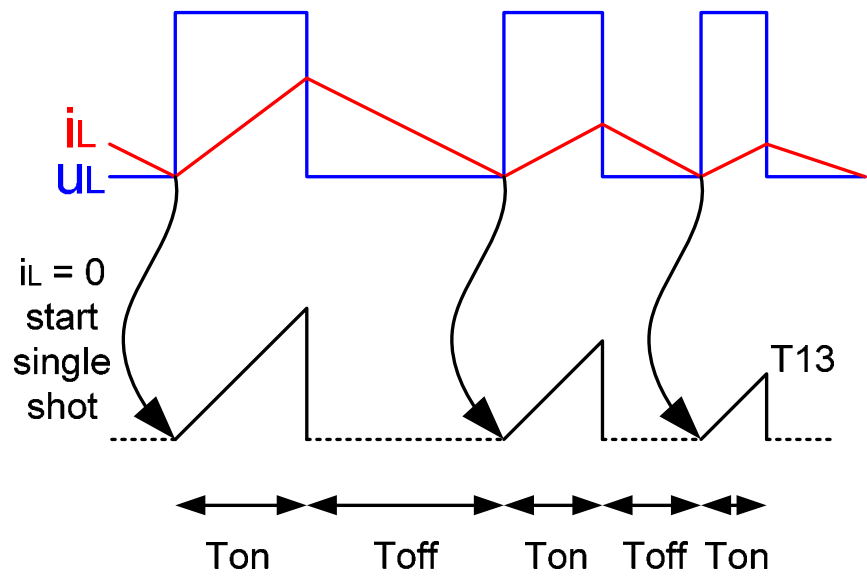
Result Control

EX: CC6_1/2

CC6 – Single Shot and Synchronization

Single Shot and Synchronization

- T12 and T13 can run in single shot mode
- T12 and T13 can be started on several events
 - external start – T12HR/T13HR
 - period/compare match of the other timer
- Synchronization T13 on T12
- Inductive Load Control
- Trigger ADC



Lampballast, SMPS, PFC, Current Measurement

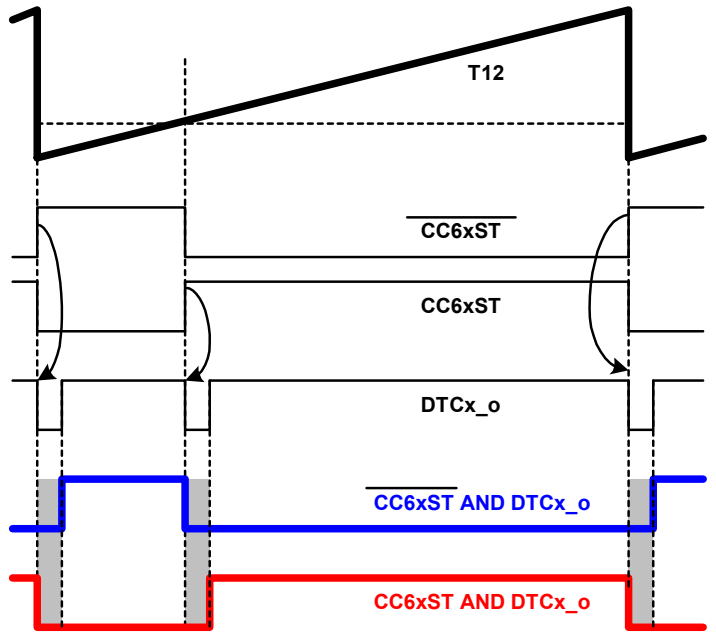
EX: CC6_3/4

Never stop thinking

CC6 – Deadtime Generation

Deadtime Generation

- Dead time generation on T12 Channels
 - by programmable dead time counter DTC
- Dead time feature can be used
 - in edge and center aligned mode
 - together with 0% - 100% duty cycle



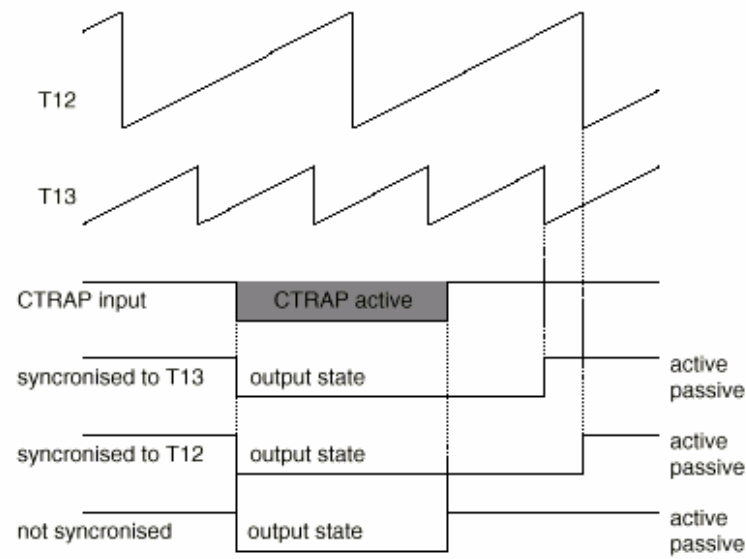
One to Three Phase - Halfbridge Control

EX: CC6_5/6

CC6 – Hardware Trap Generation

Hardware Trap Generation

- TRAP control
 - in TRAP state **all** outputs can be switched to selected passive state
 - several possibilities for leaving TRAP state, synchronization to PWM
 - TRAP state can be triggered by SW or HW



One to Three Phase - Halfbridge Control

EX: CC6_5/6

stop thinking
Never

CC6 – Hysteresis Like Control Mode

Hysteresis Like Control Mode

- CCPOSx Inputs
 - phase can be switched inactive upon comparator signal, e.g. overcurrent
 - simple & ultralowcost hardware control structure possible

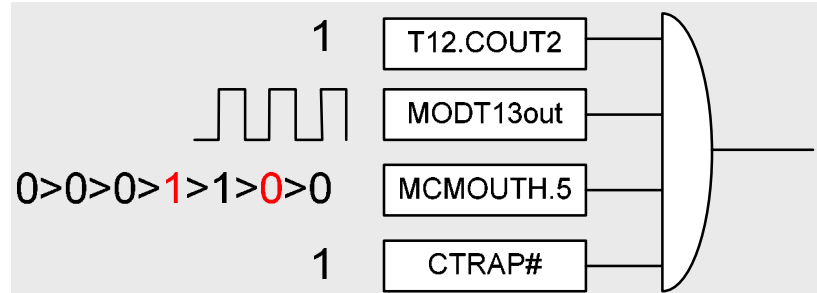
One to Three Phase - Halfbridge Control

EX: CC6_7

CC6 – Multichannel Control Mode

Multichannel Mode

- Modulation Control
 - T12output (3 channel)
 - T13output (1 channel)
 - MCMOUT.x (6 Bits)
 - CTRAP



