CCU\_Clock\_1
for KIT\_AURIX\_TC397\_TFT
Clock configuration via CCU

AURIX™ TC3xx Microcontroller Training V1.0.0





# Scope of work

The clock system is configured based on a PLL frequency of 200 MHz and the clock signal is provided at an external port pin.

The Clock Control Unit (CCU) is used to configure the PLL clock. This clock signal is routed to an external clock output pin, which can be observed with an oscilloscope.



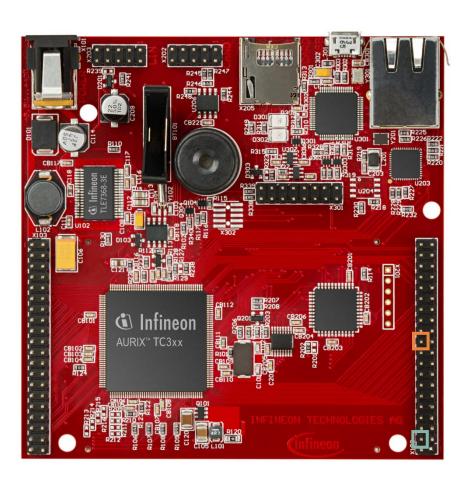
### Introduction

- The Clock Control Unit (CCU) controls the clock system and contains different blocks:
  - Basic clock generation
  - Clock speed upscaling
  - Clock distribution
  - Individual clock configuration
- The Clock Generation Unit (CGU) is part of the CCU and allows a flexible clock generation.
- Phase Lock Loops (PLLs) are provided for upscaling the clock frequency from an internal or external oscillator.
- The System Peripheral Bus (SPB) is used to enable the Fractional Divider (FDR) to divide the source clock.

**Note:** For backward compatibility, some of the registers and functions have the prefix "SCU" (System Control Unit). In AURIX™ TC2xx, the clocking system was a part of the System Control Unit.







This code example has been developed for the board KIT\_A2G\_TC397\_5V\_TFT.

An oscilloscope is needed to observe the clock at the pin P23.1. Connect the clock and the ground to the oscilloscope.

\_x102

PC.		X102	
	P14.5	40 39	P14.4
	P33.10	38 37	P20.9
	P15.7	36 35	P15.6
Clock	P15.5	34 33	P15.4
	P15.3	32 31	P15.2
	P22.3	30 29	P22.2
	P22.1	28 27	P22.0
	P33.11	26 25	P23.4
	P23.3	24 23	P23.2
	P23.1	22 21	P23.0
	P33.6	20 19	P33.8
	P33.12	18 17	P33.1
	P33.2	16 15	P33.3
	P33.4	14 13	P33.5
	AN0	12 11	AN8
	AN2	10 9	AN3
	AN11	8 7	AN13
	AN20	6 5	AN21
	GND	4 3	GND
	V_UC	2 1	VCC_IN





# **Configuring Clock Control Unit**

Configuration of the Clock Control Unit (CCU) is done once in the setup phase by calling the initialization function *initCcuClock()*, which contains the following steps:

- Create an instance of the IfxScuCcu\_Config structure which contains the CCU configuration.
- Initialize the configuration by calling the iLLD function IfxScuCcu\_initConfig().
- Set the PLL dividers (N, P, K2) to get the desired PLL frequency (see page 6) (the desired frequency is 200 MHz for this example).
- Set SPB frequency to the desired value by calling the function IfxScuCcu\_setSpbFrequency() (SPB frequency is 100 MHz for this example).
- Initialize the CCU with the iLLD function IfxScuCcu\_init().

The *initCcuClock()* function is contained in the *CCU\_Clock.h*, while the other functions are part of the iLLD header *lfxScuCcu.h*.





### PLL divider calculation example

The PLL frequency (f<sub>DIIO</sub>) is defined according to the following formula:

$$f_{pll0} = \frac{f_{osc} * N}{K2 * P}$$

where the oscillator's frequency (f<sub>OSC</sub>) is 20 MHz (dependent on hardware).