6x

BLDC Motor Control

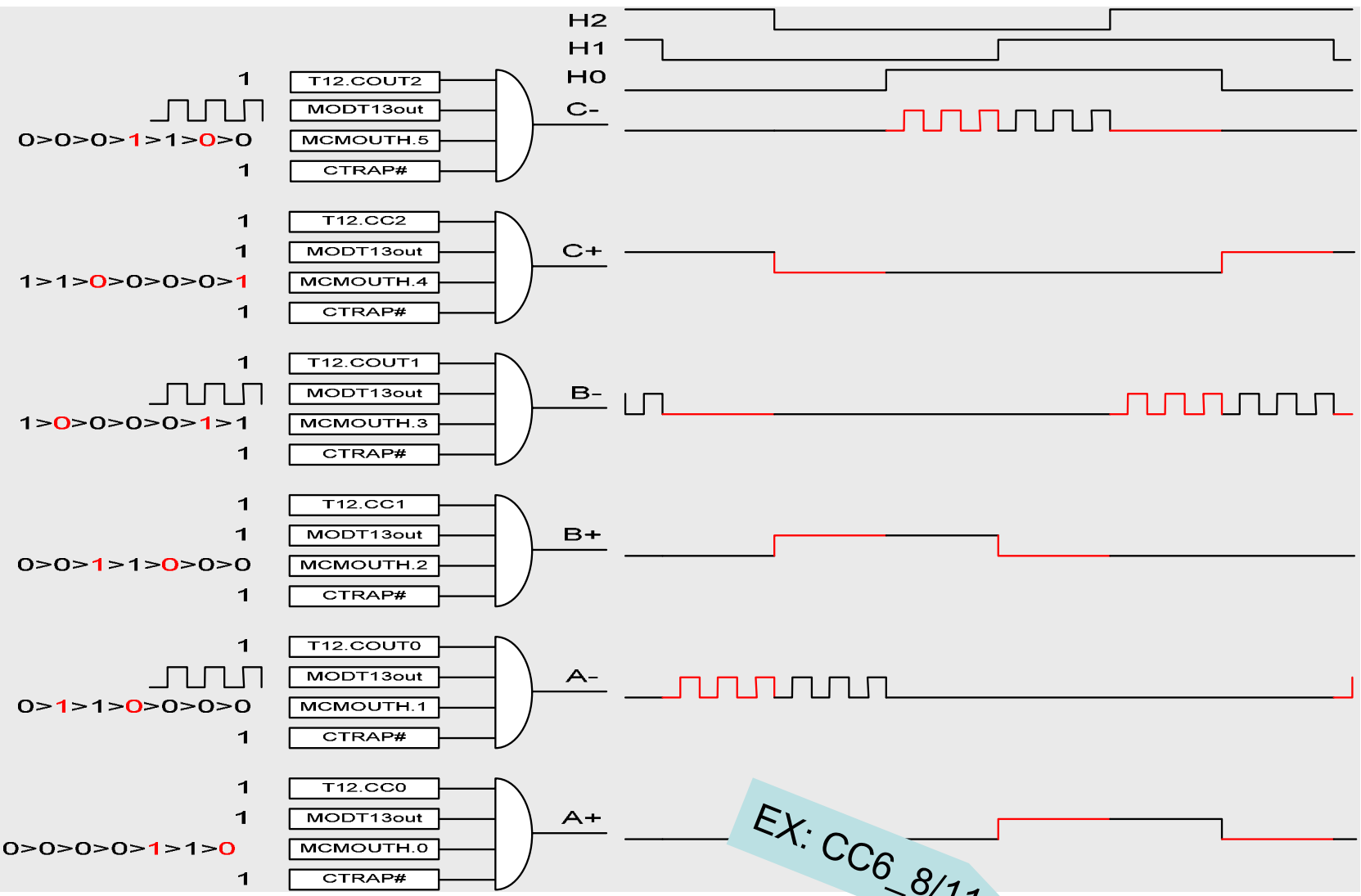
EX: CC6_8

Never stop thinking

CC6 – MCM

Generate the PWM Pattern for BLDC Motor

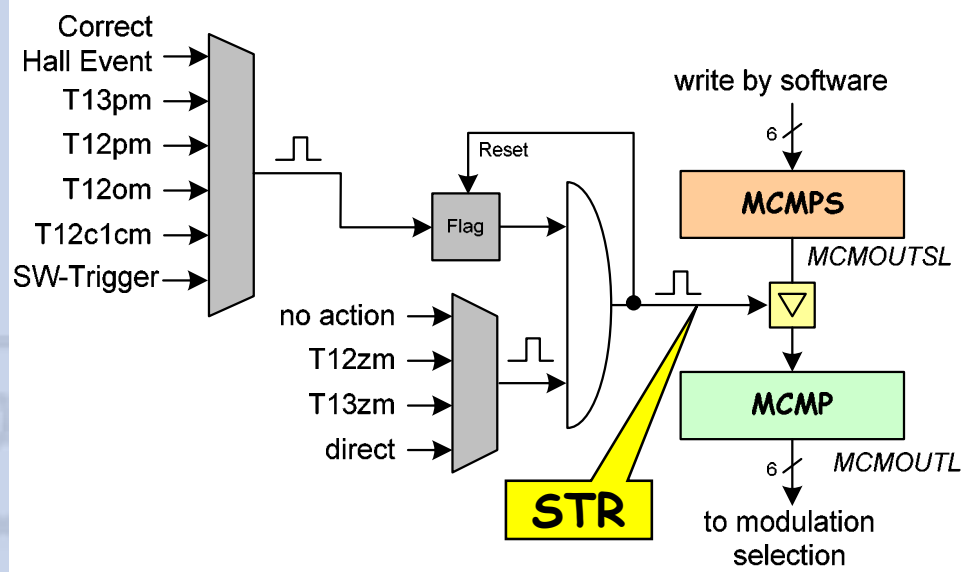
stop thinking
Never



EX: CC6_8/11

CC6 – Multichannel Control Mode

Multi Channel PWM Pattern Switching



- **Software Modulation Control**
 - Switching Selection
 - Switching Synchronization
 - New Bit **STR** „Shadow Transfer Request“ for qualified interrupt generation

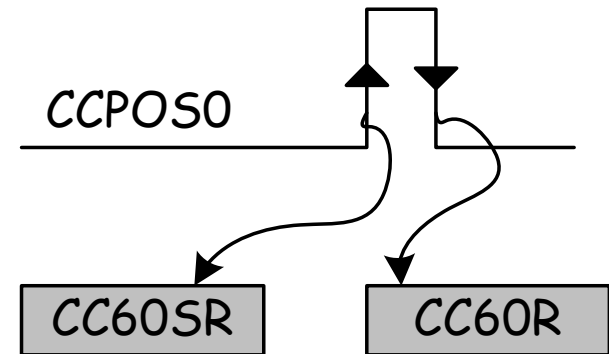
BLDC Motor Control / Sophisticated Pulse Pattern

EX: CC6_8

CC6 – Capture Modes

Double Register Capture

- Selective Capture
 - rising / falling edge
 - for period measurement
 - for duty cycle measurement



Hall Sensor „Speed“ Measurement

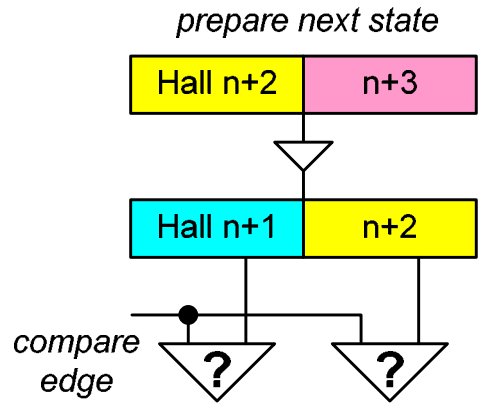
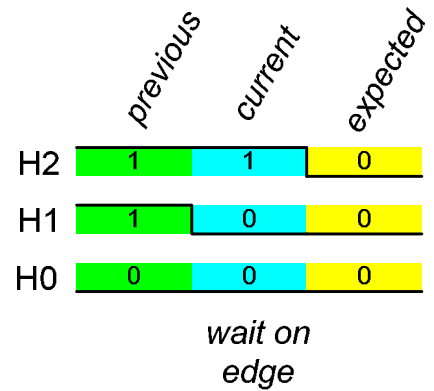
EX: CC6_9

CC6 – Hall Pattern Mode

Hall Pattern Mode

Hall Pattern Control

- statemachine without any timer involved
- flexible input control



Soft-/Hardware - Statemachine

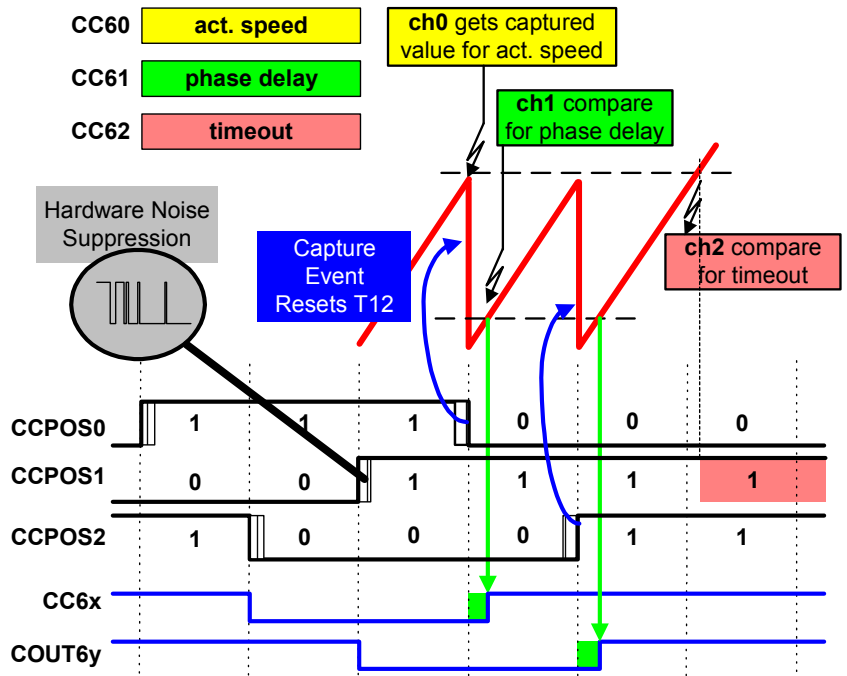
EX: CC6_10

stop thinking
Never

CC6 – Hall Sensor Mode

Hall Sensor Mode

- BEMF-Detection/Hall Signals
 - HW-noise filter on CCPOSx inputs (BEMF-signals)
 - automatic reset of T12
 - actual speed by capture on ch0
 - phase delay function on ch1
 - time out function on ch2
 - qualified interrupt for next state by STR



BLDC Motor Control

EX: CC6_11



Any Questions?

Never^{stop} thinking

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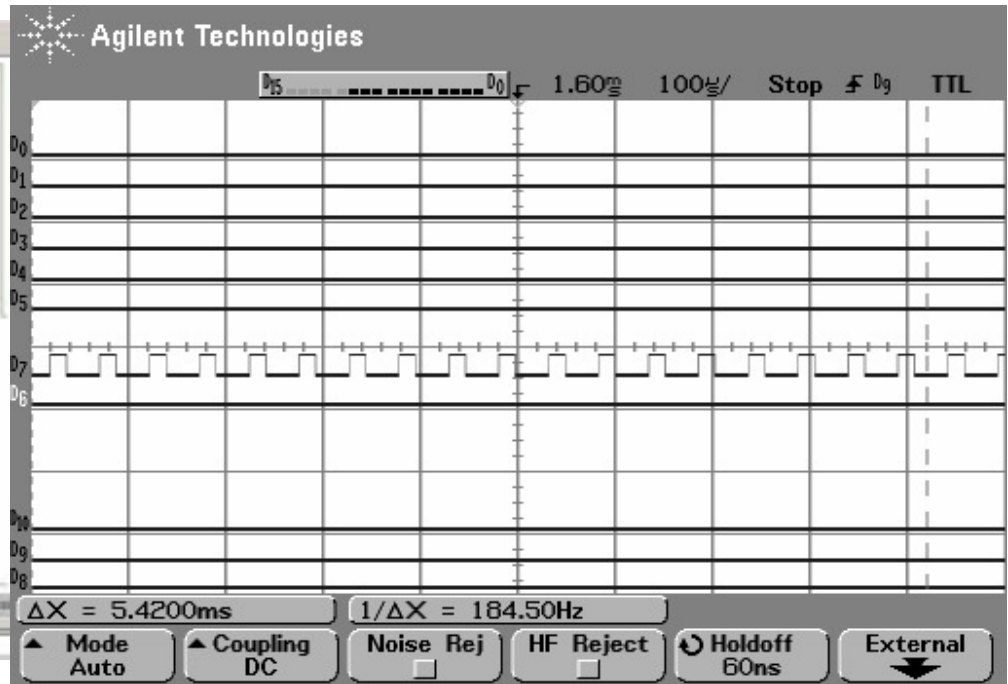
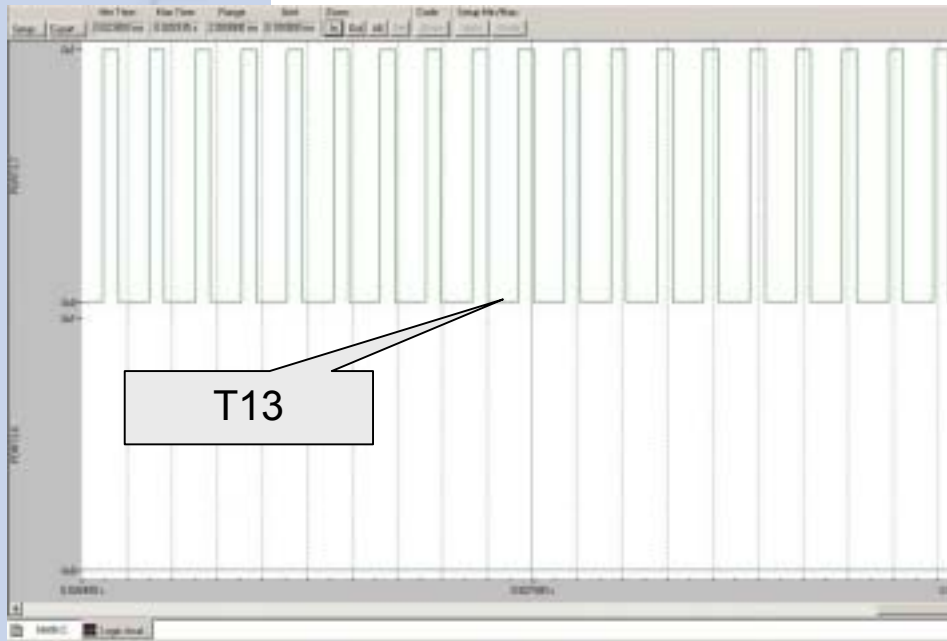
■ Introduction – Why such a CC6?

■ Special Features of XC8xx's CC6 with Application Examples

■ **Practical Usage – Software Examples**

How to use the CC6 – CC6-Example 1

- CC6_1 – Single Channel Constant PWM on T13
- Logic Analyzer in μ Vision
- Scope Screenshot



How to use the CC6 – CC6-Example 2

■ CC6_2 – Single Channel Variable PWM on T13 with CTRAP

- interrupt routine for CTRAP
- interrupt routine for T13PM with update of duty cycle
- main routine forces CTRAP by pulldown on P3.6

■ Copy following code

- main.c

```

// USER CODE BEGIN (MAIN_Main,1)
uword uwBufT13PR;
// USER CODE END

void main(void)
{
// USER CODE BEGIN (MAIN_Main,2)
uword i = 0;
// USER CODE END

MAIN_vlnit();

// USER CODE BEGIN (MAIN_Main,3)
SFR_PAGE(_cc1, SST0); // switch to page 0
uwBufT13PR = CCU6_T13PR;
SFR_PAGE(_cc0, RST0); // restore ccu_page
// USER CODE END

while(1)
{
// USER CODE BEGIN (MAIN_Main,4)
// force CTRAP
for (i=0x1000; i>0; i--);
SFR_PAGE(_pp1, SST0); // switch to page 1
P3_PUDSEL ^= 0x40; // force CTRAP by pulldown on P3.6
// alternatively use debugger

SFR_PAGE(_pp0, RST0); // switch to page 1
// USER CODE END
}

} // End of function main

```

Copy following code

- shared_int.c

```

// USER CODE BEGIN (NodeI0,1)
uword uwDuty3 =0;
extern uword uwBufT13PR;
// USER CODE END

void SHINT_viXINTR10Isr(void) interrupt XINTR10INT
{
*...

if(CCU6_ISH & 0x02) //if ISH_T13PM
{
//timer T13 period match detection

SFR_PAGE(_cc0, noSST); // switch to page 0

CCU6_ISRH = 0x02; //clear flag ISH_T13PM

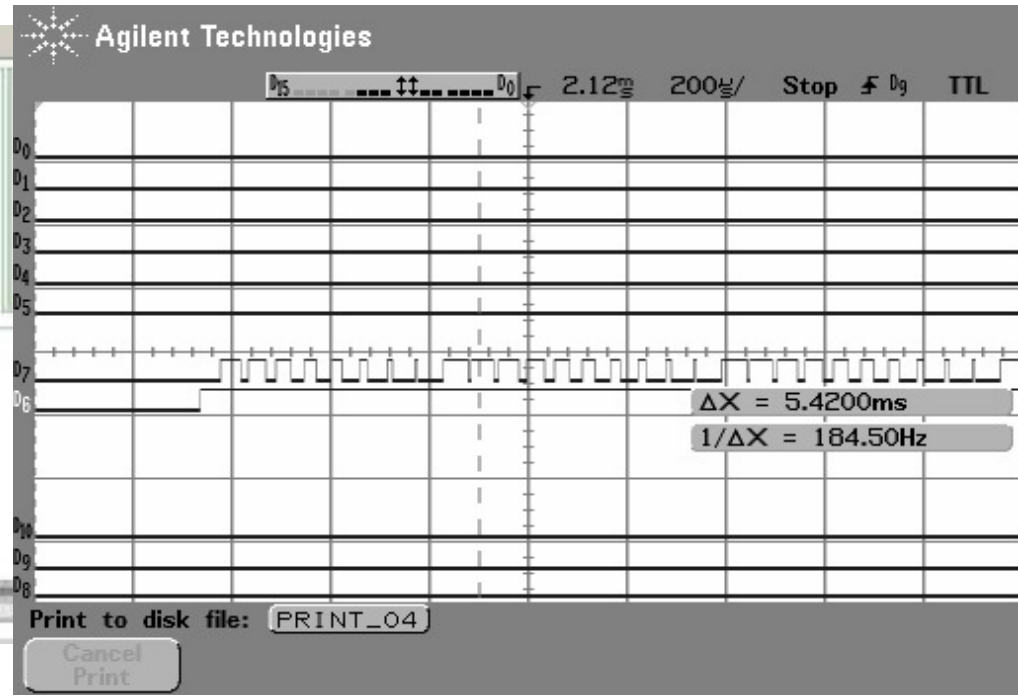
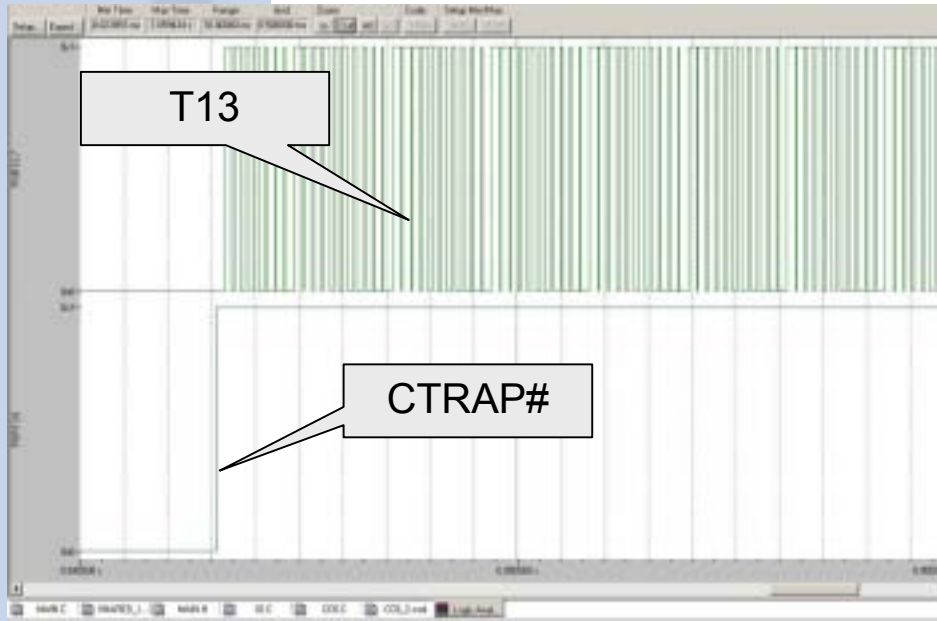
// USER CODE BEGIN (NodeI0,19)
// update duty cycle for Channel 3
uwDuty3+=0x0080;
if (uwDuty3>uwBufT13PR) uwDuty3=0;
CCU6_CC63SR = uwDuty3;
CC6_vEnableShadowTransfer_CC6_TIMER_13();
SFR_PAGE(_cc1, RST0); // restore ccu_page

// USER CODE END
}
}

```

How to use the CC6 – CC6-Example 2

- CC6_2 – Single Channel Variable PWM on T13 with CTRAP
- Logic Analyzer in μ Vision
- Scope Screenshot



How to use the CC6 – CC6-Example 3

- **CC6_3 – Single Shot Mode T13**
 - external run (T13HR) from P2.1 falling edge
 - interrupt service routine for T13PM
 - main routine forces T13HR by pulldown on P2.1
- Copy following code
 - main.c
- Logic Analyzer in µVision

```

void main(void)
{
// USER CODE BEGIN (MAIN_Main,2)
uword uwi = 0;
// USER CODE END

MAIN_vinit();

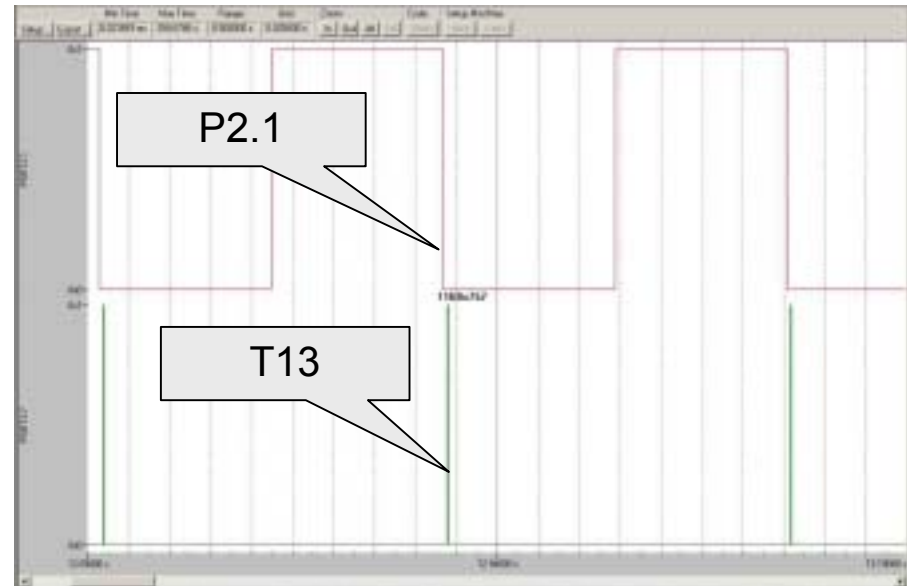
// USER CODE BEGIN (MAIN_Main,3)

// USER CODE END

while(1)
{
// USER CODE BEGIN (MAIN_Main,4)
// force P2.1 edge
for (uwi=0x1000; uwi>0; uwi--);
SFR_PAGE(_pp1, SST0); // switch to page 1
P2_PUDSEL ^= 0x02; // force T13HR on P21
SFR_PAGE(_pp0, RST0); // switch to page 1

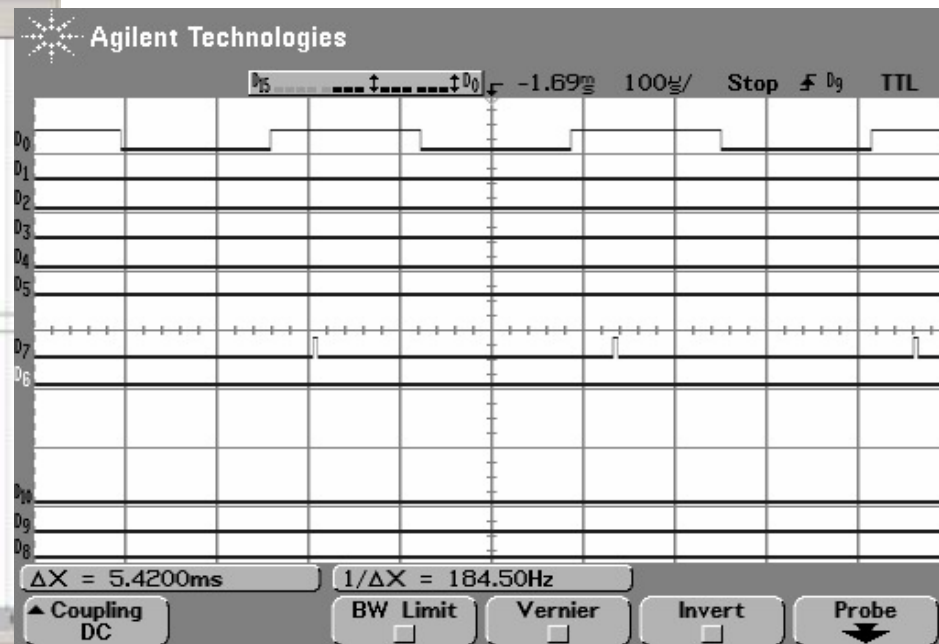
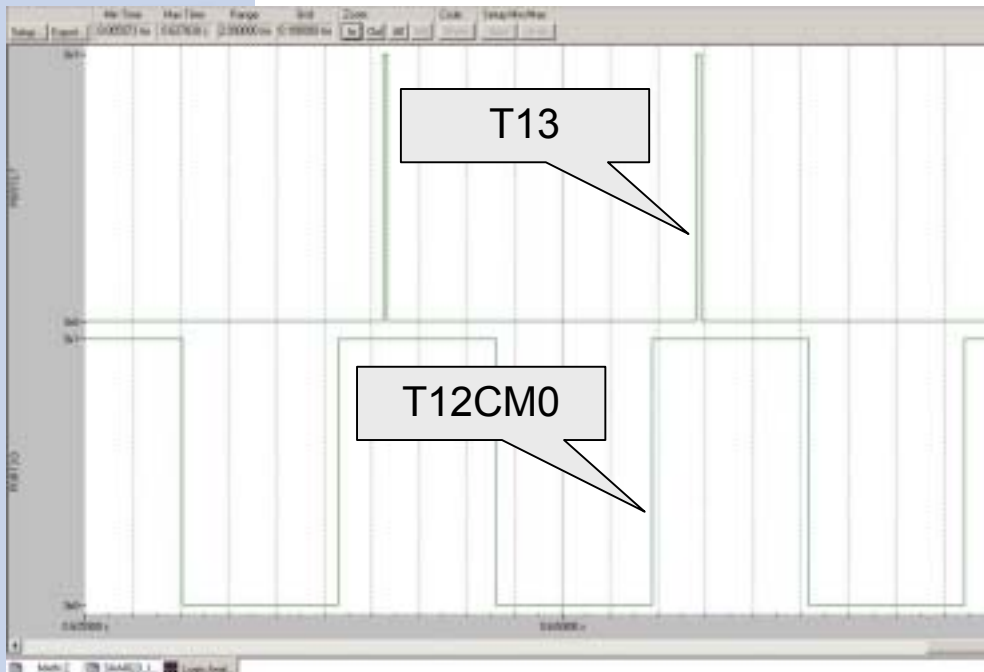
// USER CODE END

}
} // End of function main
  