In this example  $f_{pll0} = 20$  MHz, therefore  $\frac{N}{K2*P} = 20$ . To obtain this value, N should be set to 20, P to 1 and K2 to 2 (P = 1 and K2 = 2 are the defaults values).

**Note:** For selecting appropriate values for the dividers, please consult the User Manual.





### **Configuring the Clock output**

Configuration of the clock output is done once in the setup phase by calling the initialization function *configOutputCcuClock()*, which contains the following steps:

- Call the iLLD function IfxScuWdt\_clearSafetyEndinitInline() to disable the Safety Endinit protection in order to modify the SCU register.
- Set SCU\_CCUCONO.B.CLKSEL to 0x1 to select the clock source.
- Set SCU\_EXTCON.B.EN0 and SCU\_EXTCON.B.SEL0 to enable and select output frequency (f<sub>OUT</sub>) as external source (SCU\_EXTCON.B.EN0 = 0x1, SCU\_EXTCON.B.SEL0 = 0x0).
- Set SCU\_FDR.B.STEP to the desired reload value (see page 9) and SCU FDR.B.DM to choose the normal divider mode.
- Call the iLLD function IfxScuWdt\_setSafetyEndinitInline() to re-enable the Safety Endinit protection.

The functions IfxScuWdt\_clearSafetyEndinitInline() and IfxScuWdt\_setSafetyEndinitInline() are contained in iLLD header IfxScuWdt.h.





### Configuring the port pin

Configuration of the port pin is done as well in the function *configOutputCcuClock()* with the following steps:

- Call the iLLD function IfxPort\_setPinMode() with
   IfxPort\_Mode\_outputPushPullAlt6 as parameter to select CCU external clock as output.
- Set pin pad driver to increase pin's speed by calling the iLLD function IfxPort\_setPinPadDriver() and setting IfxPort\_PadDriver\_cmosAutomotiveSpeed1 as parameter.

The functions *IfxPort\_setPinMode()* and *IfxPort\_setPinPadDriver()* are contained in iLLD header *IfxPort.h*.





### **Step Value calculation example**

The Step Value in normal divider mode is defined according to the following formula:

$$f_{OUT} = \frac{f_{SPB} * \frac{1}{n}}{2}$$
, with n = 1024 - Step

Therefore, 
$$Step = 1024 - \frac{f_{SPB}}{2 * f_{OUT}}$$

In this example, the desired external frequency value ( $f_{OUT}$ ) is 1 MHz, and  $f_{SPB}$  is 100 MHz.

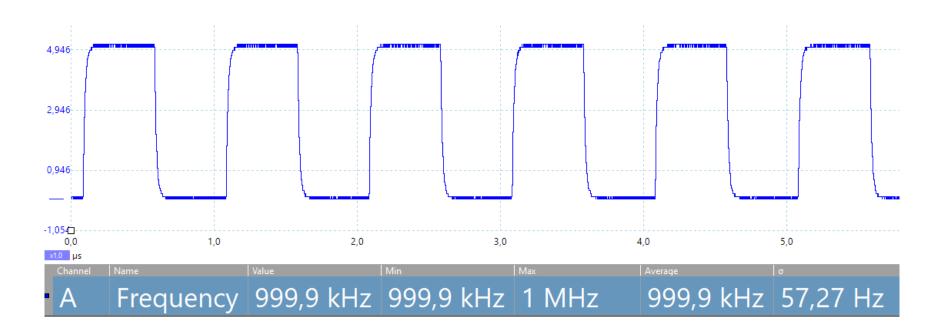
After calculation, the Step Value is 974 (0x3CE).



# Run and Test

After code compilation and flashing the device, perform the following steps:

- Connect the oscilloscope to the board via port pin P23.1 and ground.
- Observe the desired clock on the oscilloscope's screen.



# References







- https://www.infineon.com/aurixdevelopmentstudio
- Use the "Import..." function to get access to more code examples.



- More code examples can be found on the GIT repository:
- https://github.com/Infineon/AURIX\_code\_examples



- For additional trainings, visit our webpage:
- https://www.infineon.com/aurix-expert-training



- For questions and support, use the AURIX™ Forum:
- https://www.infineonforums.com/forums/13-Aurix-Forum

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