```



How to use the CC6 – CC6-Example 4

- **CC6_4 – Single Shot Mode T13**
 - T12 in center aligned mode, PWM on ch0, 50%
 - interrupt service routine for T12PM
 - single shot mode T13, synchronize and start with T12CMch0 upcount
 - duty cycle for T13 10%, output on P3.7
 - interrupt service routine for T13PM
- Logic Analyzer in μ Vision
- Scope Screenshot

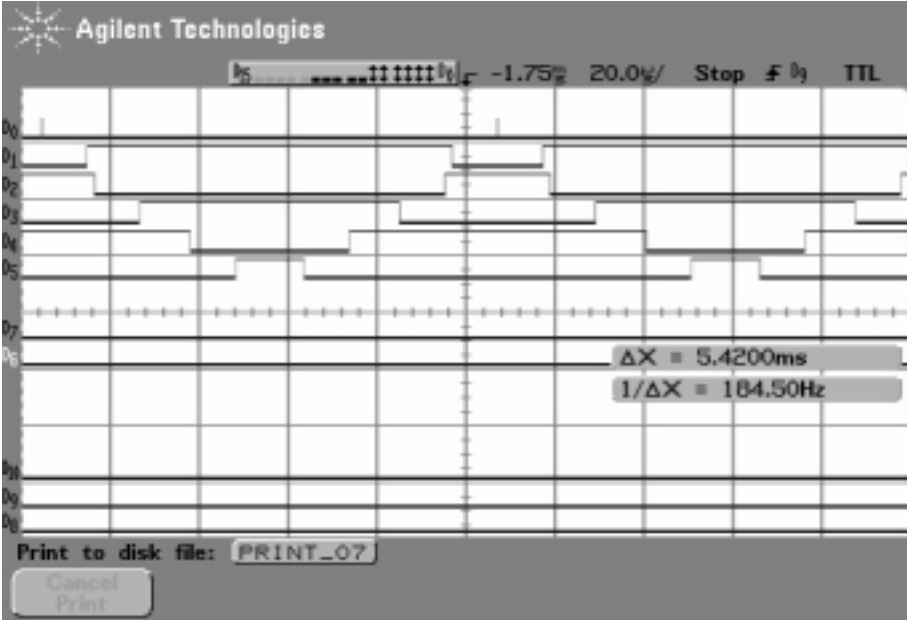
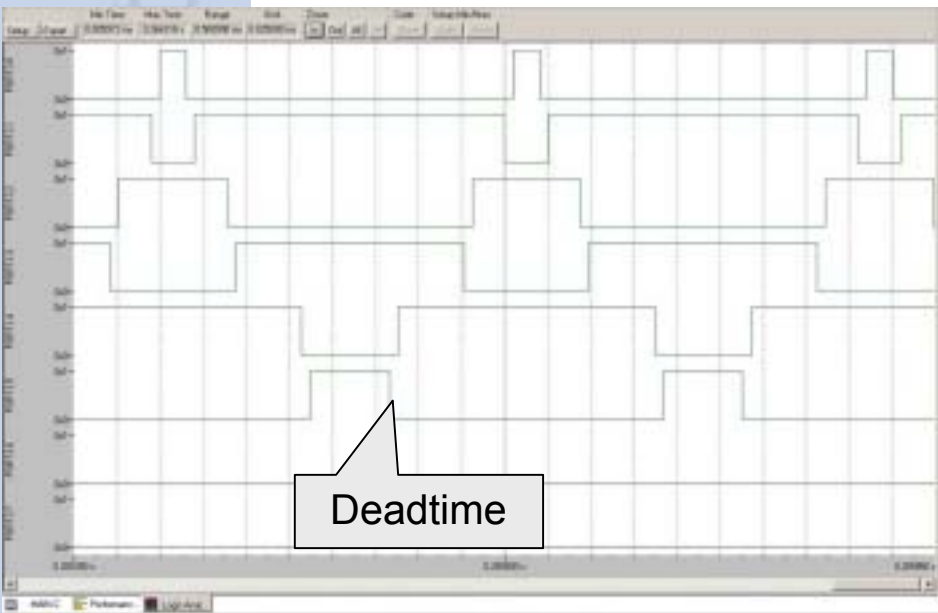


How to use the CC6 – CC6-Example 5

- **CC6_5 – 3 channel PWM with deadtime on T12**
 - 3ch/6outputs with inverted output level and deadtime
 - for driving stage with highside & lowside active high
 - T12 in center aligned mode
 - interrupt service routine for T12PM

■ Logic Analyzer in μ Vision

■ Scope Screenshot



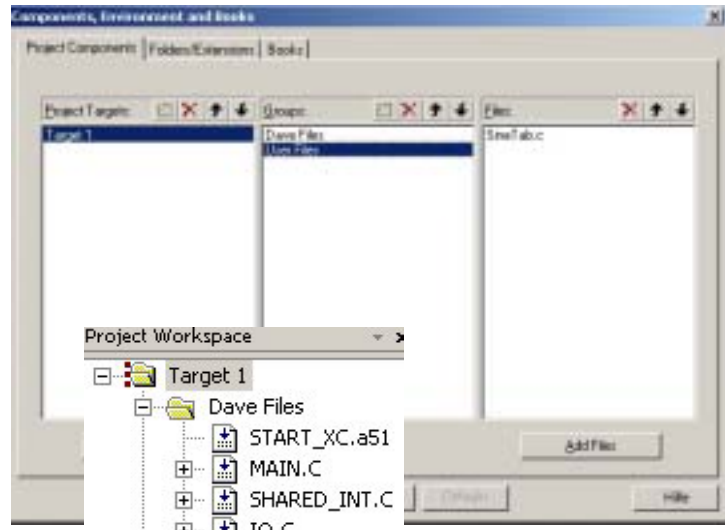
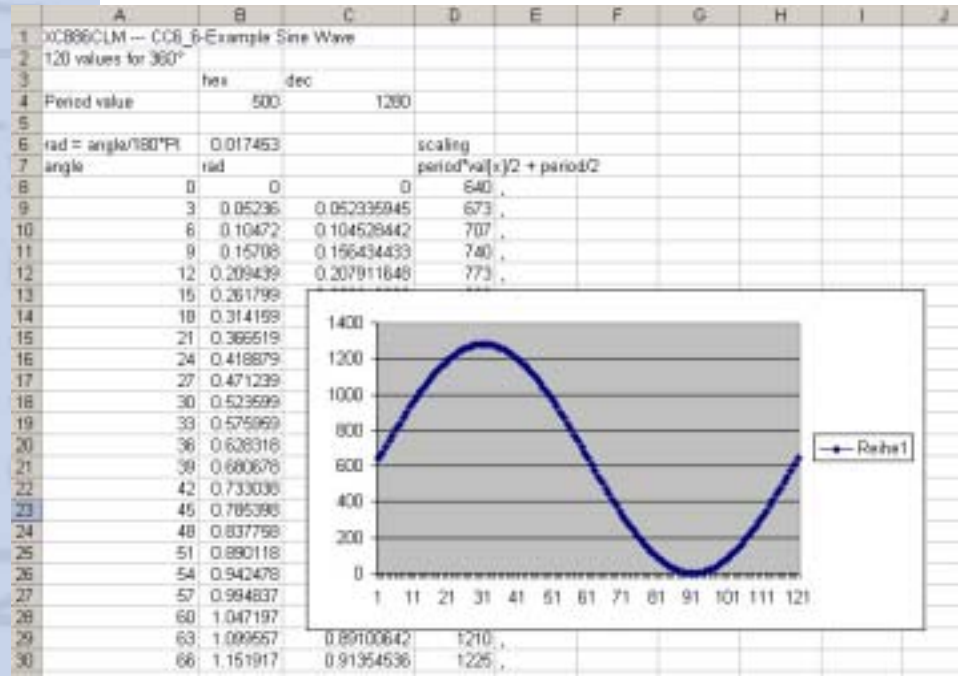
How to use the CC6 – CC6-Example 6

■ CC6_6 – 3 channel sinusoidal PWM with deadtime and CTRAP

- update duty cycles with every T12PM interrupt
- simple sinusoidal table >> see excel sheet SineTab.xls
- force CTRAP by pulldown on P3.6
- leave trapstate synchronized to T12period

1) Generate **Sine-Table** from Excel

2) Import **SineTab.c** into project



How to use the CC6 – CC6-Example 6

3) Copy following code

– main.c

```
void main(void)
{
  // USER CODE BEGIN (MAIN_Main,2)
  uword uwi = 0;
  // USER CODE END

  MAIN_vlnit();

  // USER CODE BEGIN (MAIN_Main,3)

  // USER CODE END

  while(1)
  {

    // USER CODE BEGIN (MAIN_Main,4)
    // force CTRAP
    for (uwi=0x1000; uwi>0; uwi--);
    SFR_PAGE(_pp1, SST0); // switch to page 1
    P3_PUDSEL ^= 0x40; // force CTRAP on P3.6
    SFR_PAGE(_pp0, RST0); // switch to page 1
    // USER CODE END

  }

} // End of function main
```

How to use the CC6 – CC6-Example 6

- 4) Copy following code
 – shared_int.c

```

//*****
// @Imported Global Variables
//*****
// USER CODE BEGIN (SHARED_INT_General,6)
extern const unsigned int code SineTab[120];
// USER CODE END
  
```

...

```

// USER CODE BEGIN (NodeI0,1)
ubyte idxA = 0;
ubyte idxB = 40;
ubyte idxC = 80;
uword i;
// USER CODE END

void SHINT_viXINTR10Isr(void) interrupt XINTR10INT
{
  
```

...

...

```

if(CCU6_ISL & 0x80) //if ISL_T12PM
{
  //timer T12 period match detection
  SFR_PAGE(_cc0, noSST); // switch to page 0
  CCU6_ISRL = 0x80; //clear flag ISL_T12PM
  // USER CODE BEGIN (NodeI0,17)

  idxA++;
  if (idxA > 119) idxA=0;
  CCU6_CC60SRLH = SineTab[idxA];

  idxB++;
  if (idxB > 119) idxB=0;
  CCU6_CC61SRLH = SineTab[idxB];

  idxC++;
  if (idxC > 119) idxC=0;
  CCU6_CC62SRLH = SineTab[idxC];

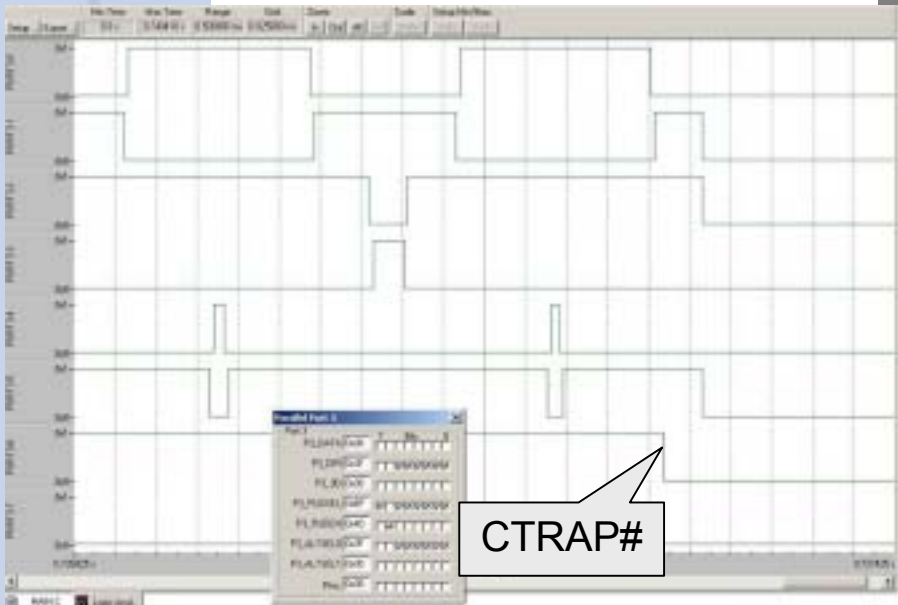
  CC6_vEnableShadowTransfer_CC6_TIMER_12();

  // USER CODE END
  
```

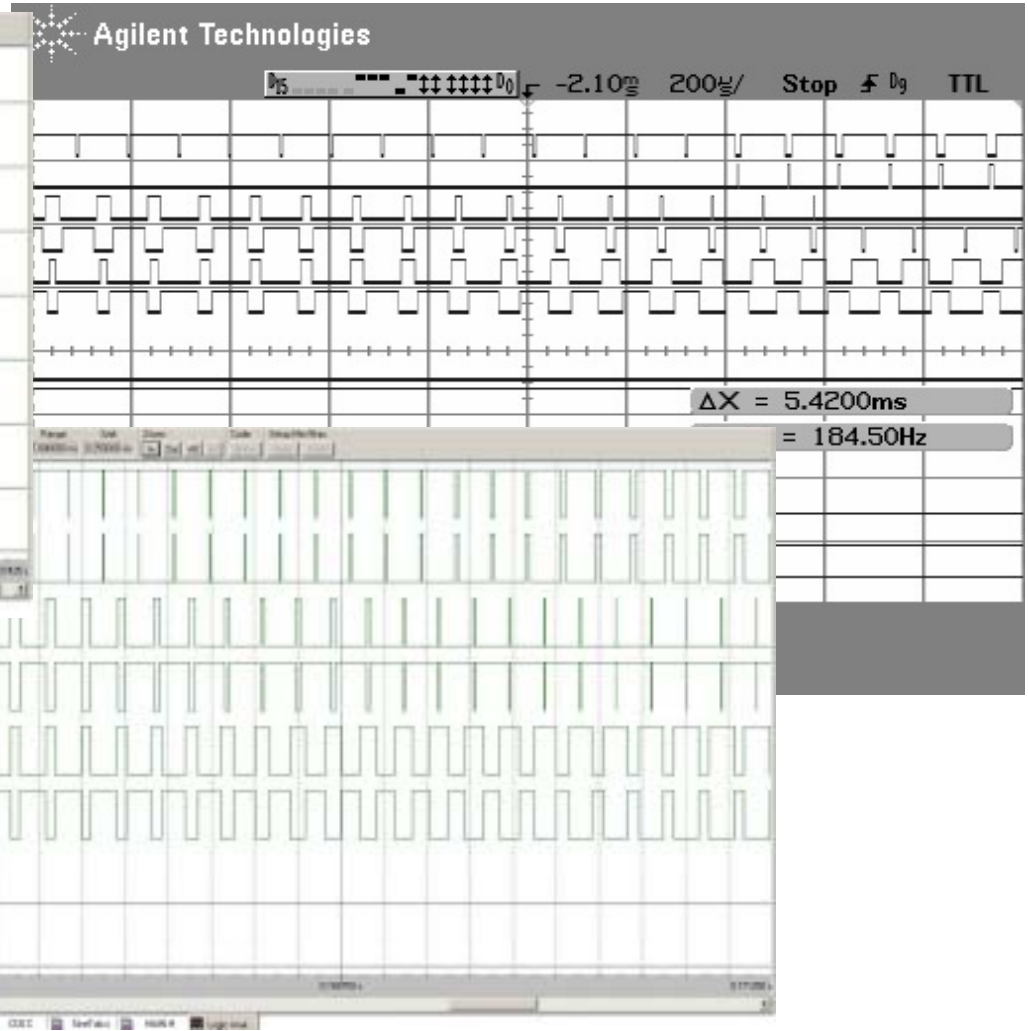
stop thinking
Never

How to use the CC6 – CC6-Example 6

- Logic Analyzer in μ Vision



- Scope Screenshot



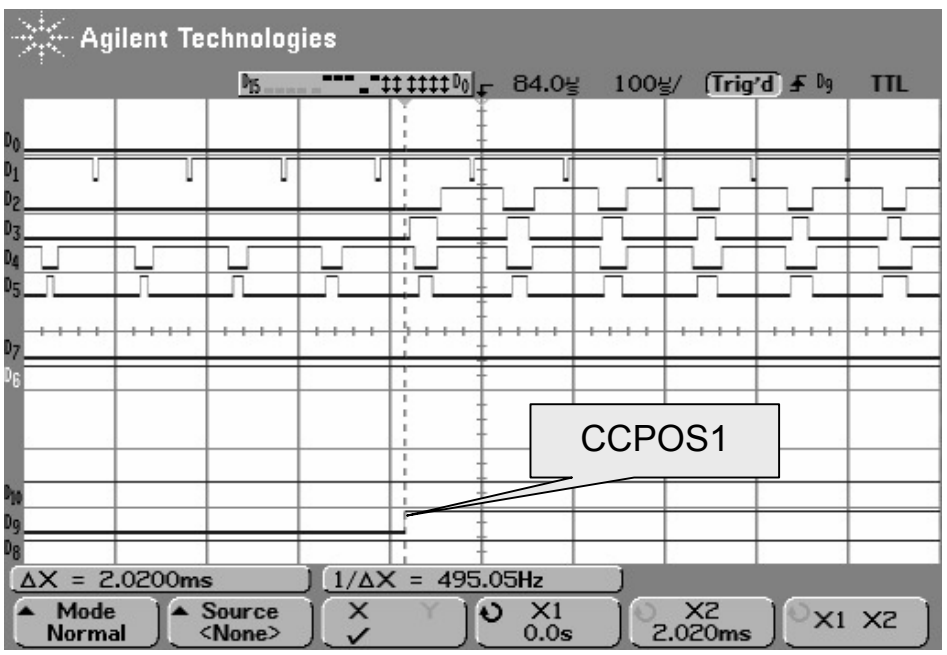
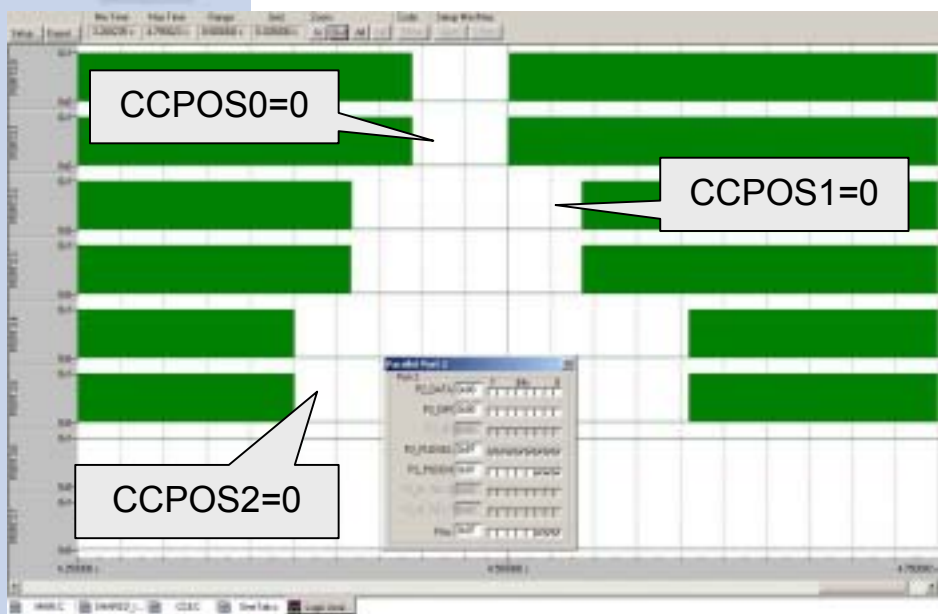
How to use the CC6 – CC6-Example 7

- **CC6_7 – Hysteresis like Mode with 3 channel sinusoidal PWM on T12**
 - update duty cycles with every T12PM interrupt
 - simple sinusoidal table >> see excel sheet SineTab.xls
 - force Hysteresis Control via P2.0/1/2 pulldevices

- 1) Follow step 1- 4 from Example 6
- 2) Select in **Pin Control 1** setting for CCPOSx
- 3) Select in **Channels / Mode Control >> Hysteresis like mode**

How to use the CC6 – CC6-Example 7

- Logic Analyzer in μ Vision
- Scope Screenshot



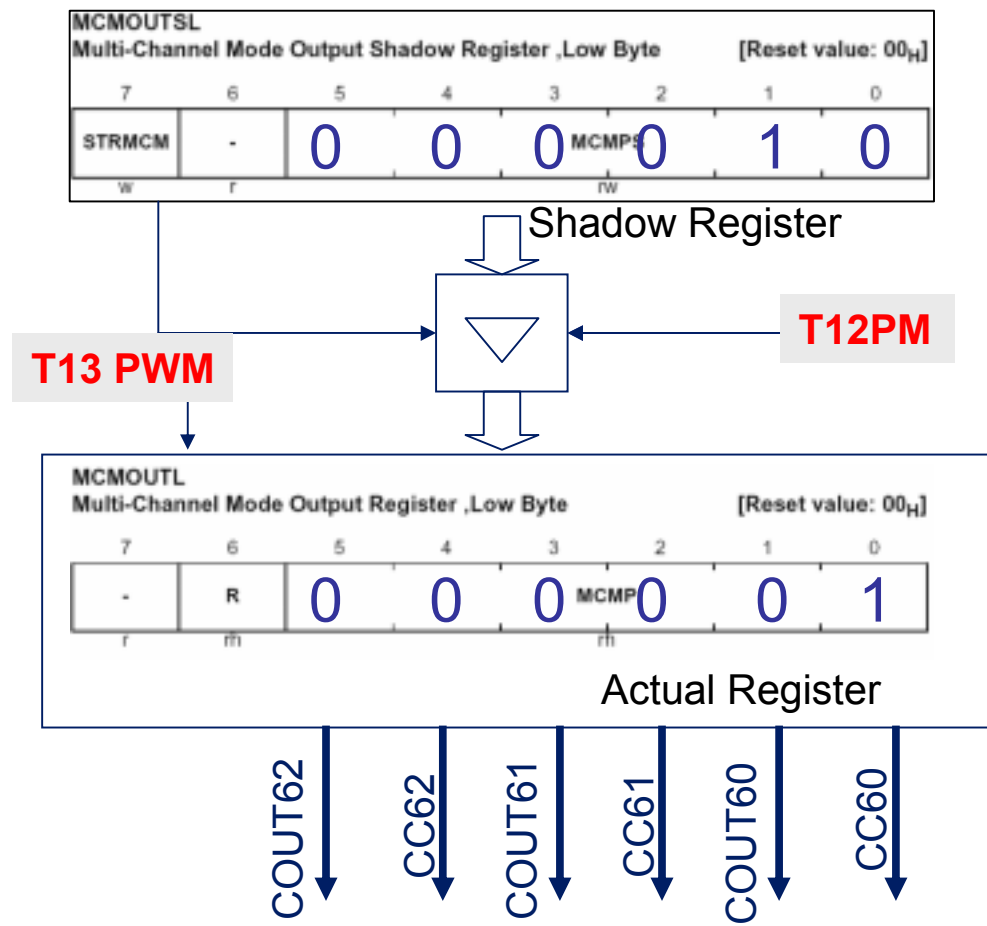
How to use the CC6 – CC6-Example 8

■ CC6_8 – Multichannel mode T12/T13 and MCMOUTx

- T13 modulation on CC6x/Cout6x (~20kHz) with **variable duty cycle**
- T12 periodically switches to next multichannel state with **var. period(~0.5-1kHz)**
- switching transfer on T12PM
- switching synchronization on T13ZM
- CTRAP enabled for all CC6 pins
- interrupt for STR and CTRAP

■ PWM-Pattern:

- 0x01 >> 0x02 >> 0x04 >>
- 0x08 >> 0x10 >> 0x20



How to use the CC6 – CC6-Example 8

- Copy following code
 - shared_int.c

```
// USER CODE BEGIN (NodeI0,1)
const unsigned char code MCMstate[6] =
{0x01, 0x02, 0x04, 0x08, 0x10, 0x20}; //MCM states
unsigned char idxMCM;
// USER CODE END

void SHINT_viXINTR10Isr(void) interrupt XINTR10INT
```

...

```
SFR_PAGE(_cc3, noSST); // switch to page 3

if(CCU6_ISH & 0x80) //if ISH_SSTR
{
// shadow transfer has taken place.
SFR_PAGE(_cc0, noSST); // switch to page 0
CCU6_ISRH = 0x80; //clear flag ISH_SSTR
// USER CODE BEGIN (NodeI0,24)
// change MCM state
idxMCM++;
if (idxMCM>5) idxMCM=0;
CCU6_MCMOUTSL = MCMstate[idxMCM];
CCU6_MCMOUTSL |= 0x80;

// change duty cycle of T13
CCU6_CC63SRLH+=0x80;
if (CCU6_CC63SRLH > 0x0500) CCU6_CC63SRLH=0;
//check limit
CC6_vEnableShadowTransfer_CC6_TIMER_13();

// change period of T12
SFR_PAGE(_cc1, SST1); // switch to page 1
CCU6_T12PRLH-=0x800;
if (CCU6_T12PRLH < 0x3000) CCU6_T12PRLH=0x6000;
// check limit
SFR_PAGE(_cc1, RST1); // restore page
CC6_vEnableShadowTransfer_CC6_TIMER_12();

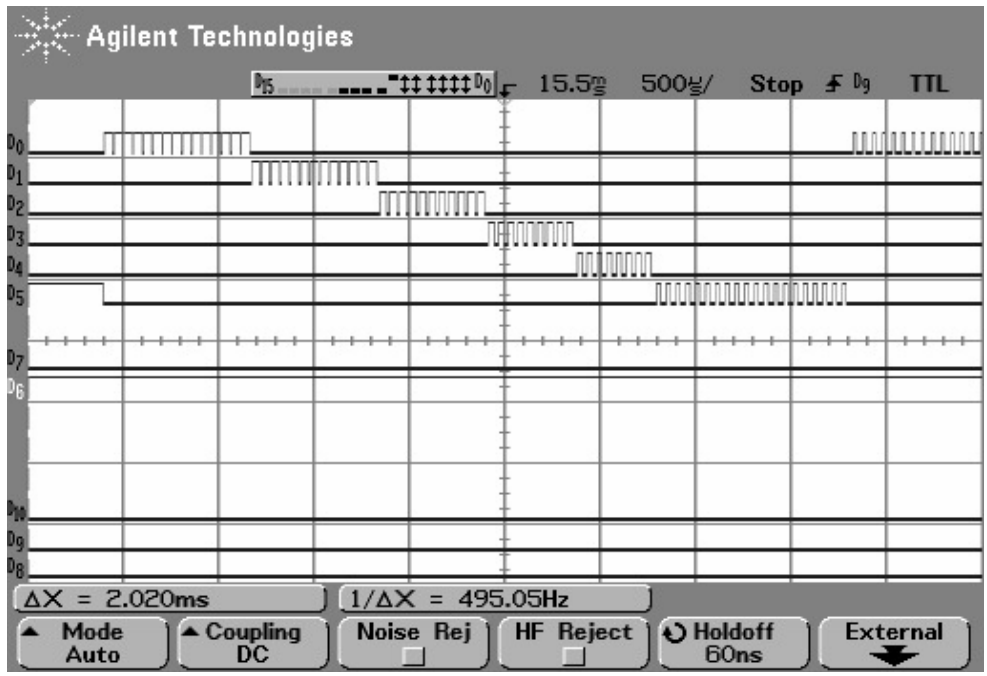
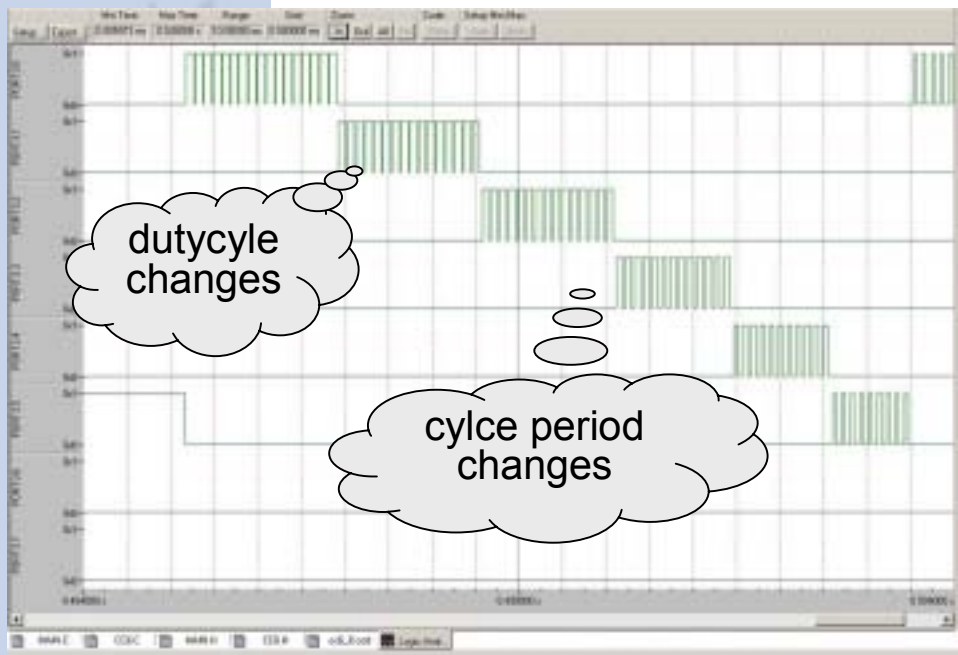
// USER CODE END }
```

stop thinking
Never

How to use the CC6 – CC6-Example 8

- Logic Analyzer in μ Vision

- Scope Screenshot



How to use the CC6 – CC6-Example 9

- **CC6_9** – Double register capture with T12
 - capture on rising edge on pin CC60 to CC60RLH
 - capture on falling edge on pin CC60 to CC60SRLH
- Copy following code
 - main.c

```

void main(void)
{
  // USER CODE BEGIN (MAIN_Main,2)
  unsigned int i;
  // USER CODE END

  MAIN_vlnit();

  // USER CODE BEGIN (MAIN_Main,3)

  // USER CODE END

  while(1)
  {
    // USER CODE BEGIN (MAIN_Main,4)
    for (i=0x1800;i>0;i--);
    SFR_PAGE(_pp1, SST0);      // switch port page
    P3_PUDSEL &= ~0x01;       // falling edge
    SFR_PAGE(_pp1, RST0);     // restore the old port page

    for (i=0x0800;i>0;i--);
    SFR_PAGE(_pp1, SST0);      // switch port page
    P3_PUDSEL |= 0x01;        // rising edge
    SFR_PAGE(_pp1, RST0);     // restore the old port page
    // USER CODE END
  }
}

```

- Copy following code
 - shared_int.c

```

// USER CODE BEGIN (Node0,1)
unsigned int uiCapRise, uiCapFall;
// USER CODE END

void SHINT_viXINTR10lSr(void) interrupt XINTR10INT
.....

if(CCU6_ISL & 0x01) //if ISL_ICC60R
{
  //capture, compare match rising edge detection an channel 0
  SFR_PAGE(_cc0, noSST);    // switch to page 0
  CCU6_ISRL = 0x01;        //clear flag ISL_ICC60R
  // USER CODE BEGIN (Node0,10)
  // double register capture mode 0100
  // rising edge >> capture to CC60RLH
  SFR_PAGE(_cc1, SST0);    // switch to page 1
  uiCapRise = CCU6_CC60RLH;
  SFR_PAGE(_cc1, RST0);    // restore page
  // USER CODE END
}
SFR_PAGE(_cc3, noSST);    // switch to page 3

if(CCU6_ISL & 0x02) //if ISL_ICC60F
{
  //capture, compare match faling edge detection an channel 0
  SFR_PAGE(_cc0, noSST);    // switch to page 0
  CCU6_ISRL = 0x02;        //clear flag IS_ICC60F
  // USER CODE BEGIN (Node0,11)
  // double register capture mode 0100
  // falling edge >> capture to CC60SRLH
  uiCapFall = CCU6_CC60SRLH;
  // USER CODE END
}

```

stop thinking
Never

How to use the CC6 – CC6-Example 10

■ CC6_10 – Hallpattern and Hallogic example

- Hall-Logic without timer involved
- Delay Bypass
- manual porttoggling in CHE ISR
- CHE / WHE interrupt generation

■ Copy following code

– main.c

```

const unsigned char code HallPatt[6] =
{0x3E, 0x34, 0x20, 0x01, 0x0B, 0x1F}; //Hall states
// USER CODE END

void main(void)
{
// USER CODE BEGIN (MAIN_Main,2)
unsigned char i;
unsigned int ida;
// USER CODE END

MAIN_vlinit();

// USER CODE BEGIN (MAIN_Main,3)
#define MCM_transfer 0x80

i = (P2_DATA & 0x7); //111>110>100>000>001>011
    case 7: i=0; break;
    case 6: i=1; break;
    case 4: i=2; break;
    case 0: i=3; break;
    case 1: i=4; break;
    case 3: i=5; break;
    default : i=0; break;
}

CCU6_MCMOUTSH = HallPatt[i] | MCM_transfer;
i++;
CCU6_MCMOUTSH = HallPatt[i];

// USER CODE END

```

■ Copy following code

– main.c

```

// DBYP/HSYNC
SFR_PAGE(_cc2, noSST); // switch to page 2
CCU6_T12MSELH = 0x80; // DBYP=1, any edge at CCPOSx
SFR_PAGE(_cc0, noSST); // switch to page 0
// USER CODE END
while(1)
{
// USER CODE BEGIN (MAIN_Main,4)

for (ida=0x500; ida>0; ida--);
SFR_PAGE(_pp1, SST0); // switch to port page 1
P2_PUDELSEL = 0x07; //111
SFR_PAGE(_pp1, RST0); // restore page
for (ida=0x600; ida>0; ida--);
SFR_PAGE(_pp1, SST0); // switch to port page 1
P2_PUDELSEL = 0x06; //110
SFR_PAGE(_pp1, RST0); // restore page
for (ida=0x700; ida>0; ida--);
SFR_PAGE(_pp1, SST0); // switch to port page 1
P2_PUDELSEL = 0x04; //100
SFR_PAGE(_pp1, RST0); // restore page
for (ida=0x800; ida>0; ida--);
SFR_PAGE(_pp1, SST0); // switch to port page 1
P2_PUDELSEL = 0x00; //000
SFR_PAGE(_pp1, RST0); // restore page
for (ida=0x900; ida>0; ida--);
SFR_PAGE(_pp1, SST0); // switch to port page 1
P2_PUDELSEL = 0x01; //001
SFR_PAGE(_pp1, RST0); // restore page
for (ida=0xA00; ida>0; ida--);
SFR_PAGE(_pp1, SST0); // switch to port page 1
P2_PUDELSEL = 0x03; //011
SFR_PAGE(_pp1, RST0); // restore page

// USER CODE END

```

How to use the CC6 – CC6-Example 10

- Copy following code
 - shared_int.c

```
// USER CODE BEGIN (Node0,1)
extern code unsigned char HallPatt[];
unsigned char i;
// USER CODE END

void SHINT_viXINTR10Isr(void) interrupt XINTR10INT
```

```
if(CCU6_ISH & 0x10) //if ISH_CHE
{
//correct hall event detection

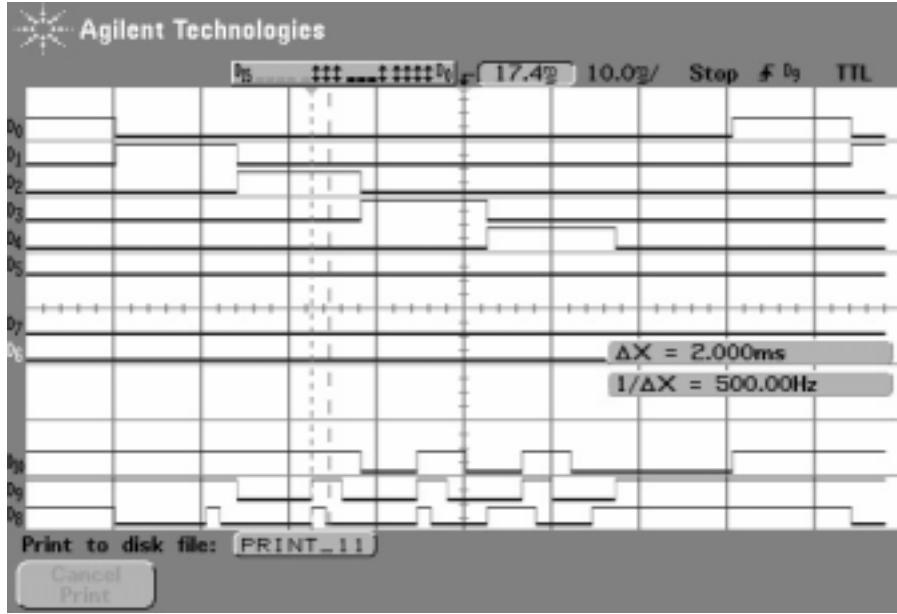
SFR_PAGE(_cc0, noSST); // switch to page 0
SFR_PAGE(_pp0, SST1); // switch to port page 1
CCU6_ISRH = 0x10; //clear flag ISH_CHE

// USER CODE BEGIN (Node0,23)

i = CCU6_MCMOUTSH & 0x07; //get next hall state
switch (i) { //111>110>100>000>001>011
case 7: i=0; P3_DATA=0x00; break;
case 6: i=1; P3_DATA=0x01; break;
case 4: i=2; P3_DATA=0x02; break;
case 0: i=3; P3_DATA=0x04; break;
case 1: i=4; P3_DATA=0x08; break;
case 3: i=5; P3_DATA=0x10; break;
default : i=0; P3_DATA=0xff; break;
}
CCU6_MCMOUTSH = HallPatt[i]; //the shadow transfer will be automatic

// USER CODE END
```

Simulator currently does not support this mode



How to use the CC6 – CC6-Example 11

- **CC6_11 – Hallsensor Mode**
 - complete statemachine for hallsensor mode
 - emulation of hallpattern using pullups on P2 in mainloop or uVision-simulator
 - T13modulation
 - capture on T12Ch0, (phase shift on T12ch1), timeout on T12ch2
 - Hallpattern on P2.0/1/2
 - PWMpattern on P3.0-6
 - interrupts for CTRAP, T12CH2, WHE, CHE, (STR)

- Emulation or Simulation of Hallpattern

How to use the CC6 – CC6-Example 11

- Copy following code
 - main.c

```

//*****
// @Global Variables
//*****
// USER CODE BEGIN (MAIN_General,7)
// MCMOUTSH
// STRHP --- CURHS2 / 1 / 0 EXPHS2 / 1 / 0
// 111>110>100>000>001>011
// 11 1110    3E        111>110
// 11 0100    34        110>100
// 10 0000    20        100>000
// 00 0001    01        000>001
// 00 1011    0B        001>011
// 01 1111    1F        011>111
const unsigned char code HallPatt[6] =
{0x3E, 0x34, 0x20, 0x01, 0x0B, 0x1F}; //Hall states
const unsigned char code OutputPatt[6] =
{0x01, 0x02, 0x04, 0x08, 0x10, 0x20}; //Output states
// USER CODE END

```

```

// USER CODE BEGIN (MAIN_Main,1)
extern const unsigned char code Hallstate[6]; //Hall states
extern const unsigned char code MCMstate[6]; //MCM states
unsigned char i;
unsigned int ida;
// USER CODE END

void main(void)

```

```

void main(void)
{
// USER CODE BEGIN (MAIN_Main,2)
// USER CODE END

MAIN_vlnit();

// USER CODE BEGIN (MAIN_Mai
#define MCM_transfer 0x80 = (P2_DATA & 0x7);
switch (i) { //111>110>100>000>001>011
case 7: i=0; break;
case 6: i=1; break;
case 4: i=2; break;
case 0: i=3; break;
case 1: i=4; break;
case 3: i=5; break;
default : i=0; break;
}
CCU6_MCMOUTSH = HallPatt[i] | MCM_transfer;
CCU6_MCMOUTSL = OutputPatt[i] | MCM_transfer;
i++;
CCU6_MCMOUTSH = HallPatt[i];

CCU6_MCMOUTSL = OutputPatt[i];
// USER CODE END

```

How to use the CC6 – CC6-Example 11

- Copy following code
 - main.c (hall pattern emulation)

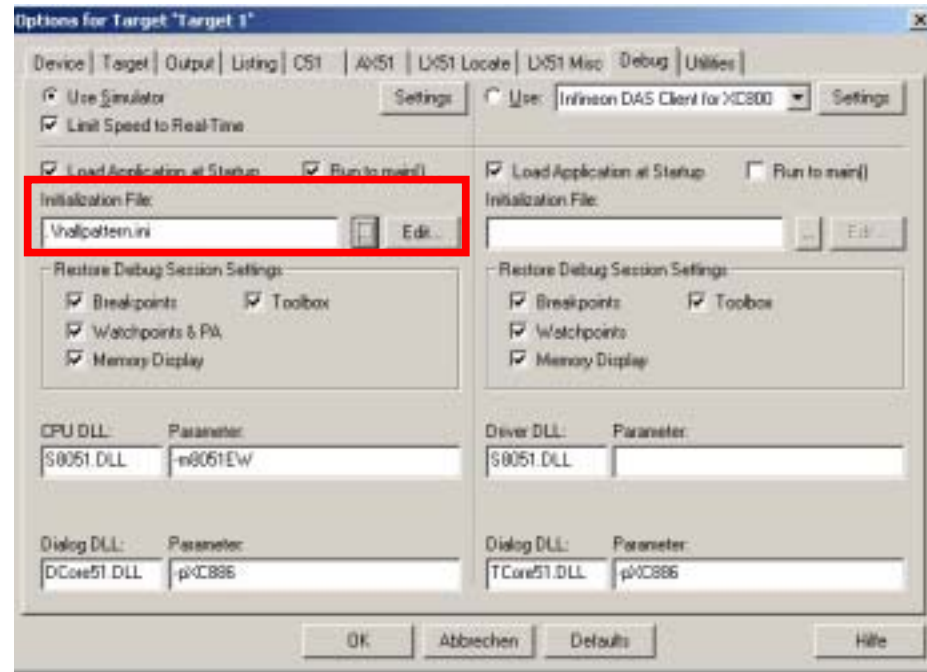
```

while(1)
{
    // USER CODE BEGIN (MAIN_Main,4)
    // /* hall pattern emulator
    SFR_PAGE(_pp1, SST1);    // switch to port page 1
    for (ida=0x500; ida>0; ida--);
    P2_PUDSEL = 0x07;                //111
    for (ida=0x600; ida>0; ida--);
    P2_PUDSEL = 0x06;                //110
    for (ida=0x700; ida>0; ida--);
    P2_PUDSEL = 0x04;                //100
    for (ida=0x800; ida>0; ida--);
    P2_PUDSEL = 0x00;                //000
    for (ida=0x900; ida>0; ida--);
    P2_PUDSEL = 0x01;                //001
    for (ida=0xA00; ida>0; ida--);
    P2_PUDSEL = 0x03;                //011
    SFR_PAGE(_pp1, RST1);    // restore page
    // */
    // USER CODE END

}

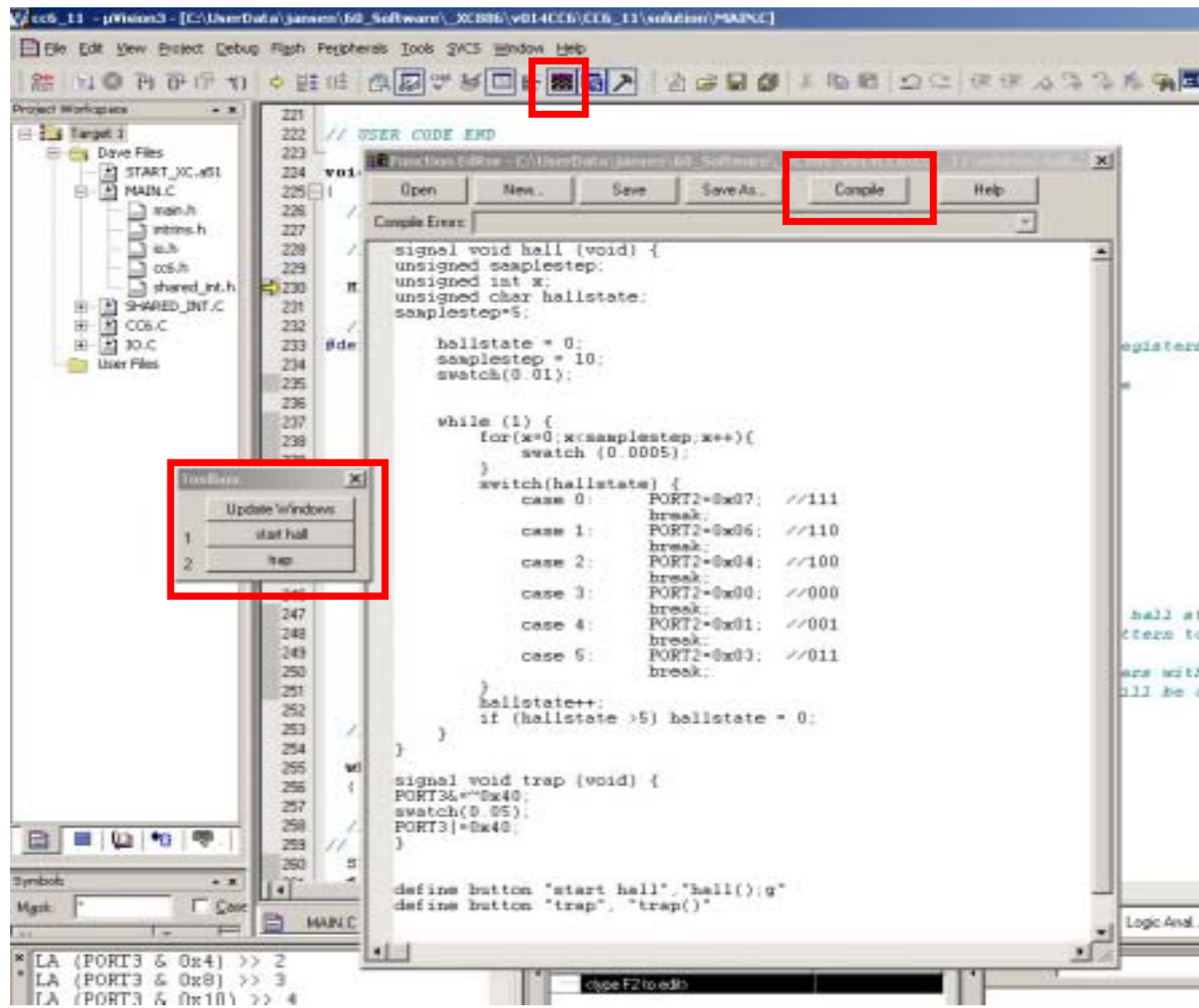
} // End of function main
    
```

- Hall pattern simulation
 - hallpattern.ini



How to use the CC6 – CC6-Example 11

- Hall pattern simulation



Never stop thinking

How to use the CC6 – CC6-Example 11

- Copy following code
 - shared_int.c

```
extern code unsigned char HallPatt[];
extern code unsigned char OutputPatt[];
unsigned char i;

// USER CODE END
SFR_PAGE(_su3, SST0);    // switch to page 3

if (IRCON4 & 0x10) // if CCU6SR3
```

```
if (IRCON4 & 0x10) // if CCU6SR3
{
    IRCON4 &= ~(ubyte)0x10;

    // USER CODE BEGIN (Node13,3)
    // USER CODE END

    SFR_PAGE(_cc3, noSST);    // switch to page 3

    if(CCU6_ISL & 0x04) //if ISL_ICC61R
    {
        //capture, compare match rising edge detection an channel 1
        SFR_PAGE(_cc0, noSST);    // switch to page 0
        CCU6_ISRL = 0x04; //clear flag ISL_ICC61R

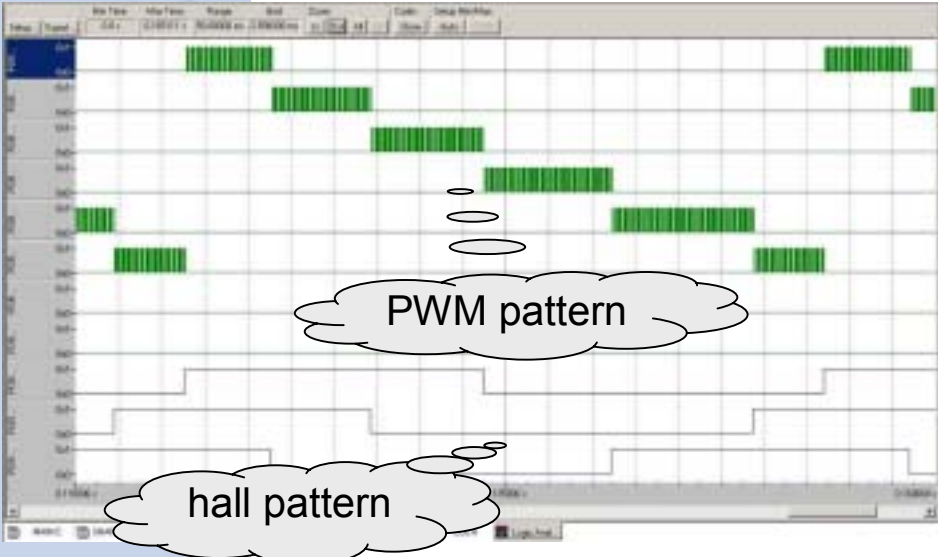
        // USER CODE BEGIN (Node13,12)

        i = CCU6_MCMOUTSH & 0x07; //get next hall state
        switch (i) {           //111>110>100>000>001>011
            case 7: i=0; break;
            case 6: i=1; break;
            case 4: i=2; break;
            case 0: i=3; break;
            case 1: i=4; break;
            case 3: i=5; break;
            default : i=0; break;
        }
        CCU6_MCMOUTSL = OutputPatt[i];
        //program shadow registers with next state values
        CCU6_MCMOUTSH = HallPatt[i];
        //the shadow transfer will be automatic

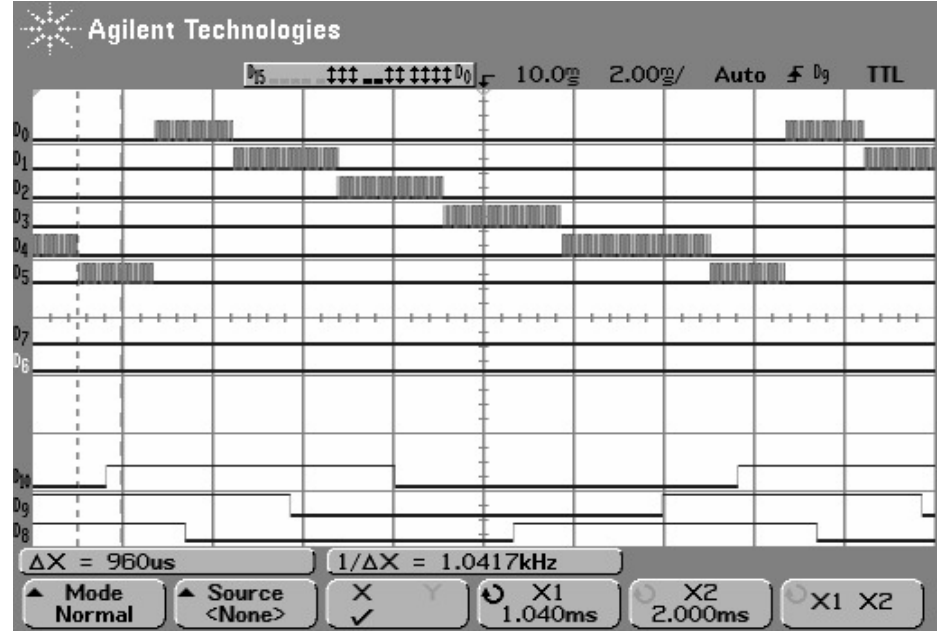
    // USER CODE END
```

How to use the CC6 – CC6-Example 11

- Logic Analyzer in μ Vision



- Scope Screenshot





Any Questions?

Never ^{stop} thinking